

# Energy-Efficient Resource Allocation for NOMA-based Backscatter Communications

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**Abstract**—Backscatter communication (BackCom) is a promising technique for achieving high spectrum efficiency and power efficiency in the future Internet of Things systems. The capacity of BackCom networks can be maximized by optimizing the backscatter time and the reflection coefficient (RC). However, system energy efficiency (EE) cannot be guaranteed usually. In this paper, we investigate the energy-efficient resource allocation problem of a non-orthogonal multiple access (NOMA)-based BackCom. Particularly, the base station (BS) transmits signals to two cellular users based on the NOMA protocol, meanwhile, a backscatter device backscatters the signals to users using the passive radio technology. The total EE of the considered system is maximized by jointly optimizing power allocation for each NOMA user and the RC of backscatter device where the decoding order and the quality of service (QoS) of each user are guaranteed. To solve such a non-convex problem, we develop an efficient iterative algorithm to obtain the optimal solutions by using Dinkelbach's method and the quadratic transformation approach. Numerical results show that the proposed algorithm can significantly improve the system EE compared with the orthogonal multiple access (OMA) scheme and the NOMA system without backscatter devices.

**Index Terms**—Backscatter communications, NOMA, resource allocation, energy efficiency.

## I. INTRODUCTION

ENERGY consumption is a critical issue for the fifth generation (5G) wireless communication systems [1], which should be addressed in the future systems. Backscatter communications (BackComs) [2], [3] have been considered as a candidate to extend the lifetime of IoT systems by directly reflecting the incident radio frequency (RF) signals to the indicated receivers without modulating or generating RF signals by itself. Therefore, BackCom could enhance the signal quality received at the users and reduce the energy consumption of system. Moreover, to provide more access opportunities for massive number of IoT users, non-orthogonal multiple access (NOMA) [4], [5] can be adopted by allowing multiple users to share the same resource block.

To overcome the near-far problem in communication systems, NOMA-based BackCom systems have been investigated to improve system capacity and spectrum utilization [6]. In [7], the closed-form expression of the outage probability and the ergodic rate of NOMA users have been provided for a downlink NOMA-based BackCom system. In [8],

the outage probability has been derived for a NOMA-based BackCom system where the base station (BS) is equipped with multiple antennas. In [9], the exact analytical closed-form expression for the fading-free scenario and semi closed-form expression for the fading scenario have been derived for an uplink NOMA-based BackCom system. However, the above works focus on the performance analysis of the system (e.g., outage probability expression). In [10], the resource allocation (RA) problem for a NOMA-based BackCom system has been formulated as a max-min throughput problem and solved by jointly optimizing the backscatter time and reflection coefficients (RCs). The suboptimal solution has been obtained by using the block coordinated decent and successive convex optimization approaches.

Although the aforementioned works [6]–[10] have laid solid contributions for understanding BackCom systems from various perspectives, e.g., performance analysis and throughput maximization, the optimal solutions of the RA problems have not been obtained yet. Moreover, the decoding order of NOMA user is only considered under the quasi-static channel relationship. Due to the coupled relationship of RC and channel coefficients, however, the effect of dynamic RC is not reflected in the decoding order of NOMA. To the best of our knowledge, this is the first paper to consider the EE-based RA problem for a downlink NOMA-based BackCom system. The main contribution of this paper is summarized as follows: (i) We formulated the RA in NOMA-based BackCom systems as an EE maximization problem by jointly optimizing the transmit power of BS and the RC of the backscatter device (BD), which considers the the minimum signal-to-interference plus-noise ratio (SINR) required by each NOMA user and the decoding order constraint. (ii) The non-convex and fractional optimization problem is converted into an equivalent problem based on the Dinkelbach's method. The difference of concave function (DC) problem is transformed into the convex format by using a quadratic transformation approach. The closed-form solutions are obtained by using the Lagrange dual method and the subgradient approach.

## II. SYSTEM MODEL AND PROBLEM FORMULATION

As illustrated in Fig. 1, we consider a downlink NOMA-based BackCom system. By considering the hardware complexity of successful interference cancellation (SIC), we take two-user case as an example [11], [12]. The BS with the single antenna transmits the superposition signal to user 1 (i.e., the nearby user with good channel condition) and user 2 (i.e., the far-away user with poor channel condition) in the

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$$C_7 : \frac{p_2(h_2 + \rho\bar{g}_2)}{p_1(h_2 + \rho\bar{g}_2) + \sigma^2} \geq \gamma_2^{\min}, \quad (9)$$

where  $\bar{C}_5$  can be obtained by substituting (3), (6) into  $C_5$ .  $C_6$  and  $C_7$  can be obtained by substituting (4), (6) into  $C_4$ . Even though the problem is more tractable, there are coupling relationships among different optimization variables. In order to solve it, we first present the following Proposition.

**Proposition 1:** For any given system setting and optimization variable, the optimal RC,  $\rho^*$ , of **P2** is calculated as

$$\rho^* = \min \left( 1, \max \left( 0, \frac{h_1 - h_2}{g^d(g_2^u - g_1^u)} \right) \right). \quad (10)$$

*Proof:* Please see Appendix A.

*Remark 1:* The proposed Proposition 1 serves two purposes. Firstly, we provide a closed-form expression for the optimal RC and hence get the optimal RC using the above closed-form expression without requiring any iterative algorithms, which reduce the computational complexity significantly. Secondly, we can get more insights about on the optimal RC. For example, when  $\rho^* = 1$ , the optimal RC can be obtained when the BD is close to user 1, namely,  $h_1 + g^d g_1^u > h_2 + g^d g_2^u$  from  $\bar{C}_5$ . Since the data rate of user 1 has no co-channel interference in (4), it can further increase the sum rate of users. When  $\rho^* = (h_1 - h_2)/(g^d(g_2^u - g_1^u))$ ,  $g_2^u > g_1^u$  means that the BD is closer to user 2.

### B. Optimal Power Allocation

When  $\rho = 1$ , we obtain **P3**. When  $\rho = (h_1 - h_2)/(g^d(g_2^u - g_1^u))$ , we obtain **P4**. According to the proposed Proposition 1, we denote  $h = \rho = h_1 - h_2/(g(g_2 - g_1))$ . Then **P2** can be equivalent to the following two power allocation optimization problems, i.e.,

$$\begin{aligned} \mathbf{P3} \quad & \max_{p_1, p_2} \log_2 \left( 1 + \frac{p_1(h_1 + \bar{g}_1)}{\sigma^2} \right) - \eta \left( \sum_{i=1}^2 p_i + P_c \right) \\ & + \log_2 \left( 1 + \frac{p_2(h_2 + \bar{g}_2)}{p_1(h_2 + \bar{g}_2) + \sigma^2} \right) \end{aligned} \quad (11)$$

$$s.t. \quad C_2 - C_3, \quad C_6 : \frac{p_1(h_1 + \bar{g}_1)}{\sigma^2} \geq \gamma_1^{\min},$$

$$C_7 : \frac{p_2(h_2 + \bar{g}_2)}{p_1(h_2 + \bar{g}_2) + \sigma^2} \geq \gamma_2^{\min},$$

$$\mathbf{P4} \quad \max_{p_1, p_2} \log_2 \left( 1 + \frac{p_1(h_1 + h\bar{g}_1)}{\sigma^2} \right) - \eta \left( \sum_{i=1}^2 p_i + P_c \right)$$

$$+ \log_2 \left( 1 + \frac{p_2(h_2 + h\bar{g}_2)}{p_1(h_2 + h\bar{g}_2) + \sigma^2} \right)$$

$$s.t. \quad C_2 - C_3, \quad \tilde{C}_6 : \frac{p_1(h_1 + h\bar{g}_1)}{\sigma^2} \geq \gamma_1^{\min},$$

$$\tilde{C}_7 : \frac{p_2(h_2 + h\bar{g}_2)}{p_1(h_2 + h\bar{g}_2) + \sigma^2} \geq \gamma_2^{\min}, \quad (12)$$

It is noted that **P3** and **P4** have the same structure in which there are the concave objective function and linear constraints except for the second item of the objective function.

**Proposition 2:** For any given system settings, define  $\bar{h}_2 = h_2 + h\bar{g}_2$ , the function  $G(p_1, p_2) =$

$\log_2(1 + p_2\bar{h}_2/(p_1\bar{h}_2 + \sigma^2))$  is a non-convex or non-concave function.

*Proof:* Please see Appendix B.

In order to make the problem traceable, by applying the quadratic transformation [15], **P3** and **P4** can be converted into the convex form as

$$\begin{aligned} \mathbf{P5} \quad & \max_{p_1, p_2, y} \log_2 \left( 1 + \frac{p_1\bar{h}_1}{\sigma^2} \right) - \eta \left( \sum_{i=1}^2 p_i + P_c \right) \\ & + \log_2 \left( 1 + 2y\sqrt{p_2\bar{h}_2} - y^2(p_1\bar{h}_2 + \sigma^2) \right) \end{aligned} \quad (13)$$

$$s.t. \quad C_2 - C_3, \quad C_8 : p_1\bar{h}_1 \geq \sigma^2\gamma_1^{\min},$$

$$C_9 : p_2\bar{h}_2 \geq p_1\bar{h}_2\gamma_2^{\min} + \sigma^2\gamma_2^{\min},$$

where  $y$  is a non-negative auxiliary variable.  $\bar{h}_1 = h_1 + \bar{h}\bar{g}_1$ ,  $\bar{h}_2 = h_2 + \bar{h}\bar{g}_2$  and  $\bar{h} = \min \left( 1, \frac{h_1 - h_2}{g_2 - g_1} \right)$ . For the fixed  $p_i$ , the optimal solution to  $y$  is

$$y^* = \frac{\sqrt{p_2\bar{h}_2}}{p_1\bar{h}_2 + \sigma^2}. \quad (14)$$

which is equivalent to

$$y^* = \begin{cases} \frac{\sqrt{p_2(h_2 + gg_2)}}{p_1(h_2 + gg_2) + \sigma^2}, \rho = 1 \\ \frac{\sqrt{p_2(g_2h_1 - g_1h_2)/(g_2 - g_1)}}{p_1(g_2h_1 - g_1h_2)/(g_2 - g_1) + \sigma^2}, \rho = \frac{h_1 - h_2}{g(g_2 - g_1)} \end{cases} \quad (15)$$

For the fixed  $y$ , **P5** is a convex optimization problem, which can be effectively solved by the CVX tool. However, to further analyze the system performance, we solve it by using Lagrange dual approach to get the closed-form solutions. The Lagrangian function of **P5** can be written by

$$\begin{aligned} L(p_1, p_2, y, \alpha, \beta, \lambda) = & \log_2 \left( 1 + \frac{p_1\bar{h}_1}{\sigma^2} \right) - \eta \left( \sum_{i=1}^2 p_i + P_c \right) \\ & + \log_2 \left( 1 + 2y\sqrt{p_2\bar{h}_2} - y^2(p_1\bar{h}_2 + \sigma^2) \right) + \alpha \left( P - \sum_{i=1}^2 p_i \right) \\ & + \beta (p_1\bar{h}_1 - \sigma^2\gamma_1^{\min}) + \lambda (p_2\bar{h}_2 - p_1\bar{h}_2\gamma_2^{\min} - \sigma^2\gamma_2^{\min}), \end{aligned} \quad (16)$$

where  $\alpha, \beta$  and  $\lambda$  are the non-negative Lagrange multipliers. Define the dual objective  $D(\alpha, \beta, \lambda)$  as the solution to the following:

$$D(\alpha, \beta, \lambda) = \max_{p_1, p_2, y} L(p_1, p_2, y, \alpha, \beta, \lambda). \quad (17)$$

The dual optimization problem is:

$$\min_{\alpha, \beta, \lambda} D(\alpha, \beta, \lambda), \quad s.t. \quad \alpha \geq 0, \beta \geq 0, \lambda \geq 0. \quad (18)$$

According to Karush-Kuhn-Tucker (KKT) conditions [16], the optimal power  $p_1$  and  $p_2$  can be calculated by  $\partial L/\partial p_1 = 0$  and  $\partial L/\partial p_2 = 0$ , respectively, i.e.,

$$p_1^* = \left[ \frac{A_4 + \sqrt{A_4^2 + 4\bar{h}_1\bar{h}_2y^2(A_1\sigma^2 - A_3/A_2)}}{2\bar{h}_1\bar{h}_2y^2} \right]^+, \quad (19)$$

$$p_2^* = \left[ \frac{B_2^2 + 4B_3 - B_2\sqrt{B_2^2 + 8B_3}}{8B_1^2\bar{h}_2} \right]^+, \quad (20)$$

where  $[x]^+ = \max(0, x)$ ,  $A_1 = 1 + 2y\sqrt{p_2\bar{h}_2} - y^2\sigma^2$ ,  $A_2 = \eta + \alpha + \lambda\bar{h}_2\gamma_2^{\min} - \beta$ ,  $A_3 = \bar{h}_1A_1 - y^2\bar{h}_2\sigma^2$ ,  $A_4 = \frac{2\bar{h}_1\bar{h}_2y^2}{A_2} +$

$y^2 \bar{h}_2 \sigma^2 - \bar{h}_1 A_1$ ,  $B_1 = \eta + \alpha - \lambda \bar{h}_2$ ,  $B_2 = B_1(1 - y^2(p_1 \bar{h}_2 + \sigma^2))$ , and  $B_3 = A_1 y \bar{h}_2$ .

*Remark 2:* For the fixed channel parameters, if  $p_1$  increases,  $B_2$  decreases and  $p_2$  increases based on (20). The reason is that the larger  $p_1$  means user 2 suffers from severe interference from user 1, and the transmit power of user 2 has to be increased to overcome the effect of such interference for guaranteeing the minimum QoS requirement of user 2 from  $C_7$ .

Based on the subgradient methods, the Lagrange multipliers can be updated by

$$\alpha^{t+1} = \left[ \alpha^t - d_1(t) \times \left( P - \sum_{i=1}^2 p_i \right) \right]^+, \quad (21)$$

$$\beta^{t+1} = [\beta^t - d_2(t) \times (p_1 \bar{h}_1 - \sigma^2 \gamma_1^{\min})]^+, \quad (22)$$

$$\lambda^{t+1} = [\lambda^t - d_3(t) \times (p_2 \bar{h}_2 - p_1 \bar{h}_2 \gamma_2^{\min} - \sigma^2 \gamma_2^{\min})]^+, \quad (23)$$

where  $t$  denotes the iteration number.  $d_1(t)$ ,  $d_2(t)$  and  $d_3(t)$  are the positive step sizes at the  $t$ -th iteration. The algorithm can be guaranteed to converge to the optimal values when the steps are chosen to be sufficiently small [17].

### C. Iterative RA Algorithm Design

To obtain the optimal power allocation for NOMA users and the optimal RC for the BD user, we propose an iterative algorithm (e.g., Algorithm 1). As shown in Algorithm 1, under the error tolerance  $\varepsilon$  and the maximum iteration number  $T_{\max}$ , we solve **P5** under the fixed  $\eta$  and  $y$  during each iteration and obtain the optimal solutions by the Lagrange dual approach. The optimal solutions are obtained when  $\sum_{i=1}^2 \log_2(1 + \gamma_{i \rightarrow i}) - \eta \left( \sum_{i=1}^2 p_i + P_c \right) \leq \varepsilon$  or  $t = T_{\max}$  is reached.

## IV. SIMULATION RESULTS

In this section, we provide numerical results to illustrate the performance of the proposed EE-based BackCom scheme with NOMA users. The simulation settings are as following: the channel gain is the same as [18],  $\varepsilon = 10^{-6}$ ,  $\sigma^2 = -100$  dBm,  $\gamma_1^{\min} = \gamma_2^{\min} = 2$  dB,  $P_c = 1$  mW [19]. The unit bandwidth is considered for simplicity. For performance comparisons, we consider the pure NOMA scheme (e.g.,  $g = 0$ , without BackCom) and the pure backscatter scheme with the orthogonal multiple access (OMA) technique.

Fig. 2 shows the total EE of NOMA users versus the channel gain from the BD to user 2. From the figure, the total EE of users increases with the increasing channel gain from the BD to user 2, i.e.,  $g_2^u$ , when  $g_2^u < g_1^u$ . The RC is  $\rho = 1$ , which does not affect the performance. However, the total EE of users increases when the channel condition between the BD and user 2 is improved. When  $g_2^u > g_1^u$ , the total EE of users is the same for the same  $g_1^u$  because the effect of direct channel gain  $g$  is canceled by the expression  $\rho * g^d$ . Moreover, the total EE of users under  $g_1^u = 0.45$  is larger than that under  $g_1^u = 0.3$  subject to the same channel gain from the BS to the BD.

### Algorithm 1 Our proposed iterative RA algorithm.

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**Input:**  $h_1, h_2, g, g_1, g_2, P_c, \sigma^2, P, \gamma_1^{\min}, \gamma_2^{\min}$ .  
**Output:** optimal  $p_1^*, p_2^*, \rho^*$ .

- 1: Set  $T_{\max}, \varepsilon, t = 0, \eta = 0$ .
- 2: Initialize  $\alpha(0), \beta(0), \lambda(0), d_1(0), d_2(0), d_3(0)$ .
- 3: **repeat**
- 4:   **if**  $g_2 > g_1$  **then**
- 5:     Set  $\rho^* = \frac{h_1 - h_2}{g(g_2 - g_1)}$ ,  $\bar{h}_1 = h_1 + \rho^* g g_1$ , and  $\bar{h}_2 = h_2 + \rho^* g g_2$ .
- 6:   **else**
- 7:     Set  $\rho^* = 1$ ,  $\bar{h}_1 = h_1 + g g_1$ , and  $\bar{h}_2 = h_2 + g g_2$ .
- 8:   **end if**
- 9: Solve the problem **P5** with the fixed  $\eta$ .
- 10: Update the auxiliary variable  $y$  by (14).
- 11: Update the transmit power  $p_1$  and  $p_2$  by (19) and (20).
- 12: Update the Lagrange multipliers  $\alpha, \beta$  and  $\lambda$  by (21)–(23).
- 13: **if**  $\sum_{i=1}^2 \log_2(1 + \gamma_{i \rightarrow i}) - \eta \left( \sum_{i=1}^2 p_i + P_c \right) \leq \varepsilon$  **then**
- 14:   Set Flag=1 and return.
- 15: **else**
- 16:   Set Flag=0,  $\eta = \frac{\sum_{i=1}^2 \log_2(1 + \gamma_{i \rightarrow i})}{(\sum_{i=1}^2 p_i + P_c)}$  and  $t = t + 1$ .
- 17: **end if**
- 18: **until** Flag=1 or  $t = T_{\max}$ .

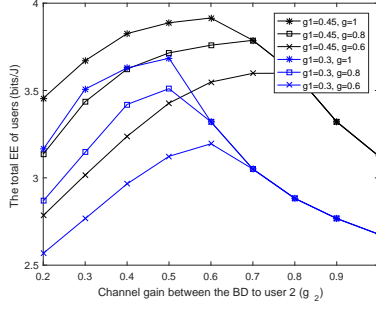
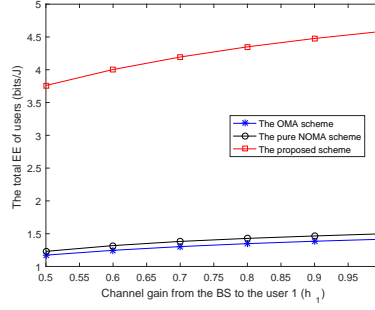
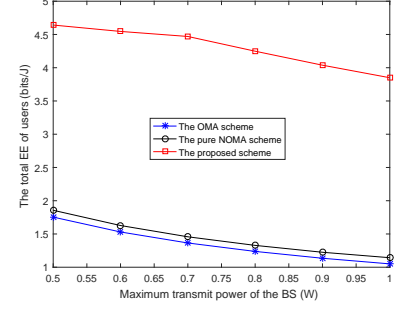
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Fig. 3 presents the relationship between the total EE achieved by NOMA users versus the channel gain between BS and user 1 under the fixed  $P = 1$  W. From the figure, the total EE of users increases with the increasing  $h_1$ . Since larger  $h_1$  refers to higher RC to improve the backscatter data rate. Furthermore, the proposed algorithm performs the best in terms of EE achieved by considering NOMA and BackCom simultaneously. The OMA scheme is the worst one. Because the NOMA scheme can reduce the co-channel interference by the SIC at the receiver, the EE becomes larger than that of the OMA scheme. Furthermore, the proposed scheme not only considers the NOMA transmission but also the backscatter communication for the high EE.

Fig. 4 shows the total EE of NOMA users versus different maximal transmit power budget at the BS with the fixed  $h_1 = 0.5$ . From the figure, the proposed scheme achieves the highest EE compared to the pure NOMA scheme and the OMA scheme. Moreover, the total EE degrades with the increasing transmit power budget at the BS. With increasing transmit power budget  $P$ , the feasible region is enlarged for improving data rates of users. Moreover, the EE of each user decreases with the transmit power budget at the BS.

## V. CONCLUSIONS

In this paper, we investigated the downlink transmissions of NOMA-based BackCom systems. In order to maximize the total EE of NOMA users, we have formulated it as an optimization problem. By proposing a new iterative algorithm, we have obtained the optimal RC of backscatter device and power allocation for NOMA users. It has shown that the NOMA-based BackCom scheme outperforms the NOMA scheme without backscatter way, and the OMA scheme in

Fig. 2. Total EE versus channel gain  $g_2$ .Fig. 3. Total EE versus channel gain  $h_1$ .Fig. 4. Total EE versus transmit power  $P$ .

terms of EE, which could be used to extend the network lifetime.

#### APPENDIX A

##### THE PROOF OF PROPOSITION 1

Define  $F = F_1 + F_2$ ,  $F_1(\rho) = \log_2 \left( 1 + \frac{p_1(h_1 + \rho\bar{g}_1)}{\sigma^2} \right)$ ,  $A = p_1(h_2 + \rho\bar{g}_2) + \sigma^2$  and  $F_2(\rho) = \log_2 \left( 1 + \frac{p_2(h_2 + \rho\bar{g}_2)}{p_1(h_2 + \rho\bar{g}_2) + \sigma^2} \right)$ , thus we have the first-order derivations, i.e.,

$$\frac{\partial F_1}{\partial \rho} = \frac{p_1\bar{g}_1}{\ln 2(p_1h_1 + p_1\rho\bar{g}_1 + \sigma^2)} > 0, \quad (\text{A.1})$$

$$\frac{\partial F_2}{\partial \rho} = \frac{p_2\bar{g}_2\sigma^2}{\ln 2(A^2 + A(p_2h_2 + p_2\rho\bar{g}_2))} > 0. \quad (\text{A.2})$$

Thus, we have the second-order derivations, i.e.,

$$\frac{\partial^2 F_1}{\partial \rho^2} = -\frac{(p_1\bar{g}_1)^2}{\ln 2(p_1h_1 + p_1\rho\bar{g}_1 + \sigma^2)^2} < 0, \quad (\text{A.3})$$

$$\frac{\partial^2 F_2}{\partial \rho^2} = -\frac{p_2\sigma^2\bar{g}_2^2(A(2p_1 + p_2) + p_1p_2(h_2 + \rho\bar{g}_2))}{\ln 2(A^2 + A(p_2h_2 + p_2\rho\bar{g}_2))^2} < 0. \quad (\text{A.4})$$

Therefore,  $F$  is a concave function with respect to  $\rho$  and an increasing function with the variable  $\rho \in [0, 1]$ . As a result, the maximum value of the objective function in **P2** can be determined by the upper bound of the RC. According to  $C_5$ - $C_7$ , we have  $\rho \leq \frac{h_1 - h_2}{g^d(g_2^u - g_1^u)}$  if  $g_2^u > g_1^u$ . Accordingly, the optimal RC is  $\rho^* = \frac{h_1 - h_2}{g^d(g_2^u - g_1^u)}$  when  $h_1 - h_2 < g^d(g_2^u - g_1^u)$ . When  $h_1 - h_2 > g^d(g_2^u - g_1^u)$ , the optimal value is  $\rho^* = 1$ . When  $g_2^u < g_1^u$ , the constraint  $C_5$  is always established since  $\rho \geq 0$ . Under this case, the optimal RC is  $\rho^* = 1$ .

#### APPENDIX B

##### THE PROOF OF PROPOSITION 2

According to the first-order derivation, we have  $\frac{\partial G}{\partial p_2} = \frac{\bar{h}_2}{(p_1 + p_2)\bar{h}_2 + \sigma^2}$  and  $\frac{\partial G}{\partial p_1} = \frac{\bar{h}_2}{(p_1 + p_2)\bar{h}_2 + \sigma^2} - \frac{\bar{h}_2}{p_1\bar{h}_2 + \sigma^2}$ . Thus, the second-order derivations are

$$\frac{\partial^2 G}{\partial p_2^2} = \frac{\partial^2 G}{\partial p_2 \partial p_1} = \frac{\partial^2 G}{\partial p_1 \partial p_2} = -\frac{\bar{h}_2^2}{\ln 2((p_1 + p_2)\bar{h}_2 + \sigma^2)^2} < 0, \quad (\text{B.1})$$

$$\frac{\partial^2 G}{\partial p_1^2} = \frac{p_2\bar{h}_2^3(p_2\bar{h}_2 + 2(p_1\bar{h}_2 + \sigma^2))}{\ln 2((p_1\bar{h}_2 + \sigma^2)(p_1\bar{h}_2 + \sigma^2 + p_2\bar{h}_2))^2} > 0. \quad (\text{B.1})$$

Therefore,  $G(\cdot)$  is a non-convex or non-concave function, which is the difference of two concave function (i.e., D.C. function), e.g.,  $G = \log_2(1 + (p_1 + p_2)\bar{h}_2 + \sigma^2) - \log_2(1 + p_1\bar{h}_2 + \sigma^2)$ .

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