



23 **Abstract**

24 Microseismicity, induced by the sliding of a glacier over its bed, can be used to characterize  
25 frictional properties of the ice-bed interface, which are a key parameter controlling ice stream  
26 flow. We use naturally occurring seismicity to monitor spatiotemporally varying bed properties  
27 at Rutford Ice Stream, West Antarctica. We locate 230000 micro-earthquakes with local  
28 magnitudes from  $-2.0$  to  $-0.3$  using 90 days of recordings from a 35-station seismic network  
29 located  $\sim 40$  km upstream of the grounding line. Events exclusively occur near the ice-bed  
30 interface and indicate predominantly flow-parallel stick-slip. They mostly lie within a region of  
31 interpreted stiff till and along the likely stiffer part of mega-scale glacial landforms. Within these  
32 regions, micro-earthquakes occur in spatially ( $<100$  m radius) and temporally (mostly 1-5 days  
33 activity) restricted event-clusters (up to 4000 events), which exhibit an increase, followed by a  
34 decrease, in event magnitude with time. This may indicate event triggering once activity is  
35 initiated. Although ocean tides modulate the surface ice flow velocity, we observe little periodic  
36 variation in overall event frequency over time and conclude that water content, bed topography  
37 and stiffness are the major factors controlling microseismicity. Based on variable rupture  
38 mechanisms and spatiotemporal characteristics, we suggest the event-clusters relate to three  
39 end-member types of bed deformation: (1) continuous creation and seismogenic destruction of  
40 small-scale bed-roughness, (2) ploughed clasts and (3) flow-oblique deformation during  
41 landform-formation or along bedrock outcrops. This indicates that multiple processes,  
42 simultaneously active during glacial sliding, can accommodate stick-slip behaviour and that the  
43 bed continuously reorganizes.

44

45 **Keywords**

46 Microseismicity, icequake, basal sliding, ice stream, glacier bed, West Antarctica

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## 50 **1 Introduction**

51 The potential collapse of the West Antarctic Ice Sheet remains the largest source of uncertainty  
52 in projections of future sea level rise (Feldmann & Levermann, 2015; Robel et al., 2019). This  
53 uncertainty is partly a result of incomplete ice sheet process models (Ritz et al., 2015; Tsai et al.,  
54 2015; Zoet & Iverson, 2020). Mass transfer from the ice sheet interior to the oceans is dominated  
55 by ice stream flow (Rignot et al., 2011), which, in turn, is governed by deformation within the ice,  
56 and friction and deformation at the bed, i.e. the contact between ice and underlying sediments  
57 or bedrock. Furthermore, tidally-induced modulations influence the flow dynamics of some ice  
58 streams, likely by introducing pressure modulation at the bed (Anandakrishnan et al., 2003;  
59 Gudmundsson, 2006). Poorly constrained processes and conditions at ice stream beds therefore  
60 contribute to the uncertainty in sea-level rise projections. Better understanding of the dynamic  
61 response of ice streams to a warming climate and oceans therefore requires improved models of  
62 these basal processes and the spatial variation in properties. Here we focus on the understanding  
63 of basal sliding and deformation characteristics through the analysis of naturally occurring micro-  
64 earthquakes at the ice-bed interface. These events are used to examine the nature of basal slip,  
65 tidal influences, and spatial and temporal variations.

66 The beds of ice streams consist of bedrock and sediment, often known as till. Till stiffness is  
67 variable and depends on the dynamic conditions and material properties. Ice flow at the bed is  
68 then facilitated by a combination of slip over a hard bed and by slip and deformation within a  
69 soft bed. Fluids further modulate basal ice stream flow. Where bedrock is exposed or subglacial  
70 till has relatively low permeability and is of low porosity, subglacial water may form a film at the  
71 ice-bed interface or accumulate in channels and pools and act to lubricate flow (Benn & Evens,  
72 2014; Piotrowski et al., 2004). Alternatively, if the bed is composed of more permeable, high  
73 porosity till, subglacial water may penetrate, resulting in a deformable bed. Ice flow over a low  
74 permeability, low porosity bed is likely to be dominated by sliding, whereas deformation is more  
75 pronounced in the presence of more permeable, high porosity till (Blankenship et al., 1986;  
76 Reinardy et al., 2011; Stokes, 2018). In addition, drag at the glacial bed can lead to the formation  
77 of subglacial landforms, which in turn, modulate ice stream flow (Lipovsky et al., 2019; Stokes,  
78 2018). Basal resistance may be increased at localized “sticky-spots” (Barcheck et al., 2020; U. H.

79 Fischer et al., 1999; Robert W Jacobel et al., 2009; Rösli et al., 2016; E. C. Smith et al., 2015),  
80 where deformation occurs through microseismicity, termed icequakes, which exhibit stick-slip  
81 behaviour. Understanding the scale and dynamics of such bed perturbations is crucial when  
82 building realistic numerical models of ice flow dynamics.

83 Insights into basal conditions can be gained through the study of icequakes if their hypocentres  
84 lie near the ice-bed interface (Rösli et al., 2016; E. C. Smith et al., 2015). Basal icequakes have  
85 been detected widely at glaciers in Antarctica and elsewhere (Anandakrishnan & Bentley, 1993;  
86 Blankenship et al., 1987; Danesi et al., 2007; Helmstetter et al., 2015; Rösli et al., 2016; E. C.  
87 Smith et al., 2015; Walter et al., 2008) and several reasons have been suggested for their  
88 occurrence. These include localized bed heterogeneities, water-pressure fluctuations or water-  
89 induced crack opening (U. H. Fischer et al., 1999; E. C. Smith et al., 2015; Walter et al., 2013).  
90 There is also the possibility that a combination of these mechanisms may be at play  
91 simultaneously. However, many icequake studies suffer from short deployment times or  
92 heterogeneous network geometry. This makes it difficult to isolate the effect of spatiotemporally  
93 varying basal properties on icequake occurrence. Here, we use 90 days of passive seismic data to  
94 detect basal microseismicity at Rutford Ice Stream, West Antarctica (Fig. 1). The data were  
95 recorded by 35 seismometers with a nominal spacing of 1 km over a 10 x 10 km grid deployed  
96 ~40 km upstream of the grounding line (Fig. 1b). Within this area, seismic surveys have shown  
97 that the bed consists of till, with varying water content, consolidation state and degree of  
98 deformation (King et al., 2016; A. M. Smith, 1997; A. M. Smith & Murray, 2009). Furthermore, it  
99 has been shown that surface ice flow is heavily modulated by a biweekly tidal signal  
100 (Gudmundsson, 2006; Minchew et al., 2017). Thus, our seismic network covers a region of diverse  
101 bed topography and rheology and captures several tidal cycles. This allows us to investigate basal  
102 slip in an ice stream with unprecedented spatiotemporal resolution. Here we locate icequakes,  
103 but also determine their source characteristics including event magnitude, source mechanisms  
104 and spatiotemporal clustering. Based on these results we can better constrain the mechanisms  
105 for seismicity and how the icequakes reveal the basal properties of the RIS.

## 107 2 Survey location

108 Rutford Ice Stream (RIS) (Fig. 1a) drains  $\sim 49,000 \text{ km}^2$  of the West Antarctic Ice Sheet into the  
109 Ronne Ice Shelf (Doake et al., 2013). To the west and east, RIS is bound by the Ellsworth  
110 Mountains and the Fletcher Promontory, respectively. At our study site, the ice flow velocity is  
111  $\sim 375 \text{ m a}^{-1}$  (Adalgeirsdóttir et al., 2008) and the ice stream is around 2.2 km thick and grounded  
112 at 1.6-1.8 km below sea level (King et al., 2009). RIS occupies a deep trough with a “w-shaped”  
113 cross-section (King et al., 2016). The centre of our network is deployed on the ice stream surface  
114 above a basal central high ( $\sim 1.8 \text{ km}$  below sea level); the bed topography descends to the SW  
115 and NE into troughs on either side (Fig. 1b). Slightly downstream ( $\sim 2 \text{ km}$ ) of our survey location,  
116 the bed topography is dominated by a prominent knoll, which also creates a surface expression.  
117 By contrast, the ice surface is flat within our seismic network. Nevertheless, the bed below the  
118 seismic network features a diverse morphology. This morphology can be emphasized through the  
119 ‘residual elevation’ (Fig. 1c), calculated by King et al. (2016) by subtracting a filtered version of  
120 the bed DEM (2 km x 2 km smoothing filter) from the original data. In the upstream part of our  
121 seismic network, the short-wavelength topography is formed of several elongated mega-scale  
122 glacial landforms (MSGs), of which the central one is the most prominent. The topography in  
123 the downstream part of our network is more irregular and features multiple hummocks of non-  
124 uniform shape, orientation and size (King et al. (2016); Fig. 1c).

125 Based on radar and seismic surveys, it has been shown that the bed is composed of a basal till  
126 layer with spatially varying properties, resulting in different basal deformation regimes (King et  
127 al., 2009; Schlegel et al., 2021; A. M. Smith, 1997; A. M. Smith & Murray, 2009). Upstream, the  
128 MSGs are likely composed of water-saturated, deformable till. Seismic surveys over these  
129 landforms, repeated over timescales of a few years, reveal sediment transport and bedform  
130 erosion of up to  $1 \text{ m a}^{-1}$  at the downstream termination of the MSGs (A. M. Smith et al., 2007;  
131 A. M. Smith & Murray, 2009). The deformable till layer likely overlays a stiffer and more  
132 consolidated unit that outcrops locally and predominantly northwest of the central high (Schlegel  
133 et al., 2021; A. M. Smith & Murray, 2009). Downstream of the MSGs, the till layer is generally  
134 stiffer and likely stiffest southeast of the central high where very consolidated till or possibly  
135 sedimentary rock are proposed to exist (Schlegel et al., 2021). This first-order discrimination of

136 different bed domains was supported by drilling results (A. M. Smith (2020); see Fig. 1c for drill  
137 locations). In the regions of stiffer till, basal sliding rather than bed deformation predominantly  
138 accommodates basal motion at the ice-bed interface. The two domains of dominantly bed  
139 deformation and basal sliding can be discriminated from each other based on their characteristic  
140 polarity and intensity reflection values from seismic surveys (A. M. Smith, 1997). Together with  
141 the different geomorphological appearance (MSGs vs. hummocks), this allows for the definition  
142 of a “bed character boundary” separating the two domains (King et al. (2016); G. Boulton - pers.  
143 communication in Smith et al., (2015)). This boundary is highlighted in Figures 1b/c and all  
144 subsequent map view figures. In the following, we will refer to the domain upstream of this  
145 boundary as a ‘soft sediment’ bed and to the domain downstream of the boundary as a ‘stiff  
146 sediment’ bed. This is based on the assumption that the bed character variability across the  
147 boundary mainly depends on porosity because the bed composition may be similar.

148 Our study site has been the focus of previous passive seismic surveys. In a pioneer study, A. M.  
149 Smith et al. (2006) deployed 10 geophones in a circular array with 3 km inter-station spacing for  
150 a 11-day observation period. The recordings from this network were not sensitive enough to  
151 allow for precise event locations but showed six times more basal micro-earthquakes originated  
152 from regions of stiff sediments. E. C. Smith et al. (2015) improved this understanding using  
153 another 10-station network, deployed in two sub-arrays with 1 km station spacing over a period  
154 of 35 days. Due to higher sensitivity instruments and different network configuration 3000 basal  
155 icequakes were precisely located, mostly in areas of stiff sediment bed. This confirmed findings  
156 from the earlier study and suggested that basal ice flow mechanics depend on basal conditions.  
157 Furthermore, they showed that seismicity generally featured low-angle faulting mechanisms,  
158 which indicates basal sliding in the flow direction as major source triggering seismicity.

159 In addition to icequake occurrence, the basal hydraulic system of RIS varies dependent on bed  
160 rheology (Murray et al., 2008). Based on radar and seismic surveys, it was shown that water  
161 channels or bodies exist in the region of soft sediments over a long distance along the landforms  
162 (at least 1 km long and 200 m wide; King et al. (2004), Murray et al. (2008) and Schlegel et al.  
163 (2021)). Furthermore, water may be present on top of MSGL ridges (King et al., 2009; Murray et

164 al., 2008; Schlegel et al., 2021). Within the stiffer sediment region, free water appears in isolated  
165 spots and pools (Murray et al., 2008; Schlegel et al., 2021).

166 Lastly, an ice stream flow velocity modulation, related to the spring-neap tidal cycle, has been  
167 measured at RIS (Adalgeirsdóttir et al., 2008; Gudmundsson, 2006; Murray et al., 2007). At the  
168 grounding line, the biweekly modulation of the surface ice stream flow velocity is up to 20%. This  
169 signal propagates, with decreasing amplitude, up to 60 *km* upstream. A linked hydrological and  
170 numerical modelling study suggests that only a combination of stress transmission through the  
171 ice and changes of basal water pressure can explain such modulations in surface ice flow velocity  
172 (Rosier et al., 2015). In addition, the model assumes a highly effective basal drainage system, low  
173 effective pressure and a nonlinear sliding law.

174

### 175 **3 Seismic network and data processing**

#### 176 **3.1 Network description**

177 We use three months (mid-November 2018 to mid-February 2019) of continuous passive seismic  
178 recordings to generate a microseismic event catalogue. This dataset was collected as part of the  
179 BEAMISH project (A. M. Smith et al., 2020) during the 2018/19 field season. The seismic network  
180 broadly forms a rectangle with  $\sim 1$  *km* station spacing. It overlays both bed-domains (Fig. 1c). The  
181 geometry of the network was modified twice during the observation period. Initially, 19 stations  
182 in the northern and central part of the network were deployed in November 2018. The network  
183 was then extended with 14 stations to the east and north in December. In January 2019, two  
184 further stations were added and three stations from the westernmost corner of the array were  
185 redeployed in the central part of the network. In total 38 sites were occupied, with 19 to 35  
186 stations recording concurrently. During a strong storm in December, 15 of these stations were  
187 inactive for up to five days (see Fig. S1 for details).

188 Each station consisted of a Reftek RT-130 data logger with a 4.5 *Hz* 3-component geophone  
189 (either GS11-3D or L28-3D), which was buried to  $\sim 1$  *m* depth (see Fig. S1 for details of the

190 network). The sampling frequency was 1000 Hz. Energy supply was ensured through a solar panel  
191 and battery. Timing was obtained from an attached GPS antenna.

### 192 **3.2 Microseismic event catalogue and spatial clustering**

193 Thousands of microseismic events were recorded during the deployment period. These events  
194 tend to cluster closely spaced in time, are characterized by an impulsive P-wave onset, and two  
195 prominent S-wave arrivals (Fig. 2a). The detection of two independent shear waves is an  
196 indication of the anisotropic nature of the ice comprising the RIS (E. C. Smith et al., 2017). Typical  
197 frequencies for P-waves are between 10 and 200 Hz. S-wave frequency is predominantly between  
198 30 and 100 Hz. We use the QuakeMigrate software (Hudson et al., 2019; J. D. Smith et al., 2020)  
199 to detect and locate events from the continuous seismic records. Instead of a classic station-by-  
200 station trigger, QuakeMigrate implements a detection scheme based on the coherency of seismic  
201 phase arrivals recorded at all seismic stations. This makes it an ideal detection tool if many,  
202 temporally overlapping, small earthquakes occur. Based on the P- and S-wave onset times and  
203 uncertainties derived in QuakeMigrate, the initial locations are refined using NonLinLoc (Lomax  
204 et al., 2000), which yields a more realistic location error estimate due to a probabilistic location  
205 approach and a weighting scheme for pick uncertainties. For QuakeMigrate, we use a  
206 homogeneous velocity model ( $v_p=3.841 \text{ km s}^{-1}$ ;  $v_s=1.970 \text{ km s}^{-1}$ ). The P-wave velocity ( $v_p$ )  
207 corresponds to the ice velocity at RIS obtained from an earlier seismic survey (A. M. Smith, 1997).  
208 The S-wave velocity ( $v_s$ ) is derived from  $v_p$  and the  $v_p/v_s$ -ratio of 1.95 taken from a Wadati  
209 diagram using one day of data (~36000 P- and S-picks; Fig. S2). In NonLinLoc, we further refine  
210 the velocity model and included a uniformly 100 m thick layer to represent firn ( $v_p=2.839 \text{ km s}^{-1}$ ;  
211  $v_s=1.456 \text{ km s}^{-1}$ ; A. M. Smith (1997)) below the seismic stations and above the solid ice.  
212 Uncertainties in the velocity model (according to A. M. Smith (1997) less than  $\pm 0.015 \text{ km s}^{-1}$ ) are  
213 assessed through relocating sample events while considering travel time dependent errors (see  
214 Section S1 for details). We do not include a velocity discontinuity below the ice, which would  
215 represent the glacial bed, as such a layer is likely to introduce artificial event-clustering (E. C.  
216 Smith et al., 2015). Theoretical calculations based on till and bed properties expected at RIS (A.  
217 M. Smith, 1997) showed that the direct upgoing P-phase likely forms the first arrival for epicentral  
218 distances of up to 10 km. Less than 0.01% of our P- and S-picks have greater epicentral distances.

219 Thus, including only the ice and firn layer in the velocity model does not lead to misidentified  
220 phases. Furthermore, we do not include the effect of anisotropy in ray tracing but tune  
221 QuakeMigrate through the ‘detection threshold’-parameter to pick the first possible S-wave  
222 onset. We assess the effect of anisotropy by using a sample event, which is located using the first  
223 and second peak in the S-waveform, respectively (Figs. S3/S4). The discrepancy between the two  
224 resultant hypocentres is most significant in the vertical direction and can be neglected in  
225 horizontal directions, which we consider when discussing the results.

226 We apply quality restrictions to the automatically detected picks and events to ensure that no  
227 false picks and events are included in the final event catalogue. We accept only events with a  
228 total root-mean-square (RMS) value of travel time residual of 0.02 s at the maximum likelihood  
229 hypocentral location, a maximum azimuthal gap of 280°, maximum 10% of picks with a P/S travel  
230 time residual (observed subtracted by predicted arrival time) larger than 0.02 /0.2 s, and at least  
231 three P-picks and two S-picks. These selection criteria are obtained from the visual inspection of  
232 data sub-sets and reduce 295785 potential events initially detected from QuakeMigrate to  
233 227029 events. Further details on location methodology and implementation to our dataset can  
234 be found in the supplementary material (S1/2 and Table S1).

235 We account for the movement of the seismic stations relative to the bed due to ice flow by  
236 shifting each event location in the final catalogue downstream. RIS moved ~94 m downstream  
237 during the 90-day survey period, whereas our stations are specified at fixed locations during  
238 event location, clearly evidencing the necessity for such a shift. We perform this shift by  
239 calculating the stations’ locations at the time of each individual event relative to the start of the  
240 deployment, using their GPS locations, and apply this lateral shift to that event hypocentre. This  
241 is repeated for all events in the catalogue to compensate for ice flow.

242 Finally, we group the events into clusters as glacial microseismicity is known to occur in bursts of  
243 temporal and spatially focused activity (E. C. Smith et al. (2015)). We apply the DBSCAN (‘Density-  
244 Based Spatial Clustering of Applications with Noise’) cluster algorithms (Pedregosa et al., 2011)  
245 to search for spatial patterns in our microseismic event catalogue. This SciKit python module is  
246 designed to find core samples of high spatial density and to extend clusters around them. Only

247 events with magnitudes larger than the magnitude of completeness (including a 0.2 magnitude  
248 units buffer to account for uncertainty), which we determine as the maximum in the logarithmic  
249 magnitude plot of Fig. 2b, are included in the cluster analysis. This event cut-off is implemented  
250 to avoid a bias in the output clusters due to spatially differing completeness magnitudes (see  
251 details on parameterization in Section S3).

252

### 253 **3.3 Event magnitudes**

254 Magnitudes are calculated using a two-step approach. First, we determine the moment  
255 magnitude ( $M_w$ ; Hanks & Kanamori (1979)) for a subset of our data (1<sup>st</sup> of January 2019, 1520  
256 events) from the far-field displacement of the P-wave (Shearer (2009); implementation of  
257 Hudson et al. (2020)) and assuming density ( $917 \text{ kg m}^{-3}$ ) and seismic velocity ( $3.841 \text{ km s}^{-1}$ ) at the  
258 source (Maurel et al., 2015; A. M. Smith, 1997). We then calibrated a local magnitude scale (ML),  
259 obtained from the maximum amplitudes in the waveforms, to the  $M_w$  scale (see processing  
260 windows in Fig. 2a and processing details in supplementary material S4). We choose this two-  
261 step approach as the  $M_w$  calculation is most accurately conducted only if the focal mechanism is  
262 known and if a Brune model (Brune, 1970) can be fit to the displacement spectrum, whereas ML  
263 can be calculated for all events in our catalogue.

264 The derived local magnitude scale is based on Smith et al. (2015), whose local magnitude scale  
265 for RIS is adapted from the well-established but empirically derived Richter scale (Richter, 1935)  
266 and follows the equation:

$$267 \quad ML = \log_{10}(A) + m \times d_{epi} - t \quad (1)$$

268 where  $A$  is the maximum amplitude of either of the two horizontal components (in instrument  
269 counts; all instruments were corrected to a consistent 'counts' scale). The distance term  $m$   
270 accounts for the decay of amplitudes with increasing epicentral distance ( $d_{epi}$ ) and  $t$  is a scaling  
271 parameter that bridges the offset between  $M_w$  and ML. We derive ML or  $M_w$ , for all stations of  
272 an event separately. The final magnitude of an event is then calculated as the median of all single-  
273 station measurements. The uncertainties are derived as the mean absolute deviation (MAD) of

274 the single-station ML or  $M_w$ , values from the median. Further processing steps for ML and  $M_w$   
275 are detailed in Section S4.

276 We obtain a 1:1 fit (Pearson correlation coefficient of 0.96, with 1 being a linear fit and 0 being  
277 no fit) between  $M_w$  and ML for the dataset used for scaling but also a high correlation (Pearson  
278 coefficient of 0.88) when considering additional events with rupture mechanism that were not  
279 used when initially deriving the  $M_w$ -ML scaling (Fig. S5). This confirms that a linear  $M_w$ -ML scaling  
280 is adequate to fit our dataset (Butcher et al., 2020) and that the relatively simple approach of  
281 calculating ML is sufficient. This is likely because the total range of observed magnitudes spans  
282 only approximately 1.7 magnitude units (Fig. 2b) and because picks from many different azimuths  
283 are available for each event.

284

### 285 **3.4 Event focal mechanisms and stress inversion**

286 We determine fault plane solutions from first motion polarities and P to S amplitude ratios using  
287 the HASH software (Hardebeck & Shearer (2002), Hardebeck & Shearer (2003); implementation  
288 following Bloch et al. (2018)). As the P-wave onset of RIS microseismicity is impulsive and the  
289 signal-to-noise ratio is high (Figs. 2a, 3), an automated gradient-based polarity picker is  
290 implemented (see Section S5 for details on processing approach). Take-off angles are derived  
291 from the same velocity model used for the NonLinLoc relocations (a two-layer model of firn and  
292 ice). To account for errors in the polarity picks, 15% outliers (non-matching polarities in the final  
293 solution) are allowed during the inversion. We further perform multiple inversions while  
294 perturbing take-off angles (standard deviation of  $5^\circ$ ) to allow for uncertainties in the velocity  
295 model and the event location. The final set of good solutions is derived based on quality criteria,  
296 which are the stability of solution upon variations of input, the azimuthal gap of the final set of  
297 stations used (should be smaller than  $180^\circ$ ) and the final number of input picks (should be larger  
298 than seven). Due to the clear waveforms, we derive stable solutions for events in the centre of  
299 the network domain (Fig. 3a; 52% of all events with backazimuthal gap smaller than  $90^\circ$  have a  
300 rupture mechanism solution), but also for events at its extremities (Figs. 3b, c; 28% of all events  
301 with backazimuthal gap between  $90$  and  $180^\circ$  have a solution).

302 In addition to single-event solutions, we calculate cluster-wise stress tensors using all individual  
303 focal mechanisms of a cluster as input data. The stress inversion is conducted using the software  
304 slick (Michael, 1987). Slick performs a linear inversion to minimize the number of rotations  
305 around an arbitrary axis necessary to rotate the input focal mechanisms to fit a uniform stress  
306 tensor. We assess the quality of the cluster-wise solutions via bootstrap tests. In these tests, the  
307 data are resampled 100 times while the fault and auxiliary plane are exchanged for 10% of all  
308 input mechanisms. The spread of the results obtained from bootstrap inversions provides a  
309 measure of inversion robustness. We only use clusters for which more than seven mechanisms  
310 are available.

311

## 312 **4 Results**

### 313 **4.1 Spatial icequake distribution and magnitudes**

314 A map and profiles of all icequake locations are presented in Figures 4 and 5. Magnitudes range  
315 from  $-2.0$  to  $-0.3$  (average  $-1.3$ ) with an uncertainty range of 0 to 0.4. A logarithmic plot of event  
316 number against magnitude highlights two different magnitude populations (Fig. 2b). These  
317 populations can be separated based on different decay slopes (b-values). For larger events ( $ML >$   
318  $-0.6$ ) a b-value of 10.9 is measured. This is three times larger than the b-value of smaller events.  
319 These two magnitude populations are highlighted with different colours (small= blue; large=red)  
320 in Figures 4a and 5, aiming to convey an impression on the distribution of largest magnitude  
321 events in the study domain.

322 Events are generally well constrained with an average horizontal standard error (as defined by  
323 Lee & Lehr (1972)) derived from the pick uncertainties of 27 and 26 *m* in east-west and north-  
324 south, respectively. The mean vertical standard error is 48 *m*. In addition to these formal errors,  
325 we expect a perturbation of the hypocentres of  $\sim 5$  *m* due to errors in the velocity model when  
326 considering the uncertainty given by A. E. Smith (1997). In addition, a more severe hypocentre  
327 perturbation arises due to seismic anisotropy. This may introduce an error of  $\sim 10$ -20 *m*  
328 horizontally and up to  $\sim 100$  *m* vertically. Lastly, laterally variable errors in the velocity model may

329 be introduced as the firn-ice transition likely forms a gradual, rather than a sharp, velocity  
330 increase (for more details on uncertainty derivation see Sections S1 and S2 and Fig. S6).

331 All events cluster near the ice-bed interface, the depth of which is derived from radar data (King  
332 et al., 2016). On average, the events locate 16 *m* below the interface, which is within the average  
333 vertical location uncertainty derived here and the absolute location error of 10-20 *m* given by  
334 (King et al., 2016). The difference may result from velocity variations within the ice, which are  
335 not captured with the two-layer model used here or from uncertainties in the absolute reference  
336 frame used by King et al. (2016), or both.

337 Despite their common depth location, the events show a discontinuous spatial distribution across  
338 the study region. Most events, including the largest in our dataset, locate either at the boundary  
339 between the soft and stiff sediment regions or further downstream in the region of stiff  
340 sediment. Within the stiff sediments, there appears to be no correlation between event density  
341 and the location of hummocks identified from radar data (King et al. (2016); see geographic labels  
342 in Figs. 1b and 4b for orientation). However, more events occur southwest of the central high  
343 than northeast of it. In regions of very high seismic activity, events partly appear to arrange in  
344 distinct regions ( $\sim 300 - 500$  *m* radius), which are seismically active at their rims and aseismic in  
345 their centres (e.g., Fig. 6a). This configuration is robust, even when considering the event  
346 hypocentre uncertainties. Seismicity across the transition from soft to stiffer sediments  
347 correlates with a step-up in bed elevation across the boundary. If this step is large (e.g. 20 *m*  
348 residual elevation increase in Fig. 5b), seismicity is most pronounced and large magnitude events  
349 occur, whereas negligible seismicity is associated with a transition without a change in residual  
350 bed elevation (e.g., Figs. 5a, c). Events upstream of the bed character boundary tend to occur in  
351 the troughs separating MSGLs, while seismicity at the MSGL crests is absent (Figs. 5d-f).

352

#### 353 **4.2 Event cluster characteristics and rupture mechanisms**

354 In addition to this large-scale icequake distribution, we observe a small-scale structure in the  
355 spatial distribution of most icequakes. Icequakes rarely occur as single events in space and time.  
356 Instead, seismicity is focused on spatially isolated spots of less than 100 *m* radius (highlighted in

357 Fig. 6a., zoom in of these spots in Fig. 6b), which produce many icequakes over a short timescale.  
358 We use DBSCAN to isolate these spots of focused activity, finding 828 spatial clusters with eight  
359 or more events. These clusters include 188174 events with magnitudes larger than  $-1.5$ , which  
360 means that 93% of all events with magnitudes larger  $-1.5$  are clustered. In the following  
361 discussion, the term ‘cluster’ will be used to refer to discrete, spatially restricted, sites of icequake  
362 activity. By contrast, a ‘temporal sub-cluster’ refers to a temporally limited period of high seismic  
363 activity at the cluster location. Within temporal sub-clusters, inter-event times are in the minute  
364 range, whereas the time of quiescence between two temporal sub-clusters is on average 3.7 days  
365 (see also Section S3 and Figs. S7 & S8 for more detailed cluster characteristics).

366 Most clusters exhibit a common behaviour regarding their rupture mechanisms and regarding  
367 their magnitude evolution with time:

- 368 ○ Events within one cluster feature highly similar rupture mechanisms (example in Figs. 6b,  
369 c), resulting in well constrained cluster-averaged stress tensors (Fig. 6d). We obtain stress  
370 tensors for 428 clusters, which comprise in total 70023 individual mechanisms. The  
371 average spread value in these clusters is  $4.6^\circ$  (min./max.:  $1.7/17.9^\circ$ ). The spread is a  
372 measure of how well individual mechanisms match the resulting stress tensor. This small  
373 spread value indicates highly similar focal mechanisms within each cluster.
- 374 ○ We observe a modulation of event magnitude within the clusters. Most ML-activity-time  
375 plots show a short-term increase and decrease of event magnitude with time (Fig. 7). On  
376 average, these activity cycles last from two to six hours (mean  $\sim 3.5$  h) and several of these  
377 activity cycles may occur in succession (e.g. Fig. 7a). This relation is still valid when  
378 considering the uncertainty in magnitude (Fig. S9). We observe these magnitude patterns  
379 for all clusters with a magnitude range larger than  $\sim 0.4$  (Fig. S10).

380 Despite these common characteristics, the clusters exhibit different behaviour in terms of their  
381 stress tensor-orientation relative to ice flow (Fig. 8a) and in terms of their spatiotemporal  
382 occurrence (Fig. 8b):

- 383 ○ We observe two dominant orientations of cluster-averaged stress tensors, which can be  
384 discriminated from each other based on their P-axes orientation. As the dip of all stress

385 tensors is sub-horizontal, indicating sub-horizontal sliding, the P-axes orientation can  
386 serve as a measure of the slip-direction associated to an icequake cluster. The mean P-  
387 axes azimuth of all stress inversions is  $144 \pm 12^\circ$ . This is comparable to the surface ice flow  
388 direction (azimuth of  $148^\circ$ ) measured with GPS, which suggests flow-parallel sliding at the  
389 base of the ice stream. This agrees with previous source mechanism observations at RIS  
390 (Hudson et al., 2020; E. C. Smith et al., 2015). Here, the P-axes describe a gentle rotation  
391 ( $\pm 11^\circ$ ) towards the ice stream margin on either side of the central high along with this  
392 large-scale trend. In addition, we observe a larger rotation ( $\pm 36^\circ$ ) relative to flow for 5%  
393 (23 clusters) of all mechanisms (Fig. 8a). These mechanisms primarily occur across the bed  
394 character boundary and indicate sliding along the base but at an oblique angle relative to  
395 ice flow.

396 ○ Clusters show three distinct types of spatiotemporal behaviour. Most clusters (81%) are  
397 active only once for few days (typically  $< 5$  days) while only a smaller percentage (19%) is  
398 active multiple times for few days. These repeatedly active clusters can be grouped into  
399 either ‘spatially stable’ clusters (9%), which always occur at the same geographical  
400 position, albeit the ice moves above them, or in clusters where icequake hypocentres  
401 migrate downstream with ice stream flow velocity (10%; Fig. 8b). The occurrence of this  
402 different spatiotemporal behaviour is largely independent of their location with respect  
403 to the bed character boundary, the number of events in a cluster, or cluster duration (Figs.  
404 8c/d). At the same time there is no correlation between the number of events and  
405 duration of activity (Fig. S7).

406 Lastly, we note that the clusters appear to range in shapes and sizes in map view (e.g. circular  
407 or elongated). However, we do not consider these variations here. Determining the exact  
408 dimension and shape of these features is at the edge of the resolution capacity of this  
409 icequake catalogue. If double-difference relocation methods were used, the single clusters  
410 might collapse to even more concentrated features.

411

412

### 413 4.3 Temporal evolution of icequake activity

414 Despite these pronounced spatial variations, the entire microseismic dataset shows little overall  
415 systematic temporal variation in activity, nor a strong correlation with daily or biweekly  
416 periodicities in the tidal signal at the grounding line (Fig. 9). Instead, we observe the total number  
417 of detected events and the cluster onset times to be dependent on the weather conditions at RIS  
418 (Figs. 9a-c; e). During periods of strong wind, noise levels are higher and therefore fewer events  
419 are detected. However, Figure 9 shows that approximately two months (January/February 2019)  
420 of our data were acquired during stable weather conditions and with a consistent network  
421 geometry. Although the seismic network had been active during scientific drilling in the same  
422 area (A. M. Smith et al., 2020), we do not observed a notable spatial or temporal correlation of  
423 icequakes in our catalogue and the periods of drilling (5-8<sup>th</sup> January, 18-22<sup>th</sup> January, 6-11<sup>th</sup>  
424 February; Anker et al. (2021)).

425 During the stable weather period, we note that a weak correlation with biweekly tidal maxima  
426 might exist when considering only events from the larger magnitude population (Fig. 9d; events  
427 with  $b=10.9$  in Fig. 2b). For the period of stable weather conditions, the peaks in this histogram  
428 vaguely correspond to the temporal positions of the neap tides. The mean time difference of the  
429 events to the closest neap tide is 1.7 days (std of 1.0 days), whereas the mean time difference to  
430 the closest spring tide is 5.8 days (std of 1.7 days). However, apart from this weak correlation,  
431 Figure 9f illustrates the near chaotic temporal behaviour of the event clusters. For instance, the  
432 four largest clusters in our dataset behave completely differently with time. Whereas one of the  
433 clusters produces all events during  $\sim 5$  days of intense activity, the other clusters are split into  
434 several temporal sub-clusters with varying numbers of events and activity times. Neither of these  
435 clusters or sub-clusters correlates with daily or biweekly trends in the tidal signal. Finally, the  
436 largest clusters (those with the highest number of individual events) do not necessarily include  
437 the events with the largest magnitude.

438

439

440

## 441 5 Discussion and Interpretation

### 442 5.1 Little influence of tidal forcing on icequakes

443 Tidally induced sea-level modulations at the grounding line have been shown to cause periodic  
444 coupling and decoupling of the ice and bed at other West Antarctic ice streams. For example, at  
445 Kamb Ice Stream (KIS), such modulations have been measured as far as 85 km upstream of the  
446 grounding line (Anandakrishnan & Alley, 1997). A likely tidally induced modulation of ice flow  
447 speed, yielding a temporally variable icequake rate has been observed at Whillans Ice Plain (WIP)  
448 (Barcheck et al., 2018, 2020; Winberry et al., 2013) as well. Also, at RIS, a biweekly modulation of  
449 ice flow velocity is observed at the surface (Adalgeirsdóttir et al., 2008; Gudmundsson, 2006;  
450 Murray et al., 2007). However, in our icequake dataset, we observe only a weak correlation  
451 between the occurrence of the largest magnitude events and the neap tide at the grounding line  
452 (Fig. 9d). This is when the glacier flow velocity at the surface reduces (Gudmundsson, 2006). A  
453 similar weak correlation of larger magnitude icequakes with the tidal cycle has been observed  
454 before (Adalgeirsdóttir et al., 2008; E. C. Smith et al., 2015). Although this trend is weak, it has  
455 been observed in three different datasets, collected in different years (1997-1998, 2008-2009  
456 and 2018-2019), so is likely a characteristic of basal microseismicity at RIS. Although magnitude  
457 variation can be caused by a number of other factors (e.g., fault size, variable loading velocity), a  
458 temporal modulation of icequake magnitudes could suggest that the pressure regime at the ice-  
459 bed interface changes temporally. The two different b-value trends we observe for our dataset  
460 (Fig. 2b) also allude to this. Variable b-values can occur due to changes in the stress regime during  
461 the observation period (El-Isa & Eaton, 2014) or during the transition from tectonic to fluid  
462 assisted failure (Kettlety et al., 2019).

463 However, apart from the possibility of a gentle magnitude modulation with the tidal cycle, the  
464 bulk of basal seismicity does not show any clear biweekly trend. A correlation between icequake  
465 intensity and daily tidal height at the grounding line is not observed either. Thus, our observations  
466 contrast with the results at KIS or WIP, where variations of seismicity rates with one or two daily  
467 peaks, often but not always associated to the tidal cycle, have been observed (Anandakrishnan  
468 & Alley, 1997; Pratt et al., 2014). At KIS basal icequakes are thought to accommodate significant

469 parts of the basal ice stream motion (Anandakrishnan & Alley, 1997). At WIP, microseismic events  
470 likely indicate the nucleation phase for a tidally induced large-scale movement of the ice stream  
471 (Winberry et al., 2013). Furthermore, Barcheck et al. (2020) inferred an alignment of seismicity  
472 and MSGs. This basal seismicity is periodic and influenced by glacial flow variations, likely  
473 produced by the tidal cycle.

474 The situation at RIS is clearly different and prompts two possible interpretations. On one hand,  
475 our observations could be explained by a scenario where basal sliding varies temporally, like the  
476 observed surface modulation, but is not reflected by stick-slip seismicity at the bed. Thus,  
477 icequakes would make up only a small proportion of the total motion and the tidal signal could  
478 be accommodated by aseismic deformation and movement at the bed (E. C. Smith et al., 2015).  
479 On the other hand, there could be intra-ice deformation at RIS, which modulates the deformation  
480 signal from the surface to the bed. Such tidally-induced modulations in the vertical strain rate  
481 have recently been detected in ice sheets (Vankova & Nicholls, 2019). Furthermore, the ice at RIS  
482 is much thicker than at WIP (2200 *m* at RIS, 650-800 *m* at WIP; Fretwell et al. (2013)), which could  
483 explain why intra-ice deformation has a larger impact at RIS. In addition, at RIS, icequakes along  
484 the MSGs occur with a similar spatial distribution to WIP but without a clear temporal pattern.  
485 This discrepancy would be an argument for tidal forcing at the base of RIS being less pronounced  
486 than at other ice streams. In addition, the bed topography of RIS is more extreme (see e.g. Fig.  
487 1c), compared to the relatively flat bed of WIP, which might hinder the upstream propagation of  
488 a tidally induced pressure change along the ice-bed interface. On the contrary, in modelling  
489 studies, tidal forcing has been suggested to periodically modulate the surface ice flow via friction  
490 at the bed (Rosier et al., 2015). This would require the tidal signal at the bed to be even more  
491 pronounced than at the surface and would be an argument for dominantly aseismic motion at  
492 the bed of RIS. Ultimately, measurements that monitor the strain or fabric modulations through  
493 the ice column might help to discriminate between these different scenarios. However, in either  
494 case, this study shows that the basal seismicity at RIS is not, to first order, controlled by the tidal  
495 cycle.

496

497 **5.2 Network wide icequake distribution: Role of bed topography, bed properties and water in**  
498 **triggering icequakes**

499 As the tidal influence in icequake distribution appears minor, other characteristics, such as bed  
500 topography and till properties at the bed, must have a greater impact on temporal and spatial  
501 icequake distribution. Soft till will accommodate ice flow by deformation whereas stiff till favours  
502 basal sliding (A. M. Smith, 1997). Accordingly, and in agreement with previous icequake studies  
503 at RIS (A. M. Smith, 2006; E. C. Smith et al., 2015), we observe more icequakes within the stiffer  
504 bed domain than in the soft sediment units (see Maps in Figs. 1c and 4b for the geographic  
505 locations used in the following discussion). However, due to the superior network configuration  
506 and size compared to previous studies, we observe previously unresolved second order  
507 structures. We observe, for instance, fewer icequakes northeast of the central high than  
508 southwest of it within the broad domain of stiff sediments downstream of the bed character  
509 boundary. A lower radar reflectivity has been inferred for the latter, which suggests outcropping  
510 bedrock or very compressed sediments (Schlegel et al., 2021). Thus, larger regions of reduced  
511 seismicity within stiff till units could indicate the presence of compressed sediment or  
512 outcropping bedrock.

513 Furthermore, the icequake distribution highlights features that we suggest indicate variations in  
514 bed character over scales of hundreds of meters. This can best be illustrated within the soft  
515 sediment upstream of the bed character boundary, where we observe large-scale flow-parallel  
516 alignment of events within the valleys separating MSGs (e.g., Fig. 5d). This suggests that stiff till  
517 must be present in the valleys to favour seismogenic stick-slip behaviour. Barcheck et al. (2020)  
518 inferred similar alignment of seismicity and MSGs at WIP. They also related these patterns to  
519 changes in frictional properties (soft sediments on top, stiffer at base). This alignment could be  
520 due to either the constructional or erosive creation of MSGs. In both cases, soft sediments would  
521 be expected at the MSGs crests. However, at RIS, seismic studies showed that MSGs likely form  
522 when soft deformable sediments are accumulated (A. M. Smith et al., 2007). Thus, the similar  
523 character of seismicity at WIP and RIS might hint toward a constructional creation of MSGs in  
524 general.

525 Another bed feature at the scale of a few hundreds of meters highlighted by our icequake  
526 catalogue is the seismicity arranged in circular patterns with the centres depleted in seismicity  
527 within the broad domain of stiff sediments (e.g., Fig. 6a). At least one of these central regions  
528 corresponds to an area where free water is proposed to exist at the glacier bed (Schlegel et al.,  
529 2021). However, we can rule out a direct role of fluid in creating icequakes through tensile crack  
530 opening as the RIS icequakes are likely caused by a double-couple source. Icequakes directly  
531 triggered through the hydraulic system at the glacial bed may manifest themselves through non-  
532 double-couple tensile crack faulting (Walter et al., 2013). We infer the double-couple nature of  
533 the RIS icequakes from the station coverage that allows for many rupture mechanisms the  
534 coverage of the entire focal sphere (e.g., Fig. 3a). If the icequake source would have a significant  
535 non-double-couple component, a less clear separation of positive and negative polarities close  
536 to the nodal planes would be expected. In addition, results of full-waveform modelling for one  
537 icequake at RIS show a double-couple source to be more likely (Hudson et al., 2020). Full-  
538 waveform modelling would allow for the resolution of different source types. Thus, both studies  
539 suggest that neither the direct role of fluids (e.g., through hydrofracturing) or other processes  
540 that require tensile forces (e.g., crevasse opening) seem to drive the icequakes at RIS. Instead,  
541 we propose that a weakening of the till resulting from the presence of fluid penetrating the till  
542 layer (Rathbun et al., 2008) or fluctuations in the hydraulic pressure caused by fluids (Rösli et  
543 al., 2016) may eventually result in a series of stick-slip events adjacent to regions of free water at  
544 the ice-bed interface. The role of fluids in promoting icequakes would also explain the temporal  
545 and spatial event clustering we observe (T. Fischer et al., 2014; Greenfield et al., 2019) and the  
546 large b-values (El-Isa & Eaton, 2014; Schlaphorst et al., 2017; Wilks et al., 2017). Large b-values  
547 are indicative for swarm-like earthquake behaviour, which, in turn can be triggered from fluid  
548 induced pressure variations.

549

### 550 **5.3 Zooming into individual icequake clusters: Types of subglacial stick-slip deformation**

551 Icequakes typically occur clustered in space and time, as observed at the bed of other glaciers in  
552 Antarctica and elsewhere (e.g., Danesi et al. (2007); Helmstetter et al., (2015); Barcheck et al.,

553 (2020)). Despite cluster nature, size and repeat time being highly variable, clustered icequake  
554 activity is generally interpreted to be caused by sticky-spots (Barcheck et al., 2020; U. H. Fischer  
555 et al., 1999; Robert W Jacobel et al., 2009; Rössli et al., 2016; E. C. Smith et al., 2015), where  
556 basal resistance increases. Although descriptive, this interpretation does not necessarily imply a  
557 specific physical mechanism. Also, at RIS, we observe a large spatiotemporal variability of cluster  
558 nature. Due to the relatively long observation period and large network aperture compared to  
559 previous studies, as well as the detailed knowledge of bed properties from seismics, drilling and  
560 radar, we suggest that sticky-spots at RIS can be attributed to three different end-member types  
561 of stick-slip behaviour at the glacier bed, which are schematically shown in Figure 10. We note,  
562 however, that there is likely no strict separation between these different end-member types and  
563 they can occur simultaneously or intermingled. As a whole they may be indicative of the  
564 deformation characteristics of subglacial till beds.

565 In the following interpretation it is assumed that all icequakes occur very close to the ice-bed  
566 interface. This assumption is justified as the vertical location uncertainty (Fig. S6), including  
567 possible effects of model errors and anisotropy (Sections S1 and S2), and the uncertainty in the  
568 radar-constrained interface (King et al., 2016), places all events at the interface. This agrees with  
569 full-waveform source inversions that suggest that such icequakes at RIS occur within metres of  
570 the ice-bed interface (Hudson et al., 2020). Furthermore, we note that our event catalogue does  
571 not allow us to draw detailed conclusions on the shape of the individual clusters. The event  
572 cluster size is generally in the 10 to 100 *m* range and with variable shape. However, based on the  
573 location errors derived from the pick uncertainties and additional uncertainty from unmodelled  
574 errors in the velocity model (isotropic and due to anisotropy), it is likely that the different shapes  
575 of individual clusters may be within the location uncertainty. Thus, all events in one temporal  
576 sub-cluster may originate from a single spatial location, i.e., a single fault.

577

578 **5.3.1 Type 1 - Self-destructive asperities:** Most of the icequake clusters (81%) are active for less  
579 than five days (mean 3.5 days, std 8.4 days; Figs. 8d/S7a). During this time, the ice stream flows  
580  $\sim 3.7$  *m* downstream. We detect icequakes with inter-event times in the one- to five-minute range  
581 (mean 4.6 minutes, std 9.3 minutes; Fig. S7d). These clusters are then inactive for the remainder

582 of our observation period, which suggests that these spots are unlikely to be stationary obstacles  
583 in the ice stream bed. Stationary obstacles would likely produce repeating seismicity, e.g., upon  
584 variations in basal water pressure (U. H. Fischer et al., 1999) or due to constant ice loading.  
585 Instead, we favour a concept of asperities within the subglacial till, which are randomly built by  
586 the glacial movement and subsequently destroyed through a sequence of stick-slip events. Such  
587 asperities may be envisaged as sites of increased friction that develop during continuous ice  
588 stream movement as sediment is transported and dilates and reorganizes (McBrearty et al., 2020;  
589 Thornsteinsson & Raymond, 2000; Van Der Meer et al., 2003). If glacial till is sheared, its pore  
590 volume is increased (Boulton & Hindmarsh, 1987). Till can then be weakened if pathways that  
591 permit water flow into the dilated material exist (Rathbun et al., 2008). This may lead to the  
592 formation of an asperity along which slip-deficit can build-up. Freezing-on of part of the bed could  
593 additionally contribute and would favour velocity weakening (Lipovsky et al., 2019), which is a  
594 requirement for stick-slip behaviour. Once the shear resistance of the asperity is overcome, stress  
595 is released in a series of icequakes and the specific asperity is destroyed. The displacement per  
596 event at RIS is estimated to be in the range of 0.03 to 0.07 *mm* (E. C. Smith et al., 2015), which is  
597 less than the glacial movement that would accumulate during typical inter-event times ( $\sim 0.8 \text{ mm}$   
598  $\text{min}^{-1}$ , assuming the same velocity at the base of the ice stream and the surface). Thus, it is  
599 unlikely that each new event in an icequake cluster is created by continuous loading. It rather  
600 suggests that a spot mostly deforms aseismically but slip-deficit can accumulate occasionally. As  
601 we rarely observe single events, but event clusters, it appears that glacial till does not support  
602 the accumulated slip-deficit to be released in a single large event (e.g. comparable to megathrust  
603 earthquakes in subduction zones), but rather in many small icequakes. If the asperities develop  
604 due to the ice stream movement and reorganization of till, different event counts per clusters, as  
605 observed here, can be envisaged. The sharp magnitude cut-off at larger magnitudes (b-value of  
606 10.9) obtained here might also suggest that an upper magnitude threshold exists for the largest  
607 possible icequake. This magnitude threshold may be governed by the till properties and the  
608 maximum available normal stress.

609

610 In this concept of self-destructive asperities, the bed material must be strong enough to allow for  
611 the build-up of stress locally. This may explain why more icequake clusters occur in the stiff-  
612 sediment domain. Furthermore, the bed character boundary sections with a large step in residual  
613 topography may be favoured for the occurrence of such clusters as they represent natural  
614 obstacles for flow. On the contrary, it seems that very stiff surfaces, like the stiff-sediment units  
615 northeast of the central high, are less favourable for asperity formation. This may be as sediment  
616 reorganization is expected to happen more slowly. Instead, they may give rise to polished  
617 surfaces, possibly overlain by a homogeneous water film, where aseismic glacial sliding is the  
618 dominant basal motion process.

619 **5.3.2 Type 2 - Ploughed clasts:** For some clusters (numbering 72 – 9% of all clusters), we observe  
620 the downstream migration of the seismically active sites at the same speed as ice flow at the  
621 surface, which is  $\sim 1.05 \text{ m day}^{-1}$  (Fig. 8b). This phenomenon occurs for  $\sim 50\%$  of all clusters which  
622 are active for a sufficient duration that the observed migration is larger than the single event  
623 location uncertainty. This observation suggests that an object, held within the ice, is being  
624 transported downstream and causing the icequakes. During this transportation process the spot  
625 is periodically seismically active. Likely candidates for such a mobile object are clasts held in the  
626 basal ice and dragged through the glacial sediments or over harder materials (Zoet & Iverson,  
627 2020). The presence of clasts embedded in the bed had been proposed based on scientific drilling  
628 at RIS (A. M. Smith et al., 2020). If clast motion is hindered for some time, allowing slip-deficit to  
629 accumulate, the seismic activity could represent the moment in which the clast slips forward. An  
630 icequake with double-couple source would then be created by frictional sliding between the clast  
631 and/or the ice and till layer. Laboratory experiments showed that ploughing clasts can cause  
632 velocity weakening behaviour (Iverson, 2011; Thomason & Iverson, 2008). The clast may  
633 eventually become lodged due to melt out or changes in the properties of the sediment. Such  
634 clasts will have variable shape, size and penetration depth, and so different numbers of events  
635 in the clusters appears logical. Our event catalogue does not allow us to comment on the size or  
636 shape of such clasts, as we consider them to be within the horizontal resolution of the event  
637 locations. In contrast to icequakes originating from breaking asperities, bed deformation is  
638 expected in the case of ploughed clasts (Zoet & Iverson, 2020).

639 Apart from downstream migrating clusters, we observe some clusters (numbering 82 – 10% of all  
640 clusters) that are active repeatedly at the same location (Fig. 8b). These could represent the  
641 presence of a more permanent obstacle to ice flow. Either basal drag could be too weak or the  
642 till matrix too strong to allow for the mobilization of a clast. Alternatively, these clusters could be  
643 related to bed asperities. Part of an asperity may remain locked after the initial cascade of  
644 icequakes and break at a later stage.

645 **5.3.3 Type 3 – Flow-oblique landforms as obstacles:** Our stress inversion dataset contains 23  
646 clusters (5% of all clusters with stress inversion results) that indicate flow-oblique deformation  
647 (Fig. 8a). This rotation ( $\pm 36^\circ$ ) is clearly supported by the data. For instance, seismic stations,  
648 crucial for constraining the rupture mechanism, show different polarities for either flow-parallel  
649 or flow-oblique mechanisms (Figs. 3b, c). Furthermore, the rotated events occur close to  
650 mechanisms that are not rotated. Thus, their occurrence is unlikely to be an effect of network  
651 geometry. Such flow-oblique mechanisms have not been observed at RIS before and we suspect  
652 that it is the dense seismic network and the low noise level that allows them to be resolved here.  
653 Based on our first-motion mechanisms we infer that the main difference between these  
654 icequakes and those discussed above is the rotation of the strike of the rupture mechanism. A  
655 comparative analysis of the source characteristics of the different icequake populations might  
656 yield further discrimination.

657

658 Although scenarios can be envisaged where rotated rupture mechanisms originate from self-  
659 destructive asperities of ploughed clasts, it is striking that these mechanisms mainly occur along  
660 the bed-character boundary and at the termination points of MSGs. This suggests a causal  
661 relationship. These flow-oblique focal mechanisms may be related to intra-till deformation that  
662 occurs during the formation of subglacial landforms – either at the ice-bed interface or within  
663 the deforming till. This agrees with laboratory experiments conducted by Lipovsky et al. (2019),  
664 who concluded that shear seismicity may indicate geomorphological activity. Here, the flow-  
665 oblique mechanisms occur mostly along the bed character boundary. The bed character  
666 boundary is thought to be modified over time scales of a few years by sediment deformation

667 (King et al., 2016; A. M. Smith & Murray, 2009). Furthermore, the flow-oblique mechanisms tend  
668 to focus along the termination points of MSGs, where active erosion and deposition has been  
669 interpreted from seismic data (A. M. Smith et al., 2007). A. M. Smith et al. (2007) concluded that  
670 sedimentary processes may be the most likely explanation for this erosion. The flow-oblique focal  
671 mechanisms are likely the brittle manifestation of such sedimentary processes. Alternatively, or  
672 in addition, the flow-oblique focal mechanisms may originate at outcropping bedrock. Such  
673 bedrock units cannot be eroded and may form an obstacle that creates a local distortion of the  
674 stress regime.

675

## 676 **6 Summary and outlook**

677 We present a microseismic event catalogue for a 10 x 10 km region, ~40 km upstream of the  
678 grounding line of RIS. The seismic network used to derive this catalogue straddles a change in  
679 bed character properties (soft to stiff sediments) with consistent station spacing. Thus, we can  
680 identify seismic and aseismic regions within our network domain with high certainty.

681 All ~230000 micro-earthquakes (magnitudes between -2.0 and -0.3) detected in a 90-day  
682 observation period are located near the ice-bed interface. Most of these events indicate flow-  
683 parallel stick-slip. We propose that the interplay between the topography, bed character type  
684 and the hydraulic system at the bed controls the spatiotemporal patterns in icequake occurrence.  
685 Icequakes focus at the transition from soft to stiff till and in defined spatial domains of stiffer till.  
686 The domains within stiffer till can be either large, coherent regions or more subtle structures, like  
687 the valleys separating MSGs. Within the regions of stiffer till, fluids may modulate the strength  
688 of the till to promote seismicity. In contrast, tidally induced pressure fluctuations at the bed seem  
689 to be less pronounced or have little effect on icequake occurrence. This suggests that part of the  
690 tidally induced modulation is taken up by aseismic bed or intra-ice deformation.

691 On a smaller scale, most icequakes (93%) occur in clusters that are spatially and temporally  
692 restricted bursts of seismic activity. Accordingly we measure high b-values (between 3.3 and  
693 10.9) in event number-magnitude plots, which are indicative for swarm-like behaviour of  
694 earthquakes (El-Isa & Eaton, 2014). Modulations in b-values might be due to pressure

695 fluctuations at the ice-bed interface or indicate an upper limit for the maximum icequake size.  
696 These clusters are generally less than  $\sim 100$  m in radius and are active for only a few days. Based  
697 on the calculated location uncertainty, we suspect that all events in a specific cluster could  
698 originate from the same spatial spot, i.e. a single fault. These clusters show an increase and  
699 decrease of event magnitude with time while the events in a specific cluster feature highly similar  
700 rupture mechanisms. We further observe a gentle correlation of increasing inter-event times  
701 with increasing magnitudes. Similar icequake characteristics have been observed in very different  
702 glacial settings in the European Alps and in Greenland (Helmstetter et al., 2015, 2018; Rösli et  
703 al., 2016), although observation time spans in these studies are shorter than in this study. Thus,  
704 these common characteristics may provide insight to the rupture mechanism of icequakes, i.e.  
705 the rupture of an asperity surrounded by aseismic slip, in general. Furthermore, such common  
706 characteristics hint towards a unique driving force within a cluster and suggests event triggering  
707 within the clusters once the activity period is initiated, possibly facilitated by frictional heating. A  
708 detailed investigation of the source mechanisms, the inter-event locations (e.g., through double-  
709 difference methods) and of the material properties surrounding the events might help to  
710 discriminate between such processes.

711

712 Apart from these common features, the clusters can be discriminated from each other based on  
713 distinct spatiotemporal evolution characteristics and the orientation of rupture mechanisms  
714 relative to ice flow. We attribute their distinct characteristics to different end-member  
715 deformation mechanisms that may act at the bed simultaneously. These are the dynamic creation  
716 and seismogenic destruction of spots of increased friction that develop due to sediment  
717 transport and/or due to temporal variable till properties ('asperities'), the ploughing of clasts  
718 through the underlying sediment, and flow-oblique deformation either associated with the  
719 erosion and formation of subglacial landforms or due to bedrock obstacles at the ice stream bed.  
720 Among these, the seismogenic destruction of asperities is the most common process. Taking  
721 these different processes together, we conclude that the bed of RIS can be envisaged as an  
722 actively and heterogeneously deforming subglacial bed mosaic (Piotrowski et al., 2004) with a  
723 variety of deformation processes active simultaneously. Our analysis suggests that the friction at

724 the bed varies over a small scale and that the glacial bed is in a process of continuous  
725 reorganization. Both impact ice stream flow directly.

726

## 727 **Acknowledgements**

728 This work was funded by NERC AFI award numbers NE/G014159/1 and NE/G013187/1. We thank  
729 the staff at Rothera Research Station and BAS logistics for enabling the fieldwork associated to  
730 this project and the BEAMISH field team (2018/19) for acquiring the passive seismic data. Seismic  
731 instruments were provided by NERC SEIS-UK (Loan 1017), by BAS and by the Incorporated  
732 Research Institutions for Seismology (IRIS) through the PASSCAL Instrument Center at New  
733 Mexico Tech. The facilities of the IRIS Consortium are supported by the National Science  
734 Foundation's Seismological Facilities for the Advancement of Geoscience (SAGE) Award under  
735 Cooperative Support Agreement EAR-1851048. Jamie Oliver (BAS) helped in preparing the  
736 schematic sketch of Figure 10. We thank three anonymous referees for useful comments that  
737 improved the manuscript.

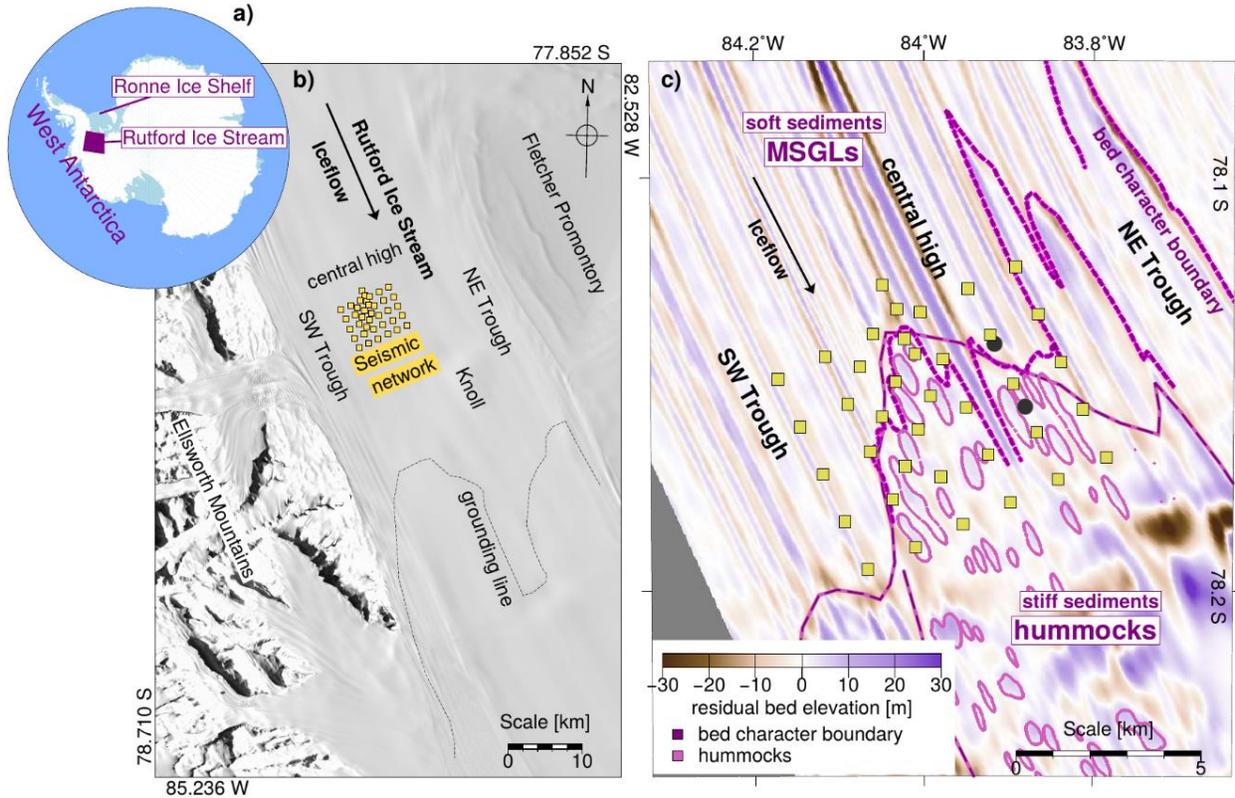
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## 739 **Data Availability**

740 The data, which supported the main findings of this work (icequake catalogue, rupture  
741 mechanisms and seismic station meta data), are available via the UK Polar Data Centre:  
742 <https://doi.org/10.5285/B809A040-8305-4BC5-BAFF-76AA2B823734> (Kufner et al., 2020). Raw  
743 seismic data is registered under the FDSN network code 9B (2016-2019;  
744 [https://doi.org/10.7914/SN/9B\\_2016](https://doi.org/10.7914/SN/9B_2016)).

745

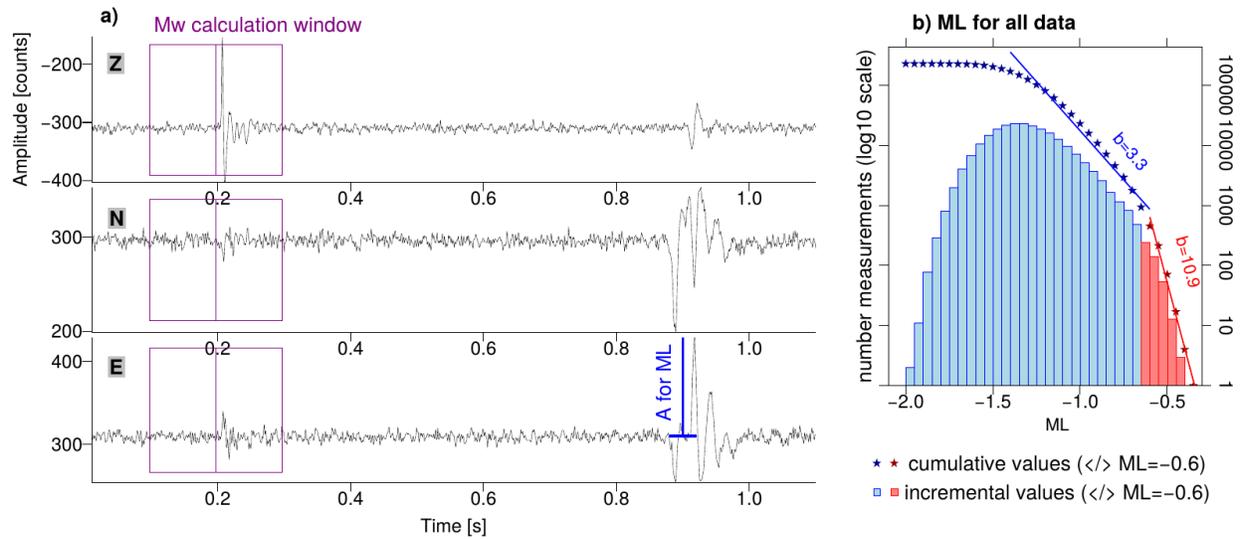
746 **Figures:**



747

748 **Figure 1: Study location.** a) Location of Rutford Ice Stream (RIS). b) Location of seismic  
 749 deployment at RIS, stations shown as yellow squares. Background shows the LIMA (Landsat  
 750 Image Mosaic of Antarctica) image (USGS, 2007) of RIS. A plan view of the stations with their  
 751 identifiers, deployment times and instrument types is included as Figure S1. c) Zoom into the  
 752 study region. Background colour coding demarcates residual bed topography, which is calculated  
 753 based on the difference between the short-wavelength topography and a long-wavelength trend  
 754 surface (King et al., 2016). Hummock locations and dashed bed character boundary are from King  
 755 et al. (2016), while the dotted pink-purple line represents an alternative bed character boundary  
 756 defined by G. Boulton (pers. communication in Smith et al. (2015)). Gray circles indicate the  
 757 location of hot-water drill sites that were operated during the BEAMISH 2018/19 season (A. M.  
 758 Smith et al., 2020).

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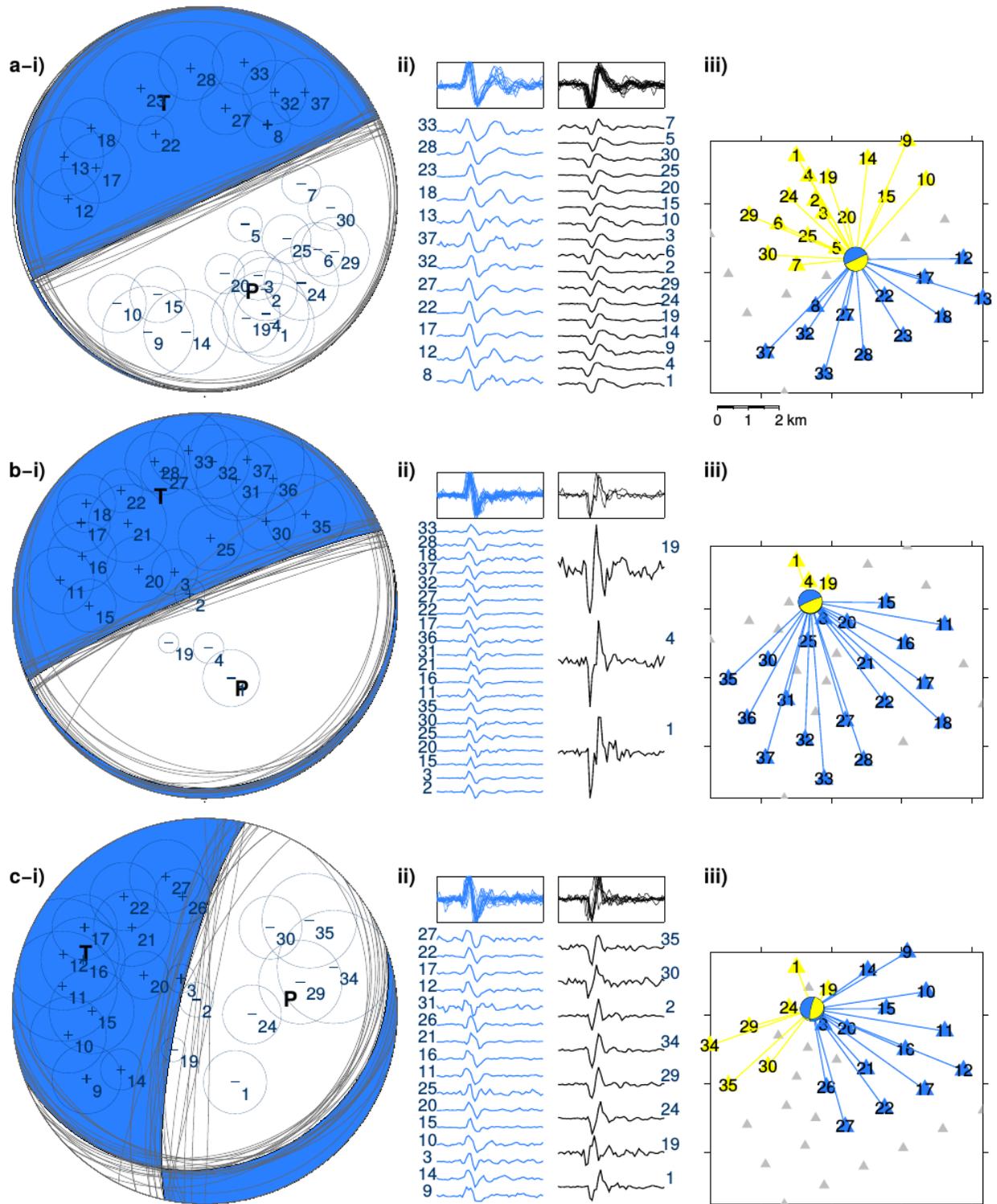


760

761 **Figure 2: Data example and magnitude histogram.** a) Three components (Z- vertical; N/E -  
 762 horizontal towards North/East) of a magnitude  $-0.9$  icequake (event time: 2019-01-  
 763 27T02:58:13.874) recorded at station R2040 (map of the station identifiers is given as Figure S1).  
 764 Amplitude is in instrument counts. The windows used for  $M_w$  derivation and the maximum  
 765 amplitude used to calculate ML are highlighted. b) Magnitude histogram for all events in 0.05  
 766 bins. ‘Cumulative values’ refer to the all events greater or equal to a specific magnitude according  
 767 to the Gutenberg-Richter law (Gutenberg & Richter, 1944). Solid lines represent regression lines  
 768 based on the cumulative values. Sections with different  $\log(\text{ML})$  decay slopes (‘b-values’) are  
 769 highlighted in red and blue, respectively.

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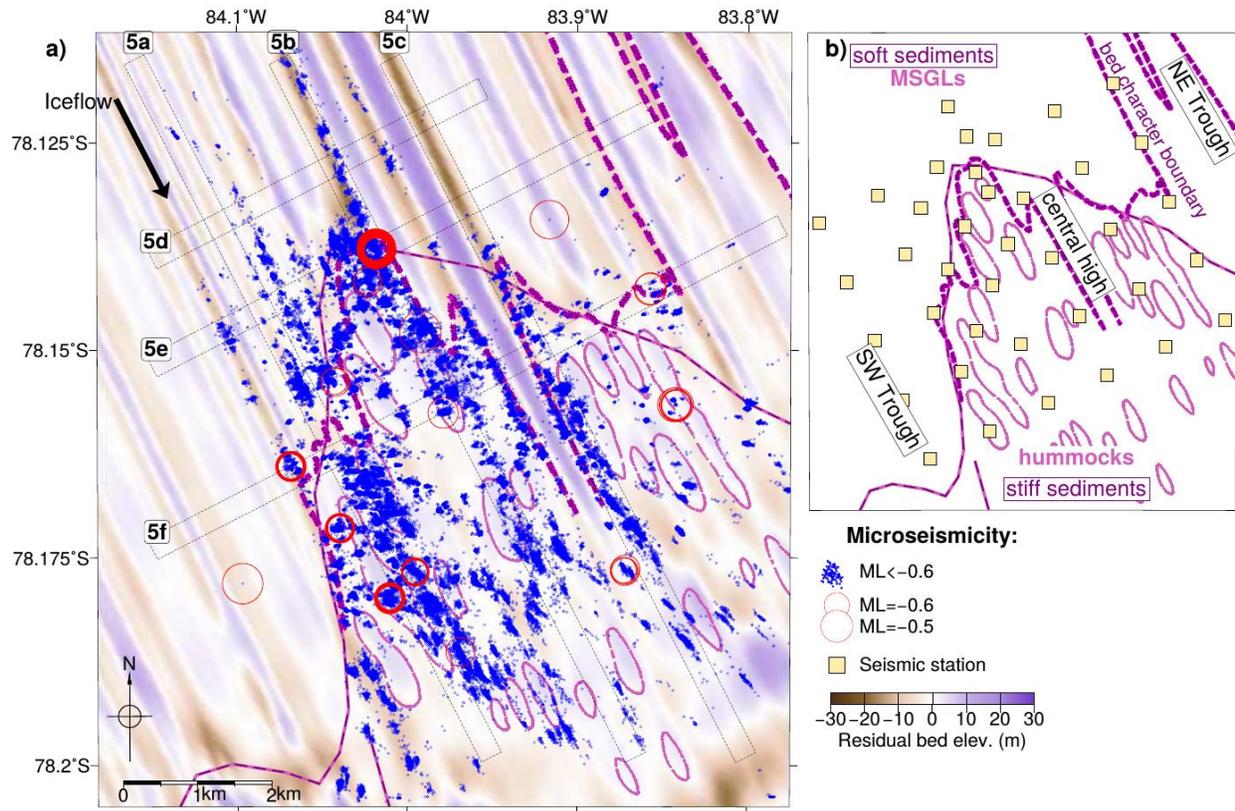
773 **Figure 3: Example focal mechanisms.** Subfigures a-c show three different sample events. Event

774 a) is the same as in Figures 2a, S3 and S4. Events b (event time: 2019-01-03T04:36:40.244) and c

775 (event time: 2019-01-01T06:42:46.998) were chosen due to their location at the margin of the  
776 seismic network. i) Lower hemisphere projection of preferred mechanism (highlighted in blue).  
777 Gray nodal planes show other possible results from bootstrap analysis. Polarity picks (+/- signs)  
778 and amplitude ratios (normalised circles) are highlighted at the position of a specific station on  
779 the stereonet. Numbers refer to specific station indices as used in sub-figures i to iii to identify  
780 individual stations. ii) P-onsets (0.05 s time window; amplitudes normed) of all stations used to  
781 constrain the focal mechanisms. Colour coding indicates negative/positive onsets (blue –  
782 positive; black – negative). The top panel plots all results of one group on top of each other. iii)  
783 map view of the event location in the context of the network. Mechanism is shown in lower  
784 hemispheric projection. Colour coding of positive onsets as (ii); negative onsets are highlighted  
785 in yellow. Gray stations were not picked. All events locate at the ice-bed interface.

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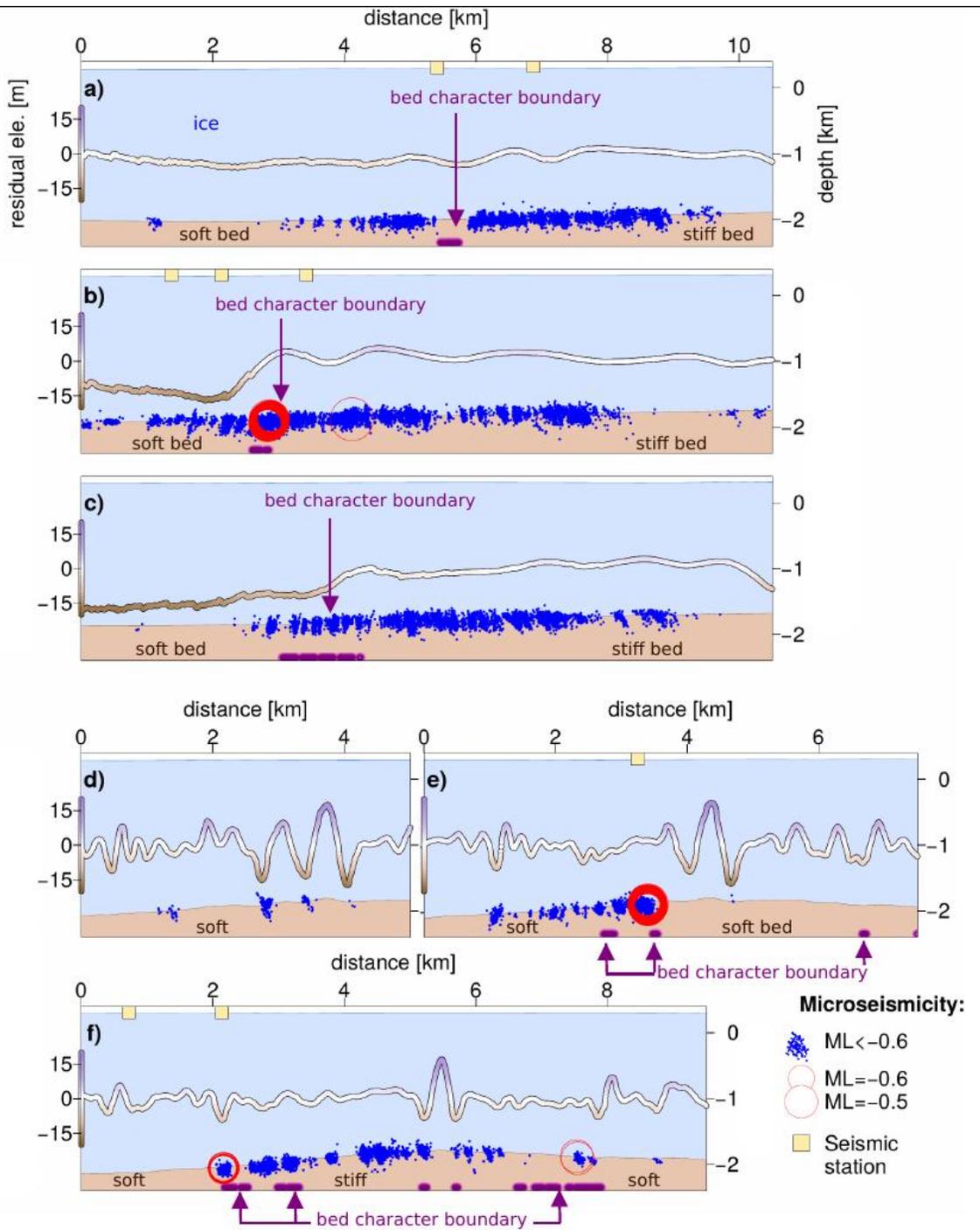


788

789 **Figure 4: Microseismic event catalogue.** a) Location of microseismicity in map view. Bed features  
 790 and geometry as in Figure 1c. See Figure S6 for further catalogue statistics. b) Simplified outline  
 791 of map domain to highlight geographic terms used in Sections 4-6. Seismic stations are plotted  
 792 as yellow rectangles.

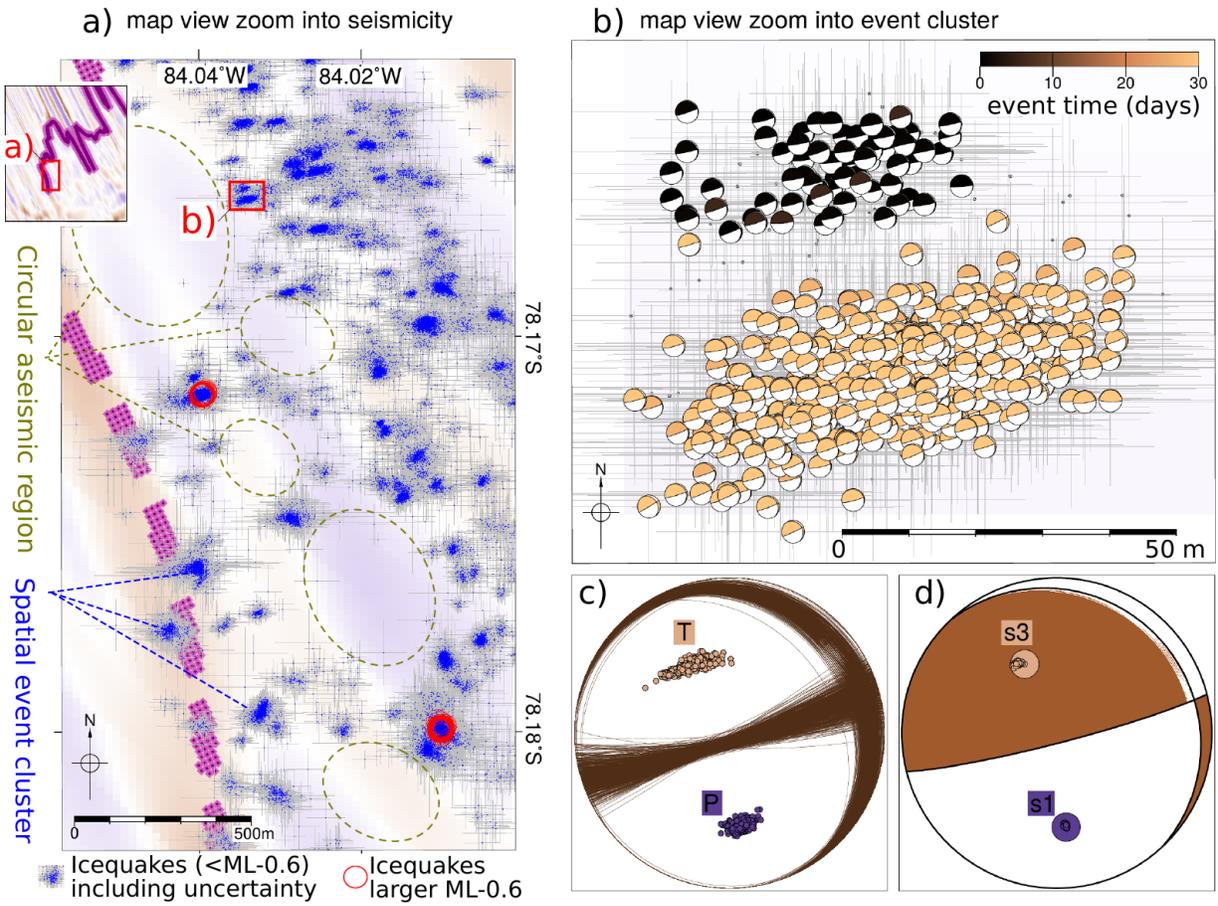
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795

796 **Figure 5: Microseismic event catalogue in profile view.** a-c) Flow-parallel and d-f) flow-  
 797 perpendicular cross sections. Profile locations are highlighted in Fig. 4a). Residual topography is  
 798 projected onto the profiles for reference. Purple domains at the base of the profiles represent  
 799 intersection points of the profiles with the bed character boundary.



800

801 **Figure 6: Zoom into a region of high microseismicity rate and stress inversion example. a)**

802 Microseismicity (blue) as in Figure 4a but plotted with horizontal location errors (grey). Large

803 events (ML>-0.6) are highlighted in red. Bed character boundary and residual topography as in

804 Figure 4a. Labels refer to features discussed in the text. Inset shows overview (same map extent

805 as Figure 4a) highlighting the locations of a). b) Zoom into one event cluster (location of zoom

806 shown as red box in a), showing the individual event focal mechanisms (lower hemisphere

807 projection) at their geographic location in map view. Gray bars indicate horizontal location errors.

808 Compressional quadrants are colour coded according to their event time relative to the first

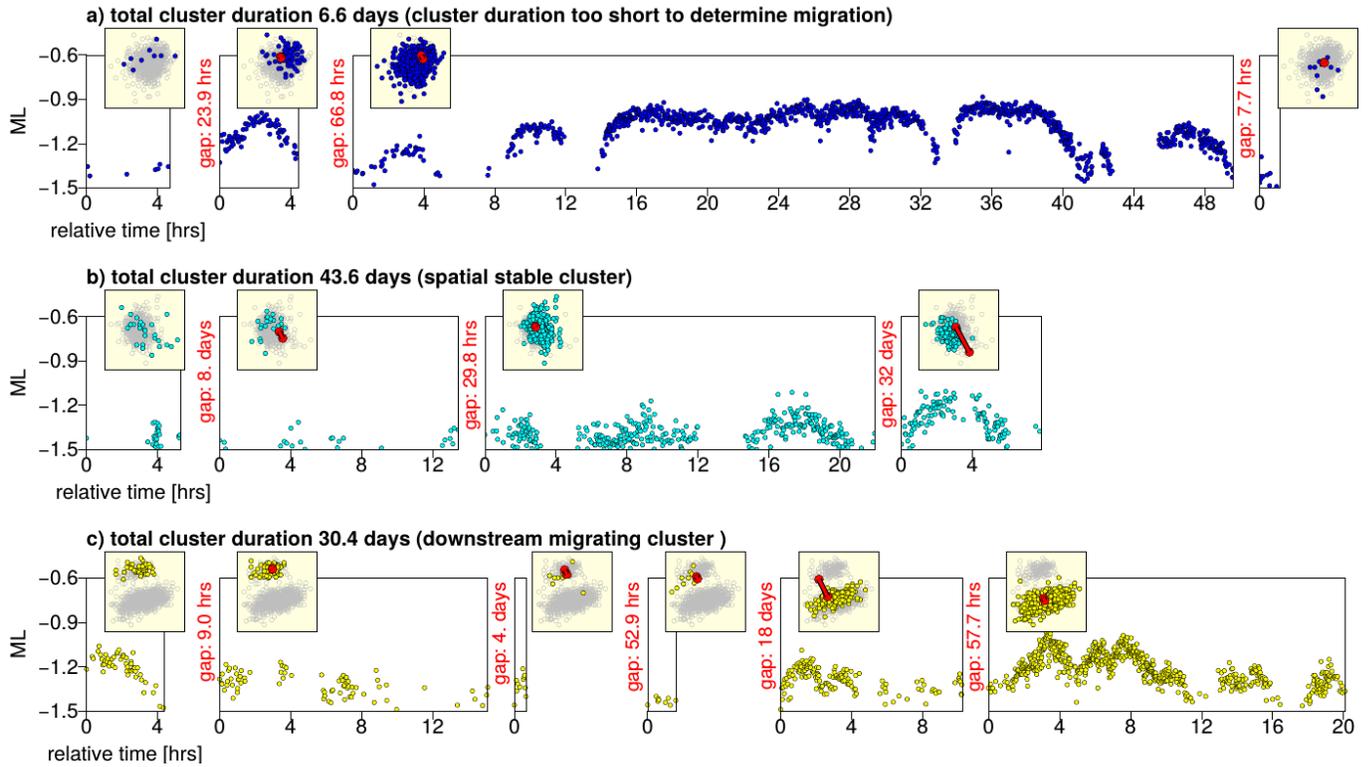
809 event in the cluster. c) Nodal plane of individual event mechanisms of this cluster with highlighted

810 P/T axes plotted on top of each other. d) Resulting stress tensor of this cluster after inversion.

811 Large brown/purple circles represent the  $\sigma_1/\sigma_3$  axes of the preferred stress tensor. Smaller

812 circles are the results of bootstrap tests.

813



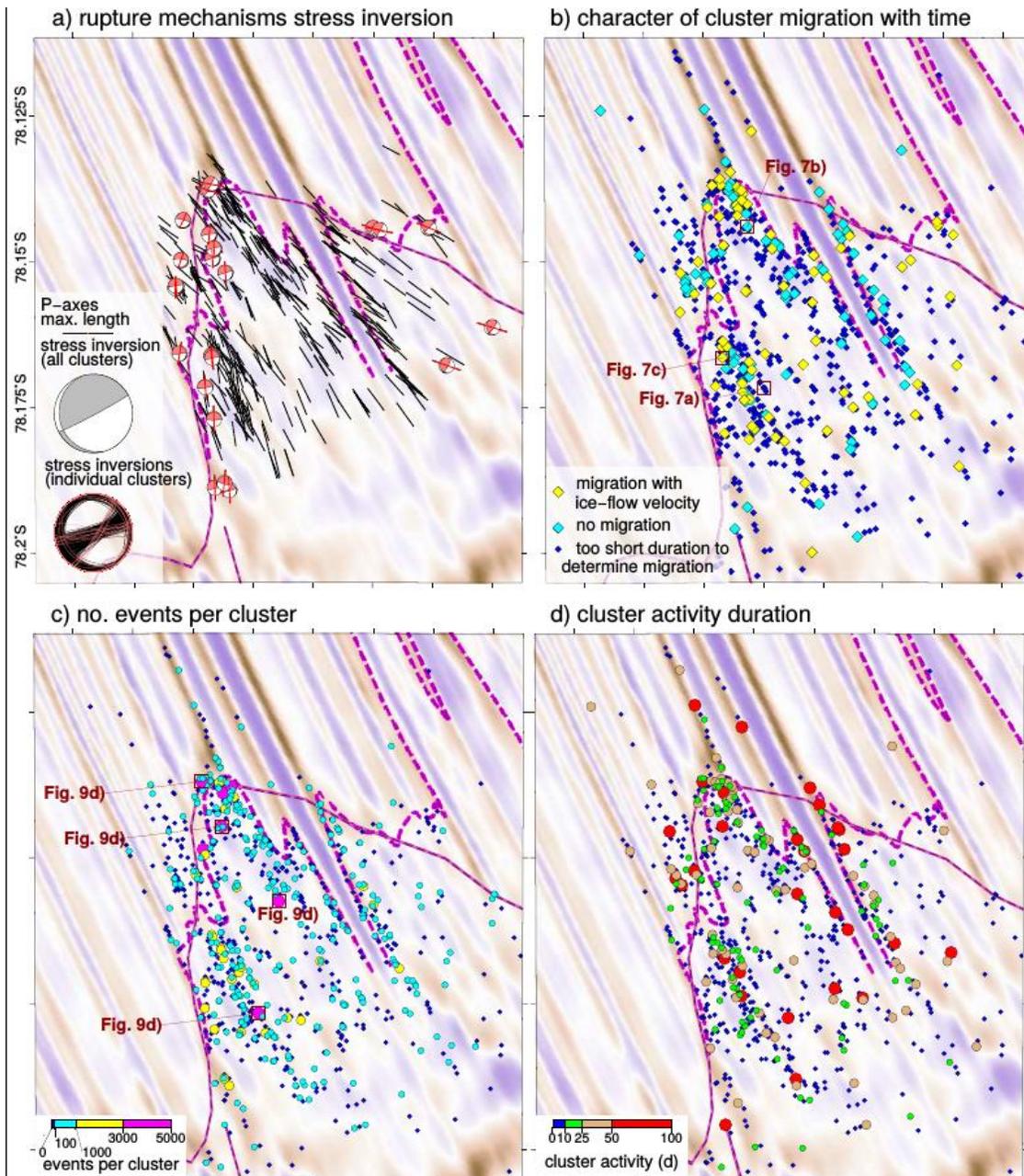
814

815 **Figure 7: Zoom into spatiotemporal evolution of three example clusters.** The main panels in a-  
 816 c) show the evolution of event magnitude with time, the inset plots the event locations in map  
 817 view. Note that the time axes are discontinuous: for inter-event times larger than five hours, the  
 818 time axes are cut, and plotting is re-started when seismicity returns. The times of inactivity are  
 819 given in red letters. In map view, events highlighted in same colour as graphs are active in a  
 820 specific time step ('temporal sub-cluster'). Grey events are all events spatially attached to the  
 821 specific cluster ('cluster'). Red circles and connection lines indicate the amount of downstream  
 822 flow of RIS in the time a specific cluster has been inactive (assuming a flow rate of  $1.05 \text{ m day}^{-1}$ ).  
 823 The lines initiate at the sub-cluster centre of the previous sub-cluster activity. a) Example cluster  
 824 for a short-lived cluster for which the time of total activity is too short to determine a trend in  
 825 cluster migration. Cluster dimension in map view is  $67 \times 56 \text{ m}$ . Starting time of the first sub-cluster  
 826 is 2019-01-04T01:12. b) Example cluster in which cluster centroid does not appear to change with  
 827 time, although significant downstream movement accumulates. Cluster dimension in map view  
 828 is  $104 \times 92 \text{ m}$ . Starting time of the first sub-cluster is 2018-12-20T04:48. c) Example cluster where  
 829 the centroid changes with time in the same range as accumulated ice stream movement. Cluster

830 dimension in map view is 95x78 *m*. Starting time of the first sub-cluster is 2019-01-01T22:33.  
831 Cluster locations are highlighted in Figure 8b. A plot with location and magnitude errors included  
832 is attached in Figure S9.

833

834

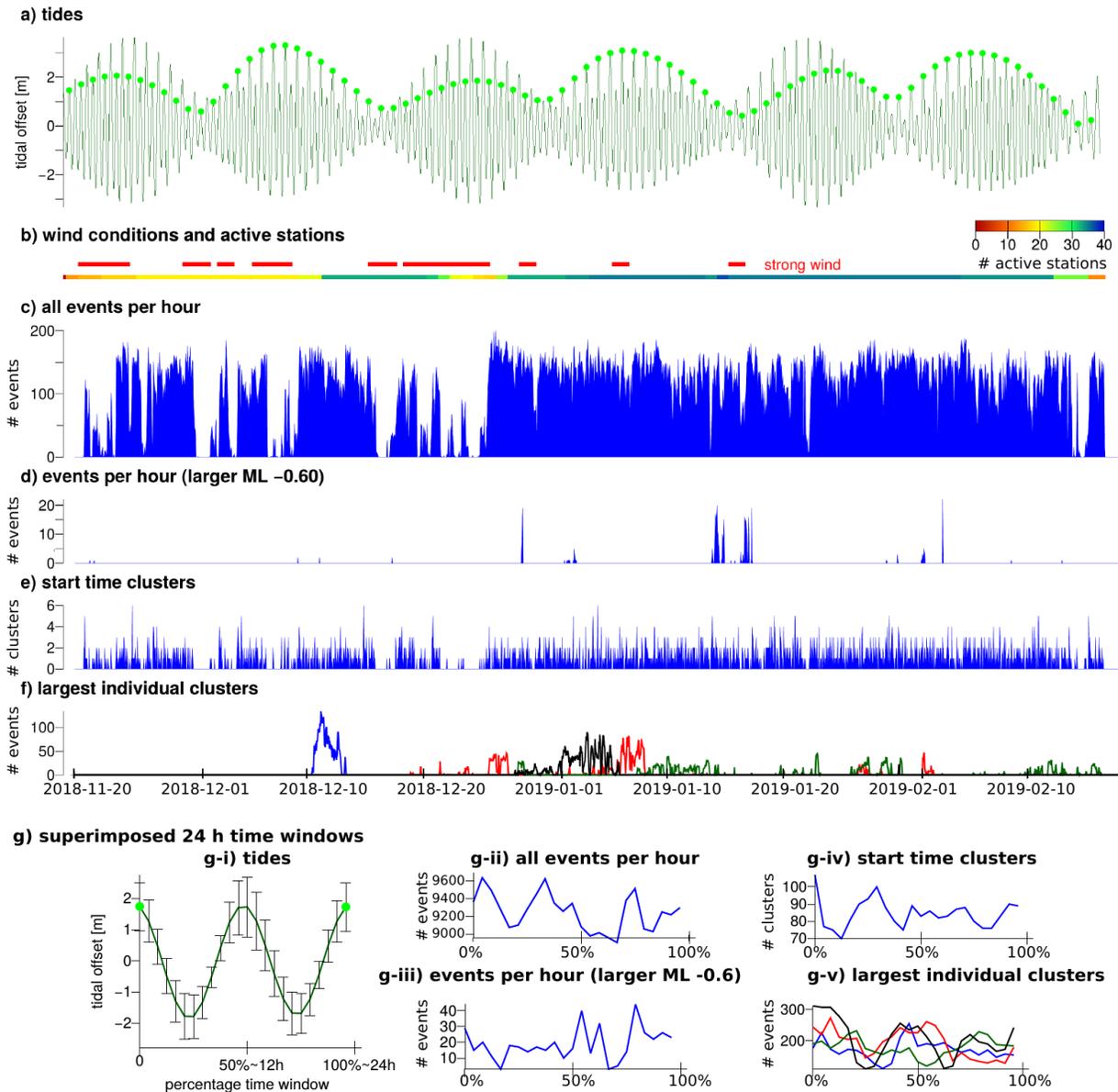


836 **Figure 8: Event cluster characteristics.** a) Stress inversion results from 70023 individual focal  
 837 mechanisms, bundled into 428 clusters. For most inversion results only the P-axes, projected into  
 838 map view, is shown. Only inversion results where P-axes azimuth deviates for more than 30° from  
 839 the solution for all clusters are highlighted and plotted with mechanism. Inset: stress inversion  
 840 for all clusters and nodal planes of individual inversions. Mechanism with large deviation are  
 841 highlighted as in the map view. b) Clusters colour coded by character of cluster migration.  
 842 Clusters shown in Figure 7 are highlighted. c) Cluster size split into small (blue; <100 events),

843 intermediate (turquoise; < 1000 events) and large (yellow/purple; up to 5000 events) clusters. d)  
844 Clusters colour coded according to their duration of activity. Activity duration is measured from  
845 the first to the last event occurring at a spatial spot. Within this time, the cluster may be active  
846 in several busts, separated by more quiet phases ('temporal sub-clusters'), or continuously (see  
847 examples in Figs. 7, 9d).

848

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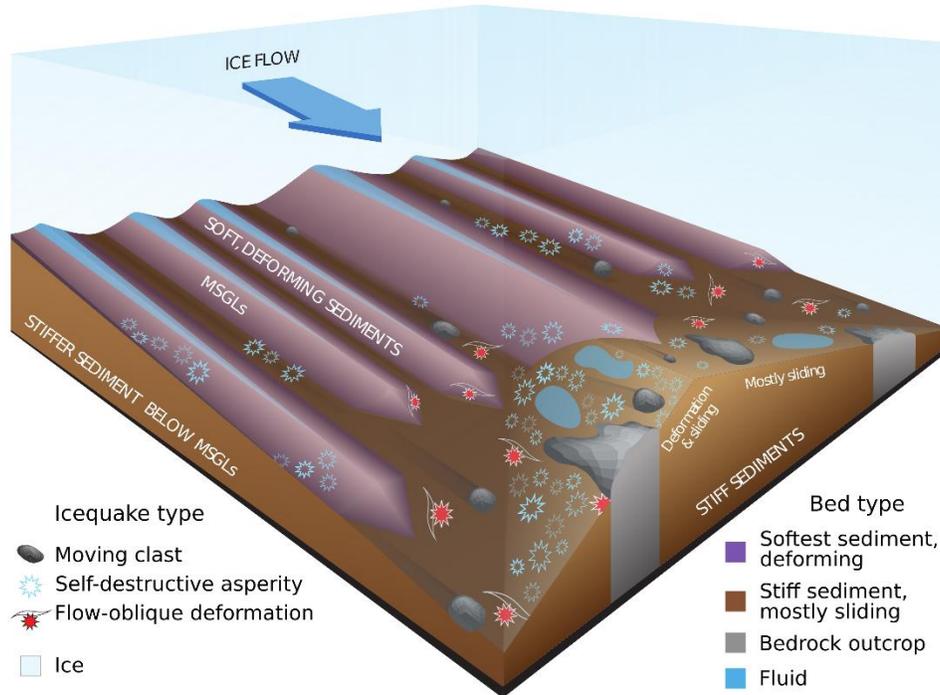
850

851 **Figure 9: Time series plots of event/cluster number and tidal modulations.** a) Tidal height at the  
 852 grounding line of RIS (82.8°W/78.6°S) calculated using the Padman tidal model code (Padman &  
 853 Erofeeva, 2004). The m2, s2, n2, k2, k1, o1, p1, q1, mf and mm mode are included in the model  
 854 calculation. Light green circles highlight the local tidal maximum of each ~24 h cycle. b) Wind  
 855 conditions and number of active stations. Periods of strong wind (according to field notes from  
 856 AB and AS) are marked with red bars. c) number of microseismic events with time. Events are  
 857 binned into one-hour sections. d) as c) but only events larger than ML=-0.6 are shown. e) as c)  
 858 but starting times of temporal sub-clusters are shown. f) as c) but the time evolution of four

859 individual clusters (plotted in different colours) is shown. Cluster locations are highlighted in  
860 Figure 8c. g) Tidal cycles and event histograms collapsed into one tidal cycle (~24 h, two tidal  
861 maxima as highlighted in a); Table S2 lists all time windows used to derive these plots).

862

863



864

865 **Figure 10: Schematic interpretation sketch on active basal processes.** The loci of icequakes  
 866 depend strongly on bed type, with most events occurring within the stiffer sediments. Different  
 867 processes can trigger the icequakes. Among these, the continuous creation of sites of increased  
 868 friction that develop due to sediment transport and/or due to temporal variable till properties  
 869 within the bed (asperities) and their seismogenic destruction is most common.

870

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