

1 **Bias Corrected Estimation of Paleointensity (BiCEP):**
2 **An improved methodology for obtaining paleointensity**
3 **estimates**

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6 **Key Points:**

- 7 • Empirical evidence suggests that paleointensity estimates for non-ideal specimens
8 are biased.
- 9 • BiCEP is a method for estimating paleointensity for ensembles of specimens, cor-
10 recting for bias
- 11 • BiCEP produces accurate results when applied to data where the true field strength
12 is known.

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13 Abstract

14 The assumptions of paleointensity experiments are violated in many natural and archae-
 15 ological materials, leading to Arai plots which do not appear linear and yield inaccurate
 16 paleointensity estimates, leading to bias in the result. Recently, paleomagnetists have
 17 adopted sets of “selection criteria” that exclude specimens with non linear Arai plots from
 18 the analysis, but there is little consensus in the paleomagnetic community on which set
 19 to use. In this paper, we present a statistical method we call Bias Corrected Estimation
 20 of Paleointensity (BiCEP), which assumes that the paleointensity recorded by each spec-
 21 imen is biased away from a true answer by an amount that is dependent a single met-
 22 ric of nonlinearity (the curvature parameter \vec{k}) on the Arai plot. We can use this em-
 23 pirical relationship to estimate the recorded paleointensity for a specimen where $\vec{k} =$
 24 0, i.e., a perfectly straight line. We apply the BiCEP method to a collection of 30 sites
 25 for which the true value of the original field is well constrained. Our method returns ac-
 26 curate estimates of paleointensity, with similar levels of accuracy and precision to restric-
 27 tive sets of paleointensity criteria, but accepting as many sites as permissive criteria. The
 28 BiCEP method has a significant advantage over using these selection criteria because it
 29 achieves these accurate results without excluding large numbers of specimens from the
 30 analysis. It yields accurate, albeit imprecise estimates from sites whose specimens all fail
 31 traditional criteria. BiCEP combines the accuracy of the strictest selection criteria with
 32 the low failure rates of the less reliable ‘loose’ criteria.

33 Plain Language Summary

34 Paleomagnetists perform experiments on rocks and pottery sherds (among other
 35 things) to estimate the strength of the ancient Earth’s magnetic field (the paleointen-
 36 sity) through time. These make assumptions that are frequently violated, leading to bias.
 37 Quantitative metrics (selection criteria) attempt to screen out ‘bad’ data. If a partic-
 38 ular experiment fails the criteria, the results are ignored. However, there is a lack of agree-
 39 ment as to which set of criteria are the most important and what is considered a fail-
 40 ure. One of these criteria quantifies the deviation from the fundamental assumption of
 41 linearity between the ancient and laboratory magnetizations. We present a new Bayesian
 42 method called Bias Corrected Estimation of Paleointensity (BiCEP), in which we assume
 43 that the estimated paleointensity depends on this deviation. We can then use this de-
 44 pendency to correct the paleointensity made on an ensemble of specimens with differ-
 45 ing deviations from ideal behavior. BiCEP allows us to calculate accurate estimates of
 46 the ancient magnetic field, without ignoring results from non-ideal specimens. We test
 47 BiCEP on paleomagnetic data for which the original field strength is well constrained.
 48 BiCEP recovers the field strength with similar accuracy to stricter sets of criteria, but
 49 gets results for a greater number of sites.

50 1 Introduction

51 Estimates of the strength of the ancient Earth’s magnetic field are currently made
 52 by performing experiments that compare the natural remanent magnetization (NRM)
 53 acquired by a specimen while cooling in the Earth’s field, to a remanence known as ther-
 54 mal remanent magnetization (TRM) acquired by the specimen while cooling in a known
 55 laboratory field. Such experiments include the Königsberger-Thellier-Thellier (KTT) fam-
 56 ily of experiments (Königsberger, 1938; Thellier & Thellier, 1959), the Shaw family of
 57 experiments (Shaw, 1974), and the multi-specimen family of experiments (Hoffman et
 58 al., 1989), among others. All of these experimental families make assumptions about the
 59 relationship between the magnetic field and the remanent magnetization which may or
 60 may not be applicable (see the review by Tauxe & Yamazaki, 2015). In this paper, we
 61 will focus on the KTT family of experiments.

62 KTT type experiments involve a double heating protocol in which a specimen is
 63 heated two or more times to a series of temperatures up to the Curie Temperature. At
 64 each temperature, the specimen is cooled in two different fields. This has the effect of
 65 replacing the NRM with a TRM acquired in a known laboratory field. Data from KTT-
 66 type experiments are normally represented by the Arai diagram (Nagata et al., 1963),
 67 which plots the NRM magnetization remaining at each temperature step against the mag-
 68 netization imparted in the laboratory (often referred to as partial TRM or pTRM). The
 69 ratio of these two magnetizations, as represented by the slope of the best fitting line to
 70 the Arai plot data, is generally taken to be the ratio of the two magnetizing fields (an-
 71 cient, B_{anc} and laboratory, B_{lab}).

72 KTT-type experiments rely on several assumptions which are frequently violated
 73 in paleointensity experiments. These include thermochemical alteration of specimens which
 74 may lead to the production of new magnetic minerals, and an assumption known as reci-
 75 procity, which requires that the blocking temperature (the temperature below which grains
 76 retain their magnetization after an external field is removed) is the same as the unblock-
 77 ing temperature (the temperature above which grains equilibrate with the external field).

78 The reciprocity assumption of Thellier and Thellier (1959) is fundamental to Néel's
 79 theory for uniaxial single domain grains (Néel, 1949). Néel theory assumes that the elec-
 80 tronic spins within magnetic grains are fully aligned, and that the alignment is in one
 81 of two directions along an energetically favorable 'easy' axis. In zero field, there is no pref-
 82 erence for either direction, but in the presence of a field there is a slight preference for
 83 the direction along the easy axis with the smallest angle to the applied field. If the reci-
 84 procity assumption is met, then the energy required for the magnetization to change di-
 85 rections along the easy axis is always the same regardless of whether the specimen is cooled
 86 from higher temperature (blocking) or heated from room temperature (unblocking) and
 87 the two temperatures are identical.

88 By assuming that electronic spins within magnetic grains are fully aligned, Néel
 89 theory fails to take into account a term in the magnetic energy of grains which causes
 90 deviations from full alignment, resulting in structures such as the vortex state of, e.g.,
 91 Williams and Dunlop (1989). Although this effect is present in nearly all magnetic grains,
 92 it is insignificant over short length scales (10s of nm) and so uniaxial single domain the-
 93 ory may be a reasonable approximation for smaller, elongate grains. Specimens in pa-
 94 leointensity experiments contain mixtures of grains with different sizes and shapes and
 95 a specimen used for paleointensity is likely to include grains for which the applicability
 96 of single domain theory does not hold.

97 Failure of reciprocity and other fundamental assumptions embedded in the KTT
 98 family of experiments (laid out by e.g., Thellier & Thellier, 1959) provides a challenge
 99 for those analyzing paleointensity data. Paleomagnetists generally use a set of selection
 100 criteria which reject an intensity result if the NRM and pTRM data behave in a way which
 101 deviate from single domain theory (linear on the Arai plot, see Figure 1a) by more than
 102 some arbitrarily chosen threshold value. This is because data that contain a large pro-
 103 portion of non single domain-like grains or which otherwise violate the assumptions of
 104 the experiment are likely to give biased results (Tauxe et al., 2021). Selection criteria
 105 generally operate in a binary way, with specimens either being 'accepted' or 'rejected'
 106 from the estimation of the site mean, where 'site' is the collection of specimens assumed
 107 to have cooled in identical external magnetic fields (say, a lava flow or ceramic fragment).

108 Figure 1 gives a demonstration of biased results in specimens from prepared mag-
 109 netite powders of increasing grain size that were magnetized in a $60 \mu\text{T}$ field (Krása et
 110 al., 2003). If all assumptions of Thellier and Thellier (1959) were obeyed, we would ex-
 111 pect the best fitting lines to data on Arai plots to give a range of values distributed closely
 112 about a mean of $60 \mu\text{T}$. As the grain size of the powder increases, the Arai plot becomes
 113 more curved and the best fitting line to the Arai plot yields a progressively lower inten-

114 sity estimate. As all the paleointensities estimated from the curved plots are below the
 115 expected value, the estimate for the ensemble can be biased, with the high temperature
 116 segment having an even lower mean value, and the low temperature segment having a
 117 high mean value. The data of Tauxe et al. (2021) also demonstrate downward curved
 118 Arai plots in natural samples are biased so this problem may effect many of the results
 119 compiled in paleointensity databases like the MagIC database (Tauxe et al., 2016) or PINT
 120 (Biggin, 2010).

121 The curvature of an Arai plot can be quantified using the curvature criterion (\vec{k})
 122 of Paterson (2011) (see also Paterson et al., 2014). Curvature is calculated using the re-
 123 ciprocal of the radius of a circle fit to scaled Arai plot data (see Section 2.2.1). While
 124 there is no theoretical basis for a circular fit (as opposed to the linear fit, which is firmly
 125 rooted in Néel theory), it is a useful approximation that we will exploit in this paper.

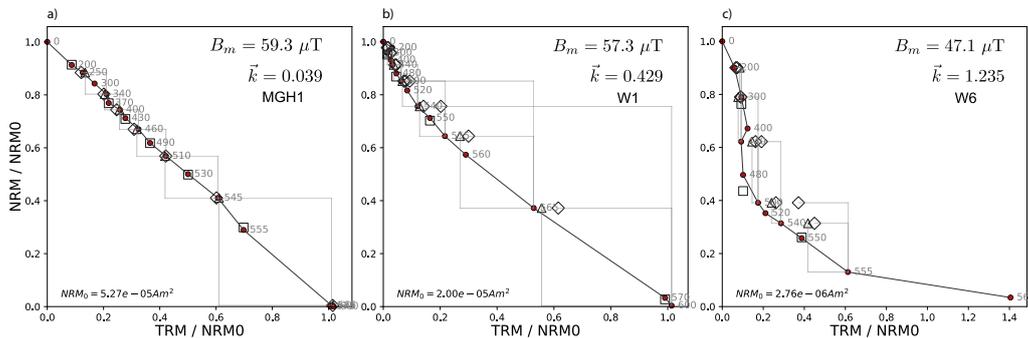


Figure 1. Arai plots from prepared magnetite powders given a TRM in a 60 μT field (Krása et al., 2003). The curvature criterion, \vec{k} (Paterson, 2011) and specimen level paleointensity estimate B_m estimated from fitting a line to the entire Arai plot are plotted on the figure as text. The grain size of the magnetite powders increases from left to right. The coarser grains have non ideal domain state, leading to curved Arai plots and estimates of paleointensity which are biased to lower values than the expected 60 μT . a) Nominal grain size of 23 nm. b) Mean grain size of 70 nm. c) Mean grain size of 12.1 μm .

126 The practice of using binary (pass/fail) selection criteria is problematic for many
 127 reasons. Paleomagnetic specimens generally contain magnetic carriers which span a range
 128 of grain sizes and may or may not conform to the assumptions of the method. In addition,
 129 micromagnetic simulations (e.g., Williams & Dunlop, 1989; Nagy et al., 2017) demon-
 130 strate that the change in magnetic domain state with grain size is a continuum, and so
 131 one individual grain’s behaviour may be more or less ideal than any other’s. With bi-
 132 nary pass/fail criteria, the distinction between ‘good’ and ‘bad’ data must be assessed
 133 with an arbitrary threshold value, which does not reflect the range of behaviors within
 134 both groups. Consequently there are a large number of selection criteria in common use
 135 (over 40 in Paterson et al., 2014), most of which have some empirical rationale, but there
 136 is little agreement on which set to use or their threshold values.

137 In this paper, we describe a new approach for paleointensity estimation that treats
 138 the quality of paleointensity data as a continuum as opposed to the binary ‘in’ or ‘out’
 139 approach using selection criteria. We assume that paleointensities become more biased
 140 as specimens’ magnetic behaviors become more non-ideal and their Arai plots become
 141 less linear. By allowing the data interpretation for specimens to be based on the shape
 142 of their Arai plots, we are able to obtain unbiased estimates of paleointensity without
 143 the need for many specimen level (binary) selection criteria. We call this method the ‘Bias

Corrected Estimation of Paleointensity' or BiCEP. In the next section, we develop a Bayesian approach to obtain accurate paleointensity estimates with realistic uncertainties, using \vec{k} as a metric of bias, and show how to combine data at the site level. In Section 3 we compare results from the BiCEP method to those of more traditional selection criteria based approaches. We discuss the results in Section 4 and summarize our conclusions in Section 5. Accompanying this paper, we release a Graphical User Interface (GUI) which can apply the BiCEP method to MagIC formatted data. Links and instructions on how to access the code can be found in Appendix 6.3.

2 Methods

2.1 Accounting for bias in paleointensity experiments

Paleomagnetists determine the paleointensity for a site by performing a Thellier-type double heating experiment on multiple specimens from that site. According to the theory for single domain grains (assuming no alteration of the specimen during heating), the ratio of NRM lost to pTRM gained is the ratio of the ancient field to the laboratory field. If the specimen conforms to theory, the Arai plot data will fall along a line the slope of which is equal to the ratio of ancient to the laboratory field (see Figure 1a).

We expect that the field strength predicted by the slope of the line on the Arai plot for each specimen (here called B_m) will be distributed about the true (expected) ancient field (B_{exp}) at the site with a Gaussian distribution. However, rarely do a set of specimens from a site all produce linear Arai plots that are easily interpretable. For example, interpretation of data from specimens with magnetic grains exhibiting non single domain magnetic domain states produce non-linear Arai plots which violate the assumptions of the method (e.g., Dunlop & Özdemir, 2001). Fitting lines to the data on such Arai plots often produces estimates of paleointensity which are biased (see Figure 1c, Krása et al., 2003), which in turn would bias site level estimates.

Paleomagnetists generally approach non-ideal data by using certain quantitative criteria chosen to eliminate results suffering from one or more pathologies (Paterson et al., 2014). If a particular criterion calculated for a specimen fails to meet some threshold value, then the specimen is excluded from the analysis. In this paper, we present an alternative approach in which we allow for specimens to behave in a non-ideal (non-linear) fashion when considering how specimen intensity estimates are distributed about a site mean and weight the contribution of individual specimen estimates according to linearity. Under such a scheme, we start by predicting a bias for each specimen, and the specimens with the smallest predicted bias most strongly determine the paleointensity at that site. In this way, biased specimens do not strongly affect our site intensity estimate, as they are down-weighted, yet provide useful constraints on the uncertainty.

To predict the amount of bias a specimen is likely to have, we require a proxy for bias in paleointensity experiments. For this we use the curvature criterion \vec{k} of Paterson (2011) (see Section 2.2.1). There are several reasons that make this criterion a useful proxy for bias in paleointensity experiments:

- Specimens that are highly linear have, by definition, low values for $|\vec{k}|$ and will generally give unbiased paleointensity estimates (e.g., Cromwell et al., 2015).
- By contrast, specimens with higher $|\vec{k}|$ yield biased paleointensities, with the magnitude of the bias generally increasing with the magnitude of $|\vec{k}|$ (e.g., Tauxe et al., 2021).
- $|\vec{k}|$ has an empirical correlation with magnetic grain size (Paterson, 2011).

Site	Citation	Material	Lat.	Long.	Year	B_{exp}	M
1991-1992 Eruption Site	Bowles et al. (2006)	lava flow	9.8	-104.3	1991	36.2	53
hw108	Cromwell et al. (2015)	lava flow	19.9	-155.9	1859	39.3	23
hw123	Cromwell et al. (2015)	lava flow	19.1	-155.7	1907	37.7	12
hw126	Cromwell et al. (2015)	lava flow	19.7	-155.5	1935	36.4	13
hw128	Cromwell et al. (2015)	lava flow	19.3	-155.9	1950	36.2	26
hw201	Cromwell et al. (2015)	lava flow	19.4	-155.0	1990	35.2	12
hw226	Cromwell et al. (2015)	lava flow	19.6	-155.5	1843	39.9	11
hw241	Cromwell et al. (2015)	lava flow	19.5	-155.8	1960	36.0	18
BR06	Donadini et al. (2007)	brick	60.1	24.9	1906	49.7	3
P	Muxworthy et al. (2011)	lava flow	19.3	-102.1	1943	44.6	36
VM	Muxworthy et al. (2011)	lava flow	40.8	14.5	1944	43.8	18
BBQ	Pick and Tauxe (1993)	submarine lava flow	9.8	-104.3	1990	36.2	12
rs25	Shaar et al. (2010)	synthetic	N/A	N/A	N/A	30.0	5
rs26	Shaar et al. (2010)	synthetic	N/A	N/A	N/A	60.0	5
rs27	Shaar et al. (2010)	synthetic	N/A	N/A	N/A	90.0	10
remag-rs61	Shaar et al. (2011)	synthetic	N/A	N/A	N/A	40.0	6
remag-rs62	Shaar et al. (2011)	synthetic	N/A	N/A	N/A	60.0	6
remag-rs63	Shaar et al. (2011)	synthetic	N/A	N/A	N/A	80.0	5
remag-rs78	Shaar et al. (2011)	synthetic	N/A	N/A	N/A	20.0	4
kf	Tanaka et al. (2012)	lava flow	65.7	-16.8	1984	52.0	3
Hawaii 1960 Flow	Yamamoto et al. (2003)	lava flow	19.5	-155.8	1960	36.0	22
SW	Yamamoto and Hoshi (2008)	lava flow	31.6	-130.6	1946	46.4	19
TS	Yamamoto and Hoshi (2008)	lava flow	31.6	-130.6	1914	47.8	53
ET1	Biggin et al. (2007)	basaltic lava	37.8	15.0	1950	43.3	3
ET2	Biggin et al. (2007)	basaltic lava	37.8	15.0	1979	44.1	2
ET3	Biggin et al. (2007)	basaltic lava	37.8	15.0	1983	44.2	4
Synthetic60	Krása et al. (2003)	synthetic	N/A	N/A	N/A	60.0	7
LV	Paterson et al. (2010)	Lithic Clasts	-23.4	67.7	1993	24.0	45
MSH	Paterson et al. (2010)	Lithic Clasts	46.2	-122.2	1980	55.6	19
FreshTRM	Santos and Tauxe (2019)	remagnetized/synthetic	N/A	N/A	N/A	70.0	24

Table 1. Table of sites used for analysis in this study, including original study locations, latitude, longitude and year of magnetization (where applicable), expected field at that location (B_{exp}), number of specimens used for analysis at that site M . Lat.: site latitude ($^{\circ}$ N). Long. site longitude ($^{\circ}$ E. N/A: Not Applicable (Synthetic)). B_{exp} is either a known laboratory field, from the International Geomagnetic Reference Field (IGRF, Thébault et al., 2015 or in two cases (hw226, hw108) using the Arch3k.1 model of Korte et al., 2009

190 To predict bias, we can use a method by which we minimize the misfit to a model
 191 assuming that B_m is linearly related to \vec{k} for all specimens. In other words, we say that:

$$B_m = B_{exp} + c\vec{k}_m + \epsilon \quad (1)$$

192 where m is an index reflecting the specimen number, ϵ is an error term and B_{exp} is the
 193 true value of B . Effectively, our model just becomes a linear fit between the specimen
 194 estimate B_m and \vec{k} , the y-intercept of which is the true value of the field B_{exp} and c is
 195 a slope constant. While there is no theoretical justification (yet) for why B_m would be
 196 related to \vec{k}_m , although it has been observed empirically (by Paterson, 2011 using the
 197 data in Figure 1, and more recently by Tauxe et al., 2021), a linear model is the simplest
 198 one to relate the two. We demonstrate in Section 3.3 that more complex models with
 199 a quadratic and cubic fit relating B_m to \vec{k}_m perform worse than the linear model when
 200 predicting the paleointensity for sites for which the paleointensity is well constrained (his-
 201 torical lava flows or laboratory remanences).

202 Arai plot curvature is not the sole cause of bias in paleointensity experiments. In
 203 some cases, specimens with Arai plots which do not have high $|\vec{k}|$ but are still non lin-
 204 ear (e.g., ‘zig-zagged’ as in, e.g., Yu et al., 2004), may still cause bias in paleointensity
 205 experiments. To counteract this, we use a Bayesian method of calculating \vec{k}_m and B_m
 206 which provides an uncertainty for both of these parameters. The benefit of this approach
 207 is that specimens whose Arai plots are not well fit by a line or an elliptical arc have less
 208 influence on the linear fit. Therefore, the specimens with the lowest uncertainty in \vec{k} are
 209 generally the most linear, and will have the most influence on the linear fit. Yet, for each
 210 specimen, there is a trade off between minimizing the circle fit at a specimen level and
 211 the linear fit between B_m and \vec{k} for specimens from the same site, an issue we will deal
 212 with in Section 2.2.3.

213 Figure 2 shows results from our method (detailed in Section 2.2) applied to sev-
 214 eral sites for which the true value of B_{anc} (here, B_{exp}) is either calculated from the In-
 215 ternational Geomagnetic Reference Field (IGRF, Thébault et al., 2015) or Arch3k.1 (Korte
 216 et al., 2009) for historical flows, or known as the NRM is a laboratory TRM imparted
 217 to the specimens. Following Equation 1, the uncertainty in the intercept value of these
 218 linear fits gives us the uncertainty for our site value of B_{anc} . In this way, we can obtain
 219 an unbiased estimate of B_{anc} without relying on arbitrary binary (accept/reject) crite-
 220 ria to exclude specimen results.

221 In the following, we detail how the specimen level circle fit \vec{k} and site level pale-
 222 ointensity for unknown values for B (here called B_{anc}) can be calculated. We then com-
 223 pare the efficacy of several different versions of our model to classical selection criteria.
 224 We do this using a data compilation from 30 sites updated from Paterson et al. (2014)
 225 and Tauxe et al. (2016) for which B_{exp} is well constrained (see Table 1 for details con-
 226 cerning the original publications of the data).

227 **2.2 Statistical Methodology**

228 **2.2.1 Estimating curvature**

229 Paterson (2011) proposed a least squares fit of circles in Arai plot data. The pa-
 230 rameter \vec{k} of Paterson (2011) is defined as the reciprocal of the radius of a best-fitting
 231 circle through the data. It is positive if the circle center is to the upper right of the Arai
 232 plot data (concave up, Figure 3a) and negative if the circle center is below and to the
 233 left of the Arai plot data (concave down, Figure 3b).

234 Before fitting to the Arai plot data, Paterson (2011) scales the pTRMs by the max-
 235 imum pTRM to ensure that the paleointensity data are independent of the laboratory
 236 field. For estimating \vec{k} , we also subtract the minimum remaining NRM (NRM_{min}) for
 237 specimens for which full demagnetization has not been completed and we subtract the

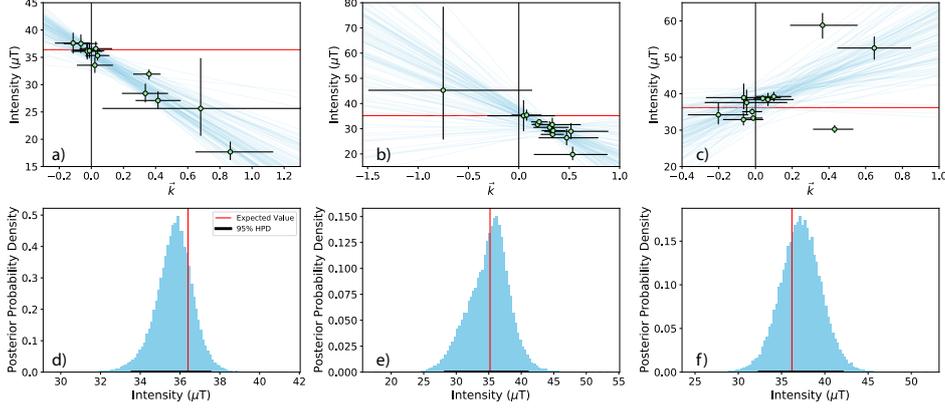


Figure 2. Example of results from the BiCEP method for several sites used as examples in this study. Lines (in blue) are fit to the values of B_m and \vec{k} for each specimen (blue dots, with uncertainties as black lines). The values of linear fits at $\vec{k} = 0$ (blue histograms) provide an unbiased estimate of the expected paleointensity value at the site from the known field (red lines). a,d) hw126. b,e) hw201. c,f) BBQ. See Table 1 for sampling and citation details and Section 3 for comparison with the expected field values, B_{exp} .

238 minimum pTRM (pTRM_{min}) for specimens for which the low temperature steps were
 239 excluded from the analysis (e.g., because of viscous remanent magnetization).

240 For the BiCEP method, we define two sets of data vectors x and y :

$$x_n = \frac{\text{pTRM}_n - \text{pTRM}_{min}}{\text{pTRM}_{max}}, \quad y_n = \frac{\text{NRM}_n - \text{NRM}_{min}}{\text{NRM}_0}, \quad (2)$$

241 where n is the index of the data point. Because scaling should be by the total (original)
 242 TRM (the NRM), we also exclude specimens whose NRM_{min} is more than 25% of the
 243 initial NRM. This is justified by the assumption that the experimenter did not carry out
 244 demagnetization to fully replace the NRM. Then, to fit a circle with center x_c, y_c and
 245 radius R to the data, we try to minimize the squared perpendicular distance d_n^2 (Fig-
 246 ure 3a) of all the n data points to the circle edge:

$$\sum_{n=1}^N d_n^2 \quad \text{where} \quad d_n^2 = (\sqrt{(x_n - x_c)^2 + (y_n - y_c)^2} - R)^2. \quad (3)$$

247 In a total least squares fit, Equation 3 would be our objective function that we would
 248 minimize. To fit circles to the Arai plot using a Bayesian method, we use Bayes' formula
 249 (Equation 4). This formula allows us to assign a probability distribution to the values
 250 of different parameters (in this case, \vec{k}_m and B_m), rather than just finding the 'best' value
 251 of the parameters. In a Bayesian context, we can simply assume that the data have some
 252 Gaussian noise distribution with some unknown standard deviation σ and apply Bayes'
 253 formula (e.g., Gelman et al., 2004):

$$P(\text{Parameters}|\text{Data}) = \frac{P(\text{Data}|\text{Parameters})P(\text{Parameters})}{P(\text{Data})}, \quad (4)$$

254 where the left hand side is the probability of the parameters given the data and the right
 255 hand side is the probability of the data given the parameters times the probability of the

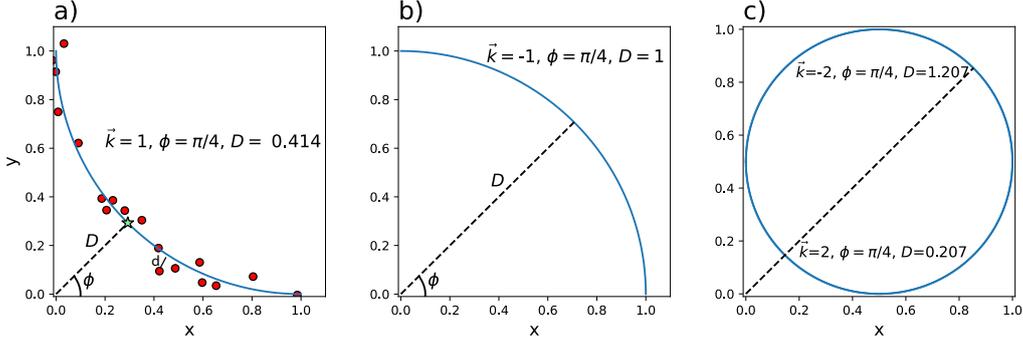


Figure 3. Example circles with different values for parameters \vec{k} and D with the same ϕ , showing how these parameters define a circle. a) Positive \vec{k} . Red dots are example data, and the green star is the intersection of D, ϕ with the circle edge (see text for definitions). d is the distance of an individual data point from the best-fit curve (blue). b) Negative \vec{k} . Note that in this case, ϕ could take any value as the circle center is at the origin, making the definition of ϕ meaningless in this case. c) Example showing how two sets of the parameters \vec{k}, ϕ, D can describe the same circle.

256 parameters, normalized by the probability of the data. In our case, the parameters are
 257 x_c, y_c, R and σ and our data are x and y so we rewrite Equation 4 as:

$$P(x_c, y_c, R, \sigma | x, y) = \frac{P(x, y | x_c, y_c, R, \sigma) P(x_c, y_c, R, \sigma)}{P(x, y)}. \quad (5)$$

258 The term $P(x, y | x_c, y_c, R, \sigma)$ is known as the “likelihood” and is based on the prob-
 259 ability of generating the observed data from a given set of parameters using the assumed
 260 Gaussian distribution. The term $P(x_c, y_c, R, \sigma)$ is known as the “prior” and is a prob-
 261 ability distribution for values of x_c, y_c, R and σ we consider to be reasonable before we
 262 see any data. We consider the priors on these parameters to be independent of one an-
 263 other, so we could rewrite this as $P(x_c)P(y_c)P(R)P(\sigma)$. The term $P(x, y)$ is known as
 264 the “evidence”, and is simply a normalizing constant that makes the “posterior” prob-
 265 ability distribution, $P(x_c, y_c, R, \sigma | x, y)$, integrate to 1. In our application, we can sim-
 266 plify the relationship by ignoring the normalization. Furthermore, we can say from the
 267 definition of the Gaussian distribution that:

$$P(x, y | x_c, y_c, R, \sigma) = \left(\frac{1}{2\pi\sigma^2} \right)^{N/2} \exp \left(\sum_{n=1}^N -\frac{d_n^2}{\sigma^2} \right). \quad (6)$$

268 Now we have an expression for our posterior probability distribution:

$$P(x_c, y_c, R, \sigma | x, y) \propto \left(\frac{1}{2\pi\sigma^2} \right)^{N/2} \exp \left(\sum_{n=1}^N -\frac{d_n^2}{\sigma^2} \right) P(x_c, y_c, R) P(\sigma). \quad (7)$$

269 Because the actual noise distribution of the Arai plot data is quite complicated (Paterson
 270 et al., 2012), we do not know the value of σ , so we use the uninformative prior $P(\sigma) \propto$
 271 $\frac{1}{\sigma}$; in other words, the smaller σ , the more likely the result. We can then substitute this
 272 prior into Equation 7 and integrate out σ to obtain:

$$P(x_c, y_c, R | x, y) \propto \left(\sum_{n=1}^N d_n^2 \right)^{-N/2} P(R, x_c, y_c) \quad (8)$$

273 where N is the total number of measurements considered.

274 The set of parameters x_c, y_c and R is not easy to solve for, because Equation 3 has
 275 multiple local minima (see Chernov and Lesort (2005) for a more detailed discussion).
 276 Consider the simple case of a specimen with a linear Arai plot; in even this simplest case,
 277 there are four minima, as both R and x_c, y_c will be either positive or negative and very
 278 large. To avoid this complexity, we can use instead a change of parameters similar to that
 279 of Chernov and Lesort (2005) which Paterson (2011) used as a basis for the circle fit-
 280 ting protocol. Based on this, we define a set of three new parameters which avoid the
 281 problem of multiple minima.

282 Firstly, we require a point on the Arai plot which can be related to a unimodal dis-
 283 tribution. We know that linear data will plot along the edge of a circle (the tangent),
 284 so if we draw a line from the origin toward the center (x_c, y_c) (not shown), this will touch
 285 the edge of the circle at some distance D (green star in Figure 3a). The angle to the hor-
 286 izontal of this line we call ϕ and we can directly estimate the \vec{k} parameter of Paterson
 287 (2011) using Equations 9,10,11. We can then establish equations for transforming be-
 288 tween these two sets of parameters (see Appendix 6.1 for a more detailed derivation):

$$x_c = \left(D + \frac{1}{\vec{k}} \right) \cos(\phi), \quad (9)$$

$$y_c = \left(D + \frac{1}{\vec{k}} \right) \sin(\phi), \quad (10)$$

$$R = \frac{1}{|\vec{k}|}. \quad (11)$$

291 Despite this transformation, the circle fitting equation can still have multiple min-
 292 ima, even with \vec{k}, D, ϕ as our parameters, as the line connecting the origin to the hor-
 293 izontal touches the circle edge in two locations (see Figure 3c). However, we can use prior
 294 distributions to avoid this.

295 Chernov and Lesort (2005) define a function of the data d_{max} to define the region
 296 of possible values for \vec{k} :

$$d_{max} = \max_{i,j} \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2} \quad (12)$$

297 Additionally, we define distance from the origin to the centroid of the data, d_{cent} :

$$d_{cent} = \sqrt{\bar{x}^2 + \bar{y}^2} \quad (13)$$

298 Using this function, we can assume that $D < 2d_{cent}$ and $|\vec{k}| < N/d_{max}$ and can de-
 299 fine priors for our parameters:

$$P(D) \sim \text{Uniform}(0, 2d_{cent}), \quad (14)$$

$$P(\phi) \sim \text{Uniform}(0, \pi), \quad (15)$$

301 and

$$P(\vec{k}) \sim \text{Uniform}(-N/d_{max}, N/d_{max}). \quad (16)$$

302 Using these priors gives us a posterior with a single maximum in most cases, which makes
 303 the problem much easier to solve computationally.

304 We can now apply a Bayesian approach to estimate \vec{k} for all temperature steps for
 305 a given specimen m . It is frequently useful to choose a subset of the temperature steps

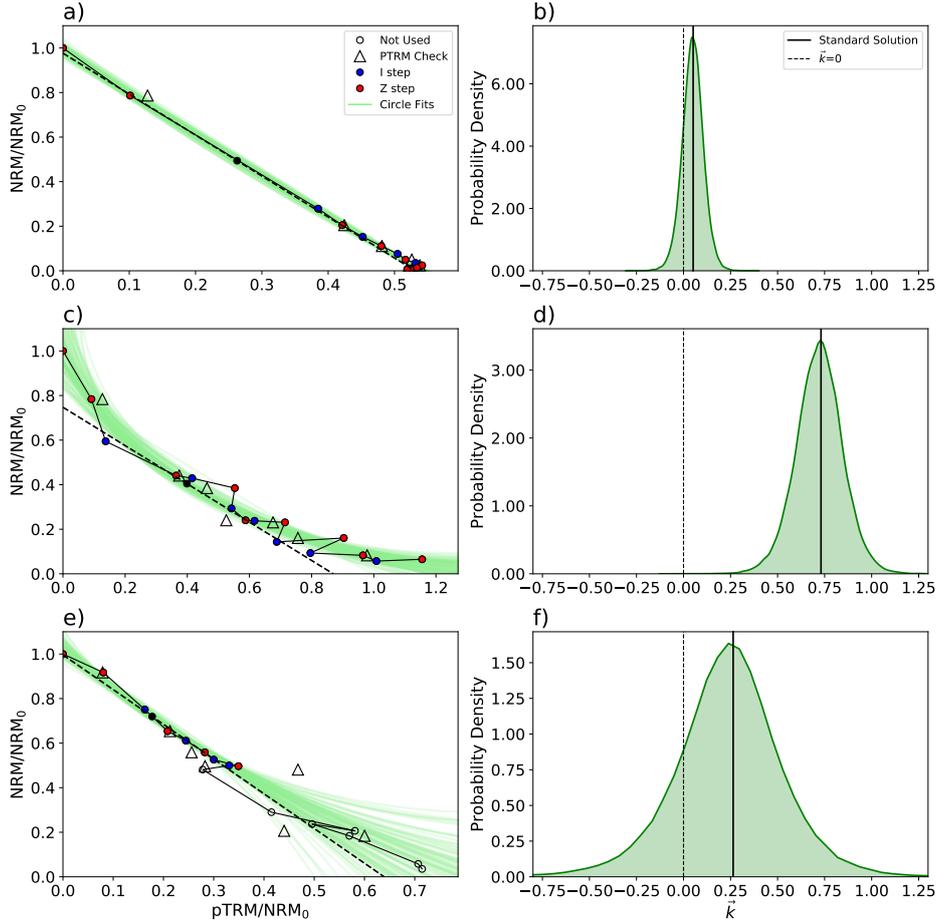


Figure 4. Examples of circle fits to Arai plots (left column) and approximate probability densities of \vec{k} (right column). Dashed lines in the left hand plots are the tangents to circles with the median values for ϕ and D . We use tangents to the circle to get an estimate for B_m as outlined in Section 2.2.2. Triangles in a), c), e) are repeated lower temperature steps (pTRM checks) that indicate alteration of magnetic minerals during the experiment when offset from the original measurements (red dots). a) Specimen hw126a1. A fit to a straight line yields a precise \vec{k} distribution with a maximum close to zero (b). c) Specimen hw126a7. A curved Arai plot with a high amount of scatter/zigzagging (left) results in a higher uncertainty in the value of \vec{k} (d). e) Specimen hw126a6. Arai plot for a specimen that underwent thermochemical alteration at high temperature. A circle fit to just the low temperature steps results in a high uncertainty in the value of \vec{k} (f). Note that we do not exclude any measurements due to thermal alteration in our results section, and that this is only done here for illustrative purposes.

306 (e.g., if there is evidence for multiple components of the NRM or heating related alteration,
 307 as detected by repeated lower temperature pTRM steps). When using a subset
 308 of steps, we scale by the maximum pTRM for all temperature steps and the NRM at room
 309 temperature; in this way we can predict the curvature for the part of the Arai plot that
 310 is missing. This means that interpretations based on a small fraction of the Arai plot
 311 will have large uncertainties in the value of \vec{k} . Therefore, our circle fit can prioritize in-
 312 terpretations using the largest fraction of the NRM.

313 Figures 4a,c,e show circle fits sampled from the posterior distributions for speci-
 314 mens from site hw126 (site level results shown in Figure 2a). The probability densities
 315 of all the \vec{k} values for each specimen are plotted in Figures 4b,d,f. The plot demonstrates
 316 how a straight Arai plot (Figure 4a) produces a narrow posterior about $\vec{k} = 0$ (Figure 4b),
 317 while a curved one (Figure 4c) produces a posterior which does not contain $\vec{k} = 0$ (Fig-
 318 ure 4d). In the example with failed pTRM checks at higher temperatures (offset trian-
 319 gles in Figure 4e), we exclude the data points represented by open circles and use a lin-
 320 ear segment with only a portion of the results, the posterior distribution of \vec{k} has a larger
 321 uncertainty on the value, translating to a larger uncertainty in the bias for that spec-
 322 imen. We do not advocate for any particular method of checking for alteration, and do
 323 not exclude any measurement steps in our results section. However, our circle fitting rou-
 324 tine allows for measurement steps to be excluded and accounts for the increased uncer-
 325 tainty in doing so.

326 **2.2.2 Obtaining a specimen level paleointensity estimate**

327 Analogous to the case in which paleointensity estimates are made using the slope
 328 of a fitted line to the Arai plot data, we can obtain a similar “slope” value for a circu-
 329 lar arc fit to the data. Consider the case in which the edge of the circle forms an exact
 330 line ($\vec{k}=0$, see Figure 4a). In this case, the slope of the line can be given by the tangent
 331 to the circle at the point where it intersects a line drawn from the origin (0,0) to the cir-
 332 cle center (Figure 3a). In other words, the “slope” of the Arai plot can be estimated as
 333 $\cot \phi$, which gives the tangent to the circle. We can then turn this into an intensity es-
 334 timate B_m using the formula:

$$B_m = \frac{B_{lab} \cot(\phi)}{pTRM_{max}}, \quad (17)$$

335 where B_{lab} is the laboratory field used to impart a pTRM to the specimen. If a spec-
 336 imen is corrected for anisotropy, cooling rate, or non-linear acquisition of TRM, we ap-
 337 ply this correction to Equation 17.

338 We now have a way of obtaining estimates for B_m and \vec{k}_m for each specimen. We
 339 use the methodology laid out in Sections 2.2.1 and 2.2.2 to plot the median value of the
 340 posterior for these parameters (with error bars) in Figure 5a, and examples of circle fits
 341 in Figures 5c, e, g. For specimens with values of \vec{k} that are approximately 0 (Figure 5g),
 342 the B_m values are quite accurate. There appears to be a bias for specimens with large
 343 \vec{k} , with the amount of bias increasing as \vec{k} increases. In this example, large positive val-
 344 ues of \vec{k} lead to a large underestimates of B_m while negative values of \vec{k} lead to overes-
 345 timates of B_m (although small in this example).

346 **2.2.3 Obtaining a site level paleointensity estimate**

347 The main problem with the method presented thus far is that we still do not have
 348 a way of obtaining an estimate for B_{anc} , the unknown value at the site level. However,
 349 in Figure 5a there appears to be a dependence between \vec{k}_m and B_m as suggested ear-
 350 lier, with most of the specimens showing a quasi-linear relationship (the only exception
 351 being the point labeled e) whose Arai plot is shown in Figure 5e) and suggests there is
 352 a great deal of uncertainty in the value of \vec{k} itself. Because of this, we can modify our
 353 model slightly by imposing the extra restriction that B_m must be linearly dependent on
 354 \vec{k}_m (with noise) using Equation 1 (substituting B_{anc} for the unknown value of B_{exp}).

355 Previous papers have assumed that B_{anc} for selected specimens follows a Gaussian
 356 distribution and we can also make this assumption here. In the following, we will show
 357 how this modification can shift results from specimens that are offset from the linear re-
 358 lationship toward the line (as in the point labeled ‘f’ in Figure 5b) and produce mod-

359
360

els (shown as blue lines) that estimate all of our B_m . We can then use the resulting models to estimate the probability distribution for B_m as:

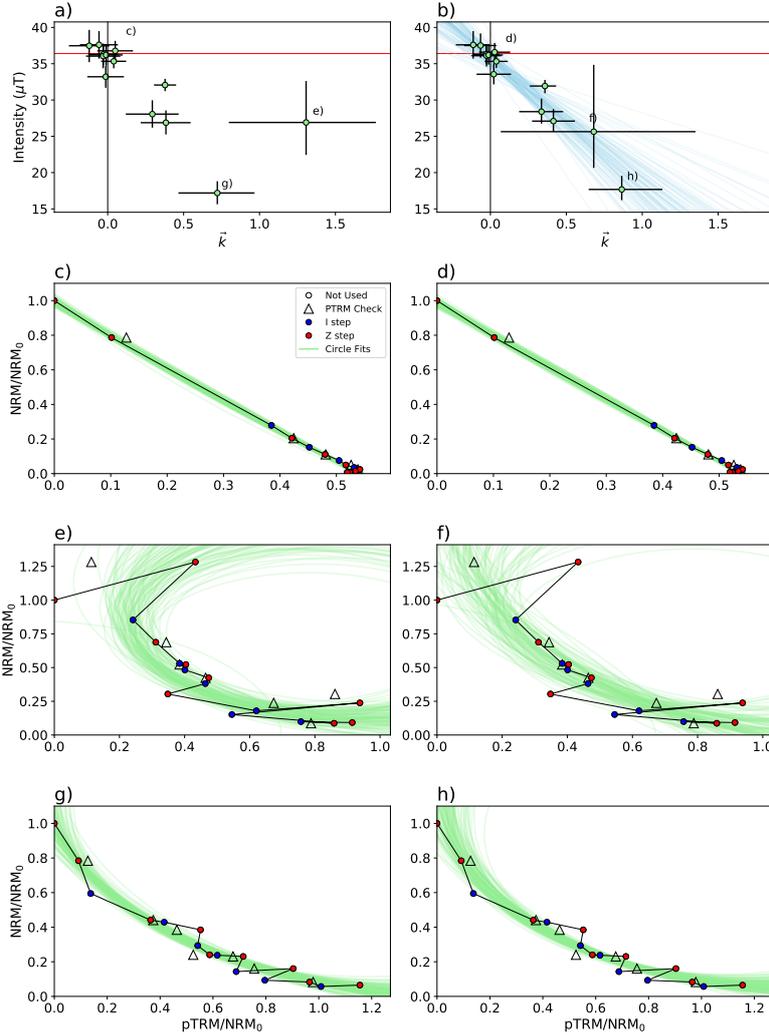


Figure 5. Examples demonstrating how the predicted \vec{k} and B_m for each specimen are modified for a site by using a hierarchical model (Equation 14). The left column shows draws from the posterior for an “unpooled” model where we estimate B_m and \vec{k}_m independently. The right column shows draws from the posterior for the BiCEP method where we assume a linear relationship between B_m and \vec{k}_m . a) Red horizontal line is B_{exp} (hw126, see Table 1). 95% credible intervals for \vec{k}_m and B_m are plotted using black error bars, with the medians as green points. b) Representative draws from the posterior distribution are plotted as blue lines assuming that the individual specimen values B_m follow the relationship stated in Equation 14. Note that the higher curvature specimens with large uncertainty in \vec{k} follow a linear trend away from B_{exp} . c),e),g): [Symbols same as in Figure 4.] Arai plots of particular specimens are shown with circle fits sampled from the posterior of the unpooled model shown in a) and plotted in green. In d), f), h), same specimens as in c), e), g) but using the posterior of the BiCEP model in b). Note that there is little change in the specimen in d) for which a close fit to the data is possible, but in f) and h) the curvature (and intensity) of the specimen are modified to fit the line better.

$$P(B_m|k_m, B_{anc}, \sigma_{site}, c) = \frac{1}{\sqrt{2\pi\sigma_{site}^2}} \exp\left(-\frac{(B_{anc} + c\vec{k}_m - B_m)^2}{2\sigma_{site}^2}\right). \quad (18)$$

361 Now we can combine our expressions for B_m and \vec{k}_m (Equations 17, Sections 2.2.1
 362 and 2.2.2) with the new constraint of a linear relationship between B_m and \vec{k}_m (Equa-
 363 tion 18). This allows us to obtain an expression for the site level intensity estimate B_{anc} :

$$364 \quad P(B_{anc}, \sigma_{site}, c, B_m, k_m, D_m|x_m, y_m) \propto \\
 P(x_m, y_m|k_m, D_m, B_m)P(B_m|k_m, B_{anc}, \sigma_{site}, c)P(B_{anc}, \sigma_{site}, c)P(D_m, k_m). \quad (19)$$

365 Equation 19 may look complicated, but we defined each of the terms already. The ben-
 366 efit of this treatment is that we can obtain $P(x_m, y_m|k_m, D_m, B_m)$ from our circle fit-
 367 ting in Equation 8 (see also Appendix 6.1). We defined $P(B_m|k_m, B_{anc}, \sigma_{site}, c)$ in Equa-
 368 tion 18. The values of \vec{k} and B_m for each specimen are needed to fit both of these terms.
 369 This means that specimens with large scatter in their Arai plots (those which have Arai
 370 plots that are not fit well by a line or a circle) are more strongly affected by the site level
 371 fit B_{anc} , and therefore by the specimens with more linear (or circular) Arai plots. Con-
 372 versely, those specimens with a small uncertainty in \vec{k} or B_m are tightly constrained by
 373 the Arai plot fit and so have more control over the fit at the site level.

374 The other two terms on the right side of Equation 19 ($P(B_{anc}, \sigma_{site}, c)P(D_m, k_m)$),
 375 are priors. $P(D_m, k_m)$ were defined in Equations 14 and 16 respectively. Now, we need
 376 to define priors for $P(B_{anc}, \sigma_{site}, c)$. For this purpose, we use a poorly constrained prior
 377 for the slope, c , where $P(c) \propto 1$. Although this is not a probability distribution, the
 378 resulting posterior distribution for B_{anc} is always a real probability distribution if the
 379 number of specimens is greater than one. We use a uniform prior between 0 and 250 μT
 380 for $P(B_{anc})$ as intensity values can never be negative and in databases such as the MagIC
 381 database (Tauxe et al., 2016) or the PINT database of Biggin (2010) rarely (if ever) ex-
 382 ceed 250 μT . For $P(\sigma_{site})$ we use a normal distribution with zero mean and standard
 383 deviation of 5 μT , truncated to always be positive.

384 Figure 5b shows our median estimates for B_m and \vec{k}_m after applying the linear restric-
 385 tion. Here, there is a tradeoff between fitting the Arai plot data with the circle, and
 386 fitting the linear trend at a site level. The effect of the linear fitting is apparent when
 387 compared to estimating \vec{k}_m and B_m for each specimen in isolation, which is shown in
 388 Figure 5a. With the linear restriction, the \vec{k} and B_m of specimens are ‘‘pulled’’ closer
 389 to a linear trend by modifying the Arai plot fits; specimens with more uncertain \vec{k}_m are
 390 more strongly affected (e.g., specimen labeled e) and f) in Figure 5a and b). The spec-
 391 imens with highly linear Arai plots (for which we have small uncertainty in \vec{k}_m), the cir-
 392 cle fits (see g and h) are mostly unchanged. Despite this modification of the circle fits
 393 to the Arai plots by the linear model, the circle fits to those specimens do not look un-
 394 reasonable.

395 2.3 Metrics of success

396 In order to ‘ground-truth’ the method, we rely on a compilation of paleointensity
 397 data updated from that of Paterson et al. (2014) and Tauxe et al. (2016). This compi-
 398 lation has data from 30 sites for which B_{anc} is well constrained (hence we use B_{exp}), ei-
 399 ther through the IGRF, or because the specimens were given TRMs in a known lab field
 400 before the Thellier experiment. One exception to this is for hw226 and hw108, lava flows
 401 erupted in Hawaii in 1843 and 1859, prior to the range included in the IGRF. For these
 402 sites, we used the Arch3k.1 model of Korte et al. (2009). A list of sites used here is given
 403 in Table 1. Instead of choosing a range of temperatures for each site, we simply use ev-
 404 ery temperature on the Arai plot for all specimens.

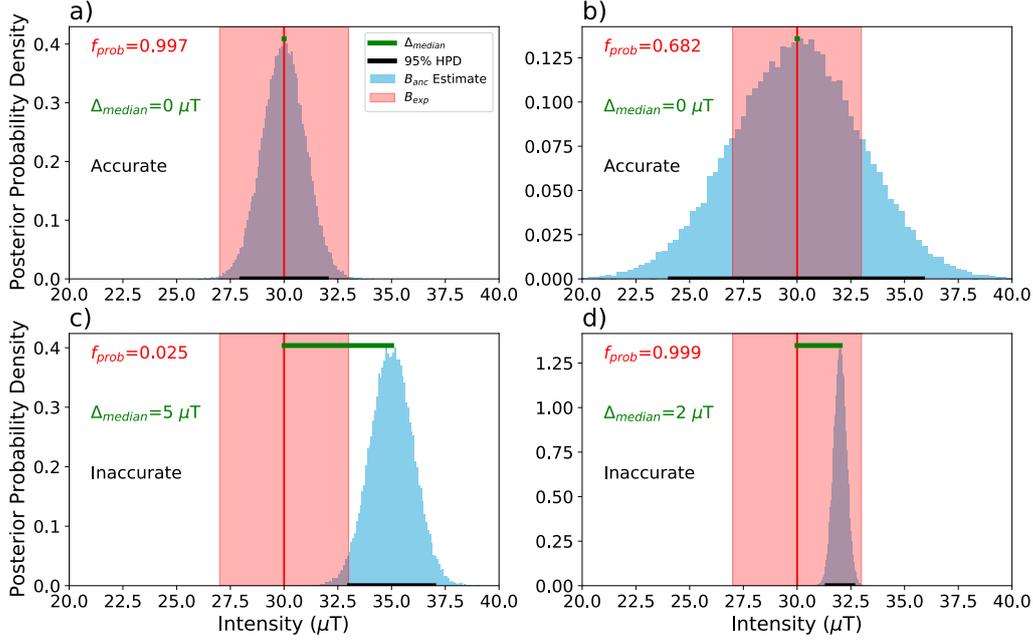


Figure 6. Examples of accuracy and precision metrics used in this study with simulated Gaussian distributions of B_{anc} for illustration. a) An accurate and precise estimate, b) An accurate but imprecise estimate, c) An inaccurate and imprecise estimate. d) A slightly inaccurate and highly precise estimate. Accuracy check used for n_{acc} checks whether the black line intersects the expected value (B_{exp}). f_{prob} is the area of the blue histogram that lies within the red shaded area. Δ_{median} is the length of the green line.

405 Because we have to estimate multiple parameters for each specimen, our method
 406 involves a high dimensional optimization problem. Therefore, we generate the estimates
 407 for B_{anc} for a given site using a Markov chain Monte Carlo (MCMC) method which ap-
 408 proximates the posterior distribution by generating pseudosamples from it (see Appendix 6.2
 409 for details). MCMC techniques are frequently used to solve high dimensional problems
 410 of this kind.

411 For each site, we quantify the effectiveness of the BiCEP method using several met-
 412 rics, f_{prob} , Δ_{median} (see Figure 6 for graphical representation), \bar{f}_{prob} , and n_{acc} :

- 413 1. f_{prob} : We report the median value of our posterior distribution and the 2.5th and
 414 97.5th percentile of the Monte Carlo sample (95% credible interval) as error bars.
 415 To quantify the effectiveness of our method, we look at the proportion of the pos-
 416 terior distribution that lies within 3 μ T of the expected value of B (B_{exp}) and call
 417 this proportion f_{prob} .
- 418 2. \bar{f}_{prob} : the mean value of f_{prob} over all sites included in the study. A value of 1 is
 419 the best possible value and means all our results are accurate and precise to bet-
 420 ter than 3 μ T.
- 421 3. Δ_{median} : the difference (in μ T) between the median value of the MCMC sample
 422 (see Section 6.2 for explanation) and B_{exp} . The median value of Δ_{median} is $\tilde{\Delta}_{median}$.
 423 Values of $\tilde{\Delta}_{median}$ close to zero are best.
- 424 4. n_{acc} : the number of sites for which B_{exp} lies within our 95% credible interval. A
 425 related parameter, f_{acc} is the fraction of results that are accurate (n_{acc}/n_{sites}),

426 where n_{sites} is the total number of sites analyzed. We expect this number to be
 427 0.95 in ideal circumstances.

428 We use these metrics to compare the BiCEP results to those obtained by several differ-
 429 ent sets of selection criteria: CCRIT (Cromwell et al., 2015), Paterson’s modified PICRIT03
 430 (here called PICRITMOD) and SELCRIT Criteria (here called SELCRITMOD, Paterson
 431 et al., 2014). For this exercise, we also calculated these two criteria with the addition
 432 of the curvature criterion of $|\vec{k}| < 0.270$, which we refer to as PICRITMODk and SEL-
 433 CRITMODk. We apply these criteria using the standard deviation optimization method
 434 in Thellier GUI. Most sets of commonly used selection criteria rely on an assumption of
 435 a Gaussian probability distribution for the site level estimate B_{anc} , which allows us to
 436 calculate these same metrics.

437 For our analyses of our success metrics, we exclude sites that contain fewer than
 438 three specimens. For fair comparison, we do not exclude sites from our analyses with tra-
 439 ditional selection criteria which have high standard deviation, as we do not do this for
 440 BiCEP. If a site fails to produce an estimate of B_{anc} for any reason (for example, selec-
 441 tion criteria passed less than two specimens), we assume the prior distribution of a uni-
 442 form distribution between 0 and 250 μT . This allows us to compare methods directly,
 443 with a penalty applied for excluding sites. An excluded site will have $f_{prob}=0.012$, whereas
 444 a site with a highly inaccurate result can have f_{prob} of 0, so exclusion is considered only
 445 slightly better than an inaccurate result in this scheme. We discuss the results of this
 446 comparison in Section 3.1.

447 2.4 Width of prior and order of fit

448 Here we consider several alternative contingent models in order to explore our choices
 449 for $P(\sigma_{site})$ and assumptions about the relationship of B_m and \vec{k} . In addition to using
 450 a standard deviation of 5 μT for $P(\sigma_{site})$, we use standard deviations of 10 μT and 20
 451 μT . The effect of this is hard to conceptualize, but wider priors will prioritize fitting cir-
 452 cles to the individual specimens over fitting the linear relationship between B_m and \vec{k}_m
 453 at a site level. The practical effect of this is wider posteriors for sites where the num-
 454 ber of specimens is small.

455 So far, we have assumed *a priori* that B_m is linearly dependent on \vec{k}_m . Because
 456 there is no theoretical reason why this should be the case, we test models for which the
 457 relationship between B_m and \vec{k}_m is described by a quadratic polynomial and a cubic poly-
 458 nomial. We would expect a higher order model to more closely fit the individual \vec{k}_m and
 459 B_m values, but with a loss of precision due to the more complicated model.

460 Results for our method, as well as for two sets of selection criteria, are given in Ta-
 461 ble 2. For each model, we calculate \bar{f}_{prob} , $\tilde{\Delta}_{median}$ and f_{acc} for comparison. In this ta-
 462 ble, our models are named for the value of the standard deviation of $P(\sigma_{site})$ as well as
 463 the order of the fit. Our preferred model is referred to as “Linear 5 μT ”, and this is the
 464 model used in this paper where otherwise unspecified.

465 2.5 MCMC sampler diagnostics

466 MCMC samplers are only ever an approximation of the posterior distribution, and
 467 the number of Monte Carlo samples needed to make an accurate approximation is not
 468 the same for every site, or every run of the sampler. To determine whether we are ac-
 469 curately sampling the posterior distribution, we look at three diagnostics which are also
 470 described in Appendix 6.2:

- 471 1. \hat{R} : (Gelman & Rubin, 1992) quantifies convergence between chains in the MCMC
 472 method. This parameter is required to be between 1.1 and 0.9 for the sampler to
 473 converge.
- 474 2. n_{eff} : the effective MCMC sample size. We are using 30,000 Monte Carlo samples
 475 and n_{eff} should be large (> 1000) to have a good representation of our param-
 476 eters.
- 477 3. f_{div} : the proportion of divergent transitions f_{div} in the MCMC sample. This should
 478 ideally be zero, but it does not appear to cause large problems for the estimate
 479 of B_{anc} if it is non zero (see Section 6.2).

480 The diagnostics n_{eff} and \hat{R} are produced for each of our parameters (each of our
 481 B_m, \vec{k}_m, D_m and B_{anc}, σ_{site}). When reporting these values, we look at the worst value
 482 of \hat{R} (furthest from unity) and the value of n_{eff} for B_{anc} . If $\hat{R} > 1.1$, we replace the dis-
 483 tribution on B_{anc} with a uniform distribution between 0 and 250 μT (the prior). The
 484 results of the MCMC sampler are presented in Section 3.4.

485 3 Results

486 3.1 Comparison of BiCEP to Selection Criteria

487 In this section, we compare the BiCEP to several sets of selection criteria (see Sec-
 488 tion 2.3). The full set of results for all sites can be seen in Figure 7, and are summarized
 489 in Supplementary Data Set S1.

Model Name	\bar{f}_{prob}	$\hat{\Delta}_{median}$ (μT)	f_{acc}	Number of Sites
Linear, 5 μT (BiCEP)	0.63	1.7	0.85	25
Linear, 10 μT	0.62	1.7	0.85	25
Linear, 20 μT	0.61	1.7	0.85	25
Quadratic, 5 μT	0.56	1.7	0.81	25
Quadratic, 10 μT	0.55	1.6	0.85	25
Quadratic, 20 μT	0.55	1.8	0.85	25
Cubic, 5 μT	0.45	2.6	0.85	22
Cubic, 10 μT	0.45	2.3	0.85	24
Cubic 20 μT	0.44	2.5	0.85	24
CCRIT	0.47	1.9	0.88	22
PICRIT (Modified)	0.56	2.2	0.77	23
PICRIT (Modified with \vec{k})	0.61	1.9	0.69	21
SELCRIT (Modified)	0.53	2.9	0.58	25
SELCRIT (Modified with \vec{k})	0.58	2.3	0.58	23

Table 2. Results comparing the models used in this study to results using CCRIT (Cromwell et al., 2015) as well as PICRITMOD and SELCRITMOD (Paterson et al., 2014), both with and without the \vec{k} criterion. See details in text and Figure 6 for explanations of the different parameters presented here. Results are sorted by the number of specimens in the site used to make the estimate using our method.

490 Figure 7 shows the 95% credible intervals for each method, normalized by the ex-
 491 pected value at the site. The median values of our results are generally similar to those
 492 found by our selection criteria. BiCEP yields the largest number of accurate and pre-
 493 cise results, with CCRIT being generally less precise and slightly less accurate. PICRIT-
 494 MOD and SELCRITMOD are generally less accurate and precise than BiCEP, however

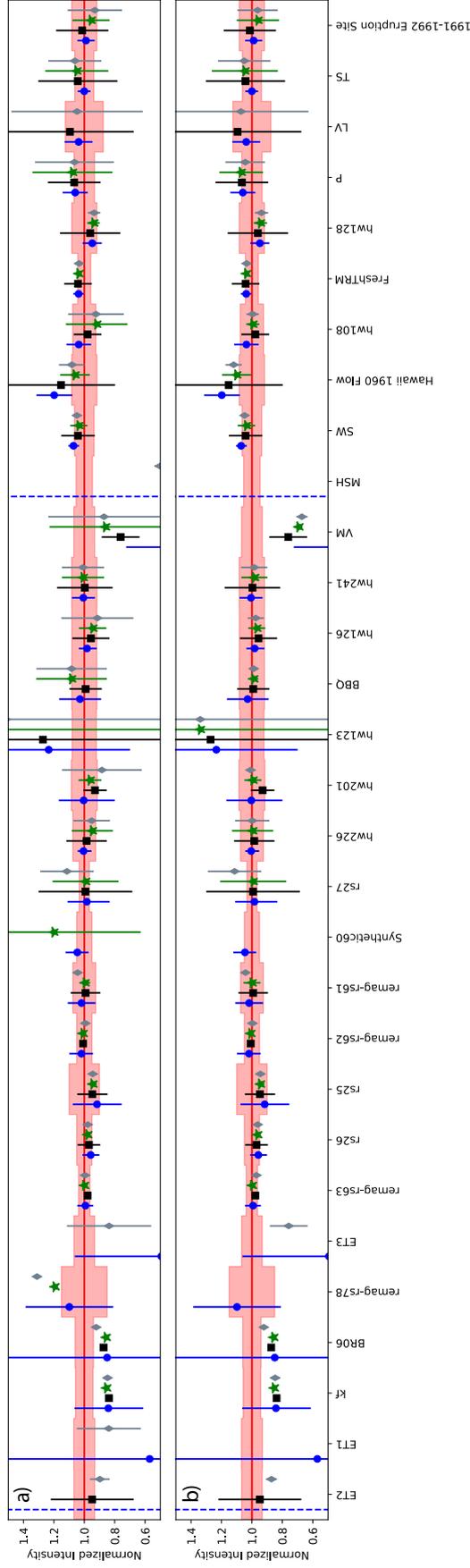


Figure 7. In a) for our collection of sites, we plot (Table 1) paleointensity estimates using BiCEP (blue circles) with 95% confidence interval compared to results using CCRIT (black squares), Paterson’s modified PICRITMOD (green stars) and SELCRITMOD (grey diamonds). In b), the same information is plotted, but green stars represent results from PICRITMODk and grey diamonds represent results from SELCRITMODk; the $\bar{k} < 0.270$ criterion has been applied to PICRITMOD and SELCRITMOD. A dashed blue line indicates a site where the sampler failed with $\hat{R} > 1.1$, so the prior distribution (a uniform distribution between 0 and $250 \mu\text{T}$) was used. The results are normalized to the expected field value for each site (black line, by definition 1) and the pink shaded region represents $\pm 3 \mu\text{T}$. Sites are ordered by the number of specimens used by BiCEP for paleointensity analysis in that site with the number of specimens increasing to the right. Results are summarized in Supplementary Data Set S1.

495 introducing the curvature criterion for PICRITMODk and SELCRITMODk improve the
 496 accuracy and precision significantly. Both PICRITMODk and SELCRITMODk boast
 497 highly precise estimates for passing sites, with similar levels of accuracy to BiCEP. How-
 498 ever, this improved accuracy and precision is achieved by excluding more sites, which
 499 penalizes these methods using our success metrics.

500 Sites in Figure 7 are sorted by the number of specimens used by BiCEP for the anal-
 501 ysis. Unique to our method, sites with low numbers of specimens (M) have wide cred-
 502 ible intervals and sites with high M have narrow credible intervals, so the estimate of
 503 B_{anc} becomes more precise as more specimens are measured. This is because calculat-
 504 ing the credible interval for a B_{anc} is more similar to calculating the standard error of
 505 the mean than the site level standard deviation, which is done for our traditional selec-
 506 tion criteria. The increasing precision on B_{anc} leads to some sites with high M having
 507 estimates of B_{anc} which are seemingly too precise. These estimates are still generally only
 508 a few μT away from the expected value, however, and we discuss potential reasons for
 509 this in Section 4.4.

510 Our results in Table 2 indicate that BiCEP is the method that yields the largest
 511 number of accurate and precise results, having a higher \bar{f}_{prob} and lower $\bar{\Delta}_{median}$ than
 512 all of our sets of selection criteria. For selection criteria which include a curvature cri-
 513 terion, much of this improvement comes from BiCEP’s inclusion of accurate results for
 514 two sites, remag-rs78 and Synthetic60. If we look exclusively at the sites which passed
 515 each criterion, PICRITMODk and SELCRITMODk achieve higher levels of precision for
 516 those sites (higher \bar{f}_{prob} than BiCEP if only passing sites considered), with PICRITMODk
 517 achieving similar levels of accuracy to BiCEP (similar $\bar{\Delta}_{median}$ for passing sites). This
 518 higher level of precision is likely an outcome of using the standard deviation optimiza-
 519 tion procedure, and is probably not reflective of the true uncertainty judging by the low
 520 \bar{f}_{acc} for both PICRITMODk and SELCRITMODk. CCRIT still achieves lower \bar{f}_{prob} and
 521 higher $\bar{\Delta}_{median}$ than BiCEP even if only passing sites are considered, indicating a slightly
 522 lower accuracy and precision overall. Our two selection criteria which do not include a
 523 curvature criterion (PICRITMOD and SELCRITMOD) have a larger number of pass-
 524 ing sites, including remag-rs78 and Synthetic60, but still have reduced \bar{f}_{prob} and $\bar{\Delta}_{median}$.
 525 Ultimately it seems that BiCEP offers the best of both worlds, passing at least as many
 526 sites as the more permissive criteria, and achieving higher accuracy and more realistic
 527 precision than the more restrictive criteria.

528 3.2 Width of the prior

529 To investigate the role of the prior distribution ($P(\sigma_{site})$), we apply the BiCEP method
 530 on the data compilation using a variety of values for its standard deviation (see Table 2).
 531 The main effect of varying σ_{site} is that for smaller values, the estimates of B_m and \vec{k}_m
 532 for specimens are “pulled” closer to the line being fitted at a site level (see Figure 5a,b).
 533 For our estimate of B_{anc} , this means that sites with fewer specimens will be more pre-
 534 cise, as it is unlikely that specimen B_m will deviate strongly from the mean. For sites
 535 with many specimens, there is little effect as σ_{site} is well constrained by the data.

536 From Table 2, we see that changes to $P(\sigma_{site})$ seem to have little influence on the
 537 effectiveness of the model, as all our \bar{f}_{acc} values are the same for our linear model regard-
 538 less of the prior distribution used. We can also see graphically in Figure 7 that our pre-
 539 cision is low for sites with small number of specimens (M). Because of this, we favor the
 540 version of the model with a 5 μT standard deviation on $P(\sigma_{site})$, as models with higher
 541 standard deviations reduce precision without capturing any more sites within their 95%
 542 credible intervals.

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3.3 Order of polynomial fit

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The results for our test sites (Table 2) demonstrate that increasing the order of the polynomial fit decreases the precision of the estimate as demonstrated by reduced values of \bar{f}_{prob} . This is expected as there are more parameters to be estimated with the same number of data. The level of accuracy is not significantly improved by increasing the model order. The best quadratic model produced a $\hat{\Delta}_{median}$ of 1.6 μT , which is not a significant improvement over the value of 1.7 μT for the best linear model to account for the reduction in precision. The number of passing sites is reduced for the cubic model, indicating that the sampler is struggling to fit this model. Consequently, the cubic model produces more inaccurate and less precise results. For this reason, we assume a linear relationship between B_m and \vec{k}_m .

554

3.4 Sampler Diagnostics

Site Name	Worst \hat{R}	n_{eff}	f_{div}
1991-1992 Eruption Site	1.00	59741	0.00
hw108	1.00	77959	0.00
hw123	1.01	11687	0.00
hw126	1.00	36130	0.01
hw128	1.00	78978	0.00
hw201	1.00	10641	0.01
hw226	1.00	7139	0.05
hw241	1.00	66565	0.00
BR06	1.01	451	0.00
P	1.00	62252	0.00
VM	1.05	1447	0.00
BBQ	1.00	63082	0.00
rs25	1.00	5614	0.00
rs26	1.00	11866	0.00
rs27	1.00	22211	0.00
remag-rs61	1.00	26746	0.00
remag-rs62	1.00	16916	0.00
remag-rs63	1.00	3788	0.00
remag-rs78	1.00	12388	0.00
kf	1.02	2712	0.00
Hawaii 1960 Flow	1.00	60184	0.00
SW	1.00	36390	0.00
TS	1.00	56518	0.00
ET1	1.01	995	0.00
ET2	6.93	6	0.03
ET3	1.01	424	0.00
Synthetic60	1.00	36572	0.01
LV	1.02	5931	0.08
MSH	2.78	24	0.45
FreshTRM	1.00	81007	0.00

Table 3. Sampler diagnostics (see Section 2.5 for an explanation of each diagnostic) for each site using the BiCEP method.

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556

The sampler diagnostics for each site are given in Table 3. Indicators of poor MCMC sampler performance (worst $\hat{R} > 1.1$, low n_{eff} , high f_{div}) tend to occur at sites with four

557 or fewer specimens, or for specimens where the Arai plots are extremely scattered and
 558 the sampler struggles to fit them. In the latter case, it may be possible to exclude these
 559 specimens by looking at which specimen level parameters have high \hat{R} , as this indicates
 560 that fitting a circle to these specimens is inappropriate. We did not exclude specimens
 561 on this basis in our analysis, however, we include an option to do this in the BiCEP GUI
 562 software (see Appendix 6.3).

563 The prevalence of high \hat{R} for sites with low numbers of specimens indicates that
 564 to get a strongly reproducible answer from this method, paleomagnetists ought to mea-
 565 sure five or more specimens per site. In practice, most studies already do this in order
 566 to have enough specimens that pass the chosen selection criteria, yet many specimens
 567 may be excluded from analysis. Here, we can use all of the specimens measured so there
 568 may be no additional burden.

569 3.5 Summary of Results

570 After testing all of our contingent models, we prefer the model which assumes the
 571 relationship between B_m and \vec{k}_m is linear, and which uses a $5 \mu\text{T}$ standard deviation on
 572 $P(\sigma_{site})$. This model performs better than classical sets of selection criteria, either pass-
 573 ing a greater number of sites (than CCRIT, PICRITMODk, SELCRITMODk) or hav-
 574 ing significantly higher accuracy and precision (than PICRIT, SELCRIT). Our preci-
 575 sion increases for sites for which the number of specimens is large, similar to calculat-
 576 ing the standard error of the mean when using selection criteria. Unlike selection crite-
 577 ria, the BiCEP method does not require exclusion of large numbers of specimens to ob-
 578 tain an accurate result, which leads us to prefer it over those methods.

579 4 Discussion

580 4.1 Advantages of BiCEP compared to selection criteria

581 BiCEP has significant advantages over the classical selection criteria approach. Firstly,
 582 we obtain paleointensity estimates for all sites with at least three specimens, including
 583 some which do not contain any specimens that would pass classical selection criteria (see
 584 Figure 7). In most cases, our estimates have similar or higher accuracy than the selec-
 585 tion criteria approach (evidenced by $\hat{\Delta}_{median}$ and Figure 7), and this is accomplished
 586 while only excluding specimens from the analysis which were not fully demagnetized. In
 587 some cases, our method yields results even if none of the selection criteria accept any spec-
 588 imens or are inaccurate. For example, for sites remag-rs78 and Synthetic60, our strict
 589 criteria (CCRIT, PICRITMODk, SELCRITMODk) produce no results, and our more
 590 permissive criteria (PICRITMOD, SELCRIT) produce less accurate (and in the case of
 591 Synthetic60, much less precise) results than BiCEP.

592 Secondly, the increasing precision of our paleointensity estimate as the number of
 593 specimens increases allows for an improved workflow when compared to classical paleo-
 594 intensity criteria. Instead of needing a minimum number of specimens to pass our se-
 595 lection criteria, we can keep measuring specimens until we reach a desired level of pre-
 596 cision. We discuss this workflow in more detail in Section 4.3. The property of increas-
 597 ing precision with number of specimens is inherent to Bayesian models and can also be
 598 found in the method of Kosareva et al. (2020), although their method does not include
 599 the bias correction found in our method.

600 Thirdly, the BiCEP method propagates the uncertainties from a specimen to the
 601 site level. Specimens with more scattered (or non linear, or non circular) Arai plots will
 602 have less influence over the specimen mean than those with highly linear Arai plots. In
 603 addition to this, the BiCEP method foregoes the need for criteria which are concerned
 604 with the length of the line on the Arai plot used to make an interpretation, like the NRM

605 Fraction (e.g., FRAC of Shaar & Tauxe, 2013). Using a set of temperatures with small
 606 FRAC will cause an increase in the uncertainty in \vec{k} (see Figure 4e, f), which will cause
 607 this specimen to have less effect on the estimate of B_{anc} , without excluding it from the
 608 analysis entirely. We discuss this further in Section 4.5.

609 **4.2 Predictive ability of the method**

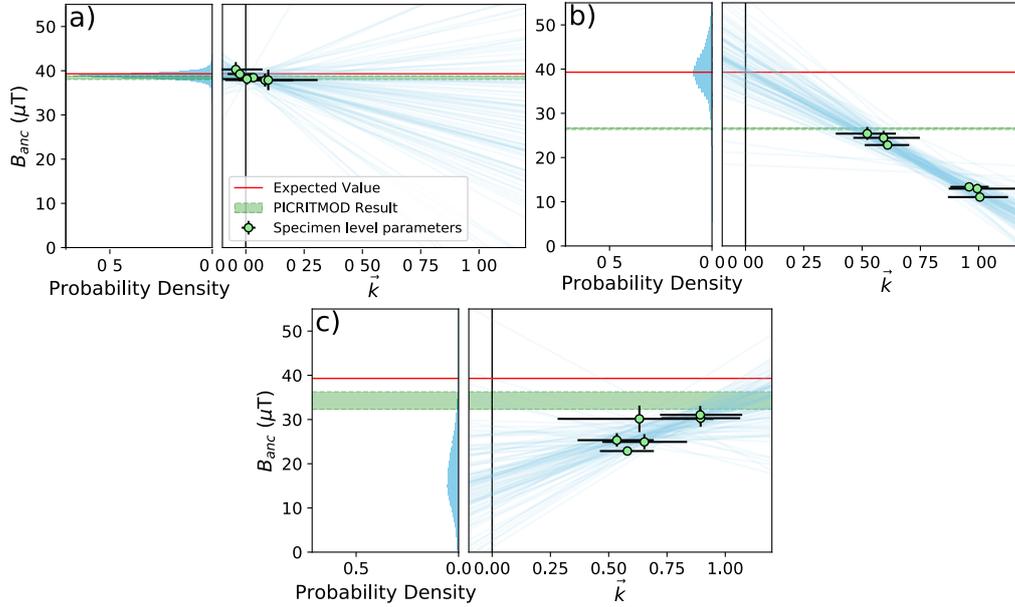


Figure 8. Example of the BiCEP method applied to three subsets of 6 specimens from site hw108 ($B_{exp} = 39.3 \mu\text{T}$). The left column in each subplot shows histograms of the BiCEP results, and the right column shows plots of specimen \vec{k} vs B_{anc} with the BiCEP line fits. Light green shaded regions with dashed edges represent the 2σ interval of the PICRITMOD estimate for these subsamples. In a) there is a small range of \vec{k} and B_{anc} values which leads to an imprecise estimate of c , but an accurate and precise estimate of B_{anc} . In b) there is a large range of values on \vec{k} , but all specimens have high \vec{k} . This leads to an estimate with a relatively precise estimate of c , and an accurate but imprecise estimate of B_{anc} . In c) there is a reasonably small range of values on B_{anc} , and the relationship between B_{anc} and \vec{k} is not linear, but BiCEP attempts to find a linear model. This leads to an imprecise and inaccurate estimate of both c and B_{anc} .

610 Although our results are promising, it is worth noting that traditional selection cri-
 611 teria also perform well for the majority of our sites. To see if the BiCEP method offers
 612 accurate results with poorer quality data, we subsampled results from site hw108, which
 613 had a range of good and poor quality specimens. Figure 8 shows the results of BiCEP
 614 applied to three different subsets of six specimens taken from this site, along with the
 615 results of the PICRITMOD criteria applied to this site (in green). It is worth noting that
 616 only the specimens in Figure 8a would pass the CCRIT criteria which gave a highly ac-
 617 curate result (within $1 \mu\text{T}$), or any of our more restrictive criteria.

618 We identify three behaviours for which BiCEP results deviate from a linear model
 619 with high precision on the slope and intercept. Figure 8a shows a subset of specimens
 620 for which the range of \vec{k} values of the specimens is very small, and so the uncertainty

621 of the slope of the linear relationship between \vec{k}_m and B_m (c) is high. In this case, how-
 622 ever, because these specimens all have \vec{k} close to zero, the estimate of B_{anc} is accurate
 623 and precise. Figure 8b shows a different subset of specimens for which the range of \vec{k} val-
 624 ues is large, but there are no \vec{k} values close to zero. This results in an estimate of B_{anc}
 625 which is still accurate, but imprecise due to the uncertainty in extrapolating the linear
 626 relationship between \vec{k}_m and B_m back to zero. The PICRITMOD result for this subset
 627 returns an average value which underestimates B_{exp} by around $\sim 13 \mu\text{T}$ or $\sim 30\%$, and
 628 criteria using the curvature criterion return no values, as all specimens have curvature
 629 values higher than the threshold. The high uncertainty in B_{anc} might still be considered
 630 a problem, but this result indicates that measuring more specimens would likely yield
 631 a more precise result.

632 Figure 8c shows a set of specimens where the range of \vec{k} is low, so the \vec{k}_m versus
 633 B_m relationship is not particularly linear. BiCEP attempts to find a linear trend with
 634 these data, and extrapolates back to a B_{anc} which is both highly inaccurate and impre-
 635 cise. This might be considered a problem for BiCEP, but it is possible to detect such be-
 636 havior as the uncertainty on both B_{anc} and the slope relating the B_m versus \vec{k}_m (c) are
 637 large. This indicates to us that we can use a metric of the uncertainty in both the slope
 638 and intercept of the linear fit in BiCEP to decide whether a site level result is accurate
 639 or not. This leads us to a laboratory workflow which uses BiCEP results to decide if a
 640 site is acceptable, might be acceptable with further work or is unlikely to give a reason-
 641 able result.

642 4.3 Workflow with BiCEP

643 Figure 9 plots the 95% credible interval on B_{anc} as a percentage against the 95%
 644 credible interval on c as a proportion of the median \tilde{B}_{anc} for all sites where $\hat{R} > 1.1$.
 645 The sizes of the points on the plot represents the number of specimens per site (M), with
 646 squares representing sites with $M < 5$. The colors show the percentage deviation from
 647 B_{exp} using BiCEP, with redder colors for more inaccurate results. With the exception
 648 of two sites (VM and hw123), as the number of specimens increases, sites trend towards
 649 the bottom left region of this plot, indicating an increase in precision. This has dimin-
 650 ishing returns as the number of specimens increases above five. The increase in preci-
 651 sion is also accompanied with an increase in accuracy. Almost all sites with an estimated
 652 precision on B_{anc} better than 40% have median values within 20% of B_{exp} . Our outlier
 653 sites VM and hw123, which are imprecise despite having large numbers of specimens ($M=12$
 654 and 18 respectively), are also inaccurate. This indicates that the width of the 95% cred-
 655 ible intervals is a useful statistic for diagnosing inaccuracy in the BiCEP method.

656 We have divided Figure 9 into four regions (labeled A-D). Sites in region A have
 657 high precision on both B_{anc} and c and are representative of the results for the major-
 658 ity of sites in this study; sites in this region are highly accurate. Sites in region B have
 659 high precision on B_{anc} (better than 40%, which for a Gaussian distribution would be equiv-
 660 alent to a standard deviation of $\pm 10\%$) but low precision on c (95% credible interval on
 661 $c/\tilde{B}_{anc} > 1$). These sites are usually analogous to the example shown in Figure 8a, with
 662 low Arai plot curvature and similar intensities for all specimens. Sites in region C have
 663 high precision on B_{anc} but a low precision on c . These sites may have a large number
 664 of curved specimens which follow a linear trend that can be extrapolated back to the cor-
 665 rect B_{exp} , and are analogous to our example in Figure 8b. Region D is representative
 666 of the worst constrained estimates, with low precision on B_{anc} and c . Sites in this re-
 667 gion may have highly inaccurate estimates of B_{anc} , often with low M . If these sites have
 668 high M , they may be similar to our example in Figure 8c in which a linear relationship
 669 between B_{anc} and c is not well determined, and the average $|\vec{k}|$ is large, leading to an
 670 inaccurate estimate of B_{anc} .

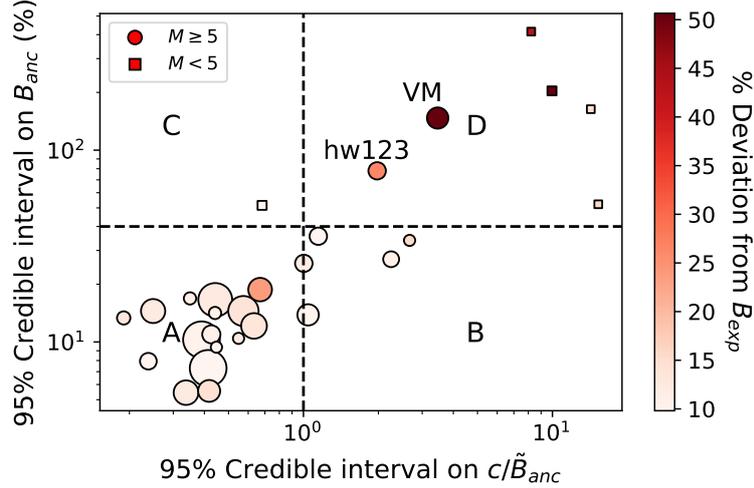


Figure 9. Plot of the 95% credible interval on B_{anc} against the 95% confidence interval on c (slope between intensity estimate and \vec{k}), normalized by the median B_{anc} for all sites with $\hat{R} < 1.1$. Circles indicate sites for which the number of specimens $M \geq 5$, and squares indicate sites where $M < 5$. Colors indicate the deviation of the median value of the estimate from the expected site value (B_{exp}) as a percentage. The size of markers is used to represent M . The horizontal dashed line indicates a value of 40% for the full width of the 95% credible interval on B_{anc} , which for a Gaussian distribution would correspond to a standard deviation of $\pm 10\%$. The vertical dashed line represents a value of 1 for the 95% confidence interval of c/\vec{B}_{anc} . Suggested workflow for sites in regions: A) or B), accept the site or continue measuring if improve precision is desired. C) Continue measuring specimens, as improved precision is likely. D) If $M \geq 5$ stop measuring the site as further effort is likely to be futile. Otherwise continue measuring specimens until $M = 5$.

671 Considering the region in which a particular site plots leads to a workflow based
 672 on the likelihood of success. In general, sites with very low numbers of specimens, ($M =$
 673 2 or 3), will begin in region D, and migrate to regions C, B or A as M increases to around
 674 five. If a site has migrated to region A or B after five specimens have been measured,
 675 then we likely have an accurate and precise estimate of B_{anc} , and we can finish measur-
 676 ing specimens (or continue to measure if a higher level of precision is desired). If a site
 677 has migrated to region C, it is likely that our estimate is accurate and that our uncer-
 678 tainty in B_{anc} can be reduced by increasing the number of specimens. If our site remains
 679 in region D after five specimens have been measured, the site level estimate may be in-
 680 accurate, and measuring more specimens would be unlikely to reduce the site level un-
 681 certainty.

682 Because the regions in Figure 9 define a workflow based on measuring five spec-
 683 imens, we wanted to test whether our methodology could identify sites which will remain
 684 in region D after a large number of specimens were measured. We randomly subsampled
 685 100 sets of 5 specimens from sites hw108, VM and hw123 and calculated B_{anc} and c us-
 686 ing BiCEP. Site hw108 was chosen because contains specimens which exhibit a wide range
 687 of behaviours, with a large number of specimens having high \vec{k} , but yields an accurate
 688 result. Sites VM and hw123 were chosen because these are our sites which remain in re-
 689 gion D after measuring a large number of specimens. Our results for these three sites
 690 are given in Supplemental Figure S2. Our subsampled hw108 obtained results in region

691 D 5 times out of 100, whereas our subsampled VM and hw123 obtained results in region
 692 D 94 and 90 times respectively. This indicates that sites which remain in region D af-
 693 ter measuring 5 specimens are likely to remain there after measuring many more, and
 694 so measuring more specimens is usually a futile effort.

695 **4.4 Overly precise estimates of B_{anc}**

696 The BiCEP method has a lower f_{acc} than CCRIT, despite having a similar degree
 697 of accuracy when using a metric like Δ_{median} . The reason for this is that the increas-
 698 ing precision on the BiCEP estimate leads to estimates which are highly precise when
 699 M is large. This is the case shown in Figure 6d.

700 Labeling sites with extremely high precision in the estimate as inaccurate may be
 701 misleading, as we have not taken into account uncertainties in the value of the expected
 702 fields at the sites in this study. For example, using differences between the observed di-
 703 rections and the IGRF, Yamamoto and Hoshi (2008) quoted the expected value at the
 704 site “SW” as $46.0 \pm 2.6 \mu\text{T}$, which is just consistent with the 95% credible interval for our
 705 specimen (48.2-49.7 μT). Because of this, we prefer to use \bar{f}_{prob} as a metric of how well
 706 a model performs as it allows for a few μT of uncertainty in the expected field value. Ad-
 707 ditionally, Yamamoto and Yamaoka (2018) suggested that the IZZI-Thellier results for
 708 sites SW and TS may be biased slightly high due to acquisition of a thermo-chemical re-
 709 manent magnetization (TCRM), which is not detectable by our method. Yamamoto et
 710 al. (2003) also invoke a TCRM mechanism to explain the paleointensity overestimate for
 711 the Hawaii 1960 Flow, which is another of their sites for which we overestimate the ex-
 712 pected intensity (see Figure 7 and Supplementary Data Set S1). We note that Cromwell
 713 et al. (2015) also sampled the 1960 flow (hw241 which targeted the fine grained flow top)
 714 and all selection criteria resulted in accurate results, with BiCEP producing the tight-
 715 est confidence interval.

716 **4.5 Exclusion of measurement level data**

717 It is frequently possible to improve the accuracy and precision of results by find-
 718 ing the ‘best’ set of temperature steps to use in the intensity interpretation. Two situ-
 719 ations frequently occur for which this might be justified. The first is the case in which
 720 thermochemical alteration occurs at high temperature (e.g., Figure 4e). For such spec-
 721 imens, the low temperature measurements can be used to make a paleointensity estimate
 722 (colored dots in the figure). Figures 4e and f show how our method can be used on a re-
 723 duced range of temperature steps on the Arai plot at the cost of precision. The plot of
 724 circle fits (green lines in Figure 4e) demonstrates that the Arai plot interpretations are
 725 poorly constrained and can continue in any direction after the last temperature step cho-
 726 sen. This results in a higher uncertainty in the curvature associated with this (Figure 4f).
 727 The second case in which a portion of the data could be excluded from the calculation,
 728 would be when the magnetization has multiple components (Figure 10a). In such a case,
 729 a paleointensity estimate can only be made using the small range of temperature steps
 730 that correspond to the characteristic component. We currently do not have an objec-
 731 tive method to choose which set of temperature steps on the Arai plot to use. We sug-
 732 gest that decisions about which data points to include should not be made based on the
 733 original in-field or zero field Arai plot measurements (dots in the Arai plots), but rather
 734 exclusively on deviating pTRM checks (triangles in, e.g., Figure 4e) or other indicators
 735 of alteration for the first case and on the directions of the magnetization vector (it must
 736 trend to the origin and be well defined) in the second case, e.g., Figure 10a.

737 Caution should be used when excluding a particular temperature steps for reasons
 738 other than this. If the set of temperature steps chosen does not represent the charac-
 739 teristic component of magnetization, this can alter the outcome of the BiCEP method, es-
 740 pecially if a large part of the Arai plot is excluded. Additionally, excluding more points

741 on the Arai plot tends to increase the chance that a specimen will cause \hat{R} failure. As
 742 such, we recommend using as many points on the Arai plot as possible unless done for
 743 one of the reasons stated above.

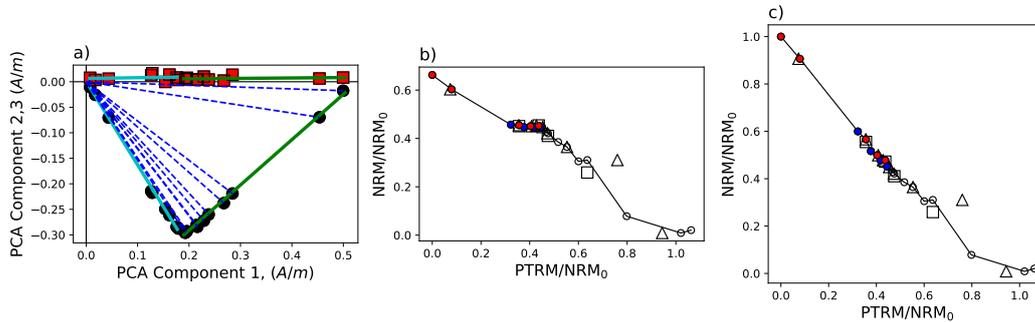


Figure 10. a) Example of vector endpoint diagram for specimen FB2-B1 from Lisé-Pronovost et al. (2020). The magnetization is rotated so that the principal component of the TRM direction for all steps lies along the x axis. Green line fit to the low temperature component and cyan line fit to the high temperature component. b) Arai plot and c) “corrected” Arai plot for a specimen from the data shown in b). NRM values for the low temperature component (filled circles) are usually calculated by taking the magnitude of the vector endpoint (blue dashed lines in the vector endpoint diagram in a). In c), these NRM values are calculated by vector subtracting the high temperature component (cyan line), taking the magnitude of our new NRM vectors (distance along green line), and adding the magnitude of the low temperature component (length of cyan line). Both b) and c) are scaled by the total NRM distance along both components (total distance along both green and cyan lines).

744 4.6 Application to multi-component magnetizations

745 We test an application of the BiCEP method on data with multi-component di-
 746 rections as shown in Figure 10a using the data of Lisé-Pronovost et al. (2020). The data
 747 are from Scottish firebricks which were used in a foundry in Australia. The date and lo-
 748 cation of firing are both well constrained, hence we have a reasonably well constrained
 749 value for B_{exp} . The bricks all contained a low temperature component associated with
 750 the Australian field. Some also displayed a high temperature component associated with
 751 the original firing in Scotland as shown in Figure 10a. Lisé-Pronovost et al. (2020) al-
 752 ready have interpretations which separate these components in the original study. To
 753 account for the change in direction of the NRM, we subtract the high temperature
 754 component from the low temperature component, and then add the magnitude of these val-
 755 ues to the magnitude of the low temperature component (see Figure 10 for a graphical
 756 explanation). The vector subtraction is necessary for the low-temperature component
 757 as we need a total TRM ($pTRM_{max}$) to scale by in order to penalize the result for shorter
 758 components. We then proceed to use the BiCEP method as previously described, using
 759 the original interpretations for the different components. For the sake of simplicity, we
 760 do not perform the magnetomineralogical change (MMC) correction (Valet et al., 1996).
 761 We also do not apply the corrections for anisotropy of TRM or cooling rate with these
 762 data, as they appeared to be negligible. Of course these could be applied in the usual
 763 fashion if necessary.

764 We display the results from multi-component remanences in Figure 11. We find that
 765 for the low temperature, Australian field, component (Figure 11a), our estimates for all
 766 firebricks contain the expected answer ($61.17 \mu T$) within the 95% credible interval. Our

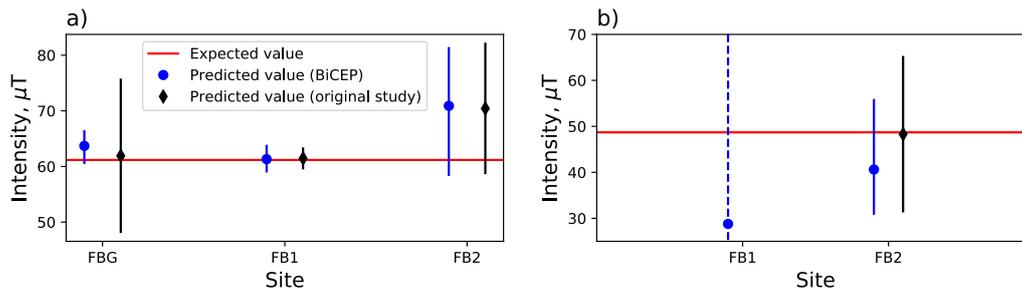


Figure 11. Expected and predicted intensities on the data of Lisé-Pronovost et al. (2020) using BiCEP (blue circles) and the method used in the original study (black diamonds). a) Results for the low temperature component (Australia, expected field value $61.17 \mu\text{T}$) for each firebrick. b) Results for the high temperature component (Scotland, expected field value $48.3 \mu\text{T}$), where this component was present. The dashed blue line indicates that the MCMC sampler failed to converge for site FB1.

767 interpretation for site FBG is slightly less accurate than the original analysis but with
 768 much higher precision. This difference is likely caused by not applying the MMC cor-
 769 rection, as the specimens at this site were mostly of good quality, with none being ex-
 770 cluded from the original analysis.

771 For the high temperature component (Figure 11b) our results behave differently.
 772 The sampler does not converge for site FB1, indicating too few specimens in the anal-
 773 ysis. For site FB2, we have a result that is less accurate, but more precise than in the
 774 original study. The lack of MMC correction may contribute to the decreased accuracy
 775 in this example, whereas the reduced precision is likely caused by the smaller length of
 776 the interpretation on the Arai plot, leading to a higher uncertainty in the curvature for
 777 that specimen. Our results for this study demonstrate that BiCEP will obtain precise
 778 estimates for components which represent most of the magnetization, and be imprecise
 779 for components which have small NRM fraction.

780 4.7 Implications for bias in curved Arai plots

781 The success of our method demonstrates that Arai plot “curvature” or sagging does
 782 lead to a progressive bias in paleointensity estimation which increases as the amount of
 783 curvature increases as described by Tauxe et al. (2021) and strongly suggested by the
 784 data of Krása et al. (2003) (see Figure 1). Our estimates are made by using the tangent
 785 to a circle fit rather than fitting a line to part of the data, so one might expect them to
 786 be biased. However, it has been demonstrated by e.g. the data of (Krása et al., 2003)
 787 that fitting lines to the high temperature or low temperature slope of Arai plots yields
 788 even more biased results than using the total TRM, which is more similar to the tan-
 789 gent. The scaling used by our method incorporates the added uncertainty in the line slope
 790 and k associated with choosing one of these slopes, which allows for more consistent anal-
 791 ysis between specimens with interpretations of varying quality. The bias seen generally
 792 underestimates paleointensity with higher (positive) curvature, but this is not the case
 793 for all sites, some of which exhibit the opposite trend.

794 The assumption of a quasi-linear dependence between the specimen level paleoin-
 795 tensities and the curvature of the Arai plot does not have any theoretical basis. This does
 796 imply that the curvature is linearly related to the change in TRM susceptibility (or de-
 797 cay of the original magnetization) between the original and lab coolings, a relationship

798 which should be further investigated. We stress that this relationship only needs to be
 799 loosely followed for our method to work. In cases where there does not appear to be a
 800 strong linear relationship between B_m and \vec{k}_m (e.g. in Figure 8a), an accurate paleoin-
 801 tensity estimate is still possible if there are enough specimens with low $|\vec{k}|$, as the inter-
 802 cept of the linear fit is still well constrained even if the slope is not. Conversely, if there
 803 are few specimens with low $|\vec{k}|$ and there is a poor linear relationship, then both the slope
 804 and intercept are poorly constrained, resulting in a huge uncertainty in B_{anc} , as is seen
 805 in Figure 8c.

806 5 Conclusions

- 807 • We present a new Bayesian method (BiCEP) which accounts for bias in paleoin-
 808 tensity estimates in specimens.
- 809 • Instead of excluding specimens from the paleointensity analysis in the traditional
 810 (binary) selection criteria based approach, our method predicts an amount of bias
 811 for each specimen, using the curvature of the Arai plot as a metric of non-linearity
 812 and a predictor of bias. In this way, the BiCEP method is quite different from the
 813 recently published Bayesian approach of Kosareva et al. (2020).
- 814 • When tested on a compilation of sites for which an approximate paleointensity is
 815 known *a priori*, our method yields levels of accuracy and precision similar to, or
 816 better than restrictive paleointensity criteria, whilst accepting as many results as
 817 permissive criteria.
- 818 • Our method generates some slightly inaccurate paleointensity estimates with high
 819 levels of precision, but these can generally be explained with inaccuracies in the
 820 expected field (see Section 4.4).
- 821 • The BiCEP method handles uncertainties in a different way than using classical
 822 selection criteria, as the uncertainty in site level estimates decreases as the num-
 823 ber of specimens increases, but this uncertainty remains high when the number
 824 of specimens is low due to inclusion of prior information. The Bayesian uncertain-
 825 ties are in this way more similar to the ‘extended error bars’ in the Thellier_GUI
 826 auto-interpreter of Shaar and Tauxe (2013).
- 827 • We propose a workflow in which sites are accepted and measurement of specimens
 828 can cease once a desired level of confidence in the site level estimate has been reached.
 829 Sites which do not reach this level of confidence after measuring several (> 5) spec-
 830 imens likely do not contain useful information and can be discarded.

831 Data Availability Statement

832 Data used in this paper may be found in the MagIC database at: [https://earthref](https://earthref.org/MagIC/17104/0326fdaa-4bcf-44f3-989d-0116b9a2fb75)
 833 [.org/MagIC/17104/0326fdaa-4bcf-44f3-989d-0116b9a2fb75](https://earthref.org/MagIC/17104/0326fdaa-4bcf-44f3-989d-0116b9a2fb75) for review and will be
 834 available to the public at <https://earthref.org/MagIC/17104> on publication.

835 6 Appendix

836 6.1 Change of variables

837 In Section 2.2.1 we mention that we need to use a change of variables to get from
 838 our original circle fitting parameters R, x_c, y_c to our new set of parameters \vec{k}, D, ϕ . We
 839 can use the Jacobian of the parameter change to get the new formula for the posterior
 840 probability under our new parameters:

$$P(D, \phi, \vec{k}|x, y) = P(x_c, y_c, R|x, y) \left| \frac{\partial(x_c, y_c, R)}{\partial(D, \phi, \vec{k})} \right|. \quad (20)$$

841 We can evaluate this Jacobian as:

$$\left| \frac{\partial(x_c, y_c, R)}{\partial(D, \phi, \vec{k})} \right| = \left| \frac{\vec{k}}{|\vec{k}|^3} \left(D + \frac{1}{\vec{k}} \right) (\cos \phi + \sin \phi) \right|. \quad (21)$$

842 So our posterior looks like:

$$P(D, \phi, \vec{k} | x, y) \propto \left(\sum_{n=1}^N \sqrt{\left(\left(D + \frac{1}{\vec{k}} \cos \theta \right) - x_n \right)^2 + \left(\left(D + \frac{1}{\vec{k}} \sin \theta \right) - y_n \right)^2 - \frac{1}{|\vec{k}|}} \right)^{-N/2}$$

$$\left| \frac{\vec{k}}{|\vec{k}|^3} \left(D + \frac{1}{\vec{k}} \right) (\cos \phi + \sin \phi) \right| P(\vec{k}, \phi, D). \quad (22)$$

844 6.2 Markov chain Monte Carlo sampling

845 The Markov chain Monte Carlo (MCMC) sampling method generates a set of sam-
 846 ples from the posterior probability distribution of B_{anc} which allows us to approximate
 847 it. We use the python bindings for the Stan software package (<http://mc-stan.org>) to
 848 generate these samples which provides diagnostic information and runs relatively quickly.
 849 For each site we run four Markov chains and generate 30,000 samples of B_{anc} in each
 850 chain. We discard the first half of the chain as ‘burn in’ for a total of 60,000 samples.

851 Stan provides several diagnostics that tell us whether we have successfully sampled
 852 the posterior distribution. These include the \hat{R} score (Gelman & Rubin, 1992) which tells
 853 us about the convergence between chains, and is required to be between 1.1 and 0.9 which
 854 is necessary for convergence, the effective sample size, n_{eff} which should be large (> 1000)
 855 for a good sample and the number of divergent transitions (f_{div}) which should be zero
 856 in ideal cases. In most cases our results display high degrees of convergence with \hat{R} close
 857 to 1 and high effective sample sizes. Some sites included divergent transitions in small
 858 numbers. These seem to occur at a specimen level for specimens where the posterior dis-
 859 tribution of one of the circle parameters is long-tailed. In theory this can mean the pos-
 860 terior was inefficiently sampled, but because these specimens generally have large un-
 861 certainties on their \vec{k} parameter, the final results do not change, even under a change of
 862 parameters. The sampler struggled to converge, with $\hat{R} > 1.1$ for several sites with very
 863 few specimens, where once again the distributions are extremely long tailed. The sam-
 864 pler also did not converge for site MSH, where the Arai plots were so non linear, with
 865 few points, that BiCEP struggled to fit circles to them. We consider these sites to have
 866 “failed” using our method (grade of ‘D’ in Figure 9) and use the prior distribution on
 867 B_{anc} (uniform between 0 and 250 μT) as an estimate of their intensity. We calculate the
 868 \hat{R} furthest from unity, the n_{eff} for B_{anc} and the proportion of divergent samples f_{div}
 869 for our model.

870 6.3 Code and GUI

871 We present a simple GUI that can perform the BiCEP method on data in the MagIC
 872 format. The code uses Jupyter notebooks and can be found at ([http://github.com/
 873 bcych/BiCEP_GUI](http://github.com/bcych/BiCEP_GUI)) and contains a readme file detailing how to use the notebook. The
 874 GUI can also be accessed at the Earthref JupyterHub site ([http://jupyterhub.earthref
 875 .org](http://jupyterhub.earthref.org)). To access the GUI this way:

- 876 • Sign up to Earthref at (<http://earthref.org>)
- 877 • Navigate to the Earthref JupyterHub site at (<http://jupyterhub.earthref.org>)
- 878 • Open and run all the cells in the “BiCEP GUI - Setup.ipynb” notebook.

- 879 • Upload MagIC formatted “sites”, “samples”, “specimens” and “measurements”
880 files to the BiCEP_GUI directory in JupyterHub. These can be formatted using
881 pmag_gui (Tauxe et al., 2016).
- 882 • Open the BiCEP GUI notebook and press the “App Mode” button.

883 For more detailed instructions, read the included readme file at the github site.

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