

Three-dimensional smoothed particle hydrodynamics modeling of preferential flow dynamics at fracture intersections on a high-performance computing platform



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I. Introduction

Free-surface flow at fracture intersections

- Fracture intersections are critical relay points along preferential flow paths and control the partitioning (i.e. dispersion) behavior in fractured porous media
- Highly non-linear and rapid flow processes such as droplets, rivulets and (adsorbed) films affect the bypass dynamics at fracture intersections (Kordilla, 2017)
- Volume-averaged models (e.g. Richards equation) with saturation-capillary-pressure relations (e.g. van Genuchten parameterization) do not account for complex flow mechanisms on a fracture- and fracture-network-scale
- Flows in unsaturated fractures are challenging to study numerically due to the presence of complex air-water interfaces

Key Objectives:

- Develop a better understanding of the controlling factor of fracture intersections towards droplet partitioning and its implications for preferential flow
- Link geometric fracture characteristics and fluid properties to determine bypass efficiency and transition thresholds
- Analytical interpretation of the controlling factors

II. Methods

SPH implementation of the Navier-Stokes equation

- The foundations of SPH rely on the Navier-Stokes equations:

$$\frac{d\mathbf{v}}{dt} = -\frac{1}{\rho}\nabla p + \frac{\mu}{\rho}\nabla^2\mathbf{v} + \mathbf{g} \quad (1)$$

- Rewritten in SPH form:

$$\frac{d\mathbf{v}_i}{dt} = -\sum_{j \in f+s} m_j \left(\frac{p_j}{\rho_j^2} + \frac{p_i}{\rho_i^2} \right) \mathbf{e}_{ij} \frac{dW(\mathbf{r}_{ij}, h)}{dr_{ij}} + 2\mu \sum_{j \in f+fluid} m_j \frac{\mathbf{v}_{ij}}{\rho_i \rho_j r_{ij}} \frac{dW(\mathbf{r}_{ij}, h)}{dr_{ij}} + \mathbf{g}_{sph} + \frac{1}{m_i} \sum_{j=1}^N \mathbf{F}_{ij} + \mathbf{f}_r(\mathbf{r}_i, \mathbf{v}_i) \frac{m_k}{\rho_i \rho_k} (\mathbf{n}_i + \mathbf{n}_k) \cdot \frac{dW(\mathbf{r}_{ik}, h)}{dr_{ik}} \quad (2)$$

\mathbf{v}_i : particle velocity t : time p : pressure of particle i m : particle mass
 ρ : mass density \mathbf{r} : position vector h : weighting function range W : weighting function
 \mathbf{g} : gravitation \mathbf{F} : particle interaction force \mathbf{f}_r : volumetric source term \mathbf{n} : normals of the interface
 \mathbf{e}_{ij} : unit vector

- In the above equation the linearized viscosity term acts in between fluid particles only
- The interaction force is defined following Tartakovsky (2005) and Kordilla (2017) as a cubic-spline type function with short-range repulsive and long-range attractive components
- The variable slip boundary condition is imposed according to Pan (2014) via a volumetric source term $\mathbf{f}_r = \beta \mathbf{v}$, where \mathbf{n} are the respective normals of the solid-fluid interface
- $\beta = 0$ (full slip) and $\beta = \infty$ (no-slip)
- Here β is chosen such that no-slip conditions are enforced
- Pressure is obtained from an equations of state (EOS)

$$p_i = \epsilon \left(\left[\frac{\rho_i}{\rho_0} \right]^\Gamma - 1 \right) + p_0, \quad (3)$$

ρ_0 : rest density p_0 : background pressure ϵ : scaling constant

- Density is obtained from a kernel summation

$$\rho_i = \int_{j=1}^N m_j W(\mathbf{r}_{ij}, h) \quad (4)$$

- Interparticle forces F_{ij} generate cohesion and adhesion

$$\mathbf{F}_{ij} = \begin{cases} s \cdot \cos\left(\frac{1.5\pi}{3k} |\mathbf{r}_{ji}|\right) \frac{\mathbf{r}_{ji}}{|\mathbf{r}_{ji}|} & \text{for } |\mathbf{r}_{ji}| \leq h \\ 0 & \text{for } |\mathbf{r}_{ji}| > h \end{cases} \quad (5)$$

s : interaction strength that can either describe solid-fluid s_{sf} or fluid-fluid interactions s_{ff}

III. Model calibration

- The static and dynamic contact angle control gravity-driven free-surface flow
- Critical calibration parameters: (a) fluid-fluid s_{ff} , (b) solid-fluid s_{sf} interaction strength, (c) speed of sound c_0 and (d) friction coefficient β

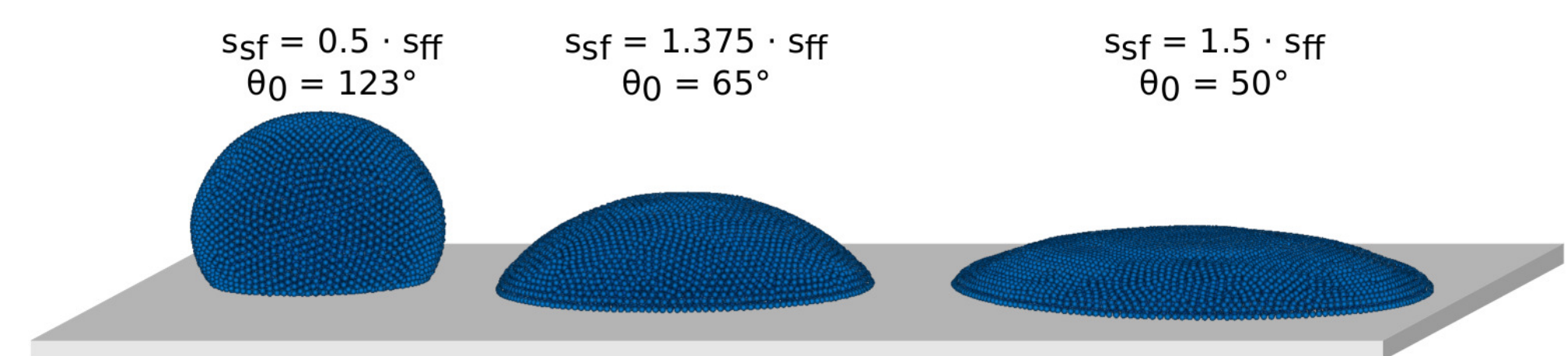


Figure 1: Contact angles formed by sessile droplets in SPH.

Surface tension

- Cohesive forces naturally created by s_{ff} and the EOS
- Young-Laplace Law

$$\sigma = \frac{R_{eq} \Delta P}{2} \quad (6)$$

R_{eq} : radius at equilibrium σ : surface tension
 ΔP : pressure difference

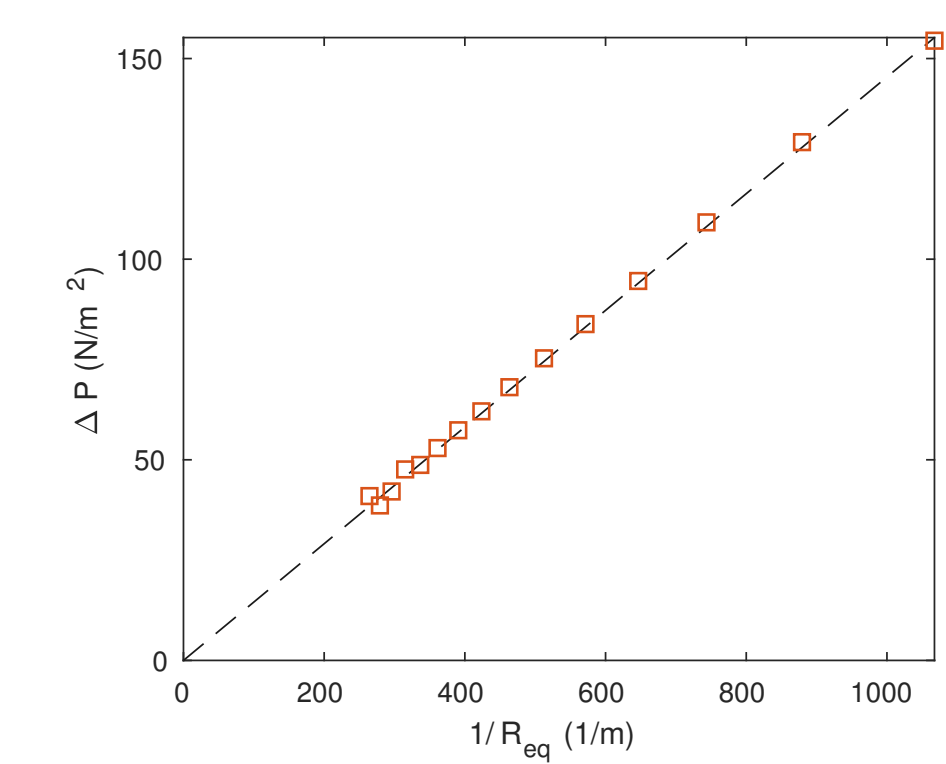


Figure 2: Pressure gradient ΔP of a simulated droplet under zero gravity

Static contact angle

- Utilized to implement different wetting characteristics (fig. 1)
- Droplets on acrylic glass matching goniometer measurements ($\sigma = 65^\circ$)

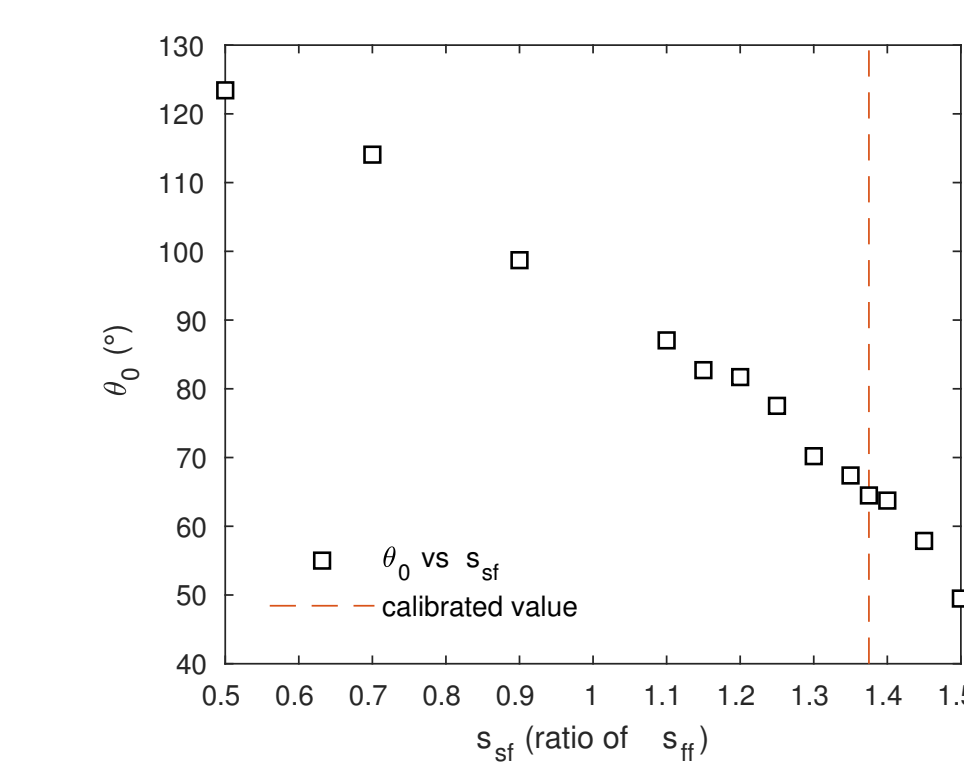


Figure 3: Numerical dependence of static contact angle θ_0 and s_{sf}

IV. Single-inlet partitioning dynamics

Model geometry

- Adjustment of aperture d_f and offset d_{off} by shifting the lower cube (fig. 4).
- Fluid masses are measured in the domains R_1 , R_2 and R_3 .

General observations

- Small droplets may not overcome discontinuities (Fig. 5a)
- Medium sized droplets get fully trapped in horizontal fracture (Fig. 5b)

- Large droplets have a more focused and enhanced momentum, allowing the droplet to hydraulically connect to the lower horizontal fracture wall (Fig. 5c,d,e)

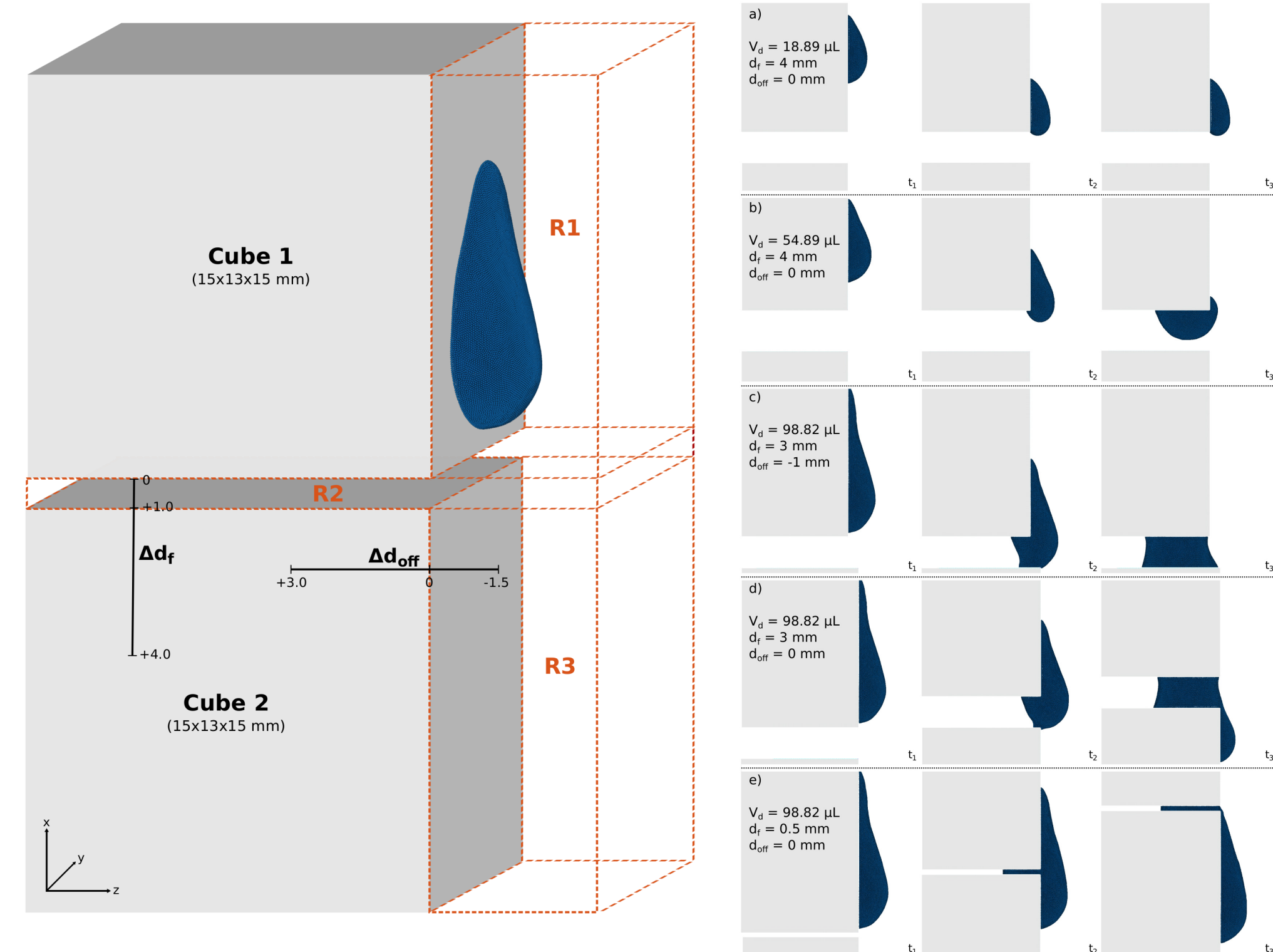


Figure 4: Morphology of the orthogonal fracture intersection in SPH.

Influence of fracture geometry

- Positive ($54\mu\text{L} \leq V < 88\mu\text{L}$) and negative offsets inhibit vertical flow (fig. 7). Washburn-type fracture inflow occurs.
- Higher accumulation of water in the horizontal fracture domain with increasing aperture d_f ($V \geq 54\mu\text{L}$)(fig. 7).
- Small droplets ($V < 54$) may hydraulically connect to the lower horizontal fracture wall (when d_f is very small)

