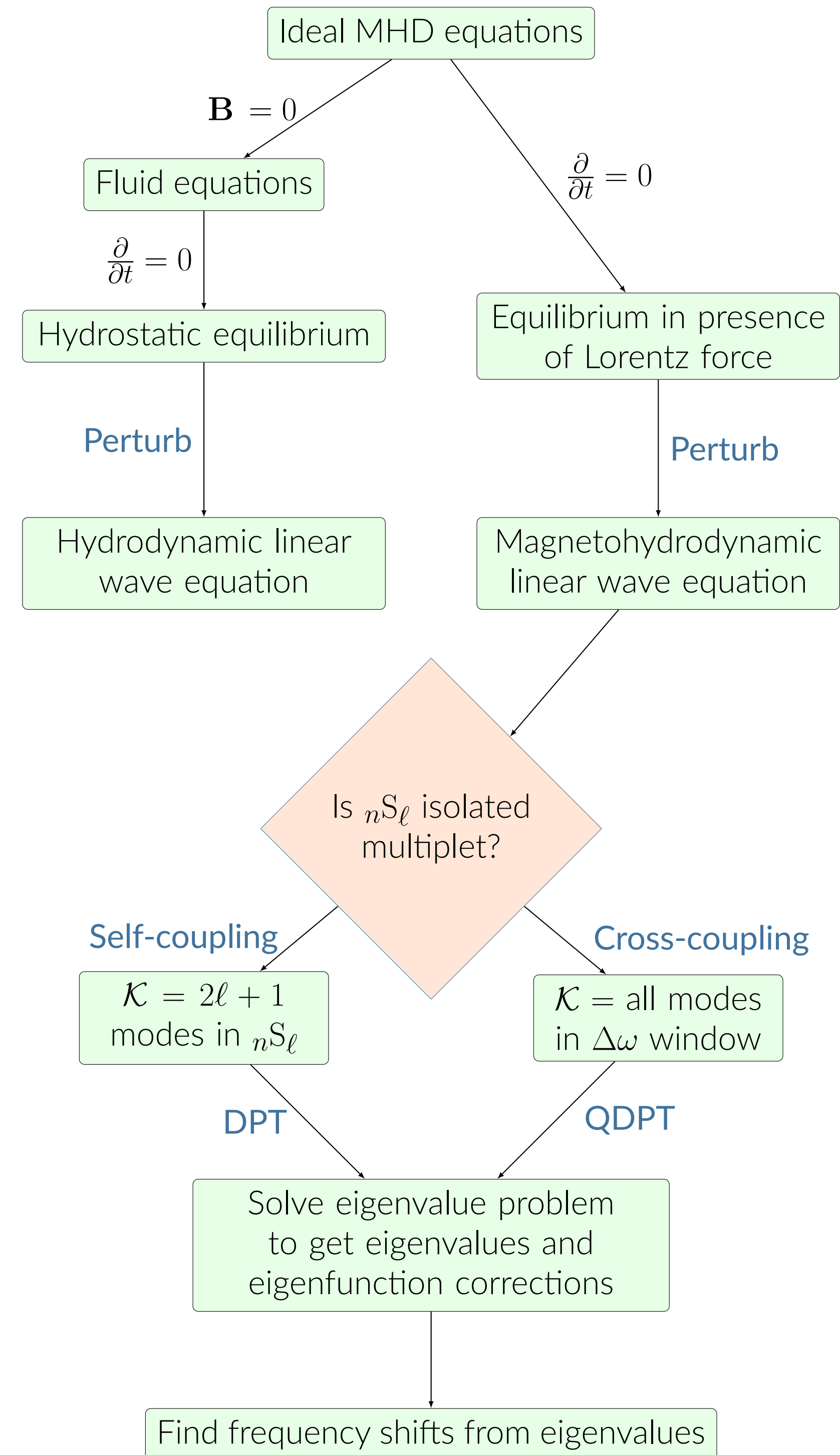


## Abstract

Departures from standard spherically symmetric solar models, in the form of perturbations such as global and local-scale flows and structural asphericities, result in the splitting of eigenfrequencies in the observed spectrum of solar oscillations. We find the Lorentz-stress sensitivity kernel for a general magnetic field, and therefore, also propose the sensitivity kernels for frequency splittings ( $a$ -coefficients) due to axisymmetric Lorentz stresses in the Sun. These results pave the way to formally pose an inverse problem, and infer solar (stellar) internal magnetic fields.

## Forward Problem: At a glance



## Magnetohydrodynamic (MHD) equations

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= -\nabla \cdot (\rho \mathbf{v}), \\ \rho \left( \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) &= -\nabla p + \frac{\mathbf{j} \times \mathbf{B}}{c} - \rho \nabla \phi, \\ \frac{\partial p}{\partial t} &= -\mathbf{v} \cdot \nabla p - \gamma p \nabla \cdot \mathbf{v}, \\ \frac{\partial \mathbf{B}}{\partial t} &= \nabla \times (\mathbf{v} \times \mathbf{B}). \end{aligned} \quad (1) \quad (2) \quad (3) \quad (4)$$

## Definitions

GSH basis :  $\hat{e}_- = \frac{1}{\sqrt{2}}(\hat{e}_\theta - i\hat{e}_\phi)$ ,  $\hat{e}_0 = \hat{e}_r$ ,  $\hat{e}_+ = -\frac{1}{\sqrt{2}}(\hat{e}_\theta + i\hat{e}_\phi)$

Expanding the displacement vectors in the basis of normal modes:

$$\begin{aligned} \boldsymbol{\xi}(\mathbf{r}, \omega) &= \sum_k \boldsymbol{\xi}_k e^{i\omega_k t}, \\ &= \sum_{st} \sum_\mu \xi_{st}^\mu(r) Y_{st}^\mu(\theta, \phi) \hat{e}_\mu \end{aligned}$$

No toroidal components in  $\boldsymbol{\xi}$ . Similarly,

$$\mathbf{B} = \sum_{st} \sum_\mu B_{st}^\mu(r) Y_{st}^\mu(\theta, \phi) \hat{e}_\mu,$$

$$\mathcal{H} = \mathbf{B} \mathbf{B} = \sum_{st} \sum_{\mu\nu} h_{st}^{\mu\nu}(r) Y_{st}^{\mu+\nu}(\theta, \phi) \hat{e}_\mu \hat{e}_\nu, \quad \mu \leftrightarrow \nu.$$

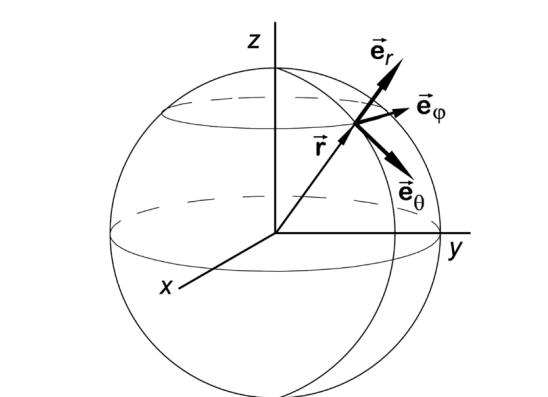


Figure 1: Spherical coordinate geometry

## Background solar model: SNRNMAIS

We adopt the method of perturbation theory. Therefore, we need a background model of the Sun which shall be perturbed to "fit" the real Sun. It is standard practise in helioseismology to start with the following simplified model, referred to as **SNRNMAIS**:

- Spherically symmetric,
- Non-Rotating,
- Non-Magnetic,
- Adiabatic,
- Isotropic,
- Static.

We use Model-S.<sup>1</sup>

## Modeling a custom magnetic field B

- Inner toroidal upto tachocline,  $r \leq 0.7R_\odot$ .
- Outer dipolar beyond  $r \geq 0.95R_\odot$ .
- Intermediate mixed (toroidal + spheroidal) field.

$$B_{st}(r) = \begin{cases} -i \frac{\alpha(r)}{\gamma_1} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \frac{\beta(r)}{\gamma_1} \begin{pmatrix} b - rb \\ -2b \\ b - rb \end{pmatrix}, & \text{for } (s, t) = (1, 0) \\ 0, & \text{for } (s, t) \neq (1, 0), \end{cases}$$

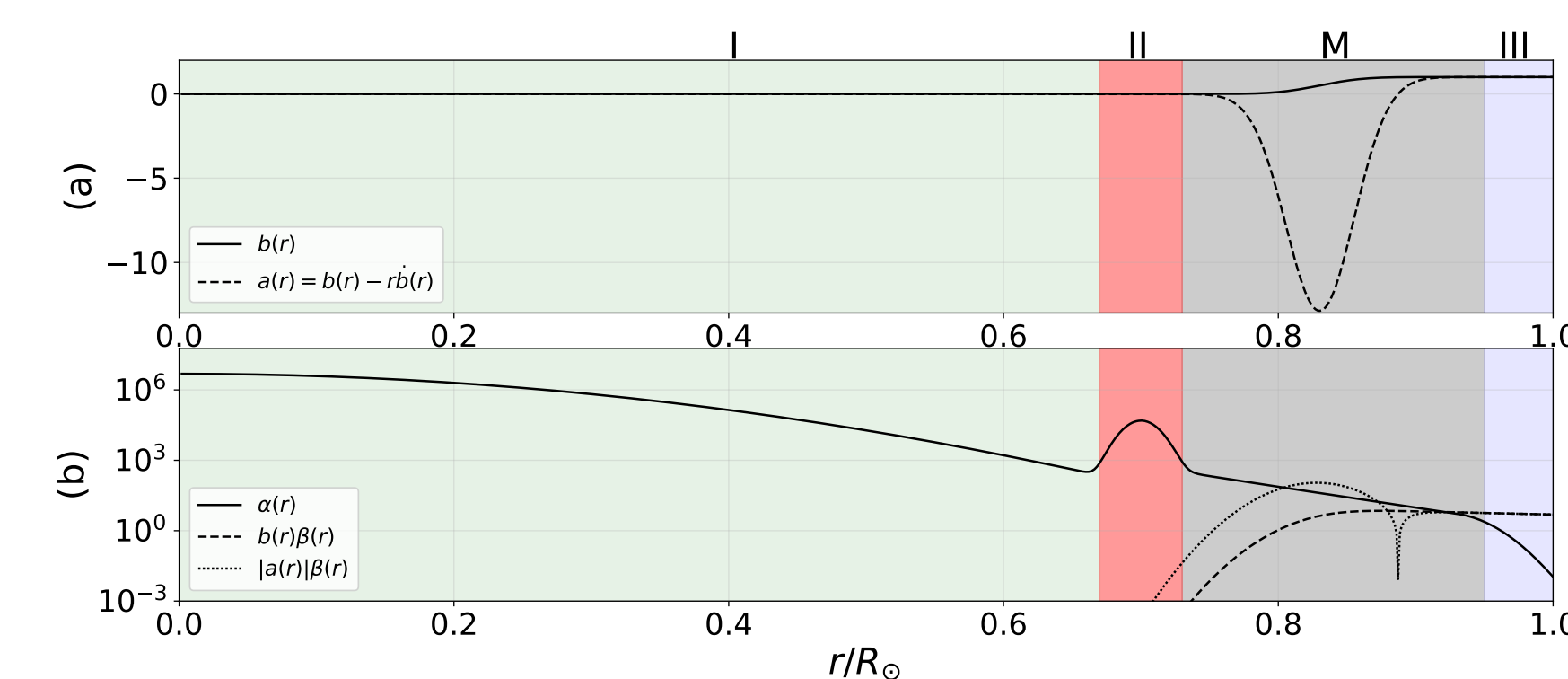
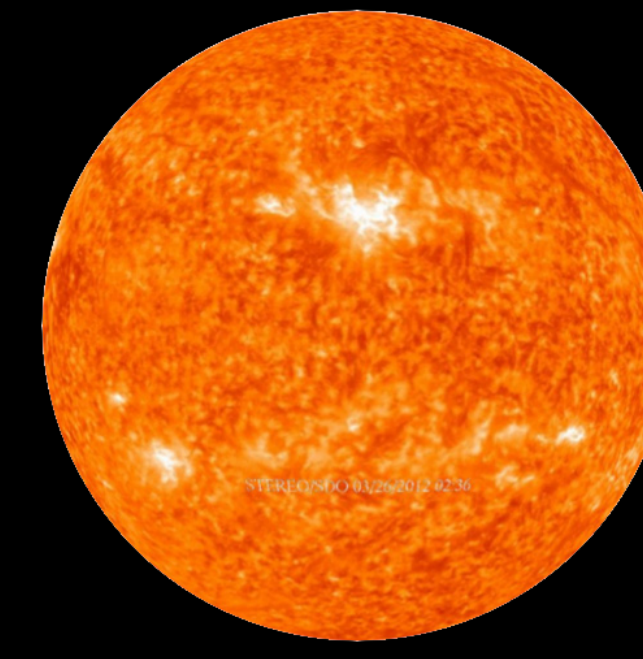


Figure 2: (a) Profiles for tunable parameters  $\alpha(r)$  and  $\beta(r)$  chosen in this study. (b) Strength associated to each GSH component of  $B_{st}^\mu$ .

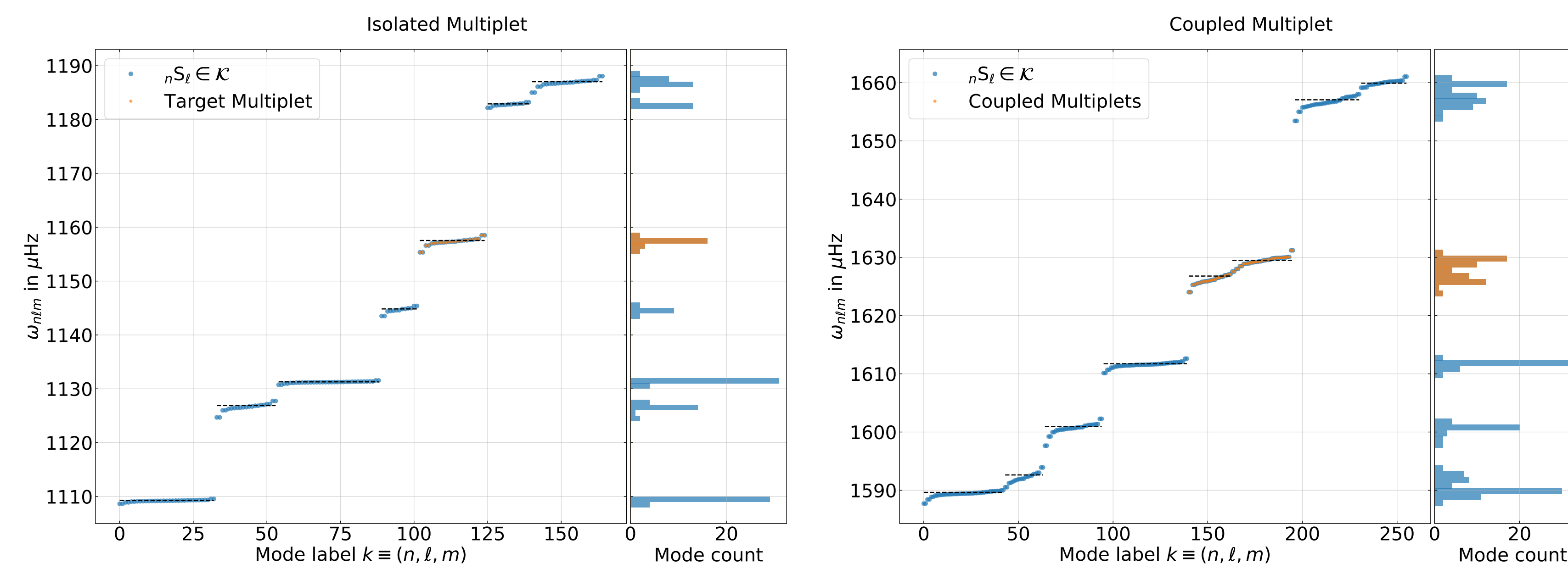
# How to find Sun's internal magnetic fields by observing the solar surface oscillation frequency?

1. Ideal MHD,
2. Normal-mode helioseismology,
3. Quasi-degenerate perturbation theory.



## Isolated multiplet vs. coupled multiplet

$$\sum_k \{ \Lambda_{k'k} - (\omega_{\text{ref}}^2 - \omega_k^2) \delta_{k'k} \} c_k = \sum_k \delta(\omega^2) \delta_{k'k} c_k \quad \text{where,} \quad \Lambda_{k'k} = \sum_{st} \sum_{\mu\nu} \int_0^{R_\odot} dr r^2 \mathcal{B}_{st}^{\mu\nu}(r) h_{st}^{\mu\nu}(r). \quad (5)$$



## Labelling multiplets: Isolated or coupled?

$$L_2^{QDPT} = \sqrt{\sum_m (\delta\omega_{n(m)}^Q)^2} \quad \text{for cross-coupling,} \quad L_2^{DPT} = \sqrt{\sum_m (\delta\omega_{n(m)}^D)^2} \quad \text{for self-coupling.} \quad (6)$$

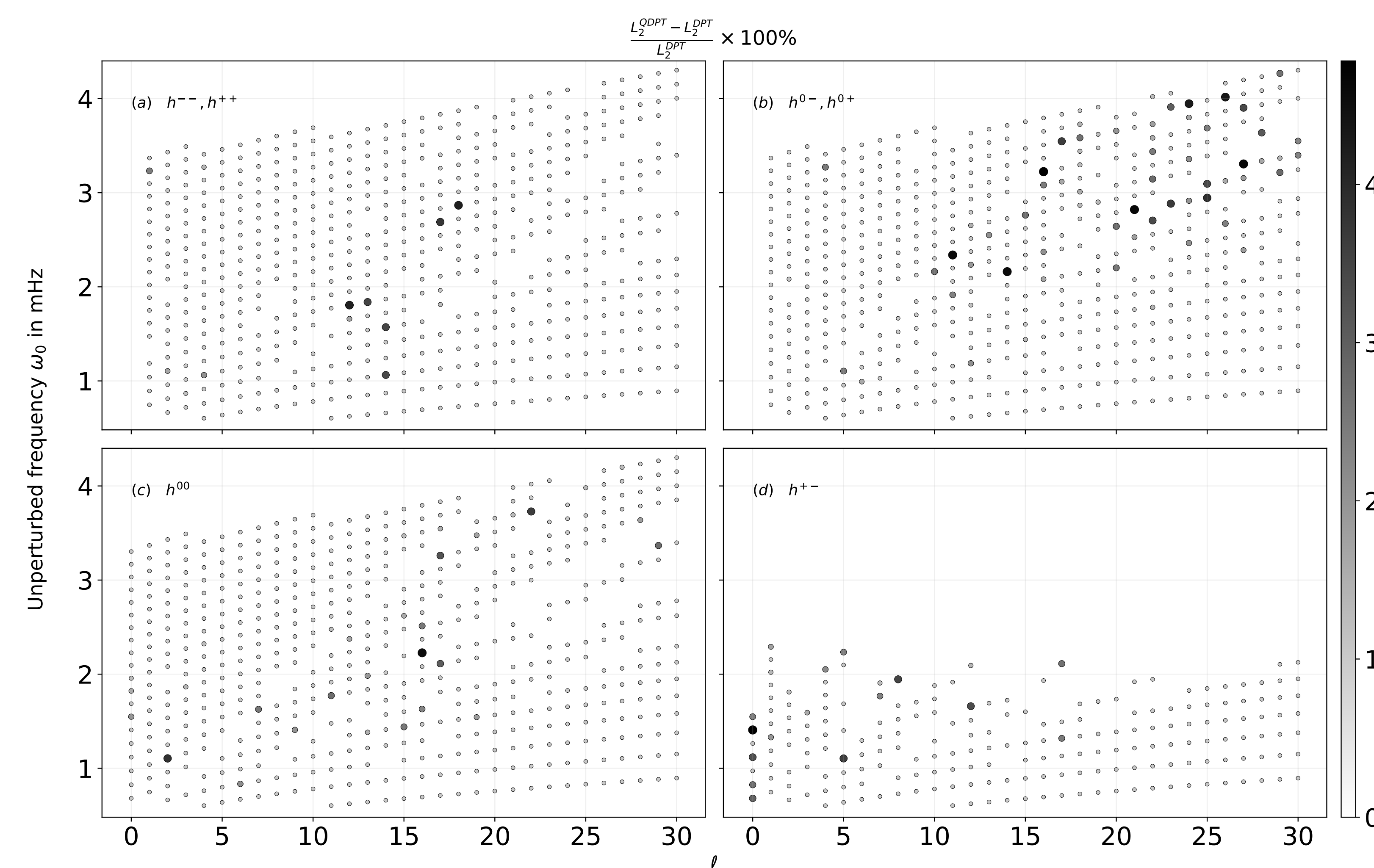


Figure 3: Darker and larger "o" represents multiplets where cross-coupling causes significant relative frequency offset with respect to self-coupling. We have used Lorentz-stress field with  $s = \{0, 1, 2, 3, 4, 5, 6\}$  including all  $l$  for a certain  $s$ . The strength of GSH components  $h_{st}^{\mu\nu} = h_0(r)$  where  $h_0(r)$  is the "total" field strength as shown in Figure 4.

## Inversion technique using $a$ -coefficients

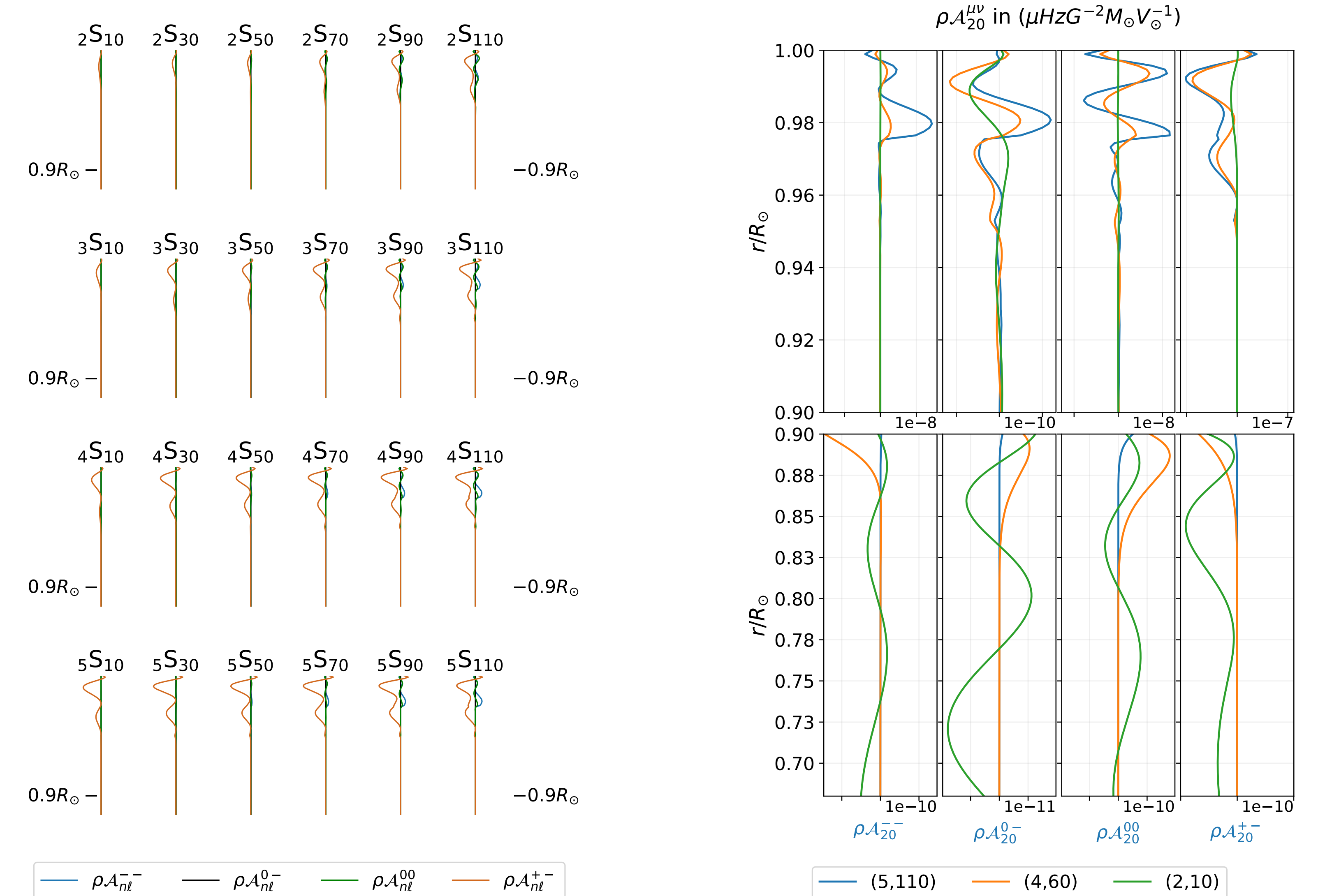
- Isolated-multiplet approximation,
- Axisymmetric perturbation  $\implies t = 0$ ,
- Extensively used for inversion of differential rotation.<sup>2</sup>

$$\begin{aligned} \delta\omega_{nl}^m &= \sum_{j=0}^{j_{\max}} a_j^{nl} \mathcal{P}_j^{(\ell)}(m), \\ a_s^{nl} &= \int_0^{R_\odot} dr r^2 \sum_{\mu, \nu} \mathcal{A}_s^{\mu\nu} h_{s0}^{\mu\nu}, \end{aligned}$$

The inverse problem  $\longrightarrow$

$$\text{where, } \mathcal{A}_s^{\mu\nu}(r) = \frac{\mathcal{K}_s^{\mu\nu}(r)}{2\omega_{nl}} \propto \frac{\mathcal{B}_{s0}^{\mu\nu}(r)}{2\omega_{nl}}.$$

## Self-coupling kernels for $a$ -coefficients



## Varying depth sensitivity of modes

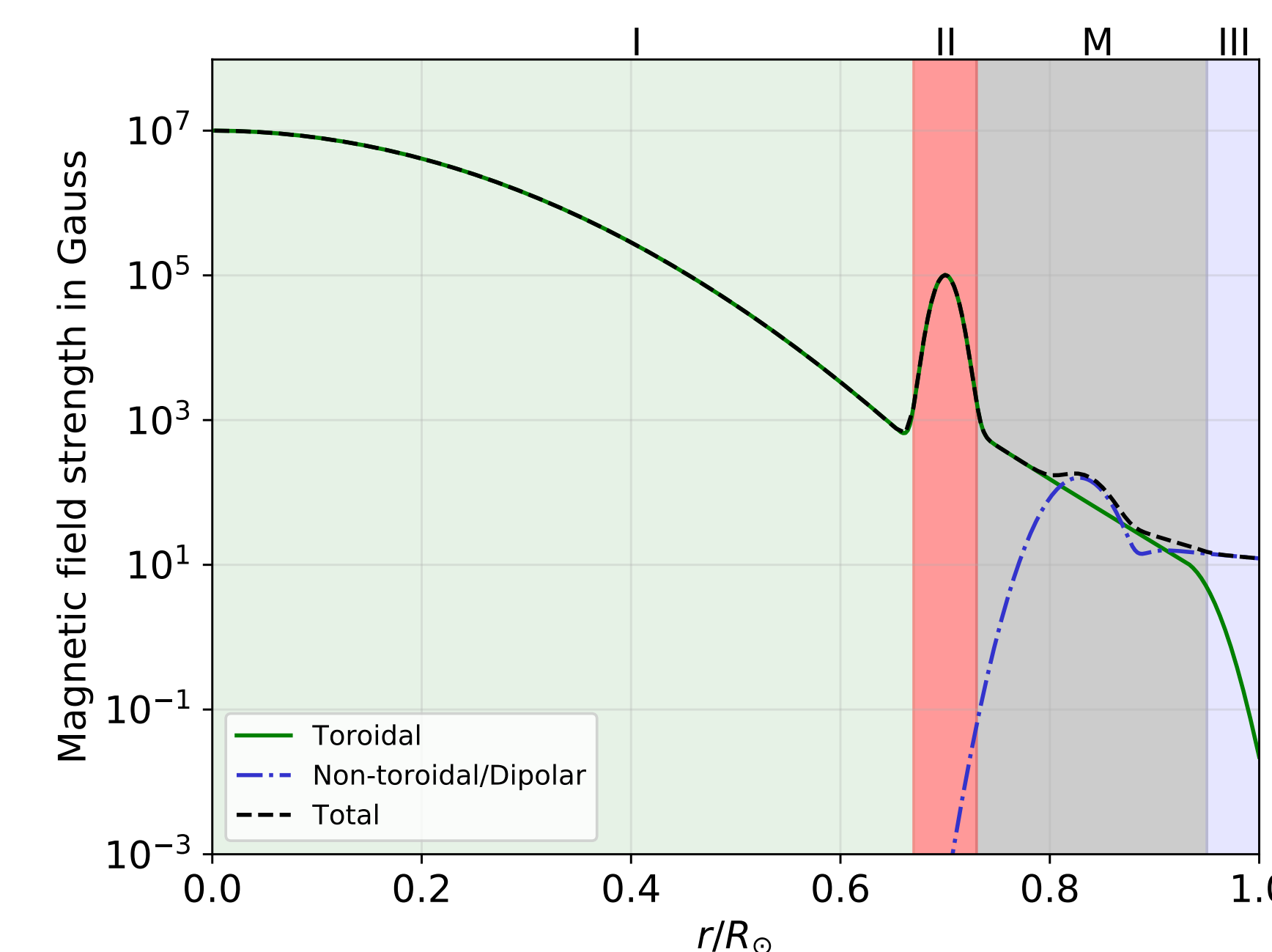


Figure 4: Magnetic field strength (Model M1 in Table 1) associated with three different regions with the following field configurations: (A) Purely toroidal for  $r < 0.7R_\odot$ , (B) Toroidal + spheroidal extending from  $r = 0.7R_\odot \leq r \leq 0.95R_\odot$  and (C) Purely dipolar for  $r > 0.95R_\odot$ .

	M1	M2	M3	M4	M5	M6	M7	M8
$B_I$	Low	Low	Low	Low	High	High	High	High
$B_{II}$	Low	Low	High	High	Low	Low	High	High
$B_{III}$	Low	High	Low	High	Low	High	Low	High

Table 1: Strength ratio High:Low = 10:1. M1 = Sun-like.

Modes	$2S_{10}$		$5S_{110}$	
$a$ -coefficients	$a_0$	$a_2$	$a_0$	$a_2$
M1	4.138	-0.501	2.399	0.628
M2	4.991	-0.167	239.986	62.863
M3	399.696	-62.360	2.399	0.628
M4	400.549	-62.026	239.986	62.863
M5	14.274	11.824	2.399	0.628
M6	15.127	12.158	239.986	62.863
M7	411.551	-50.349	2.399	0.628
M8	412.405	-50.015	239.986	62.863

Table 2: Mode-response in  $a$ -coefficients (nHz).

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$$\mathcal{B} = \frac{1}{2} \left\{ \nabla \boldsymbol{\xi}_k \cdot (\nabla \boldsymbol{\xi}_{k'}^*)^T + \nabla \boldsymbol{\xi}_{k'}^* \cdot (\nabla \boldsymbol{\xi}_k)^T \right\} + \frac{1}{2} \left\{ \nabla \boldsymbol{\xi}_{k'}^* \cdot \nabla \boldsymbol{\xi}_k + \nabla \boldsymbol{\xi}_k \cdot \nabla \boldsymbol{\xi}_{k'}^* \right\} + \frac{1}{2} \left\{ \boldsymbol{\xi}_{k'}^* \cdot \nabla \nabla \boldsymbol{\xi}_k + \boldsymbol{\xi}_k \cdot \nabla \nabla \boldsymbol{\xi}_{k'}^* \right\} - \frac{1}{2} \left\{ \boldsymbol{\xi}_k \nabla \nabla \cdot \boldsymbol{\xi}_{k'}^* + \boldsymbol{\xi}_{k'}^* \nabla \nabla \cdot \boldsymbol{\xi}_k \right\} - \frac{3}{2} \left\{ \nabla \boldsymbol{\xi}_k \nabla \cdot \boldsymbol{\xi}_{k'}^* + \nabla \boldsymbol{\xi}_{k'}^* \nabla \cdot \boldsymbol{\xi}_k \right\} + \nabla \nabla \cdot \boldsymbol{\xi}_{k'}^* \nabla \cdot \boldsymbol{\xi}_k$$