

# Predicting and forecasting root zone soil moisture with Random Forests

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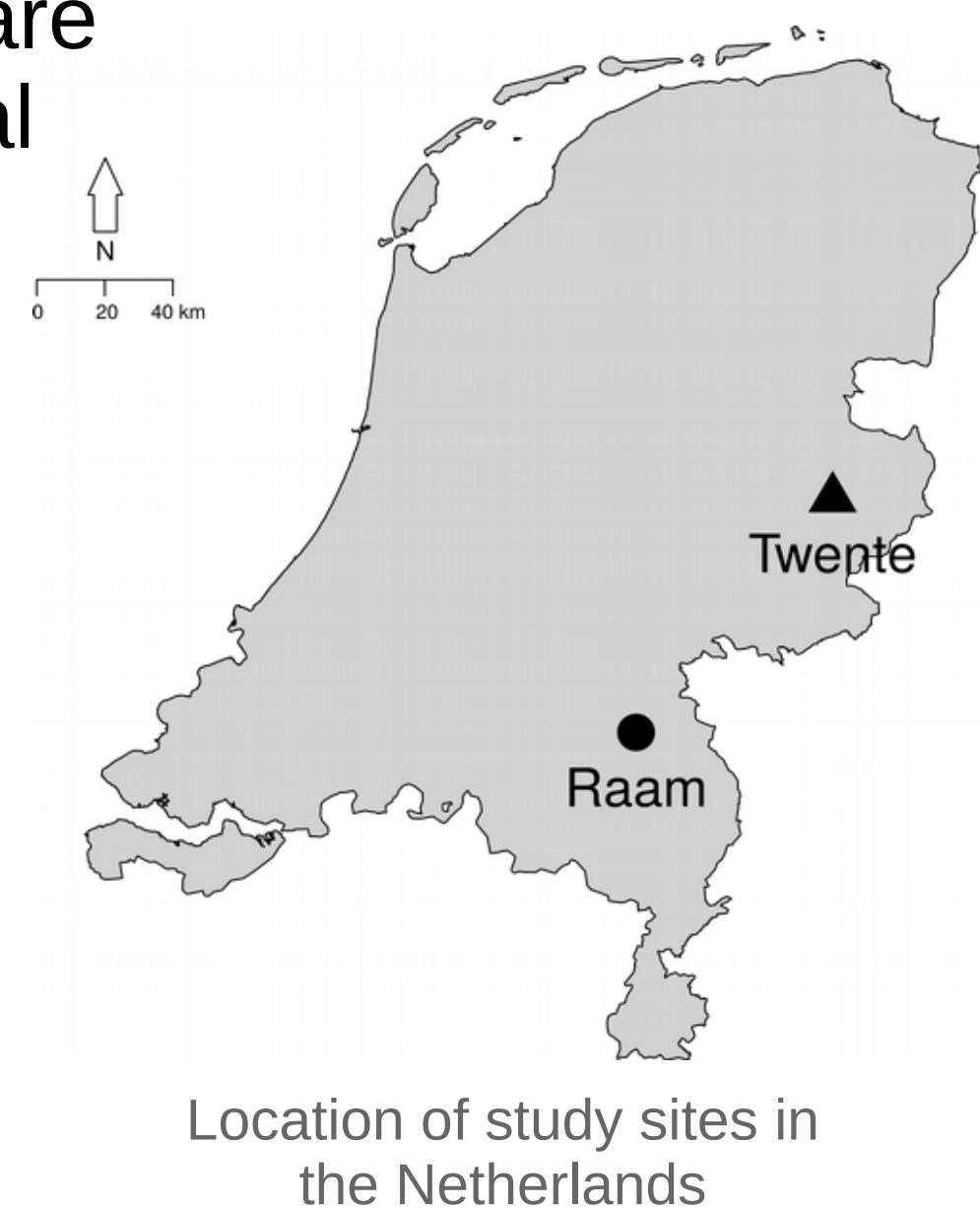
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## 1. Introduction

- Root zone soil moisture ( $\theta_{rz}$ ) is important in the hydrologic cycle and has been used for drought monitoring, water storage estimation and carbon cycle monitoring;
- Using physical hydrological models are the most common approach for estimation of  $\theta_{rz}$ ;
- Soil moisture datasets from different monitoring sites are continuously increasing and becoming more available (e.g. International Soil Moisture Network (ISMN));
- There is an opportunity to test data-driven methods such as Random Forests to estimate real-world  $\theta_{rz}$  conditions which are currently far less common than physical models.

**Objective:** Perform Random Forest (RF) to predict and forecast RZSM and compare results with simulations from a physical hydrological model (Hydrus-1D).

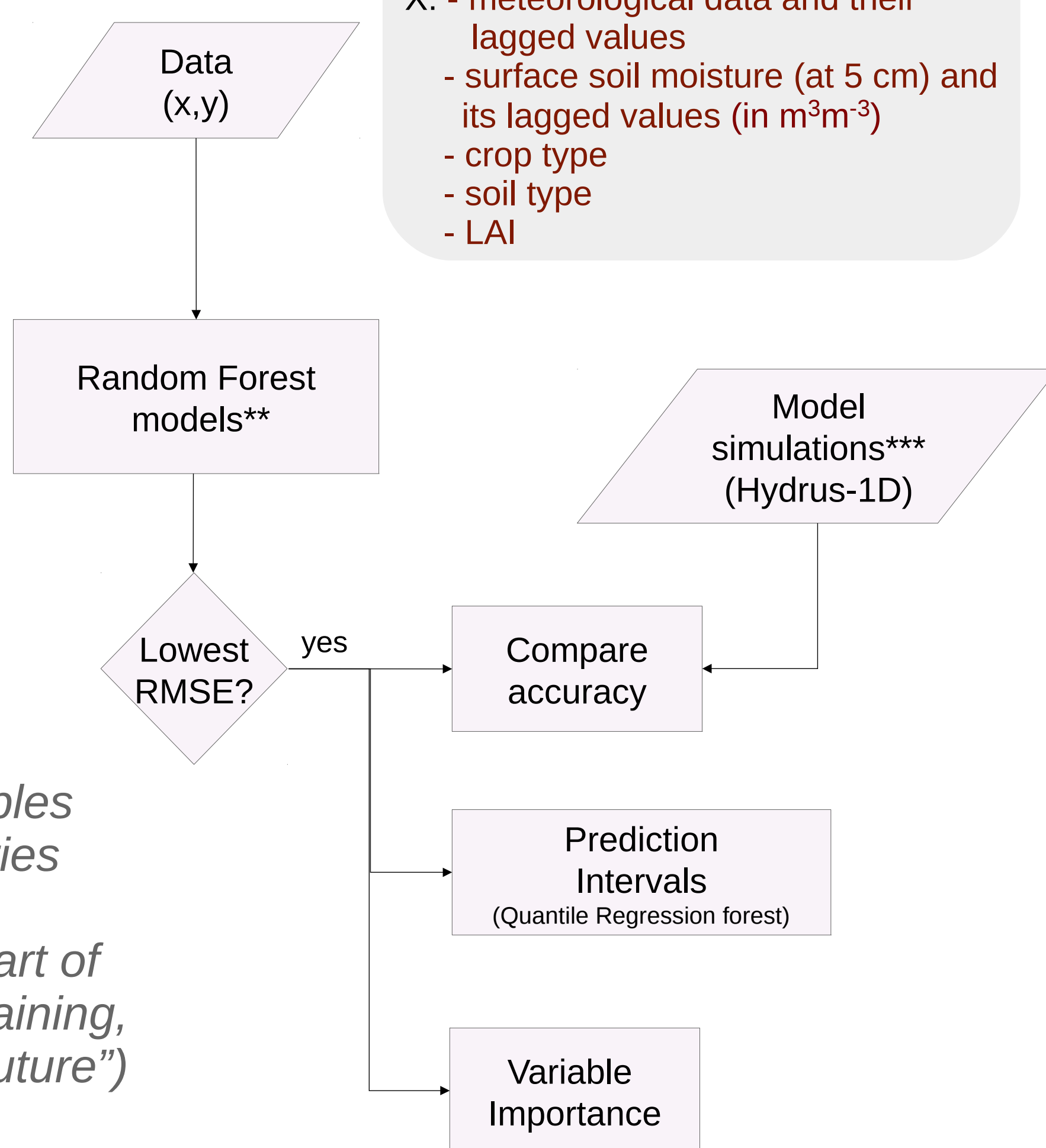


## 2. Materials and Methods

**Study area:** 4 stations within existing soil moisture networks (1 in Raam and 3 in Twente) which are closest to meteorological stations of KNMI (Royal Dutch Meteorological Institute).

Y: Depth-average  $\theta_{rz}$  up to 40 cm (in  $\text{m}^3\text{m}^{-3}$ )  
X: - meteorological data and their lagged values  
- surface soil moisture (at 5 cm) and its lagged values (in  $\text{m}^3\text{m}^{-3}$ )  
- crop type  
- soil type  
- LAI

Combinations of parameters:  
mtry: 3,4,5,6,7  
ntree: 500,600,700,800, 900,1000  
training prop\*: 0.5, 0.6, 0.7, 0.8

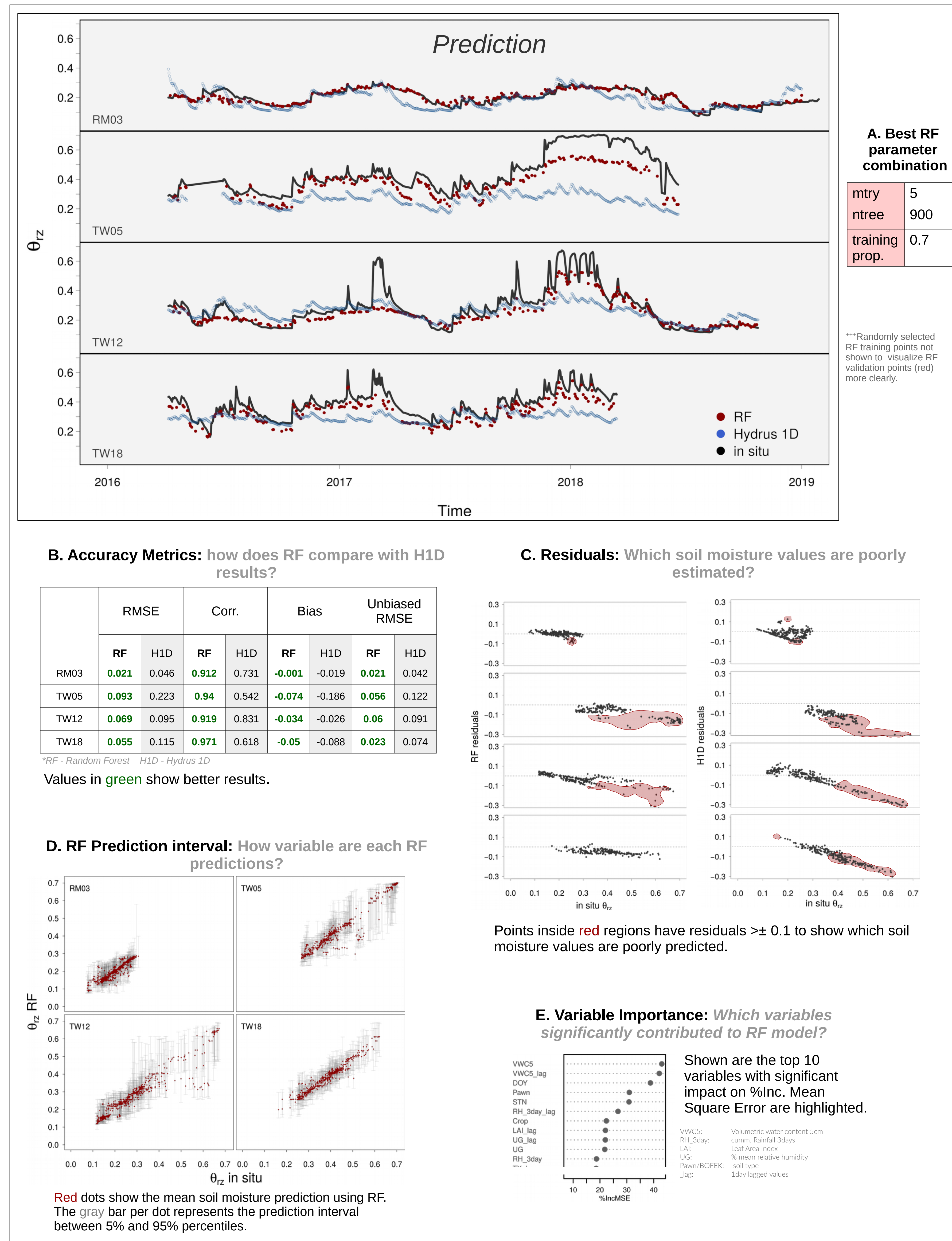


\*prediction: random samples from time series data  
forecasting: subset first part of dataset for training, remaining ("future") for validation

\*\* 120 sets of parameter combinations (based on list above) were used for training RF models. Samples from each site were combined train a single RF model

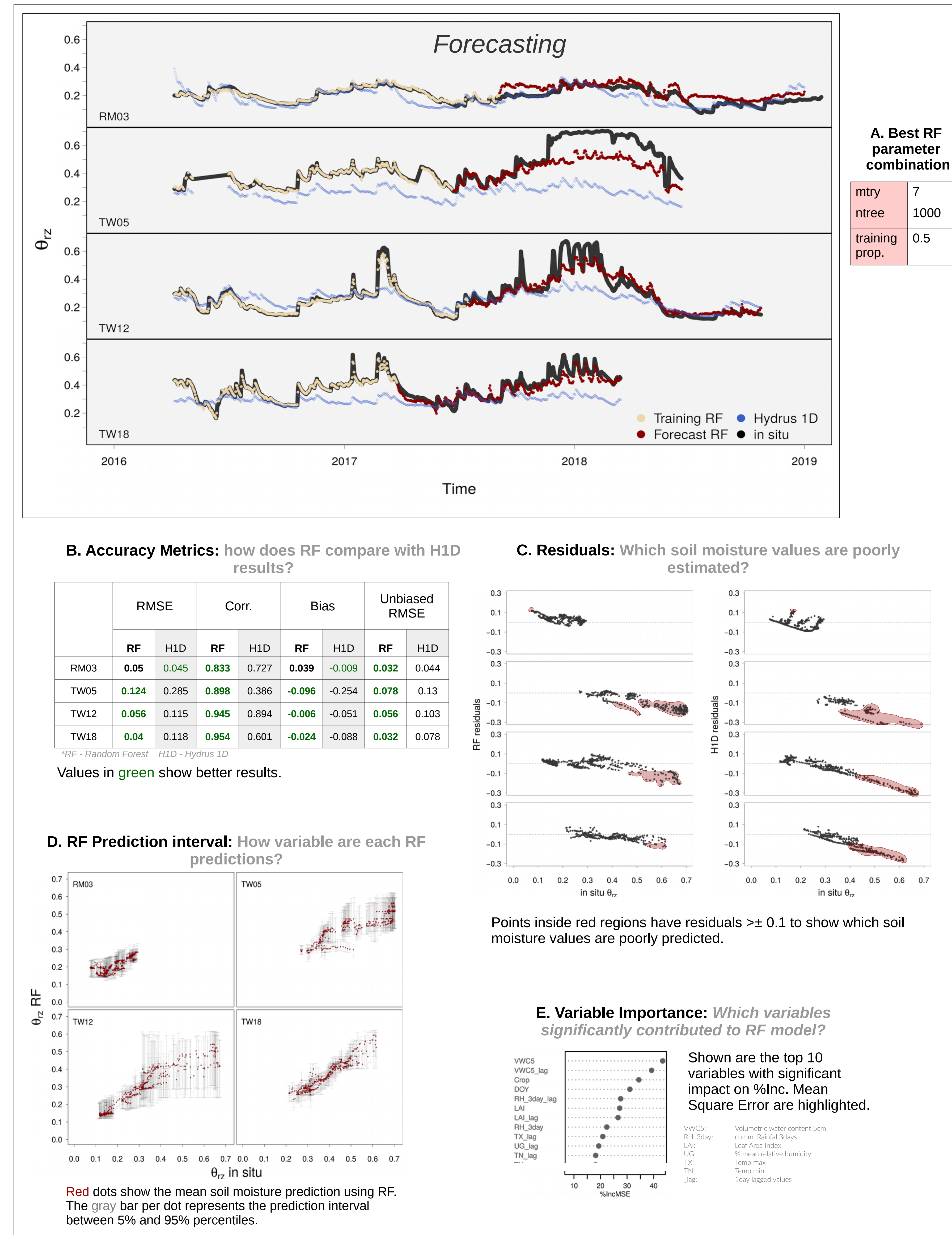
\*\*\* pore flow simulations with Hydrus-1D utilized the same independent variables (X) as RF. Additional inputs to perform the simulations were: soil hydraulic parameters, root water uptake function, site characteristics (e.g. Lat, Long) of meteorological stations

## 3. Results



## 4. Discussion

- In general, RF predictions showed better results than H1D simulations (B), for both prediction and forecasting.
- Both H1D and RF underestimate very high soil moisture values (C). Overestimation of very low values is also observed, but is not as common
- For RF, variables which represent processes that promote occurrence of very high soil moisture should be included (e.g. likelihood of macropore occurrence, bulk density).
- Range of prediction intervals appear to be site-specific (D). However, for a couple of sites (TW05 and TW12), larger intervals are observed for high soil moisture content.
- Important variables (E) show combination of meteorological conditions, vegetation and, soil properties are necessary for accurate prediction. Lagged values appear to be as important as current values.



### Why choose RF (or another data-driven method) over a physical model?

- Results from the study sites show capability of RF to accurately estimate  $\theta_{rz}$ . It even surpassed the accuracy of Hydrus-1D estimates using a pore flow model.
- Soil hydraulic parameters not required to run RF compared to physical models, which means they can be especially applicable in areas when these are not available. Prediction method also can be used to fill data gaps in soil moisture time series
- When the main objective is to estimate soil moisture states, RF can do the task. However, if processes that control soil moisture states are also sought, physical models should be applied. Although for RF, a glimpse into these processes are given by the list of important variables.

### Acknowledgements

This study is part of the project entitled Operational Water Management using Sentinel-1 Satellites (OWAS15). The project is funded by Toegepaste and Technische Wetenschappen (TTW) which is part of the Netherlands Organization for Scientific Research (NWO).