

Interpretable Deep Learning for Probabilistic MJO Prediction

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Key Points:

- A deep convolutional neural network (CNN) is used to produce probabilistic forecasts of the MJO
- The forecasts provide well-calibrated state-dependent estimates of forecast uncertainty
- The CNN forecasts are used to probe sources of predictability for the MJO

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Abstract

The Madden–Julian Oscillation (MJO) is the dominant source of sub-seasonal variability in the tropics. It consists of an Eastward moving region of enhanced convection coupled to changes in zonal winds. It is not possible to predict the precise evolution of the MJO, so sub-seasonal forecasts are generally probabilistic. We present a deep convolutional neural network (CNN) that produces skilful state-dependent probabilistic MJO forecasts. Importantly, the CNN’s forecast uncertainty varies depending on the instantaneous predictability of the MJO. The CNN accounts for intrinsic chaotic uncertainty by predicting the standard deviation about the mean, and model uncertainty using Monte-Carlo dropout. Interpretation of the CNN mean forecasts highlights known MJO mechanisms, providing confidence in the model. Interpretation of forecast uncertainty indicates mechanisms governing MJO predictability. In particular, we find an initially stronger MJO signal is associated with more uncertainty, and that MJO predictability is affected by the state of the Walker Circulation.

Plain Language Summary

The Madden–Julian Oscillation (MJO) is an important tropical climate phenomenon. It consists of enhanced convective thunderstorms and anomalous winds that propagate eastward along the Equator for a few weeks. The MJO is difficult to predict and exhibits great variability. This means that forecasts are often probabilistic. However, current models have difficulty in correctly predicting the uncertainty in the forecast based on the current conditions. In this paper, we propose a model using neural networks capable of making reliable probabilistic forecasts. We interpret the behaviour of the algorithm to verify its consistency with the known physical mechanisms of the MJO and to highlight new physical conditions that affect MJO prediction uncertainty.

1 Introduction

The Madden–Julian Oscillation (MJO: Madden & Julian, 1971) is an envelope of enhanced tropical convection with associated changes to the atmospheric circulation. It is characterised by its period of 40–50 days, its planetary scale, and its Eastward propagation at speeds of $4\text{--}8\text{ ms}^{-1}$. It is the major source of predictability on sub-seasonal timescales in the Tropics (Zhang, 2013) and influences phenomena such as the North Atlantic Oscillation and Arctic sea ice cover through global teleconnections (Ferranti et al.,

1990; Cassou, 2008; Yoo et al., 2012; Henderson et al., 2014). Subseasonal forecasts are of great socio-economic value through their potential to predict extreme weather events several weeks ahead (Vitart & Robertson, 2018). There is therefore great interest in improving predictions of the MJO, and in understanding sources of MJO predictability (Kim et al., 2018).

The chaotic nature of the Earth System means that it is not possible to predict the precise evolution of the MJO beyond a few days, so subseasonal forecasts are generally probabilistic (J. Slingo & Palmer, 2011; Bauer et al., 2015). If the probabilistic forecast *mean* is assessed, averaging out the unpredictable ‘noise’, current dynamical models have a prediction skill up to three weeks (Lim et al., 2018; Vitart, 2017). However, systematic biases remain, especially in the propagation of the MJO convective anomaly over the Maritime Continent (Kim et al., 2016; Barrett et al., 2021; Li et al., 2020). In contrast to the mean skill, the *probabilistic* skill of MJO forecasts is low (Lim et al., 2018; Vitart, 2017). Improving probabilistic forecasts is essential to quantify our confidence in the predictions, and to advance understanding of the predictability of this phenomenon.

While prediction skill is a property of the forecast model, predictability is a property of the Earth-system. MJO predictability studies have focused on the theoretically achievable prediction limit that one could achieve with a perfect model, quantified as 6–7 weeks (e.g. Neena et al., 2014; Wu et al., 2016; Kim et al., 2018). This is complementary to an approach taken in the medium-range forecasting community, where ‘predictable’ forecasts are those for which the forecast uncertainty is small (e.g. Palmer, 2000). This identification is possible because medium-range forecasts exhibit state-dependent reliability (Leutbecher & Palmer, 2008). If reliable, state-dependent, MJO forecasts could be produced, forecast uncertainty could be used as an indicator of instantaneous MJO predictability.

Increasing volumes of data, advances in computational power, and developments in statistical modelling have led to substantial interest in the use of machine learning in Earth-system science (Reichstein et al., 2019; Huntingford et al., 2019). Deep learning has been applied to the MJO for phase classification (Toms et al., 2020; Martin et al., 2021), post processing (Kim et al., 2021), and deterministic prediction (Martin et al., 2021). Here, we develop a neural network that produces well calibrated probabilistic forecasts of the MJO. We use a convolutional neural network (CNN), which has proved ef-

75 fective at identifying hidden patterns and processes in climate (Ham et al., 2019; Arco-
 76 mano et al., 2020; Schultz et al., 2021) and other areas such as image recognition (Russakovsky
 77 et al., 2015).

78 The paper is structured as follows: in Section 2, we describe the CNN, including
 79 the data used to train the model. In Section 3 we present our results. We evaluate the
 80 CNN compared to dynamical models from the Subseasonal-to-Seasonal (S2S) prediction
 81 project. We validate the CNN by seeking to understand its mean forecasts, before us-
 82 ing the CNN to uncover potential sources of predictability for the MJO. Finally we dis-
 83 cuss the significance of our results and draw conclusions in Section 4.

84 2 Methods

85 2.1 Data

86 Observational data used to train and test the CNN are taken from the ECMWF
 87 Reanalysis version 5 (ERA5) dataset between 1979–2019 (Hersbach, H., et al., 2020). We
 88 compare the CNN to models from the S2S database (F. Vitart et al., 2017). We select
 89 reforecast data from four representative models, chosen to span the range of performances
 90 of models in the S2S database. In particular, we include the European Centre for Medium-
 91 Range Weather Forecasts (ECMWF) model, which is known to produce the most skil-
 92 ful MJO forecasts (Lim et al., 2018). The remaining models chosen had the largest re-
 93 forecast ensemble size, enabling probabilistic forecast skill to be assessed. Details are pre-
 94 sented in Supporting Table S1 and Text S1.

95 2.2 Overview of Predictive Model

96 The MJO is a coupled convective-dynamic anomaly that can be summarised by the
 97 bivariate Real-time Multivariate MJO (RMM) index (Wheeler & Hendon, 2004). The
 98 RMM index classifies active MJO events (amplitude greater than one) into one of eight
 99 phases depending on geographical location (e.g. Supporting Figure S1). Using observed
 100 daily-mean maps for a single date t as inputs, we train a deep CNN to predict the mean
 101 and uncertainty in RMM1 and RMM2 computed from daily means at a later date $t+$
 102 τ , training a separate CNN for each lead time. The chosen lead times are one, three and
 103 five days, then every fifth day up to 35 days. The architecture of the CNN is shown in
 104 Supporting Figure S2.

We compute the observed values of the RMM following Wheeler and Hendon (2004) (Supporting Text S2). Subseasonal anomalies of daily-mean Outgoing Longwave Radiation (OLR) and daily-mean zonal winds at 200 hPa (UA200) and 850 hPa (UA850) between 20°S–20°N are latitudinally averaged and divided by their global variance. The first two Empirical Orthogonal Functions (EOFs) of the combined fields are computed. RMM1 and RMM2 are the projection of the daily fields onto EOFs 1 and 2.

Even though the MJO shows seasonal behaviour, we train a single model for all seasons to maximise the available training data. As inputs we use subseasonal anomalies of OLR, UA200, and UA850, consistent with fields used to compute the RMM indices. We supplement these with four further fields which provide complementary information: daily mean Specific Humidity at 400 hPa (SHUM400) was included because Barrett et al. (2021) reported large differences in SHUM400 between MJO events which propagate and weaken over the Maritime Continent; daily mean geopotential at 850 hPa (Z850) provided skill in previous work (Toms et al., 2020); daily mean Downwelling Longwave Radiation at the surface (DLR) has a marked annual cycle, which we found a more effective means of accounting for the seasonality of the MJO than including a dummy variable. Finally, daily anomalies of sea surface temperature (SST) are included, since the MJO is known to be linked to El Nino-Southern Oscillation (ENSO: e.g. Kessler, 2001). Sensitivity of CNN performance to the choice of input feature is shown in Supporting Figure S3, providing insights into sources of predictability for the MJO. Inputs are provided as maps spanning 0–360°E, 20°S–20°N on a 2.5°x2.5° grid. The different variables are input to the CNN as separate channels. This allows the CNN to learn to identify co-located phenomena. To ensure independence between the training and testing data sets, we use the first 80% of the dates for training, and the remaining 20% for testing.

We model the two forecast RMM indices as following a Gaussian Bivariate distribution with null correlation (Wheeler & Hendon, 2004). The network outputs the predicted means and variances of RMM1 and RMM2, and is trained by minimising the negative log-likelihood. The output variance represents the intrinsic chaotic (aleatoric) uncertainty in the prediction. In addition, we represent the epistemic uncertainty in the CNN model weights using a Monte-Carlo Dropout method to produce an ensemble of forecasts (Gal & Ghahramani, 2016; Gal, 2016; Scalia et al., 2019). The total forecast uncertainty is the sum of the aleatoric and epistemic variances. More details are provided in Supporting Text S3.

2.3 Interpretation using PatternNet

We use the PatternNet algorithm (Kindermans et al., 2017) to interpret forecasts made by the CNN, as it outperforms other approaches including Guided BackProp and Layerwise Relevance Propagation in both idealised test cases and for image classification problems (Kindermans et al., 2017). Inputs to the CNN include a *signal*, that contains information about the future state of the MJO, and a *distractor*, that is a residual containing information irrelevant to the prediction task (Kindermans et al., 2017). PatternNet is a distinct network to the CNN, but whose structure reflects that of the CNN in reverse, propagating the estimated signal from the output to the input space, thereby disentangling the signal from the distractor: for more details, see Supporting Text S4.

3 Results

3.1 Network performance

Figure 1 compares the network’s performance to models from the S2S database (see Supporting Text S5 for definitions of all metrics). Figures 1(a–c) show the deterministic skill of the CNN mean forecasts in terms of the Root Mean Square Error (RMSE), Amplitude Error, and Phase Error respectively. In terms of RMSE, the CNN is competitive with models from the S2S database, though has larger errors than ECMWF. Similarly to the dynamical models, the CNN forecasts suffer from an increasing amplitude error with time, indicating a decay in MJO strength over the duration of the forecast. It is known that dynamical models simulate slower MJO propagation speeds than observed, resulting in a negative phase error (Lim et al., 2018). Here the CNN outperforms the dynamical models, accurately capturing the MJO propagation speed. A fourth metric, the bivariate correlation, is shown in Supporting Figure S4: the CNN performance is poorer than ECMWF, but similar to CNRM and BOM.

Figures 1(d–f) assess the probabilistic skill of the CNN. The Continuous Ranked Probability Score (CRPS: Marshall et al. (2016)) compares forecast and observed cumulative distribution functions. The CNN is competitive with forecasts from the S2S database, outperforming three of the four dynamical models considered. Despite being widely used, the CRPS can give unintuitive rankings (e.g Bolin & Wallin, 2019), as it penalises errors in the forecast mean more than poor calibration of spread (Christensen et al., 2015).

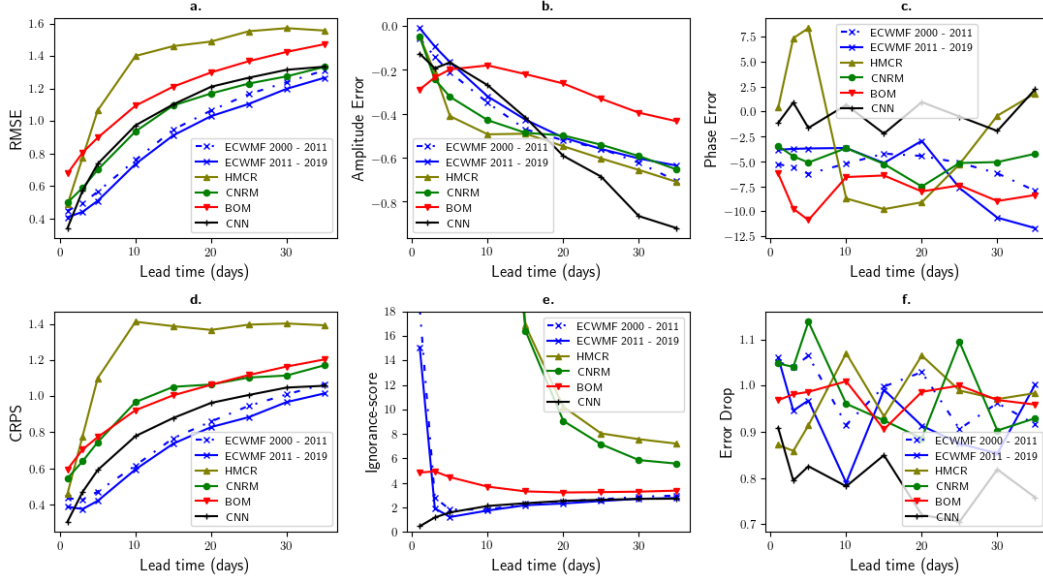


Figure 1. Skill of CNN (black), compared to forecasts from the subseasonal-to-seasonal prediction project (colours) as a function of lead time. (a) Root mean square error. (b) Amplitude error. (c) Phase error. (d) Continuous Ranked Probability Score. (e) Log-score. CNRM and HMCR scores before day-15 were too high to be shown. (f) Error-Drop. For all scores, a value closer to zero indicates a more skilful forecast. Forecasts from different models cover: ECMWF 2000-2019; HMCR 1985-2010; CNRM 1993-2017; BOM 1982-2013; CNN 2011-2019. The ECMWF data was split into two to allow direct comparison with the CNN over 2011-2019, and to give an indication of sampling uncertainty.

An alternative score is the ‘Ignorance’ or log-score (Roulston & Smith, 2002) (Panel e). This score is local, derived from information theory, and easily generalises to multivariate predictions (Roulston & Smith, 2002; Bjerregård et al., 2021). It is also consistent with the loss function used to train the network. According to the log-score, the CNN is one of the two models with the best forecast skill at lead times of 5–35 days. At shorter lead times, it outperforms all dynamical models. The poor performance of dynamical models at these short lead times is due to overconfident forecasts (Bjerregård et al., 2021), which are penalised by the log-score. In contrast, the CNN is able to balance the loss in accuracy with an increasing predicted uncertainty as the lead time increases.

For probabilistic forecasts to be useful, observations should behave as if they were drawn from the forecast probability distribution. For this to hold, a smaller forecast spread should indicate a smaller root mean squared error (RMSE) in the forecast mean on av-

erage. We assess this property using Error-Spread diagrams (Leutbecher & Palmer, 2008) shown in Figure 2. The RMSE is a measure of predictability of the atmosphere: high RMSE indicates lower predictability. The spread indicates the forecast model’s belief about the predictability. For well calibrated forecasts, RMSE and spread should be correlated, and the observed RMSE should equal the predicted standard deviation, with scattered points lying on the one-to-one line. None of the dynamical models have this property: their error distributions are independent of the forecast spread, such that the spread gives no indication of the true predictability of the MJO on that day. In contrast, if the CNN forecast spread is low, the RMSE is smaller than if the spread is high. The probabilistic forecasts produced by the CNN are a dynamic indicator of the certainty in the MJO forecasts, and therefore the instantaneous predictability of the MJO. The aleatoric uncertainty predicted by the CNN is substantially greater than the epistemic uncertainty, indicating that while the MJO exhibits chaotic unpredictability, the CNN weights are well constrained by the available data.

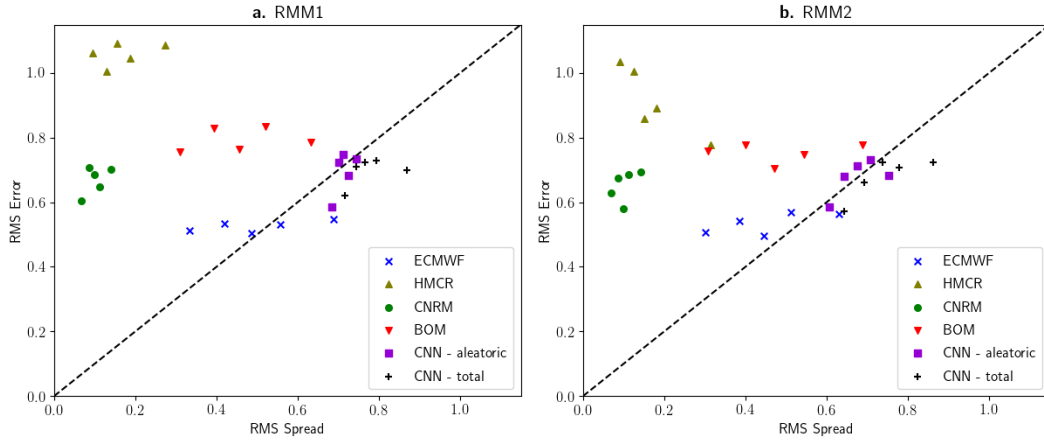


Figure 2. Error-Spread Diagrams for (a) RMM1 and (b) RMM2 at a lead time of ten days. The data are sorted according to the predicted spread before being split into five quintiles. The figure shows the average spread and RMSE for each quintile. Well calibrated forecasts lie on the one-to-one dashed line.

To quantify this property across many lead times, we incrementally remove the days with the highest predicted variance for each lead time and RMM index before computing the RMSE in the forecast of the remaining days. This produces the confidence curve (Scalia et al., 2019). If the forecast correctly ranks different days in terms of forecast un-

certainty, the confidence curve should be strictly decreasing. The error-drop (Figure 1(f)), is the ratio between the last and first points on the confidence curve (Scalia et al., 2019). The smaller the error-drop, the greater the reduction in RMSE when test days are sorted by the forecast uncertainty. The CNN performs better than all dynamical models. It can distinguish between predictable and unpredictable days at all lead times. While an under-dispersive ensemble spread can be corrected to improve the log-score of dynamical models (Figure 1), the ability to sort days according to their predictability cannot be introduced by statistical post-processing.

3.2 Interpretation to validate network behaviour

Before using the CNN to understand sources of uncertainty in the evolution of the MJO, we must understand how the CNN can make skilful forecasts of the MJO. This is necessary, as it reveals any concerning behaviour or spurious correlations (e.g. Lapuschkin et al., 2019), lending confidence to the predictions.

To interpret the CNN mean forecasts, we use the PatternNet algorithm (Kindermans et al., 2017) to derive signal maps for each forecast. These indicate where information is detected by the CNN in each input field. Because the different input variables are introduced as separate channels into the CNN, weights are shared across all variables for much of the network: the CNN distinguishes between variables in the first layer only. It is therefore useful to consider both the signal maps averaged over all variables (the *signal mean*) and the difference between the signal map for each variable and the signal mean map (the *signal anomalies*).

Since propagation over the Maritime Continent is a source of error in MJO forecasts in many models (Kim et al., 2016), we contrast one event which propagated over the Maritime Continent (28/02/2012), and one which decayed (25/02/2006) to validate the CNN’s behaviour. Supporting Figure S1 shows the observed RMM indices for these two events, and the corresponding mean forecasts initialised in phase 3, which capture the observed behaviour.

Figure 3(a–b) shows the SHUM400 input fields averaged over all days in RMM phase 3 for the decaying and the propagating events respectively. Panels (c–d) show the signal means for RMM1 for the associated ten-day CNN forecasts initialised in phase 3. (The signal means for the decaying RMM2 are much smaller, consistent with the pre-

diction that day-10 RMM2 is close to zero for the events selected: see Supporting Figure S5). For both events, the CNN signal mean maps show that the CNN integrates over a large region spanning the Indian and Pacific Oceans, rather than tightly focusing on the active MJO region: the CNN also derives information from the input fields in regions of suppressed convection (Feng et al., 2015; Barrett et al., 2021).

Figure 3 (e–f) show the corresponding PatternNet signal anomalies for SHUM400, highlighting the relative information provided by this input field. We see a large reduction in signal over the Pacific (150°E–90°W), and an enhancement over the Maritime Continent (90°E–110°E) co-located with enhanced SHUM400. Supporting Figures S6–S7 show the equivalent figure for OLR. The RMM1 signal anomaly is greater than for SHUM400, and it is stronger over the Pacific than was the case for SHUM400. Both Feng et al. (2015) and Barrett et al. (2021) found OLR precursors in this region which distinguished between propagating and non-propagating MJO events. We conclude that the CNN has identified true predictive features of MJO propagation, giving us confidence in the network.

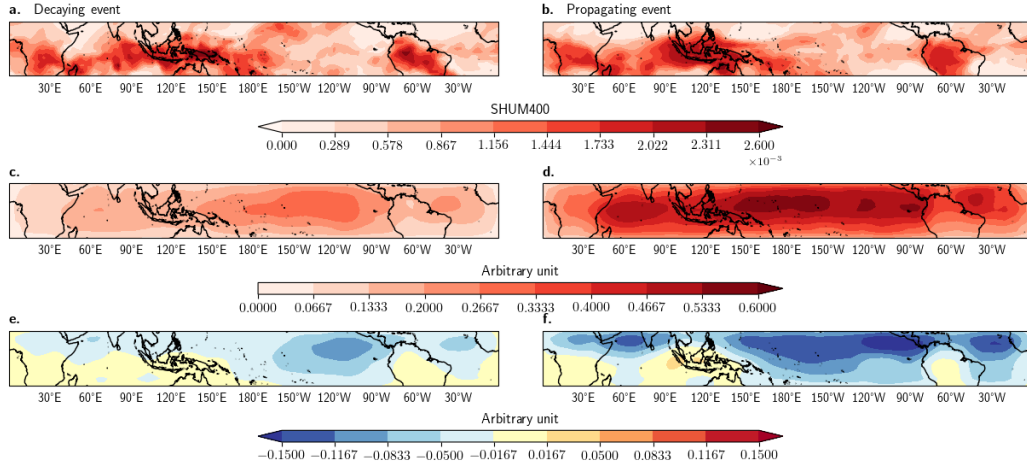


Figure 3. Interpretation of CNN mean forecasts. (a–b) Composite maps of phase-3 SHUM400 for an MJO event which (a) decays and (b) propagates over the Maritime Continent. (c–d) PatternNet RMM1 signal means (averaged over all variables) for ten-day CNN forecasts for the decaying and propagating event respectively. (e–f) RMM1 signal anomalies in SHUM400 for the decaying and propagating events respectively.

3.3 Predictors of uncertainty in MJO forecasts

The ability of the CNN to rank days by uncertainty enables us to investigate drivers of short-term predictability of the MJO. We consider cases in Boreal winter, and separate MJO events into 4 categories according to the CNN's 10-day forecast. We first categorise according to strength: for each day, an event is weak (strong) if the initial observed RMM amplitude is less than (greater than) 1.0. The data are then divided into certain and uncertain forecasts. To study the uncertainty that is directly linked to the MJO initial conditions, we use the network's predicted aleatoric uncertainty. An event is certain (uncertain) if both the RMM1 and RMM2 forecast aleatoric uncertainties are under (over) their respective 30% (70%) percentiles. For each initial observed phase and input feature, we compute the difference between certain and uncertain days, separately for weak and strong events.

Figure 4 shows results for SHUM400 for events starting in phases 3 and 7. For phase 3, the initial conditions of 'certain' forecasts have reduced humidity at the equator in the central Pacific (150°E-120°W) and Indian Ocean (45°E-100°E), combined with off-equatorial regions of enhanced humidity over the Maritime Continent and Australia (100°E-160°E). Before concluding that this 'fingerprint' is an indicator of high certainty, there are two possible confounding factors to consider: the initial strength of the signal, and the forecast strength at day-10. The difference maps for weak and strong events are similar to each other, indicating the fingerprint is independent of initial strength. However, there is a correlation between the forecast uncertainty and the forecast strength at day-10: $\sim 65\%$ of 'certain' events are forecast as weak by day-10, while $\sim 80\%$ of 'uncertain' events are forecast strong at day-10 (Supporting Table S3). Therefore sorting the data by forecast certainty unintentionally also sorts by forecast strength. To remove this confounding factor, we further stratified the events by strength at day-10. The moisture signal was muted if all events forecast as weak at day-10 were removed from the composites, whereas if only events forecast as transitioning from strong to weak were considered, the signal became more intense (not shown). This confirms that the fingerprint is primarily an indicator of forecast strength at day-10, consistent with the conclusions of (Jiang et al., 2020) who found that this structure hinders the eastward propagation of the MJO.

For events initialised in phase 7, uncertain events show reduced moisture over the Maritime Continent in the MJO suppressed region (90°E-120°E), and enhanced mois-

ture over the MJO active region (150°E-150°W), when compared to certain events. This signature of an enhanced MJO signal in the initial conditions for unpredictable events is observed for other variables for phase 7, particularly OLR (Supporting Figure S8). For events initialised in phase 7, 85% of uncertain forecasts are also likely to be strong at day-10, whereas that drops to 40% for certain forecasts (Supporting Table S4). However, if we further stratify the forecasts by final strength, we find the signature persists (not shown). Thus we conclude that an initially stronger MJO signal is associated with more uncertainty in the forecast.

Finally, we find that MJO predictability is affected by the background state through which it propagates. In particular, for events classified as certain, Z850 shows an enhanced gradient between the Eastern Pacific and the Maritime Continent for all forecasts initialised in phases 4–7 (i.e. all events crossing the Pacific: Supporting Figure S9–S10). An enhanced Z850 gradient is consistent with a higher Southern Oscillation index and a stronger Walker circulation cell over the Pacific. Further stratification by strength at day-10 indicates that this signal is unrelated to forecast strength. An enhanced (neutral or weakened) Walker circulation therefore leads to enhanced (reduced) certainty in the MJO.

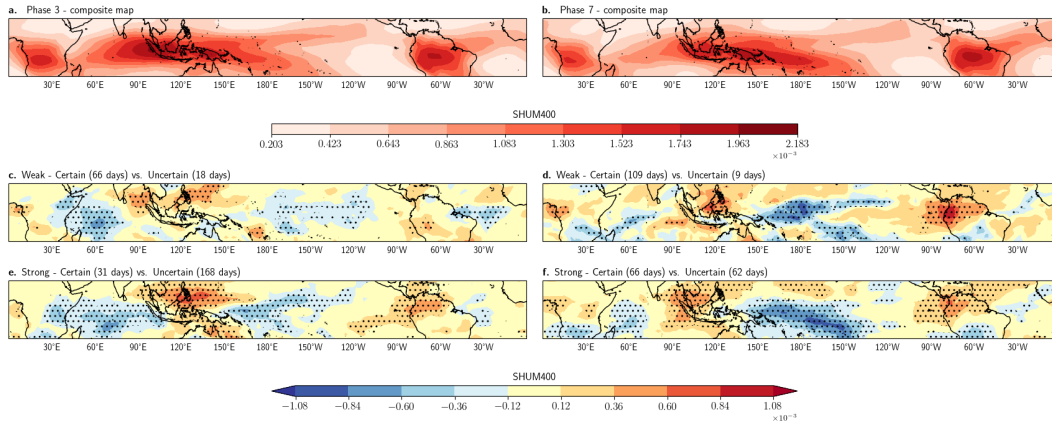


Figure 4. Interpretation of CNN uncertainty forecasts. (a-b) Composite maps of specific Humidity at 400hPa (SHUM400) for extended Boreal winter MJO events in (a) phase 3 and (b) phase 7. (c-f) Difference between input maps for predictable and unpredictable events as classified by ten-day forecasts using the CNN. (c) Weak phase 3 events (d) Weak phase 7 events. (e) Strong phase 3 events (f) Strong phase 7 events. Stippling denotes areas where anomalies are significant at the 95% level using the Student’s t-test.

4 Discussion and Conclusions

We presented a CNN which produces probabilistic forecasts of the MJO in terms of means and variances of the bivariate RMM index. The skill of the CNN is competitive with models from the S2S database. Moreover, the CNN outperforms all S2S models for one key forecast property: it can rank start dates according to the forecast uncertainty associated with the initial conditions. In other words, the CNN forecast spread is a dynamic indicator of the uncertainty in the MJO forecast on a given day.

Since the CNN exhibits state-dependent reliability, we identify ‘certain’ CNN forecasts with predictable states of the MJO and use the CNN forecasts to probe associated sources of predictability. We do this by considering composites of initial conditions which the CNN indicated led to ‘certain’ and ‘uncertain’ ten-day forecasts. We found that for forecasts initialised in phase 3, reduced humidity on the equator increases the likelihood of a decaying MJO event, which is associated with high forecast certainty. However, enhanced humidity on the equator increases the likelihood of MJO propagation over the MC, but it does not guarantee propagation, leading to high uncertainty in the forecast and low medium-range predictability.

The CNN also used background state information to determine the MJO’s instantaneous predictability. A reduced gradient in Z850 was linked to more forecast uncertainty for all MJO phases approaching the Pacific. This change in Z850 reflects a weaker Walker circulation, associated with El-Niño events. However, we found no consistent signal in East Pacific SST across these phases (Supporting Figures S11–S12). There is substantial debate about the dependency of the MJO on the state of the El Niño-Southern Oscillation (ENSO) (e.g. Ling et al., 2017). The Eastward extent of MJO activity is greater in El Niño years, (Kessler, 2001), and the MJO lifetime and propagation speed is also modulated by ENSO, though it shows sensitivity to the season of interest and type of ENSO event (Pohl & Matthew, 2007; Pang et al., 2016). In contrast, the overall amplitude of MJO activity appears unrelated to ENSO (J. M. Slingo et al., 1999; Kessler, 2001). While the dependency of the MJO on the back-ground state is usually considered in terms of SST, our results demonstrate ENSO could primarily influence the MJO via changes to the atmospheric dynamical background associated with El Niño and La Niña.

Our CNN approach is complementary to earlier MJO predictability studies (e.g. Neena et al., 2014; Wu et al., 2016; Kim et al., 2018). Instead of quantifying the poten-

tial predictability *limit* using our model, we assess relative predictability in the medium-range across different initial conditions. We can only do this because the CNN produces state dependent reliable probabilistic forecasts. Our focus was on forecasts at a lead time of 10-days. Longer lead time forecasts may show a different signal of predictability in the initial conditions: for example, while we found that a weak MJO event predictably decays over a 10-day period, the situation after those 10-days is likely to be more unpredictable than for events where the MJO persists beyond the 10-day period.

The CNN is competitive with the best available dynamical models at predicting the MJO. However CNNs are complementary to dynamical models, and further improvements to MJO forecasting may be achieved through a blend of dynamical and machine learning approaches (Kim et al., 2021). Nevertheless, developing a stand-alone CNN facilitates interpretation, enabling us to probe the performance of the CNN and develop new physical understanding, e.g. the role of different input features. This framework of combining state-dependent uncertainty estimates from neural networks with interpretation techniques could be applied to other climate phenomena, allowing us to quantify the diverse range of sources of uncertainty in the Earth System.

5 Open Research

Data related to this paper can be downloaded from the ERA5 Copernicus database (<https://cds.climate.copernicus.eu/cdsapp#!/dataset/reanalysis-era5-pressure-levels>, <https://cds.climate.copernicus.eu/cdsapp#!/dataset/reanalysis-era5-single-levels>) and the S2S project archive (<http://s2sprediction.net>) via the ECMWF portal: (<https://apps.ecmwf.int/datasets/data/s2s-reforecasts-instantaneous-accum-ecmf/>; <https://apps.ecmwf.int/datasets/data/s2s-reforecasts-instantaneous-accum-rums/>; <https://apps.ecmwf.int/datasets/data/s2s-reforecasts-instantaneous-accum-lfpw/>; <https://apps.ecmwf.int/datasets/data/s2s-reforecasts-instantaneous-accum-ammc/>). The CNN forecasts produced for this paper can be downloaded from [10.5281/zenodo.5175837](https://zenodo.org/record/5175837). The RMM indices were computed using the CLIVAR diagnostics package (<https://www.ncl.ucar.edu/Applications/mjoclivar.shtml>). PyTorch (<https://www.pytorch.org>) and DropBlock (<https://github.com/miguelvr/dropblock>) libraries were implemented to build and train the CNN model. PatternNet code was adapted from https://github.com/TNTLFreiburg/pytorch_patternnet. The

codes used in the current analysis are available at <https://github.com/antoine-delaunay/DeepLearningMJO/>.

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