

1        **Subsurface Structures Around the Subducting Seamount Illuminated by**  
2        **Local Earthquakes at the Off-Ibaraki Region, Southern Japan Trench**

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4        **Shinji Yoneshima<sup>1</sup>, Kimihiro Mochizuki<sup>1</sup>, Tomoaki Yamada<sup>1</sup>, and Masanao Shinohara<sup>1</sup>**

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9  
10      **Key Points:**

- 11            • Over 20,000 events are determined using Ocean Bottom Seismometers around the  
12            subducting seamount.
- 13            • Small events and shallow tectonic tremor are spatially complementary with each other  
14            bounded by the updip limit of the seismogenic zone.
- 15            • Two seismically active interfaces are identified around the top of the oceanic crust and  
16            below it.
- 17

**18 Abstract**

19 The off-Ibaraki region is a convergent margin at which a seamount subducts. An intensive event  
20 location was performed around the subducting seamount to reveal the regional seismotectonics of  
21 this region. By applying a migration-based event location to an Ocean Bottom Seismic network  
22 record of both P- and S-waves, over 20,000 events were determined in the off-Ibaraki region below  
23 ~M4. The seismicity showed clear spatiotemporal patterns enough to identify the seismicity  
24 changes and geometry of the interface. At the updip side, the shallow tectonic tremors and  
25 earthquakes are shown to be spatially complementary bounded by an updip limit of the  
26 seismogenic zone. At the downdip side, a semicircular low-seismicity zone was identified, which  
27 is possibly a rupture area of the Mw7.9 event. The event depth profile exhibited a gently sloped  
28 planar downdip interface subparallel to the subducting slab. This plane appears to be stably active  
29 from 2008 to 2011. Comparison with the active source seismic survey profiles exhibits that this  
30 planar downdip interface is several kilometers deeper than the top of the oceanic crust. After the  
31 Mw7.9 event, a high-angle downdip seismic interface was activated above the planar interface.  
32 Further, below the planar downdip interface, broadly scattered events occurred with a swarm  
33 manner. We successfully illuminated the complicated subsurface structures around the subducting  
34 seamount. It is suggested that most of the event occur along or below the plate interface as the top  
35 of the oceanic crust.

36

**37 Plain Language Summary**

38 In the off-Ibaraki region, where a seamount subducts, a large number of small earthquakes  
39 occurred as aftershocks of the Mw7.9 thrust event. We applied a new event location technique to  
40 the Ocean Bottom Seismometer record, and we determined more than 20,000 of these aftershocks.  
41 The obtained seismicity shows that the small earthquakes and tectonic tremors are located close to  
42 each other with little spatial gap. At the downdip portion, a semicircular low seismicity zone was  
43 identified, possibly a rupture area of the Mw7.9 event. Along the depth cross section, a simple  
44 planar downdip seismic plane was identified where the seismicity has been stably high from 2008  
45 to 2011. After the Mw7.9 event, above the planar downdip interface, a high-angle downdip seismic  
46 plane was activated at around the depth of the plate interface. Below the planar downdip interface,  
47 earthquakes occurred with a swarm manner. We successfully illuminated the complicated  
48 subsurface structures around the subducting seamount. This planar seismic plane is several  
49 kilometers deeper than the top of the oceanic crust. Our results suggest that most of the event occur  
50 along or below the plate interface as the top of the oceanic crust.

51

## 52 1 Introduction

### 53 1.1. Tectonics at the off-Ibaraki region

54 The off-Ibaraki region is a convergent margin located at the south of northeastern Japan.  
55 Accompanying the subduction of the North Pacific Plate beneath the North American plate, M6 to  
56 M7 events occurs periodically with an interval of approximately a few decades (Earthquake  
57 Research Committee, 2012; Matsumura, 2010). In early 2000, an intensive seismic survey was  
58 performed in this region, and the subducting seamount was identified (Mochizuki et al., 2008).  
59 Subsequently, attention has been devoted to this region regarding the tectonics of the seamount  
60 subduction, focusing on the role of the seamount subduction for large earthquakes (Bassett et al.,  
61 2015; Kubo et al., 2013; Kubo & Nishikawa, 2020; Nakatani et al., 2015; Sun et al., 2020; Wang  
62 & Bilek, 2014). Wang and Bilek (2014) suggested the presence of microfractures off the plate  
63 interface as a result of the seamount subduction.

64 In spite of these studies, the possible consequence of the seamount subduction to the  
65 occurrence of earthquakes is not well constrained yet. Sun et al. (2020) incorporated the small  
66 earthquake distribution from Ocean Bottom Seismometer (OBSs) and showed that part of the  
67 small earthquakes occurs at the wake of the seamount. Nevertheless, because the number of events  
68 is still limited and also the event location uses one-dimensional velocity structure (1-D), it is still  
69 insufficient to discuss the depth of these events with respect to the plate interface. The accurate  
70 event locations for large number of earthquakes are required to further develop the understanding  
71 of the seamount subduction tectonics with respect to earthquakes.

72 In 2011, as the largest aftershock of the 2011 Tohoku-oki earthquake, an Mw7.9 event  
73 occurred approximately 30 min after the mainshock. The rupture was initiated at the deeper portion  
74 and propagated toward updip (Honda et al., 2013; Kubo et al., 2013; Suzuki et al., 2020). The  
75 rupture terminated around the rim of the subducting seamount (Kubo et al., 2013). Nakatani et al.  
76 (2015) determined the epicenters of events. They reported that the seismicity was considerably  
77 enhanced after the Mw7.9 event using OBSs, especially at the northern part of the seamount. The  
78 located events, however, do not provide the event depth information, since events were constrained  
79 on the plate interface of the three-dimensional (3-D) velocity model used for the event location.  
80 The reliable 3-D event locations using OBSs are expected to provide an integrated understanding  
81 of the regional tectonics regarding the large event and subducting seamount as well as the  
82 occurrence of shallow tectonic tremors. This study reveals the precise seismicity of small  
83 earthquakes at the off-Ibaraki region and discusses its relationship with other tectonics, including  
84 the shallow tectonic tremor, seamount, and Mw7.9 event, around the off-Ibaraki region.

85 As another remarkable tectonic feature of this region, several years after the Mw7.9 event,  
86 a shallow tectonic tremor was identified at the off-Ibaraki region in and around the subducting  
87 seamount (Nishikawa et al., 2019). Kubo and Nishikawa (2020) discussed that the rupture of the  
88 Mw7.9 event in 2011 terminated at the forefront side of the seamount, and the shallow tectonic  
89 tremor begin to occur at the updip. Sun et al. (2020) showed that small earthquakes are present  
90 between the coseismic rupture area of the Mw7.9 event and the shallow tectonic tremor. Sun et al.  
91 (2020) also suggested that the rupture termination can be attributed to the increased effective  
92 normal stress at the forefront of the subducting seamount acting as a barrier.

93 To better elucidate the seamount subduction tectonics, a large number of accurately located  
94 small earthquakes are definitely helpful. For example, previous studies suggested that micro  
95 fractures in the overriding plate may evolve owing to the seamount subduction (e.g., Chesley et  
96 al., 2021; Wang & Bilek, 2011, 2014). Shaddox and Schwartz (2019) reported the occurrence of

97 highly correlated earthquakes above the plate boundary at the northern Hikurangi Margin. Recent  
98 studies showed that event locations are broadly scattered in the oceanic crust around the subducting  
99 seamount (Central Ecuador by Collot et al., 2017; Northern Hikurangi Margin by Yarce et al.,  
100 2019). The identification of events off the plate interface to illuminate subsurface structures is  
101 essential to further understand the seamount subduction tectonics.  
102

## 103 1.2. Migration-based event location workflow

104 In order to accurately determine the location of small earthquakes, the use of the OBSs are  
105 necessary. One of the advantages of using OBSs to monitor subduction zone earthquakes is fine  
106 event location accuracy beneath or in the vicinity of an OBS network around the seismogenic zone  
107 because the location error tends to be smaller beneath or around the seismic network (Bartal et al.,  
108 2000; Lilwall & Francis, 1978; Uhrhammer, 1980). By using OBSs, a variety of hypocenter  
109 distribution patterns has been reported in subduction zones (Hino et al., 2000, 2009; León-Ríos et  
110 al., 2019; Mochizuki et al., 2010; Sachpazi et al., 2020; Sakai et al., 2005; Sgroi et al., 2021;  
111 Shinohara et al., 2005; Yarce et al., 2019; Yoneshima et al., 2005).

112 To deal with large numbers of events efficiently, Yoneshima and Mochizuki (2021)  
113 proposed a migration-based event location method without manually picking arrival times. This  
114 method is rather versatile for any seismological domains but particularly demonstrated the OBS's  
115 record at the off-Ibaraki region for events occurred during October 2010–February 2011. This  
116 method enabled the processing of quite a few events in a reasonable amount of effort and time. At  
117 present, this method is not applied yet to large numbers of dataset. This study will demonstrate  
118 this event location method for the first time to the large numbers of real event data by Yoneshima  
119 and Mochizuki (2021).

120 On the other hand, for the event location accuracy as a bias from the true event location,  
121 the accurate input velocity model is crucial. However, constructing a reliable velocity model has  
122 still been a challenge, especially for the S-wave velocity model. For the migration-based event  
123 location method, an accurate 3-D velocity model is particularly desired for better beamforming  
124 perspective. For obtaining a P-wave velocity structure, active source seismic surveys such as wide-  
125 angle refraction surveys or seismic tomography can provide a detailed two-dimensional (2-D) P-  
126 wave velocity structure (Arai et al., 2017; Nakahigashi et al., 2012; Nakanishi et al., 2008) or  
127 occasionally a 3-D velocity structure (Obana et al., 2009) can be used. Such a fine velocity model  
128 directly compares the event location with velocity structure (Arai et al., 2017). While the P-wave  
129 velocity structure is well determined, the S-wave velocity structure remains uncertain.

130 In case of a S-wave velocity structure, usually, a constant  $V_p/V_s$  ratio is assigned to the P-  
131 wave velocity model, such as 1.73 for the entire velocity model, including a sediment layer while  
132 applying a station correction (e.g., Yoneshima et al., 2005). This naïve assumption of  $V_p/V_s$  value  
133 potentially results in the location bias when the assumed  $V_p/V_s$  ratio is departed from the true  
134 value. Therefore, a reliable initial S-wave velocity model is needed for both the migration-based  
135 event location and accurate event location purposes. Recently, Yamaya et al. (2021) derived the  
136 S-wave velocity structure using Rayleigh waves for sediment layer and the upper crust. To cover  
137 wider depth range for the entire event location depths, the present study estimates an average  
138  $V_p/V_s$  ratio below the basement of the sediment layer (hereafter denoted as  $K_1$ ) in order to obtain  
139 the representative value of the  $V_p/V_s$  ratio below the sediment layer.  
140

141           1.3.   Objective of this study

142           The present study addresses two objectives. First, this study defines a comprehensive event  
143 location workflow of the migration-based event location, and demonstrates the method to large  
144 numbers of events at the off-Ibaraki region in and around a subducting seamount (Mochizuki et  
145 al., 2008). This workflow contains the determination of the  $K_1$  for the accurate event location.  
146 Second, we describe the spatiotemporal seismicity patterns at the off-Ibaraki region and its  
147 relationships with other tectonics such as the seamount, Mw7.9 event, and the shallow tectonic  
148 tremor. Based on the obtained spatiotemporal seismicity patterns, the illuminated subsurface  
149 structures associated with the regional tectonics is discussed.

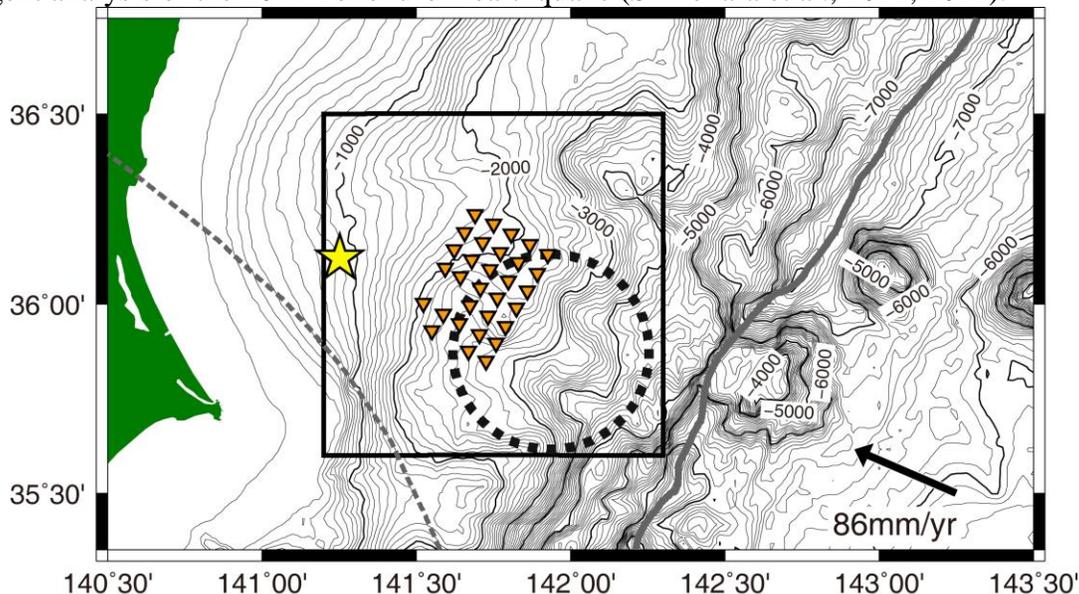
150

151 **2 Data**

## 152 2.1. OBS experiment

153 The OBS experiment was conducted from 17 October 2010 to 19 September 2011 (~11  
 154 months) at the off-Ibaraki region. The layout of the OBS network is shown in Figure 1. In total,  
 155 31 OBSs were deployed, equipped with three-component 1-Hz geophones. The seismic record was  
 156 acquired continuously at a 200-Hz sampling rate. As a notable feature of this OBS experiment, the  
 157 OBS network geometry was configured with a high-density spacing of 6 km. By contrast, the usual  
 158 OBS seismic spacing is ~20–30 km (e.g. Shinohara et al., 2012). This high-density OBS network  
 159 is expected to detect small and shallow earthquakes in the overriding plate and events along and  
 160 below the plate boundary. The other notable feature of this OBS experiment is that around the  
 161 middle of the OBS experiment, the 2011 Tohoku-oki earthquakes occurred, with the largest  
 162 aftershock of Mw7.9 event in the study area. The seismicity was continuously monitored before  
 163 and after the 2011 Tohoku-oki earthquake (Nakatani et al., 2015).

164 The overall spatiotemporal OBS availability is good regarding the 2011 Tohoku-oki  
 165 earthquake. The observation period for each OBS is mainly divided into two groups: one  
 166 spanning the entire period and the other started monitoring in the middle of February 2011 (Figure  
 167 S1). Exceptionally, some OBSs were retrieved in March 2011 owing to the occurrence and  
 168 emergent analysis of the 2011 Tohoku-oki earthquake (Shinohara et al., 2011, 2012).

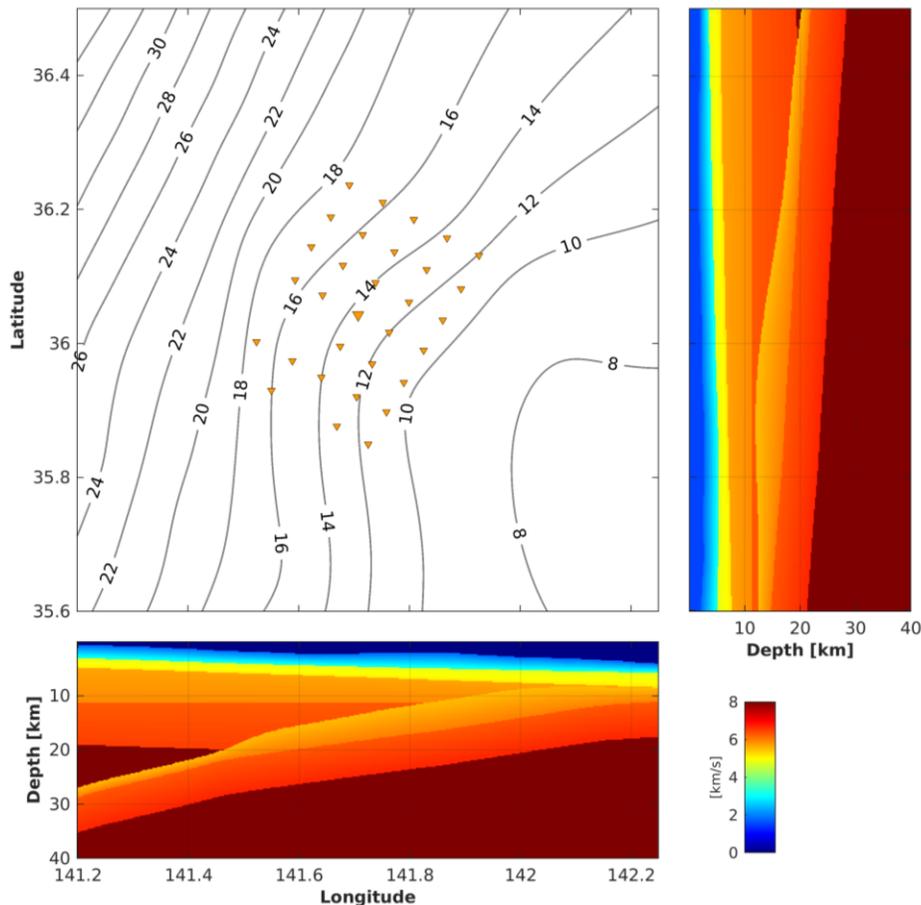


169 Figure 1. Map view of the study area at the off-Ibaraki region. The black rectangle represents the  
 170 study area of this study. The inverted triangles denote the OBSs. The bold dashed circle presents  
 171 the subducting seamount (Mochizuki et al., 2008). The yellow star represents the JMA hypocenter  
 172 of the Mw7.9 event. The dashed gray line shows the PHS limit (Nakajima et al., 2009). The bold  
 173 dark gray line presents the trench axis. The bold arrow and the value denote the relative plate  
 174 motion and the convergence rate between the Pacific plate and the North American plate (DeMets  
 175 et al., 1990).  
 176  
 177

## 178 2.2. 3-D velocity model

179 The P-wave 3-D velocity model is shown in Figure 2, together with the OBS locations.  
 180 This model is constructed after compiling the existing seismic velocity surveys: wide-angle  
 181 refraction surveys conducted by Miura et al. (2003), Nakahigashi et al. (2012) and land seismic  
 182 tomography reported by Matsubara and Obara (2011). A plate interface depth map with a  
 183 subducting seamount is developed on the basis of the report by Shinohara et al. (2011) and  
 184 superimposed with the seamount depth obtained from the report by Mochizuki et al. (2008). The  
 185 horizontal and vertical grid sizes of the velocity model are 400 and 200 m, respectively.

186 The S-wave velocity structure was addressed separately in two parts. Each set had a  
 187 different  $V_p/V_s$  ratio: one in the sediment layer above the basement (hereafter denoted as  $K_0$ ) and  
 188 the other in the consolidated layer below the basement ( $K_1$ ). The  $K_0$  was estimated for each OBS  
 189 site using the PS-converted waves and is shown in Figure S2. This estimated  $K_0$  was directly  
 190 embedded into the S-wave velocity structure, while the conventional method used a constant  
 191  $V_p/V_s$  ratio velocity model to apply a static station correction. Below the basement, in the  
 192 consolidated layer, a uniform  $V_p/V_s$  ratio value of 1.73 was tentatively assumed as  $K_1$ . After  
 193 setting up the velocity model, the synthetic travel times for P- and S-wave were computed by  
 194 solving the Eikonal equation using a fast-marching method (de Kool et al., 2006) following the  
 195 report by Yoneshima and Mochizuki (2021). This tentative velocity structure is later optimized  
 196 and its details are described in the next section.



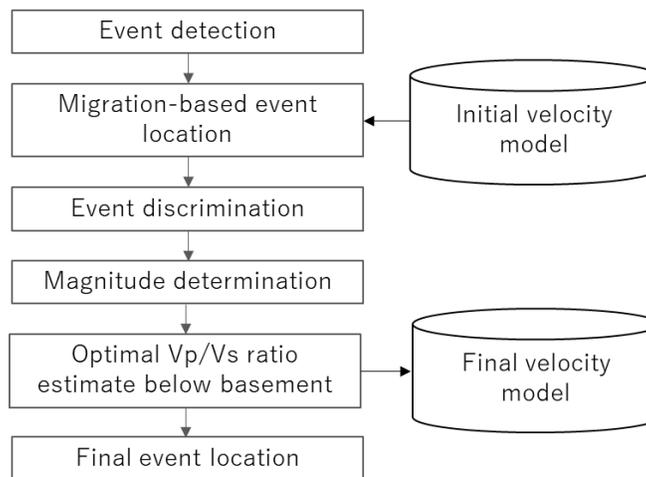
197 Figure 2. Velocity structure model used in this study. (Top left) Plain map view with the plate  
 198 depth contour, with labels presented in kilometers. The inverted triangles denote the OBS locations.  
 199

200 Station names are shown in Figure S1, namely from SMD001 to SMD035. The large inverted  
201 triangle denotes the reference OBS of SMD018 as the center of the OBS array for the cross-section  
202 views in the bottom and right panel. (Bottom and right) Cross sections of the P-wave velocity  
203 structure intersecting the reference SMD018.

204

### 205 3. Comprehensive workflow for migration-based event location

206 This section describes overall workflow of the event location. This workflow is particularly  
 207 defined for the migration-based event location to reliably determine the event location, including  
 208 the optimization of the  $V_p/V_s$  ratio of the input velocity model. Figure 3 shows the entire workflow  
 209 of the event location processing from the event detection to event finalization.  
 210



211 Figure 3. Entire workflow to process a migration-based event location, including the  $V_p/V_s$  ratio  
 212 optimization of a velocity model.  
 213  
 214

#### 215 3.1. Event location procedure

216 This section describes the event location procedure up to the finalization of the events,  
 217 including the optimization of the  $K_1$ . First, event detection is performed. For the event detection,  
 218 the present study applied a conventional short-time-average/long-term-average (STA/LTA)  
 219 triggering method combined with an amplitude threshold. The amplitude threshold was set to  $5e^{-6}$   
 220 m/s. In total, 87,084 events were detected during the observation period. Note that the seismicity  
 221 at the Tohoku-oki region was quite high during the OBS experiment. This resulted in the  
 222 contamination of these regional events outside the study area, together with the detection of local  
 223 events in the study area. At this stage, both local and nonlocal events are included in the event list  
 224 that are discriminated later.

225 After the event detection, a migration-based event location was applied for all the detected  
 226 events by applying the method proposed by Yoneshima and Mochizuki (2021), including a station  
 227 correction and an error bar calculation. A 4-Hz high-pass filter was used to suppress the low-  
 228 frequency noise. Using the synthetic travel times computed in the previous section, the migration-  
 229 based event location method was applied following the report by Yoneshima and Mochizuki  
 230 (2021). After the event location of all the detected events, event discrimination was performed to  
 231 reject the nonlocal events such as the regional/teleseismic events. This event discrimination was  
 232 performed via a visual inspection of waveforms by human eyes. Events that are located farther  
 233 than the trench axis were also excluded. After rejecting the nonlocal events, 22,562 events were  
 234 identified as the local events in the study area. The final event dataset was selected with error bars  
 235 of  $<6$  km as a 95% confidence interval of the semimajor axis or the error bar. The number of  
 236 selected events was 21,242. The waveform example is shown in Figure S3.

237 Then we determined event magnitudes using Watanabe's formula (Watanabe, 1971). This  
 238 method is widely applied in the OBS study (e.g. Obana et al., 2021). A magnitude correction is  
 239 performed using the JMA event magnitudes. In total, 3448 JMA events were matched with the  
 240 OBS event list. The magnitude correction was performed via a simple bias correction,  
 241 parameterized by a constant offset (Figure S4). Notably, the event magnitude tends to be saturated  
 242 at OBS magnitude  $\approx 4$  because of the S-wave amplitude saturation. When estimating a correction  
 243 value, these large event magnitudes were rejected (the dark gray stars presented in Figure 4). The  
 244 corrected event magnitude equation is obtained as follows:

$$245 \quad M_{OBS}^{corrected} = \frac{\log \max(A_x, A_y, A_z) + 1.73 \log r + 2.5}{0.85} - 1.75. \quad (1)$$

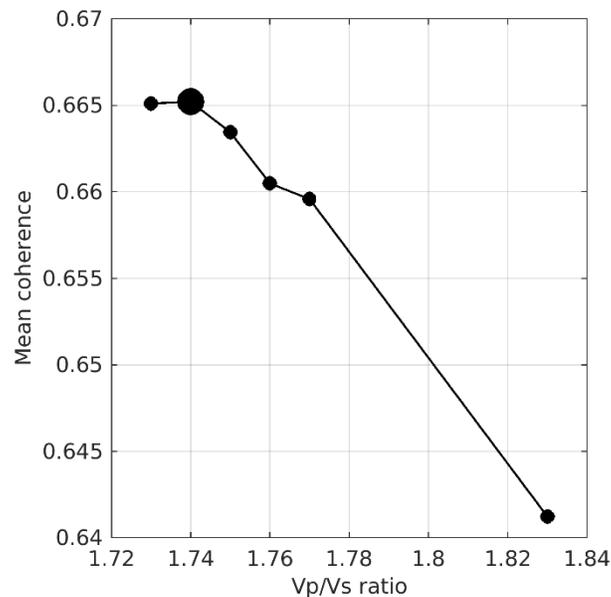
246 This equation applies to all the local events that are not listed in the JMA catalog.

247 Then, we optimized the velocity model particularly  $K_1$  to obtain the accurate event location.  
 248 As a procedure, we applied a 1-parameter grid search inversion to find the optimal  $K_1$ . For the  
 249 objective function, we used a coherence value using both P- and S-wave (Grigoli et al., 2014;  
 250 Yoneshima & Mochizuki, 2021). The objective function is defined as follows as a summation for  
 251 the number of events;

$$252 \quad f(K_1) = \frac{1}{ne} \sum_{i=1}^{ne} coherence_i(x, y, z, T0; K_1), \quad (2)$$

253 , where  $ne$  is the number of events,  $x, y, z, T0$ , are the hypocenter parameters, and  $K_1$  is the  
 254 average  $V_p/V_s$  ratio below the basement of the sediment layer. A maximum objective function in  
 255 equation (2) is sought through a grid search in the range from 1.73 to 1.83. For the inversion, we  
 256 selected 1050 events to reduce the computation time. These events were sampled from wide range  
 257 of the study area to avoid the spatial bias. After the grid search inversion, the optimal  $K_1$  was  
 258 estimated as 1.74 (Figure 4). Using the estimated value, the final event locations is determined,  
 259 applying to all the local event dataset.

260



261

262 Figure 4. The 1-parameter grid search inversion for coherence. Small solid circles are the tested  
 263 average  $V_p/V_s$  ratio below the basement of the sediment layer. The large solid circle is the  
 264 optimal value.

265

### 266 3.2. Event detection limit analysis

267 To facilitate the identification of the spatial variation of the seismicity in the study area, we  
 268 evaluated the event detection capability for both upper and lower limit.

#### 269 3.2.1. Upper detection limit

270 The OBS event magnitude begins to saturate at  $M \approx 4$ , as shown in Figure 5. This is because  
 271 of the S-wave saturation as its amplitude is approximately one order of magnitude greater than that  
 272 of the P-wave. This waveform saturation constrains the upper limit of the event detection.

#### 273 3.2.2. Lower detection limit

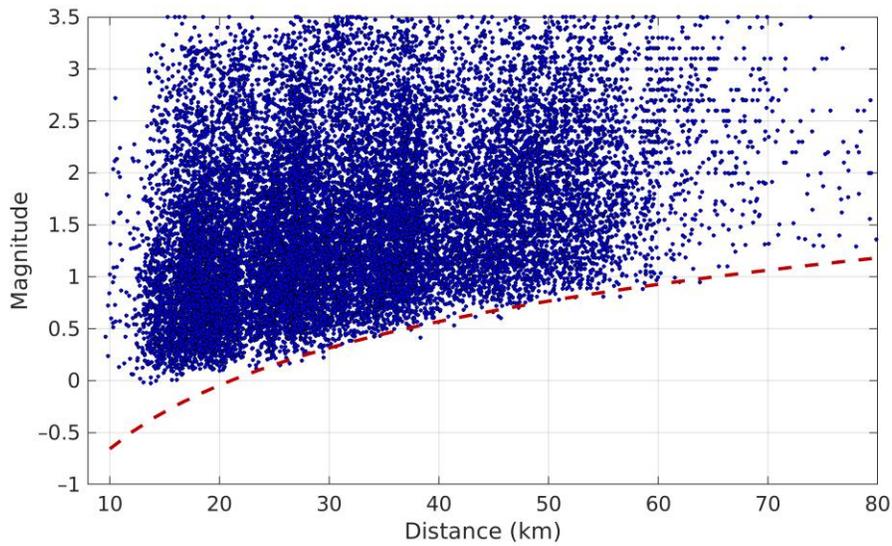
274 The lower limit of the event detection is known to be a function of the focal distance.  
 275 Accordingly, the lower detection limit is not a constant value in general. We defined the lower  
 276 detection limit at the furthestmost location of the study area from the center of the OBS network.

277 The relationship between the waveform amplitude and event magnitude in this study was  
 278 given in equation (1). While this equation is originally used for determining the event magnitude,  
 279 we use this formula to evaluate the magnitude detection limit for a given waveform amplitude.  
 280 Using Watanabe's formula, the lower limit of event magnitude detection is given as

$$281 \quad M^{lower} = \frac{\log(A^{threshold}) + 1.73 \log r + 2.5}{0.85} - 1.75, \quad (3)$$

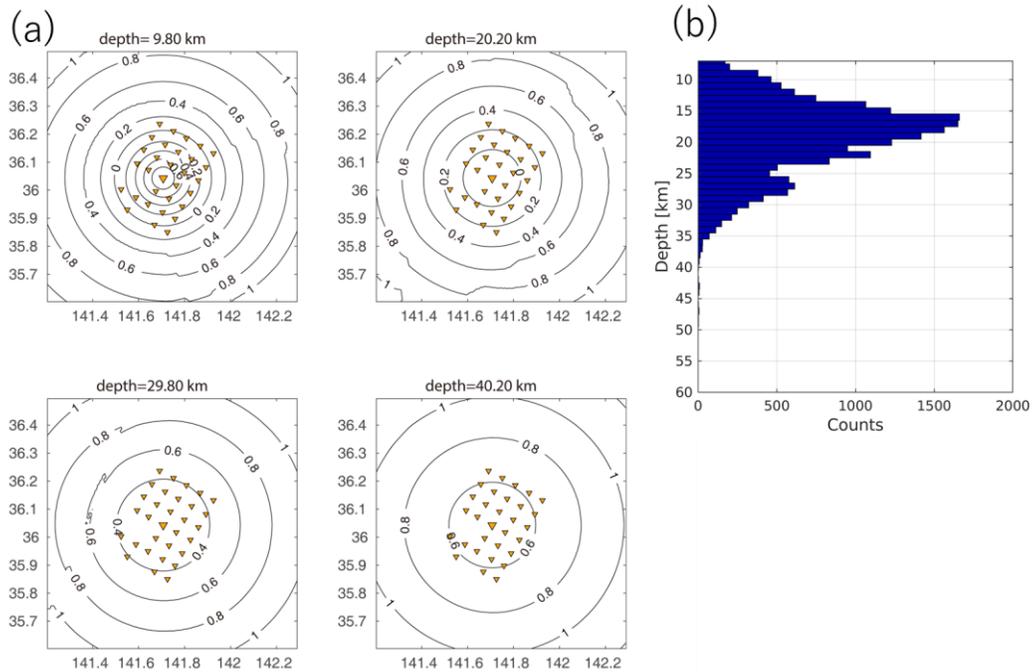
282 where  $M^{lower}$ ,  $A^{threshold}$ , and  $r$  are the lower limit of event magnitude, the amplitude threshold  
 283 at the time of the event detection, and the focal distance, respectively. When the focal distance is  
 284 defined from the center of the OBS network to the event along the raypath of the given velocity  
 285 models,  $M^{lower}$  is readily calculated. Figure 5 compares the event data and curve obtained using  
 286 equation (3). A raypath length of the P-wave from the source to SMD018 was used for the distance  
 287 calculation. The real event-detection lower limit agrees well with the theoretical curve obtained  
 288 using equation (3).\

289



290  
 291 Figure 5. Event magnitudes and focal distance from SMD018. The blue dots represent the located  
 292 events. The dashed red curve is the event detection curve obtained using equation (3).  
 293

294 Next, this event-detection lower limit was projected into the space in the study area. Figure  
 295 6 shows that ~40 km is the lower limit of the event depth distribution in this study area. At a depth  
 296 of 40.2 km, it is shown that the event detection at the corner of the plan view is approximately M1.



297  
 298 Figure 6. (a) Spatial variation of the event-detection lower limit. Plan view for depth = 9.8, 20.2,  
 299 29.8, and 40.2 km. (b) Event depth histogram.  
 300

301 One factor that potentially biases the detection lower limit is the effect of radiation pattern:  
 302 when a double couple or any angular-dependent energy is radiated from a source, it will deteriorate

303 the magnitude estimate. We believe this effect is not severe because it is reported that for a high-  
304 frequency content waveform in the order of Hertz or greater, like observed in this study, the  
305 radiation pattern of P- and S-wave becomes mild because of the scattering effect (Takemura et al.,  
306 2015, 2016). Therefore, we conclude that the event-detection lower limit of the study area is  
307 approximately M1 in this study area.

308 The temporal variation of the event magnitude distribution is examined using the M-T  
309 diagram (Figure S5). At the time of the Tohoku-oki earthquake on 11 March 2011, the event  
310 detection capability was degraded until the end of March. This is because of the occurrence of  
311 tremendous amounts of aftershocks in a swarm manner inside and outside the study area, resulting  
312 in a simultaneous temporal overlap of earthquakes recorded using OBS. It should be noted that  
313 even in this swarm period, there is no substantial change of error bar, suggesting that the quality  
314 of the successfully located event is not degraded over time.

315

316 **4. Results**

317 The final result of the migration-based event distribution is shown in Figure 7. As final  
 318 qualification, we adopted events within the  $\pm 6$ -km error bar as the 95% confidence interval. As a  
 319 result, in total 21,242 events were successfully located. Among these 21,242 events, 93.6 % of  
 320 events are less than  $\pm 2.0$  km of error bar (Figure S6).  
 321

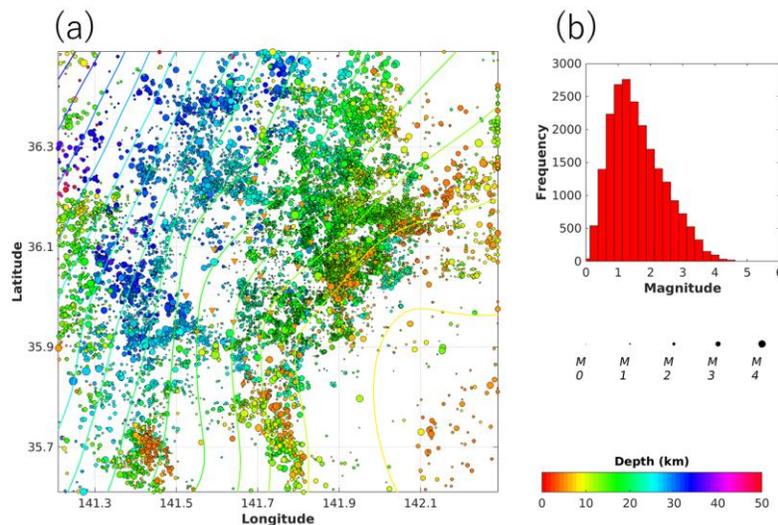
322 **4.1. Spatial distribution of hypocenters**

323 The seismicity exhibits an evident spatial pattern where the seismicity is high or low in the  
 324 study area. Some of the low-seismicity zones have a patchy circular shape. Some of these low  
 325 seismicity zones are located at the seaward outside the OBS network. Notably, as has been  
 326 evaluated, the event-detection lower limit is approximately M1 within the entire study area down  
 327 to 40-km depth; hence, the presence of a low-seismicity zone is real during the observation period.  
 328 Such spatial variation of the seismicity is more visible in the heat map of the event counts and  
 329 energy count (Figure 8).

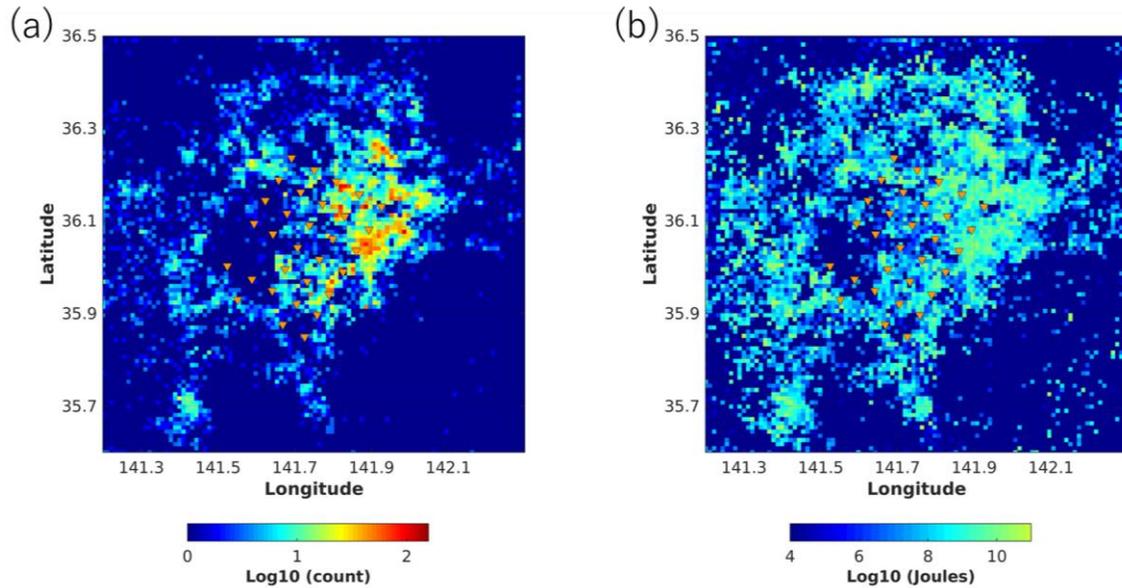
330 The most remarkable low-seismicity zone lies beneath the OBS network with a  
 331 semicircular shape. The size of this low-seismicity zone is  $\sim 30 \times 25$  km which is comparable with  
 332 the size of the OBS network. Remarkably, even after the largest Mw7.9 aftershock in the study  
 333 area, considerably low seismicity was observed during the observation period.

334 The seismicity is high toward the updip from this semicircular low-seismicity zone. The  
 335 seismicity is relatively higher on the northern side compared with the southern side. The event  
 336 depth of this high-seismicity region is  $\sim 15$ – $20$  km, which is significantly greater than the plate  
 337 interface depth at approximately 10 km. This event depth offset from the plate interface is  
 338 discussed in detail in the next Discussion section.

339 Further seaward from this high-seismicity zone, the seismicity becomes quite low. The  
 340 boundary of this seismicity change is subparallel with the isocontour of the plate interface depth  
 341 of  $\sim 10$  km. We define this seismicity change boundary at  $\sim 10$  km plate interface depth as the updip  
 342 limit of the seismogenic zone.



344 Figure 7. (a) Plan view of the final hypocenter distribution using the estimated  $V_p/V_s$  ratio. The  
 345 solid colored circles represent the events according to the event depth. The solid contour lines  
 346 present the depth of the plate boundary of the velocity model (Figure 2). The events presented in  
 347 this plan view are plotted from deeper to shallower events. (b) Histogram of event magnitude.  
 348



349  
 350 Figure 8. (a) Heat map of the event distribution for a number of events. (b) Heat map of the sum  
 351 of event energy. The size of the grid is  $1 \text{ km} \times 1 \text{ km}$ .  
 352

#### 353 4.2. Seismicity change bounded by the occurrence of the Mw7.9 event

354 As shown in the M-T diagram presented in Figure S5, the seismicity was continuously  
 355 monitored before and after the 2011 Tohoku-oki earthquakes. This enables us to examine the  
 356 temporal variation of the seismicity.

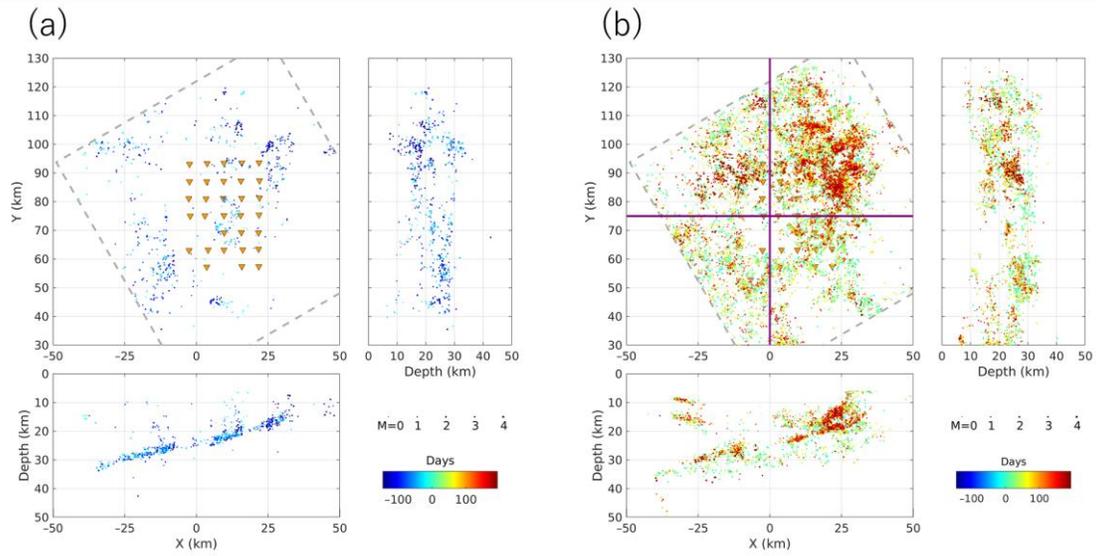
357 A temporal variation of the seismicity is shown in Figure 9. Before the occurrence of the  
 358 largest Mw7.9 aftershock, the event distribution showed a simple planar downdip trend. Hereafter  
 359 we call this interface the planar downdip interface. After the Mw7.9 event, the seismicity became  
 360 quite high and exhibited a significant depth variation. Especially, the seismicity was high for both  
 361 the shallower portion and a deeper portion from this dipping plane. This seismicity after the Mw7.9  
 362 event is consistent with the studies reported by Shinohara et al. (2011, 2012) (Figure S7).

363 The shallower portion of the activated seismicity after the Mw7.9 event shows a high-angle  
 364 dipping plane close to the updip limit of the seismogenic zone. This updip portion of the shallow  
 365 seismicity was steadily active from the Mw7.9 event till the end of the OBS experiment.

366 Meanwhile, for the deeper portion below the planar downdip interface, events are scattered  
 367 and distributed in a wide area from the updip to the downdip. Further, the seismicity activation of  
 368 this deeper portion was temporally limited: it became active only soon after the Mw7.9 event. Soon  
 369 after a few tens of days from the Mw7.9 event, this deeper portion seismicity from the downdip  
 370 plane became inactive.

371 In the next Discussion section, based on these new findings of these spatiotemporal  
 372 seismicity patterns, the seismotectonics at the off-Ibaraki region is discussed together with other  
 373 seismic and geophysical measurements in this region.

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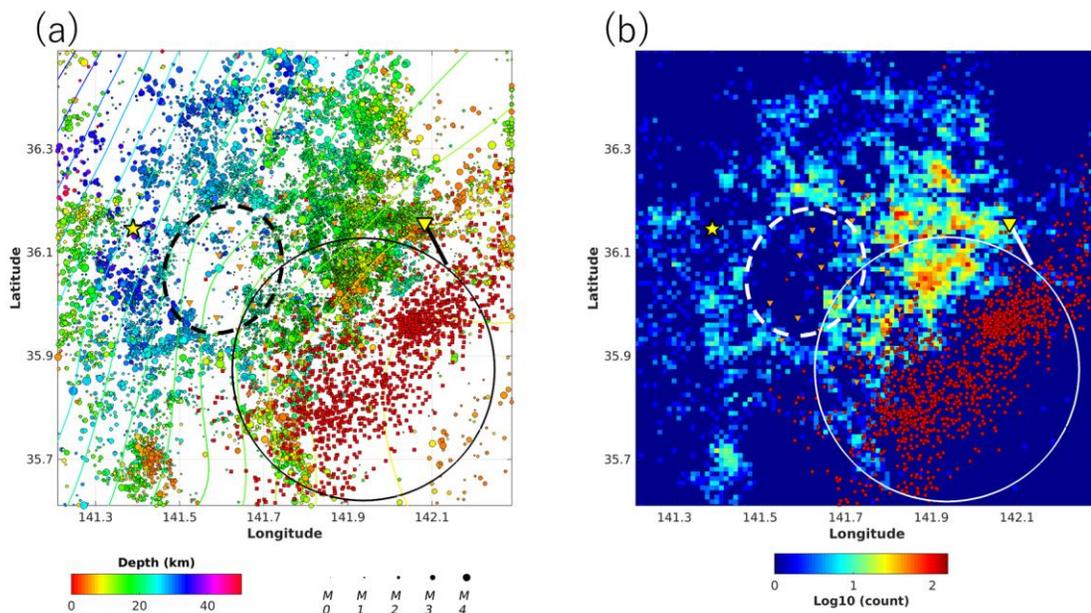
Figure 9. Cross-sectional view of the temporal seismicity variation. (a) Event locations before the Mw7.9 event. Entire spatial range of events was used for cross-section. The color of the events denotes the days after the Mw7.9 event. X is the downdip direction by rotating the horizontal axis by 30° in the anticlockwise direction. The gray dashed rectangular area is the region for cross sections. (b) Event locations after the Mw7.9 event. The purple cross lines are the center line for cross sections. Widths of cross sections in both the X and Y directions are each  $\pm 10$  km.

384 **5. Discussion**

385 This study determined >20,000 events in a subduction zone around the subducting  
 386 seamount with a high-density (~6-km spacing) OBS network. Most of the events were determined  
 387 within  $\pm 2$  km error bar. To the best of our knowledge, this is an unprecedentedly large number of  
 388 events by using temporal OBS experiments. This is owing to the dense OBS array, the occurrence  
 389 of quite a few aftershocks, and the development of an effective event location workflow. This  
 390 high-density event distribution allows us to identify the local spatial variation of the seismicity  
 391 with a 1-km grid interval (Figure 8). After the event detection capability analysis, low-seismicity  
 392 zones are securely identified in the range from approximately M1 to M4 in the study area. Further,  
 393 the resultant event distribution should be barely biased in space due to the optimization of  $K_1$ ;  
 394 therefore, the overall event depth distribution tends to be correct. In addition, the geometry of the  
 395 interface was reasonably figured out comprising of two distinct seismic interfaces.

396 These event data allow us to discuss the local seismicity pattern in time and space. The  
 397 unbiased event distribution enables us to compare with other geophysical survey results. Figure 10  
 398 shows the event distribution with the featured tectonics at the off-Ibaraki region: the subducting  
 399 seamount, relocated hypocenter of the Mw7.9 event by the present study, shallow tectonic tremor  
 400 from 2016 to 2018, and acoustic GPS (A-GPS) from 2012 to 2016.

401



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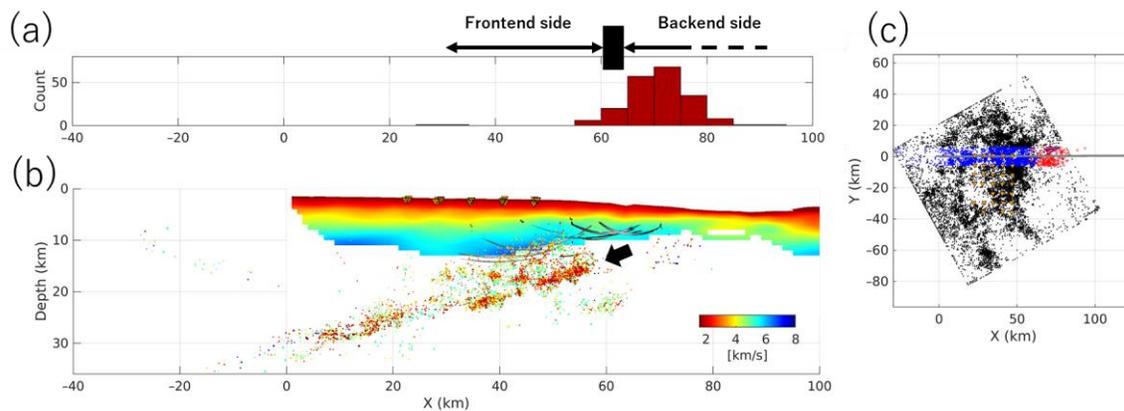
403 Figure 10. (a) Hypocenter distribution with other geophysical measurements. The solid circles  
 404 present the events colored according to event depth. The yellow star represents the relocated  
 405 hypocenter of the Mw7.9 event in this study. A manual time pick was made for this event. The red  
 406 squares denote the epicenter of the tectonic tremors reported by Nishikawa et al. (2019). The bold  
 407 dashed circle is the low seismicity zone identified in this study. The large black open circle marks  
 408 the subducting seamount reported by Mochizuki et al. (2008). The yellow inverted triangle shows  
 409 the location of A-GPS with a solid line of the displacement vector reported by Honsho et al. (2019).  
 410 (b) Heat map of the number of events on logarithmic scale. The large white open circle marks the  
 411 subducting seamount reported by Mochizuki et al. (2008). The white-dashed circle is the low

412 seismicity zone identified in this study. The yellow inverted triangle shows the location of A-GPS  
 413 with a solid white line of the displacement vector reported by Honsho et al. (2019). Other symbols  
 414 such as the hypocenter of the Mw7.9 event and the shallow tectonic tremor and the OBSs are  
 415 overlaid as same with (a).

416

417 The along-dip depth profiles of the event distribution along the seismic survey lines from  
 418 past researches are shown in Figures 11 and 12. Figure 11 presents the seismic profile of Line EW  
 419 reported by Mochizuki et al. (2008). Figure 12 shows the seismic survey Line 13 reported by Tsuru  
 420 et al. (2002), located ~30-km south of Line EW. Both seismic profiles clarify the depth of plate  
 421 boundary at the updip limit of the seismogenic zone. Each figure exhibits that the shallow tectonic  
 422 tremors and local events are spatially separated at the updip limit of the seismogenic zone. Most  
 423 remarkably, it is shown that the majority of the events are distributed several kilometers deeper  
 424 than the plate interface. The error ellipsoids of each seismic line presented in Figures 11 and 12  
 425 are shown in Figures S8 and S9, respectively. Around the updip limit of the seismogenic zone, the  
 426 maximum error bar as the 68% confident interval is ~0.4 km, which is sufficiently smaller than  
 427 the event depth offset from the plate interface. Note that all of the tectonic features shown in Figure  
 428 10 come from the ocean bottom or marine seismic surveys. No results from a sole land seismic  
 429 network are used in Figure 10 to avoid the misinterpretation of the spatial interrelationships.  
 430 Further details of the tectonics at the off-Ibaraki region are discussed in the subsequent subsections.

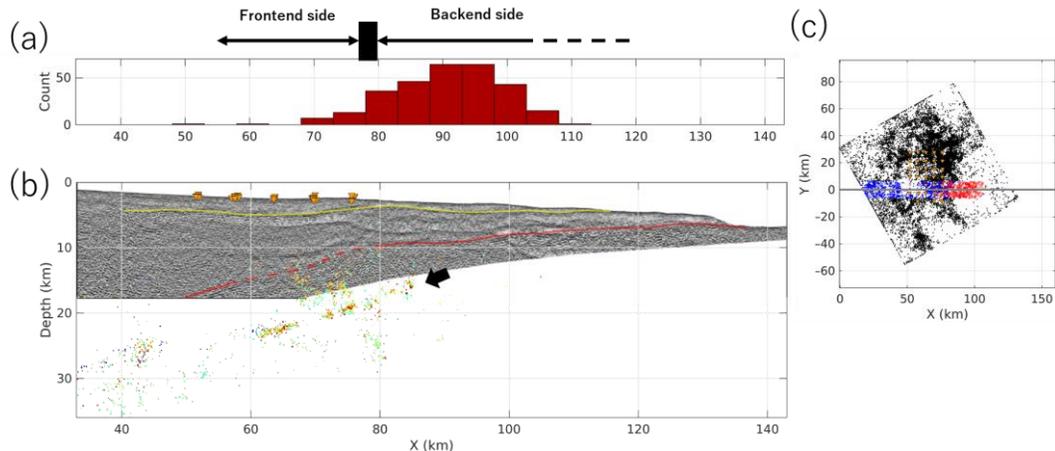
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432

433 Figure 11. Integrated cross-sectional view at Line EW reported by Mochizuki et al. (2008). (a)  
 434 Histogram of the number of tectonic tremors with Line EW (after the report by Nishikawa et al.,  
 435 2019). The thick vertical bar denotes the coarse location of the top of the seamount. (b) P-wave  
 436 velocity structure after Mochizuki et al. (2008). The gray convex curves present the intensity of  
 437 the migrated reflection arrival times from the plate interface (Mochizuki et al., 2008). Hypocenters  
 438 along Line EW from the present study are overlaid. The thick black arrow points to the planar  
 439 downdip interface. The orange inverted triangles present the locations of OBSs. Colors of  
 440 hypocenters show the days after the Mw7.9 event, as shown in Figure 9. (c) Plan view parallel to  
 441 the survey line (X-axis) and perpendicular to the survey line (Y-axis). The horizontal gray bold  
 442 line is the seismic survey line of Line EW reported by Mochizuki et al. (2008). The black dots  
 443 represent all the hypocenters obtained from this study. The blue and red dots present the selected  
 444 events for the depth profile shown in (b) and the selected tectonic tremors shown in (a). The events  
 445 within 6 km from the seismic survey line were selected. The orange inverted triangles show the  
 446 location of OBSs.

447



448  
 449 Figure 12. Integrated cross-sectional view at Line 13 reported by Tsuru et al. (2002). (a) Histogram  
 450 of the number of tectonic tremors along Line 13 (after the report by Nishikawa et al., 2019). The  
 451 thick vertical bar denotes the coarse location of the top of the seamount. (b) Seismic reflection  
 452 profile reported by Tsuru et al. (2002). Hypocenters along Line 13 from the present study are  
 453 overlaid. Colors of hypocenters show the days after the Mw7.9 event, as shown in Figure 9. The  
 454 solid red and yellow lines present the interpreted top of igneous oceanic crust and the Cretaceous  
 455 layer by Mochizuki et al. (2008), respectively. The thick black arrow points to the planar downdip  
 456 interface. (c) Plan view parallel to the survey line (X-axis) and perpendicular to the survey line (Y-  
 457 axis). The horizontal gray bold line is the seismic survey line of Line 13 reported by Tsuru et al.  
 458 (2002). The black dots represent the hypocenters obtained from this study. The blue and red dots  
 459 present the selected events for the depth profile shown in (b) and the selected tectonic tremor  
 460 shown in (a). The events in which offset are smaller than 6 km were selected from the seismic  
 461 survey line.

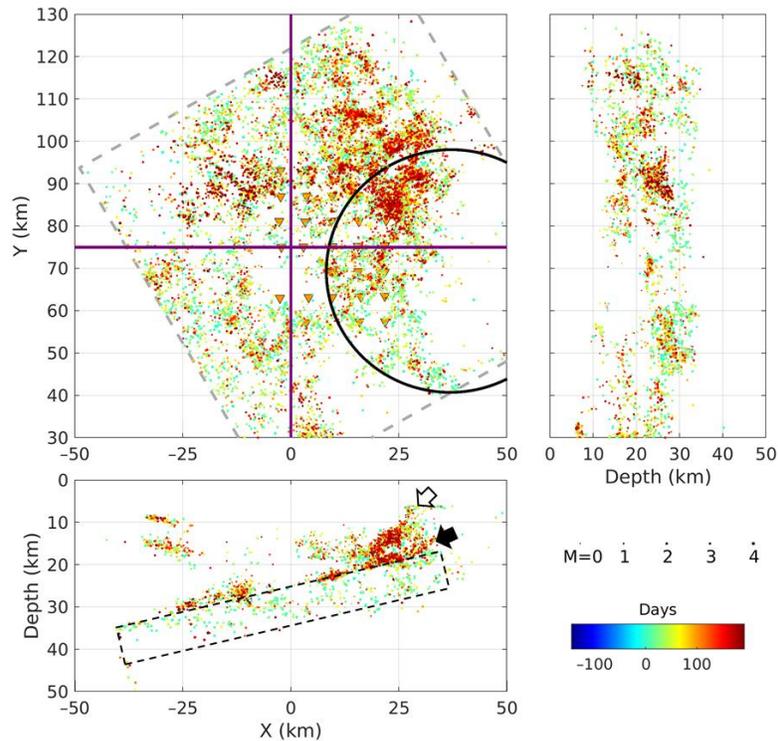
462

### 463 5.1 Seismicity overview concerning surrounding tectonics

464 The event distribution of this study showed that the high seismicity zone is concentrated at  
 465 the front-end side of the seamount (Figures 10–12). By contrast, the seismicity is quite low around  
 466 the top or back-end side of the seamount. In this low-seismicity zone, the shallow tectonic tremors  
 467 are distributed with little spatial gap with small earthquakes. We focus on the spatial relationship  
 468 between the seismogenic zone and the subducting seamount.

469 In the plan view of the seismicity shown in Figure 10, this high-seismicity zone showed a  
 470 horizontal variation along the rim of the front-end side of the subducting seamount. The seismicity  
 471 in the northern side is higher than that in the eastern or southern side. Nakatani et al. (2015)  
 472 suggested that this zone is a part of the seamount. The spatial seismicity pattern in this study is  
 473 consistent with this previous study. Nakatani et al. (2015) discussed that this horizontal and vertical  
 474 seismicity variation along the rim of the seamount may be a consequence of a stress field change  
 475 by the Mw7.9 event. On top of this consistency, this study can further discuss the event depth  
 476 variation. The event depth variation clarifies that, temporally bounded by the occurrence of the  
 477 Mw7.9 event, the depth variation of the seismicity changed considerably from a monotonic planar  
 478 distribution (Figure 9a) to a depth-variant heterogeneous distribution (Figure 13). This seismicity  
 479 suggests that subsurface structures are illuminated by the small earthquakes. Particularly, the  
 480 presence of depth-variant subfaults and/or microfractures are shown around the seamount,  
 481 including inside the oceanic crust.

482



483

484 Figure 13. Same event and layout as shown in Figure 9b with additional notations. The solid open  
 485 circle in the plain map view represents the seamount. The black and white arrows in the cross  
 486 section denote the planar downdip interface and the high-angle downdip interface, respectively.  
 487 The black dashed rectangle in the cross section denotes the temporally activated high-seismicity  
 488 zone only for a few tens of days after the Mw7.9 event.

489

490 The updip limit of the seismogenic zone corresponds to  $\sim 10$ -km plate interface depth. This  
 491 updip limit is located around the top of the subducting seamount. Using numerical modeling, Sun  
 492 et al. (2020) showed that at around the top of the seamount, the effective normal stress along the  
 493 plate interface is considerably smaller than the one along the front-end side. This updip limit  
 494 located around the top of the seamount may be explained, at least partly, by this normal stress  
 495 reduction that is incapable of generating stick-slip events along with the plate interface of the  
 496 seamount (Sun et al., 2020). However, the interpretation of the resultant seismicity in this study is  
 497 complicated due to the presence of two seismically active interfaces (Figure 13). To clarify the  
 498 plate interface, in the next subsection, 5.2, we discuss the details of the gently sloped planar  
 499 downdip interface—the most prominent interface identified in this study.

500

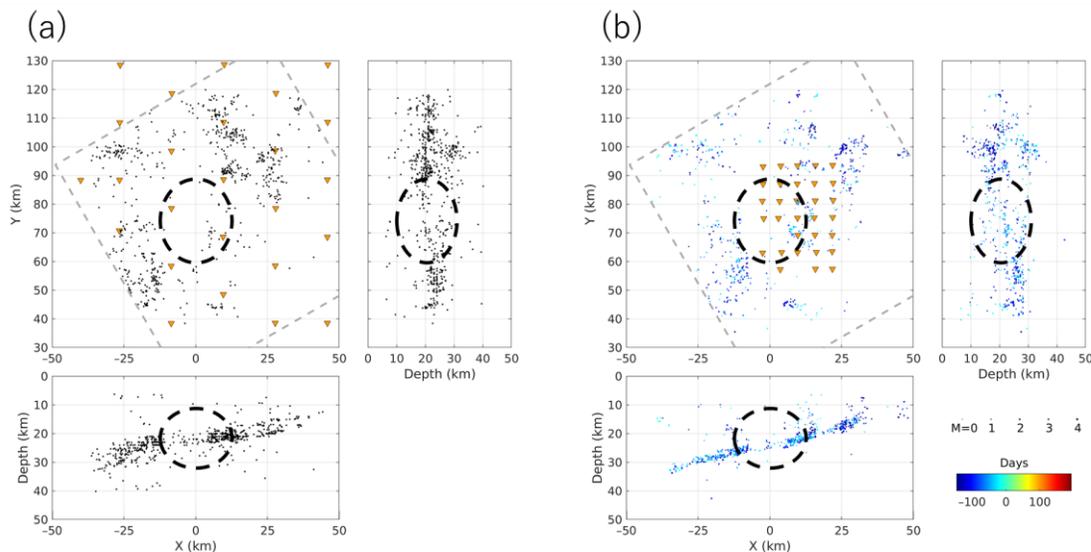
## 501 5.2 Planar downdip interface

502 The depth of the planar downdip interface is  $\sim 18$  km at the updip limit of the seismogenic  
 503 zone (Figure 13). This planar interface is also discernable by the hypocenter reported by Shinohara  
 504 et al. (2011, 2012), which is around the same depth as that in the present study (Figure S7). This  
 505 planar downdip interface had been active before the Mw7.9 event throughout the entire OBS  
 506 experiment period. The latest large earthquake in this off-Ibaraki region before the 2011 Mw7.9  
 507 event was M7.0 event on 8 May 2008 (Takiguchi et al., 2011). This M7.0 event in 2008 also

508 occurred at the deeper portion, and its rupture propagated from relatively deeper to a shallower  
 509 direction (Takiguchi et al., 2011). The aftershock distribution of this M7.0 event in 2008 was  
 510 examined by Yamada et al. (2011). The comparison of the event distribution is shown between the  
 511 aftershocks of this M7.0 event in 2008 and the event distribution before the Mw7.9 event in 2011  
 512 determined in this study (Figure 14). In the plain map view of Figures 14a and 14b, the aftershocks  
 513 of the M7.0 event in 2008 exhibit a similar spatial seismicity pattern as seismicity analyzed in the  
 514 present study before the occurrence of the Mw7.9 event. The cross sections of both seismicities  
 515 show a clear planar downdip trend. The aftershocks of Mw7.9 in 2011 reported by Shinohara et al.  
 516 (2011, 2012) are consistent with these results. That is, the hypocenters reported by Yamada et al.  
 517 (2011), Shinohara et al. (2011, 2012) and this study showed a consistent geometry for this planar  
 518 downdip interface in spite of the different dataset and the different event location method.  
 519 Therefore, we conclude that these planar downdip interfaces between 2008 and this study from  
 520 2010 to 2011 are the same seismic interfaces. If this is true, then it is natural to interpret that as an  
 521 overall tendency, this planar downdip interface has been stably sliding for years from 2008 to 2011.  
 522 The depth of this planar downdip interface is  $\sim 18$  km at around the updip limit of the seismogenic  
 523 zone.

524 Meanwhile, Yamada et al. (2011) also reported that there is a low-seismicity zone in the  
 525 study area of the present study, which overlaps with the low-seismicity zone of the 2011 Mw7.9  
 526 event in the present study (Figure 14). This low-seismicity zone appears to be seismically inactive.  
 527 Hence, this zone might be an exception of a stable sliding, which we will further discuss in section  
 528 5.5.

529



530

531 Figure 14. (a) Aftershock distribution of M7.0 event in 2008 (after Yamada et al., 2011). The  
 532 orange inverted triangles present the OBS locations during 2008 aftershock observation (Yamada  
 533 et al., 2011). The events within the study area of the present study are shown. Entire spatial range  
 534 of events shown in the plan map was used for cross section. The bold dashed circles represent the  
 535 low-seismicity zones of the 2011 Mw7.9 event. (b) Hypocenters in this study from 17 October  
 536 2010 to 11 March, 2011. The bold dashed circles represent the low-seismicity zones of the 2011  
 537 Mw7.9 event.

538

539 From the viewpoint of the geometry of this planar downdip interface and its temporal  
540 stability of the seismicity, this gently sloped planar downdip interface appears to be a plate  
541 interface of a subducting slab. However, it is questionable to conclude that this planar downdip  
542 interface is the plate interface as the top of the oceanic crust. As shown in Figures 10–12, the active  
543 source seismic surveys revealed that the depth of the plate interface as the top of the oceanic crust  
544 is ~10 km (Mochizuki et al., 2008; Tsuru et al., 2002) and not 18 km. Nishizawa et al. (2009) also  
545 performed a seismic survey close to the Line EW of Mochizuki et al. (2008) and showed that the  
546 plate interface depth at around the top of the seamount was ~13 km, a few kilometers deeper than  
547 that of Mochizuki et al. (2008). On one hand, Mochizuki et al. (2008) applied an active source  
548 seismic tomography for determining the velocity structure. Moreover, an arrival time migration  
549 method was applied to identify and determine the depth of the plate interface validated by a  
550 synthetic waveform. Nishizawa et al. (2009) applied a wide-angle refraction survey method to  
551 obtain the depth of the plate interface. Accordingly, it is difficult to directly examine the depth  
552 difference of the plate interface between these studies. However, the depths of the plate interface  
553 from these seismic surveys are considerably shallower than the event distribution of the planar  
554 downdip interface in this study.

555 The depth offset between the plate interface from the seismic profile and the planar  
556 downdip interface from the small earthquakes is more evident at Line 13 (Figure 12) than the one  
557 at Line EW (Figure 11). At Line 13, the depth offset is ~8 km at around the top of the subducting  
558 seamount. This appears to be a discrepancy between the depth of the plate interface inferred from  
559 the event distribution and those obtained from the active source seismic surveys.

560 Because the  $V_p/V_s$  ratio was optimized for the event location in the present study, we  
561 believe that the event depth is hardly biased. To further examine the effect of velocity model error  
562 against the depth of the event location, we performed a set of event location tests using different  
563 velocity models. The test conditions and results are presented in Table 1. The test result shows that  
564 the average event depth shift is at most 1.3 km. Even the nonoptimal  $V_p/V_s$  ratio of 1.78 does not  
565 explain the departure of event depth from the plate interface. In addition, the event location of P-  
566 only dataset without using the S-wave hardly changed the average event depth below the OBS  
567 network. This supports that the S-wave velocity structure is accurate enough to constrain the event  
568 depths to our final results. Consequently, we conclude that the error of the velocity structure model  
569 is not the cause of the discrepancy between the depth of event location and the depth of plate  
570 interface using the active source seismic survey.

571 The remaining possibility that can cause the event depth error is the presence of an  
572 extremely low-velocity anomaly in a real velocity structure that was not incorporated in the  
573 velocity model, especially for the S-wave around the plate interface. However, we believe that  
574 such an anomaly is unrealistic. First, the P-only event location did not have such a shift. Second,  
575 to result in the 8 km of the depth shift, ~1.0 s of the S – P time error must be accounted for  
576 throughout the study area (roughly assuming  $V_p = 6$  km/s and  $V_s = 3.4$  km/s). But past studies  
577 using the active source seismic surveys did not identify such a low-velocity layer (Mochizuki et  
578 al., 2008; Nakahigashi et al., 2012; Nishizawa et al., 2009; Tsuru et al., 2002). In this way, the  
579 velocity model error effect is difficult to explain this departure between the depth of the plate  
580 interface and the depth of events. Consequently, errors in the velocity structure are hard to explain  
581 this prominent depth offset between the top of the oceanic crust and the planar downdip interface.

582 **Table 1.** *Test Conditions of the Velocity Model Error Effect and Results.*

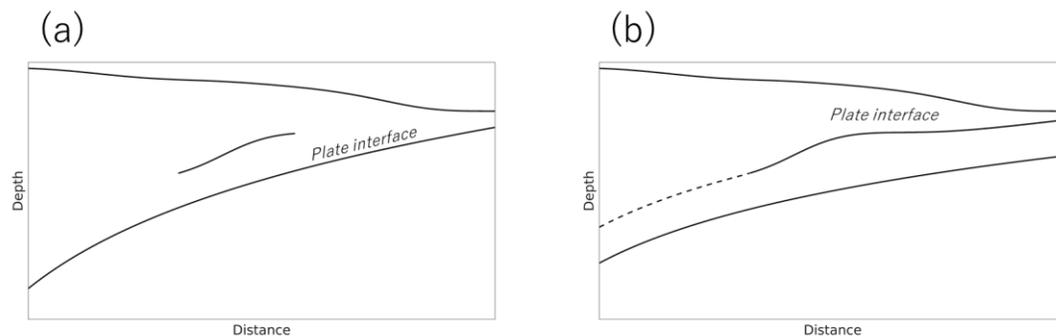
	Use of seismic phases	Vp/Vs ratio below the basement	Mean event depth [km]	Mean event depth shift [km]	Mean coherence
Reference velocity model	P&S	1.74 (optimal)	19.36	-	0.766 (best)
Reference velocity model	P-only	-	18.09	-1.27 km	0.833 (note: P-only)
Vp/Vs change	P&S	1.78	18.26	-1.10 km	0.764

584

### 585 5.3 High-angle dipping plane above the downdip planar interface

586 As presented in Figure 13, a high-angle dipping plane is identified above the downdip  
 587 planar interface. The depth of this plane around the updip limit of the seismogenic zone is ~10 km.  
 588 This depth appears to agree with the depth of the plate interface from seismic profiles. Therefore,  
 589 this high-angle dipping plane could be a part of a plate interface. However, to avoid any  
 590 misconception, we discuss the following two cases: 1) the planar downdip interface is the plate  
 591 interface as the top of the oceanic crust (Figure 15a) and 2) the high-angle dipping plane is a part  
 592 of the plate interface (Figure 15b).

593



594 Figure 15. Diagrams showing the candidates of the plate interface. (a) Case showing that the planar  
 595 downdip interface is the plate interface. (b) Case showing that the high-angle dipping plane is the  
 596 plate interface.

597

#### 598 5.3.1 Case 1: Planar downdip interface is the plate interface

599 In this case, the high-angle downdip interface is the subsurface structure above the plate  
 600 interface. Wang and Bilek (2011, 2014) suggested that the subduction of the seamount causes  
 601 microfractures in the overriding plate. As an alternative scenario, a cutting-off of the seamount  
 602 from its base may be the other candidate for the consequence of the seamount subduction (Cloos,  
 603 1992; Cloos & Shreve, 1996). Further, if this high-angle downdip interface is shallower than the  
 604 top of the seamount, an out-of-sequence fault or accretionary wedge is perhaps the other candidate  
 605 of a subsurface structure (e.g., Park et al., 2000). However, these structures are not identified in  
 606 the off-Ibaraki region (Tsuru et al., 2002). Accordingly, in the particular case shown in Figure 15a,

607 either microfractures or the cutting-off of the seamount may be the potential causes of the  
608 fracturing of the overriding plate which we further discuss below.

609 In microfractures and cutting-off scenarios, the planar downdip interface is supposed to be  
610 a plate interface. As discussed in the previous subsection, we suppose that the case presented in  
611 Figure 15a is less likely to occur. We raise a few additional factors that need further explanations  
612 for each microfracture and cutting-off scenario. First, the microfracture scenario does not explain  
613 why the shallow high-angle interface was activated only after the Mw7.9 event rather than a  
614 continual stable seismic activity. According to Wang and Bilek (2011), the microfracture is the  
615 consequence of a compressional stress against the overriding plate by a seamount subduction. The  
616 microseismicity associated with the microfractures is expected to occur continuously other than  
617 the aftershock. However, the observation in this study showed no such significant events above  
618 the plate interface. Second, if the planar downdip interface is the plate interface as the top of the  
619 oceanic crust, an explanation is needed why this interface does not exhibit no topological  
620 signature of the subducting seamount. Particularly in the case of the cutting-off scenario, an extra  
621 discussion is required if the base of the cutting-off interface is topologically smooth enough to  
622 cause a stable seismic activity even before the Mw7.9 event.

### 623 5.3.2 Case 2: High-angle downdip plane is the plate interface

624 The second case is that the high-angle dipping plane is a part of the plate interface (Figure  
625 15b). The depth of this plane around the updip limit of the seismogenic zone is  $\sim 10$  km. This is in  
626 reasonable agreement with the depth of the plate interface from the seismic survey (Figures 11 and  
627 11). This case suggests that the events are dominant along or below the plate interface and not  
628 above. Conversely, previous studies on the seamount subduction anticipated that the seismicity on  
629 the overriding plate would be enhanced by developing microfractures (e.g., Sun et al., 2020; Wang  
630 and Bilek, 2011, 2014). No reasonable models appear to exist to explain the occurrence of the  
631 events below the plate interface in previous studies. Previous seamount subduction studies  
632 implicitly suggested that the oceanic plate is not fractured (see review by Wang & Bilek, 2014).  
633 Perhaps, the subducting oceanic plate is already fractured as reported in recent studies (e.g. Hino  
634 et al., 2009, Obana et al., 2021)

635 Most importantly in this case, one open question arises, i.e., how is the stable high  
636 seismicity of this planar dipping interface accounted for if it is deeper than the plate interface? As  
637 stated, this planar downdip interface seems stably sliding for years and it is a challenge to explain  
638 how such stable sliding of this interface persists for years below the oceanic crust. This topic is  
639 beyond the scope of this study and we cannot provide an answer for this question here. Further  
640 study is required, such as investigating a double-difference relocation and a seismic tomography  
641 for determining both P- and S-wave velocities to reveal the precise geometry of these interfaces  
642 and corresponding velocity structures.

643

### 644 5.4 Spatial boundary between earthquakes and shallow tectonic tremors

645 Shallower than the updip limit of the seismogenic zone, the tectonic tremors were identified  
646 using S-net (Nishikawa et al., 2019). These tremors were found after the deployment of S-net from  
647 2016 to 2018 after the OBS experiment of this study. Meanwhile, shallow tectonic tremors were  
648 not identified during the OBS observation period. This is partly because of the difficulty in  
649 discriminating the signals of the tectonic tremors and those of the regional aftershocks of Tohoku-

650 oki earthquake. Here, we assume that the tremor distribution is temporally steady enough not to  
651 invade the seismogenic zone.

652 The noticeable feature of the shallow tectonic tremor distribution is that this tremor is  
653 spatially complementary with the normal earthquakes bounded by the updip limit of the  
654 seismogenic zone (Figure 10–12). Kubo and Nishikawa (2020) showed that the rupture area of the  
655 Mw7.9 event and the subducting seamount are spatially complementary. Sun et al. (2020) showed  
656 that small-to-moderate earthquake occurs between the rupture area and the tectonic tremor. The  
657 present study agrees with Sun et al. (2020) with much precise manner that the spatial gap between  
658 the rupture area of the Mw7.9 event and the tremor is filled by small earthquakes located at the  
659 front- end of the seamount. The rupture area of the Mw7.9 event is discussed in the next subsection  
660 5.5.

661 This spatial continuity between the small earthquakes and shallow tectonic tremors  
662 naturally suggests that the locations of these activities would be smoothly connected with the same  
663 or nearby interfaces. If this is true, it would be interesting and important to discuss what controls  
664 the boundary between this tectonic tremor and small earthquakes. The answer may not be as simple  
665 because as discussed in the previous subsection, the depth profile of the seismicity exhibited a  
666 variation along with the depth below the oceanic crust.

667 Regarding the shallow tectonic tremor, understanding the tremor generation mechanism is  
668 still in progress (e.g., Ide, 2021); however, extensive research is ongoing in subduction zones  
669 worldwide. Previous studies revealed that tectonic tremor comprises swarms of low-frequency  
670 earthquakes (LFEs) (Beroza & Ide, 2011; Nishikawa et al., 2019; Shelly et al., 2007). The duration  
671 of the tectonic tremor is approximately tens of seconds or longer (e.g., Nakano et al., 2019). The  
672 characteristic frequency content of LFEs is 1–8 Hz (Ide et al., 2007), which overlaps with those of  
673 the small earthquakes located in the study area (>4 Hz). This indicates that the tremor region is  
674 also seismogenic in the sense of radiating elastic energy at these high-frequency bands in the order  
675 of Hertz. From tectonic implications, the shallow tectonic tremors were shown to occur at the  
676 forefront of an accretionary wedge (Obana & Kodaira, 2009) or a shear zone around the  
677 décollement on the top of the oceanic crust (Hendriyana & Tsuji, 2021, Sugioka et al., 2012). This  
678 study follows these previous studies proposing that the shallow tectonic tremors occur along or in  
679 the vicinity of the plate interface.

680 However, these tectonic structures and tremor locations do not fit with the off-Ibaraki  
681 region because this region is characterized by the lack of décollement or an accretionary prism  
682 (Tsuru et al., 2002). According to the multichannel seismic survey, this earthquake-tremor  
683 boundary corresponds to the top of the seamount. No such subsurface structures are identified  
684 herein (Figures 11 and 12). Perhaps, other tectonic structures or mechanisms may be required to  
685 account for the tremor generation at the off-Ibaraki region.

686 Instead of the accretionary wedge or a shear zone around décollement, this study considers  
687 a case where the morphology of the subducting seamount surface gives control to define this  
688 seismogenic-tremor boundary. This discussion below is based on the numerical modeling study  
689 reported by Sun et al. (2020), showing that the effective normal stress around the top of the  
690 seamount is considerably smaller than that at the front-end side of the seamount.

691 As aforementioned, the updip limit of the seismogenic zone is located along ~10 km of  
692 isocontour of the plate interface depth. This 10-km contour is close to the top of the subducting  
693 seamount. According to Sun et al. (2020), a stress shadow may be generated along the plate  
694 interface at the shallow ward in the seamount's wake owing to the variation of the slope of the  
695 seamount morphology. Because this stress shadow is the region where the effective normal stress

696 is considerably reduced, a shear slip around the top of the seamount's back-end side is easier to be  
697 initiated than that at the front-end side (Sun et al., 2020). In contrast with the back-end side of the  
698 seamount that can be a stress shadow region, at the front-end side of the seamount, the effective  
699 normal stress will be considerably larger compared with that in the shallow tremor region; hence,  
700 it is harder for the tectonic tremor to be initiated. Accordingly, it is implicated that the 10 km of  
701 the isodepth plate depth contour corresponding to a spatial boundary between the earthquakes and  
702 tectonic tremors is a boundary between the non-stress shadow and the stress shadow. This model  
703 presented by Sun et al. (2020) explains the boundary of the seismogenic and tremor region  
704 observed in this study even without the presence of an accretionary wedge or a décollement along  
705 the plate interface.

706

### 707 5.5 Semicircular low-seismicity zone and the largest Mw7.9 aftershock event

708 As shown in Figure 10, a large semicircular low-seismicity zone was identified. The size  
709 of this low-seismicity zone is  $\sim 30 \text{ km} \times 25 \text{ km}$  along the strike and dip direction, respectively. The  
710 seismicity of this zone has been continuously inactive since the aftershock of 2008 M7.0 event as  
711 per the OBS observation (Figure 14a). The event detection capability is quite good in this low-  
712 seismicity zone; the event-detection lower limit at  $\sim 20\text{-km}$  depth is M0.5 (Figure 6). In this low  
713 seismicity zone, a tectonic tremor was not identified in this zone, especially before the Mw7.9  
714 event. Because of these reasons, an extremely weak coupling condition along the fault plane is  
715 very unlikely in this low-seismicity zone.

716 Meanwhile, it is well known that the aftershocks occur around the rim of the main  
717 coseismic rupture area (e.g. Mendoza & Hartzell, 1988, Yagi et al., 1999). In the present study,  
718 the hypocenter of the Mw7.9 event was relocated around the western rim of the semicircular low-  
719 seismicity region underneath the OBS network (Figure 8). Nakatani et al. (2015) reported a  
720 consistent hypocenter of the Mw7.9 event. The rupture direction of the Mw7.9 event is known to  
721 have propagated toward updip from the hypocenter (Kubo et al., 2013; Suzuki et al., 2020). These  
722 results suggest that the semicircular low-seismicity zone corresponds to a part of the coseismic  
723 rupture area of the Mw7.9 event, possibly the main rupture area. The A-GPS survey (Honsho et  
724 al., 2019, Tomita et al., 2017) showed that in contrast to the Tohoku-oki region, the southern Japan  
725 trench region including off-Ibaraki region is characterized by an afterslip region after the 2011  
726 Tohoku-oki earthquake. The A-GPS data in this off-Ibaraki region from 2012 to 2016 are shown  
727 in Figure 10. This A-GPS result suggests that the afterslip of the Mw7.9 event may have continued  
728 for years.

729 One may argue that the fault plane depth of the Mw7.9 thrust event is still controversial  
730 because there are two dipping planes of a planar downdip interface and high-angle downdip  
731 interface (Figure 15), hence the coseismic fault plane cannot be unambiguously specified. Actually,  
732 this study cannot provide a constraint regarding the depth of the fault planes. Further  
733 characterization such as a delta CFF analysis will provide a better insight into the fault plane of  
734 this Mw7.9 event.

735

## 736 6 Summary and conclusions

737 This study proposed a comprehensive workflow to apply the migration-based event  
738 location method proposed by Yoneshima and Mochizuki (2021) to the local small earthquakes

739 recorded in OBSs at the off-Ibaraki region. This workflow includes the optimization of the input  
740 velocity model particularly for the  $V_p/V_s$  ratio below the basement of the sediment layer.

741 By applying this event location workflow, we have intensively located the small  
742 earthquakes for more than 20,000 events around the subducting seamount and the rupture area of  
743 the Mw7.9 event. The error bars for majority of events are smaller than  $\pm 2$  km. The event detection  
744 capability in the study area ranged from approximately M1 to M4 that is practically enough to  
745 identify the high- and low-seismicity zones in the study area.

746 The event distribution showed noticeable seismicity patterns that are correlated with the  
747 surrounding tectonics. At the updip, bounded by the updip limit of the seismogenic zone, small  
748 earthquakes and shallow tectonic tremors were found to be spatially complementary. This  
749 boundary may be explained as the boundary between the stress shadow and non-stress shadow  
750 region in terms of the effective normal stress change that arose from the topological change of the  
751 subducting seamount, according to Sun et al. (2020).

752 At the deeper portion, a semicircular low-seismicity zone was identified beneath the OBS  
753 network. This zone was interpreted as the main coseismic rupture area of the Mw7.9 event in 2011,  
754 although the exact depth of the rupture fault plane is still uncertain.

755 A clear temporal change was identified bounded by the Mw7.9 event; the seismicity  
756 changed from a simple planar downdip interface to a depth-variant heterogeneous pattern with two  
757 distinct interfaces and a swarm-like scattered events below the planar downdip interface. The  
758 shape of a simple planar downdip interface is overall subparallel to the subducting slab identified  
759 from the active source seismic profiles. However, its depth was unexpectedly several kilometers  
760 deeper than the plate interface as the top of the oceanic crust. Our result showed that the temporally  
761 activated high-angle downdip interface after the Mw7.9 event agree with the plate interface depth  
762 determined from the seismic surveys. This also suggests that the planar downdip interface is deeper  
763 than the plate interface.

764

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770

## 771 **Open Research**

772 The JMA Mw7.9 event in Figure 2 is from the JMA unified event catalog downloaded  
773 from the National Research Institute for Earth Science and Disaster Resilience Data Management  
774 Center (<https://hinetwww11.bosai.go.jp/auth/?LANG=en>) on March 23, 2021. The A-GPS data  
775 were obtained from the reports by Honsho et al. (2019), presented in the Supporting Information  
776 document. The shallow tectonic tremor catalog was obtained from the report by Nishikawa et al.  
777 (2019) in the section of Supplementary Material document. Most of the data analysis and figures  
778 were obtained using MATLAB R2020b. Some maps were created using Generic Mapping Tools  
779 version 4 (Wessel & Smith, 1995). The FMTOMO program code, used to compute travel times,  
780 was downloaded from <http://www.earth.org.au/codes/FMTOMO/download/> on 24, February,  
781 2021. The error ellipsoid was drawn by a MATLAB function `error_ellipse` (Johnson, 2022). The  
782 hypocenter catalog determined in this study is available at

783 TBD\_TO\_BE\_SPECIFIED\_AFTER\_THE\_ACCEPTANCE. All the datasets used to make  
784 Figures are archived at <https://zenodo.org/record/6371243> for peer review.

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