

Radar sounding of subsurface water-ice in eastern Coprates and Capri Chasmata, Mars

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Key Points:

- We identified subsurface reflectors in four areas in the eastern Coprates and Capri Chasmata based on SHARAD data.
- Dielectric constants estimated using HiRISE data provide the upper limit of the possible volume fraction of water-ice as 21.2 %.
- This upper limit yields the maximum volume of putative subsurface water-ice in the chasmata of 16.6 km³.

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Abstract

We surveyed the subsurface structure in eastern Coprates and Capri Chasmata in the equatorial region using high-resolution visible images, digital terrain models, and radar sounding data. We identified subsurface reflectors in four areas of the chasmata. At the stratigraphic exposure on the chasmata walls, the corresponding depth of the reflector is ~ 60 m. The bulk dielectric constants of the layers above the reflectors are calculated as 3.4–4.0, suggesting a rock-air mixture with $\sim 46.1\%$ porosity, or a rock-air-ice mixture with $\sim 21.2\%$ water-ice fraction. Recent climate models suggest that water-ice is unstable on the surface around the equatorial regions. However, considering the recent high obliquity that occurred ~ 0.4 Ma and a slow diffusivity of water-ice, the existence of subsurface water-ice deeper than a few meters cannot be ruled out. If water-ice is actually contained in the layer, our results show the maximum volume of putative water-ice in the chasmata is 16.6 km^3 .

1 Introduction

While the effect of water on the Martian climate and geological evolution is important, the distribution of subsurface water/ice is not well known. Among the remote sensing methods, the radar sounding technique has the most potential to visualize the subsurface structure of Mars. This technique has revealed subsurface icy layering (*Putzig et al.*, 2018) and possible subglacial liquid water beneath the polar caps (*Orosei et al.*, 2018). A recent encompassing and amalgamating survey with other datasets has revealed the extent of the cryosphere using radar sounding data (*Bramson et al.*, 2015; *Morgan et al.*, 2019; *Stuurman et al.*, 2017). For example, *Bramson et al.* (2015) estimated the existence of excess ice (higher water-ice abundances than the maximum porosity of dry regolith) due to low dielectric constants estimated by compiling exposed crater terraces and the subsurface radar reflectance. Thus, compiling various remote sensing data including the radar sounding technique will unveil the water-ice beneath the surface of Mars.

Interestingly, in contrast to the climate models that imply the ice is unstable, the existence of subsurface water-ice on current Mars at mid-latitudes has been indicated/suggested by several previous studies based on remote sensing observations (*Bramson et al.*, 2015; *Byrne et al.*, 2009; *Dundas et al.*, 2014; *Stuurman et al.*, 2017). From current Martian climate conditions, the existence of subsurface water-ice is not expected (e.g., *Schorghofer and Aharonson*, 2005). One piece of evidence for the existence of subsurface water-ice at the current mid-latitudes is the ice excavated by newly formed impact craters (*Byrne et al.*, 2009; *Dundas et al.*, 2014). The radar sounding technique has found possible subsurface extents of water-ice in mid-latitude planitiae (*Bramson et al.*, 2015; *Stuurman et al.*, 2017). Analyzing morphometry of expanded secondary craters, *Viola et al.* (2015) estimated that possible subsurface water-ice in Arcadia Planitia has been preserved for tens of millions of years. Thus, in the mid-latitude area, it seems that water-ice is preserved for a longer time than suggested by climate modeling evaluations.

On the other hand, at low-latitudes, current water-ice in the shallow subsurface has not been observed explicitly, although remnants of mountain glaciers have been found (*Head and Marchant*, 2003; *Milkovich et al.*, 2006). Here, to survey the subsurface structure in the equatorial region, we compile visible images, topographic data, and radar sounding data at one of the largest outcrops on Mars: Valles Marineris. Valles Marineris has been characterized by water-related geologic features such as a distribution of a variety of aqueous minerals (e.g., sulfates *Chojnacki and Hynak*, 2008) and fluvial topography (*Carr and Head*, 2010, and references therein). Furthermore, swarms of recurring slope lineae (RSLs) possibly induced by water-related recurrent surface activity have been investigated (*Chojnacki et al.*, 2016; *Stillman et*

72 *al.*, 2017), although the formation mechanisms are still under debate (e.g., *Dundas et*
 73 *al.*, 2017). Thanks to those water-related features, dense and high-resolution remote
 74 sensing datasets have been developed. Subsurface radar reflectors exist in several
 75 areas of the Valles Marineris plateau (*Smith et al.*, 2019). Large and clear stratigra-
 76 phy exposed on the walls could be assigned to those subsurface radar reflectors. A
 77 flat and lightly cratered surface in the plateau of eastern Coprates and Capri Chas-
 78 mata, the eastern portion of Valles Marineris, provides a reliable dataset for radar
 79 sounding analysis, since rough surface topography causes artificial reflectors such as
 80 surface clutter echos (*Seu et al.*, 2004). In this context, we selected eastern Coprates
 81 and Capri Chasmata as targets of this compiling study.

82 2 Method

83 *Beyer and McEwen* (2005) described the stratigraphy of eastern Coprates and
 84 northern Capri Chasmata in detail using visible images, infrared images, spectrum
 85 data, and topographic data. There are exposed alternating thin strong layers and
 86 thicker sequences of relatively weak layers (*Beyer and McEwen*, 2005). The top-
 87 most strong layer is a 10 m-thick dark-toned layer and is thought to be a Hesperian
 88 basaltic lava flow (*Witbeck et al.*, 1991). The sequences of relatively weak layers have
 89 been indicated as sequences of thin flows interbedded with tephra or other sediments
 90 (*Beyer and McEwen*, 2005).

91 At the point of interest, we described the exposed stratigraphy of the chasma
 92 wall using visible images and topographic data (Fig.3B). Firstly, layers on outcrops
 93 that are not covered with talus deposits were identified on HiRISE images. We mea-
 94 sured the depths and thicknesses of identified layers on high-resolution topographic
 95 data HiRISE digital terrain models (DTMs). We used two-origin HiRISE DTMs
 96 1) produced by NASA/JPL/University of Arizona/USGS and 2) generated using
 97 MarsSI (<https://marssi.univ-lyon1.fr/MarsSI/>), which includes processes us-
 98 ing Ames Stereo Pipeline (*Quantin-Nataf et al.*, 2018). The procedure on MarsSI is
 99 1) import HiRISE EDR images (raw data) and calibrate, 2) create DTMs, and 3)
 100 align created DTMs to the MOLA data. Due to the availability of HiRISE DTMs,
 101 we described stratigraphy at two points: point 1 and 2 (Fig.2). Since it is difficult
 102 to describe facies in detail even in HiRISE images, we briefly classified layers into
 103 three types by their appearance: fine, coarse, and very coarse. The fine layers have
 104 no obvious boulders/rocks inside and correspond to the relatively weak layers shown
 105 in *Beyer and McEwen* (2005). The very coarse layers look like fractured lava rock
 106 or are boulder-rich. Some of them are described as the strong layers and interpreted
 107 as the last basaltic lava flow by *Beyer and McEwen* (2005). Coarse layers have an
 108 intermediate appearance between fine and very coarse layers. Based on this classifi-
 109 cation, stratigraphic columns were created using StratGen (version 1.6.0) produced
 110 by Indiana University, Indiana Geological Survey. We compared possible depths of
 111 subsurface reflectors and those stratigraphies, then considered component materials
 112 with plausible dielectric constant.

113 We identified subsurface reflectors on radargrams generated from radar sound-
 114 ing data obtained by Mars SHallow RADar sounder (SHARAD) on Mars Recon-
 115 naissance Orbiter (MRO) (*Seu et al.*, 2004). The operating frequency of SHARAD is
 116 15 – 25 MHz, the bandwidth of which (10 MHz) corresponds to the vertical resolu-
 117 tion of 8.4 m assuming pure water-ice (dielectric constant = 3.15) or 5.3 m for rock
 118 with a dielectric constant = 8 (*Bramson et al.*, 2015). The spatial resolution, based
 119 on synthetic aperture processing, is 0.3 to 1 km along the track direction and 3 to
 120 7 km along the cross-track direction (*Seu et al.*, 2004). The MRO MARS SHARAD
 121 5 RADARGRAM V1.0 we used was provided by the SHARAD team via the Geo-
 122 sciences node of the Planetary Data System (PDS) at <http://pds-geosciences>

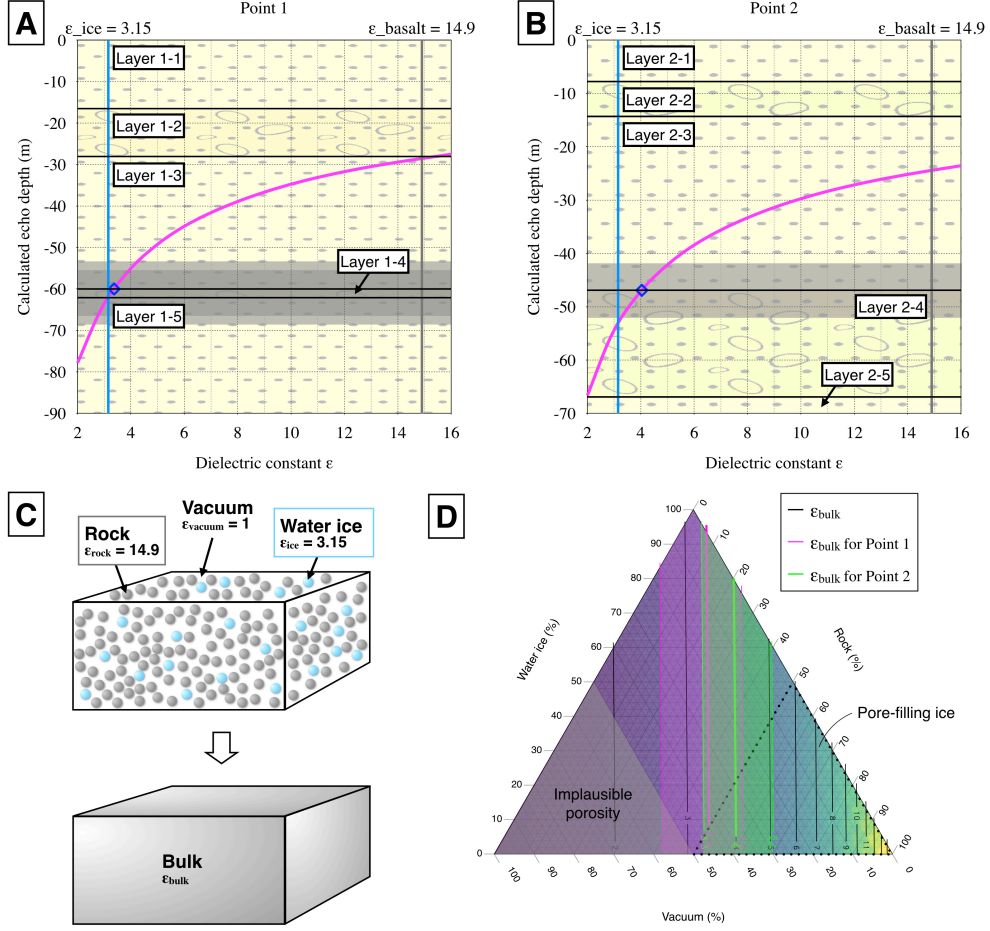


Figure 1. Estimation of dielectric constants (magenta lines) at point 1 (A) and 2 (B). Blue and gray lines indicate dielectric constant of water-ice and basalt, respectively. Depth of observed stratigraphy on HiRISE images is shown as black solid lines, and its ± 5 m error-margin is shown as gray rectangles. (C,D) Dielectric constant calculation based on *Ishiyama et al.* (2019). (C) The concept for bulk dielectric constant for a mixture of rock, air, and water-ice. (D) Ternary contour diagram of the bulk dielectric constant following the projection scheme of *Bramson et al.* (2015). A gray triangle zone indicates implausible porosities. Dotted triangle shows pore-filling ice condition.

123 .wustl.edu/missions/mro/sharad.htm. We analyzed 373 SHARAD radargrams
 124 and identified subsurface reflectors (Fig.2).

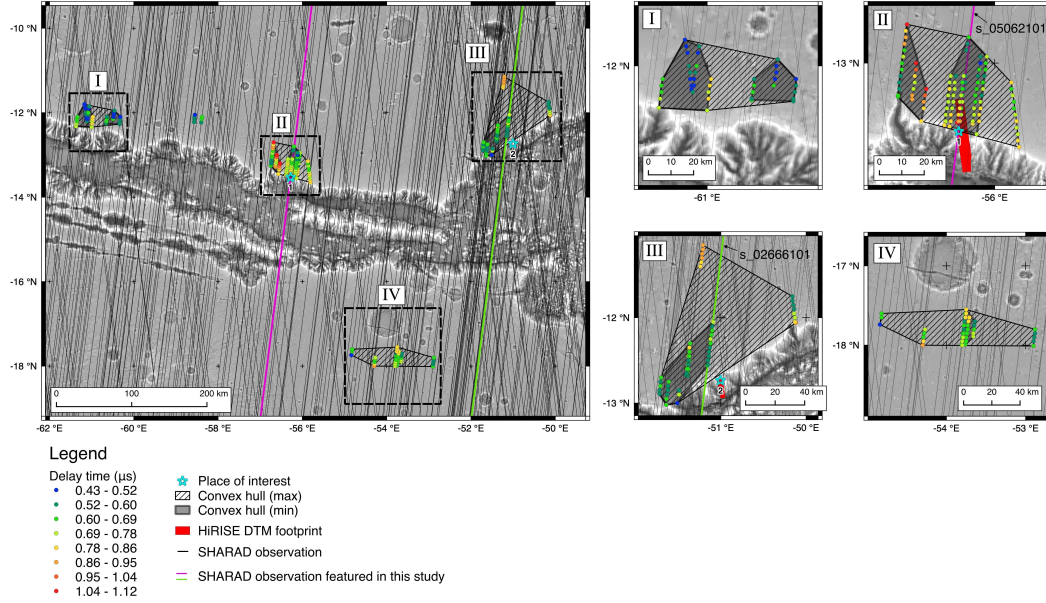


Figure 2. Investigated SHARAD observations (black, magenta, and green lines) and delay time of subsurface echoes (colored filled circles) in eastern Coprates and Capri Chasmata. Locations of the small maps on the right are shown in the larger left map (boxes with dashed outlines). Convex hulls of subsurface echo-identified points correlate to the calculation of coverage in Table 1. The base topographic map was created using HRSC MOLA Blended DEM (Ferguson *et al.*, 2018).

125 We should note that intense nadir and off-nadir surface echoes with their side-
 126 lobes could overlap with weak subsurface echoes in the radargrams. Therefore, we
 127 performed radar echo simulation by Kirchhoff Approximation Method, which calcu-
 128 lates scattered electromagnetic fields at the Martian surface based on Mars Orbiter
 129 Laser Altimeter (MOLA) data (Fig.S1B) and obtained simulated radargrams, in-
 130 cluding surface echoes only. By comparing the observed and simulated radargrams,
 131 we can identify subsurface echoes which are only found in observed radargrams. De-
 132 tailed information for this simulation is shown in the supplementary information.
 133 In addition, we checked if the levels of the identified subsurface echoes are more
 134 than 10 dB higher than the sidelobe level of the nadir surface echoes. The sidelobe
 135 level was estimated based on the Hann window, which is applied in the generation
 136 of SHARAD data used in this study. Considering this calculation, subsurface re-
 137 flectance was identified when the observed echo signal was 10 dB+ larger than the
 138 calculated sidelobe (Fig.3D).

139 *Ishiyama et al.* (2019) gives the dielectric constant of a mixture of rocks, vac-
 140 uum (air) and water-ice as

$$\varepsilon_{bulk} = \varepsilon_{vacuum} + \frac{3b}{1-b}\varepsilon_{vacuum} \quad (1)$$

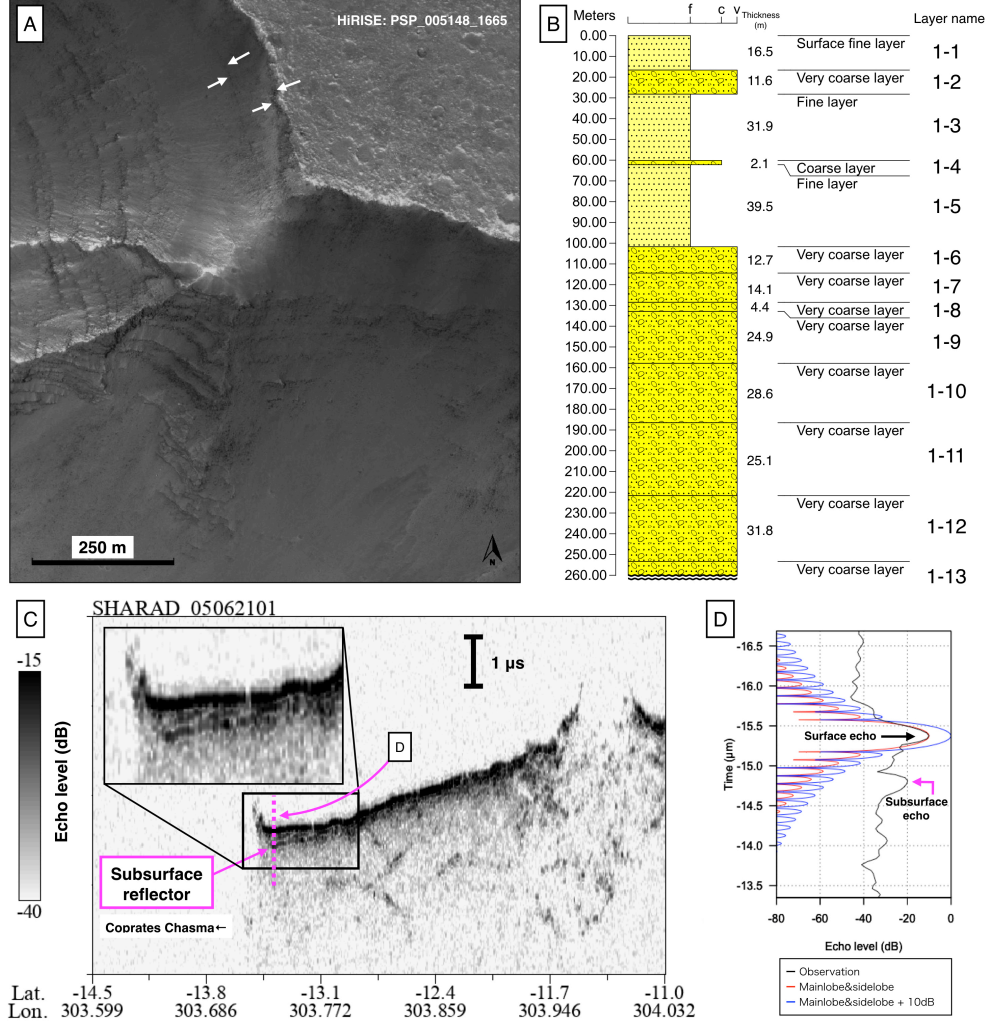


Figure 3. (A) Exposed stratigraphy on the wall, (B) its identified stratigraphy, and (C) its corresponding radargram at Point 1 in Fig.2. The thickness of each layer on the stratigraphic column (B) was measured on a HiRISE DTM (DTEED_014114_1665.005148_1665_A01.IMG). (D) The echo level versus delay time (black line). Red and blue lines indicate sidelobe and side-lobe+10 dB.

$$b = \phi_{ice} \frac{\varepsilon_{ice} - \varepsilon_{vacuum}}{\varepsilon_{ice} + 2\varepsilon_{vacuum}} + \phi_{rock} \frac{\varepsilon_{rock} - \varepsilon_{vacuum}}{\varepsilon_{rock} + 2\varepsilon_{vacuum}} \quad (2)$$

where ε_{vacuum} , ε_{rock} , ε_{ice} are the dielectric constants of vacuum, rock and water-ice (Fig.1C). Volume fractions of rock and ice in a target layer are shown as ϕ_{rock} and ϕ_{ice} . In the calculation, we applied $\varepsilon_{vacuum} = 1$ and $\varepsilon_{ice} = 3.15$ (pure water-ice; *Matsuoka et al. (1997)*). Several previous studies applied a rock dielectric constant around 8 (e.g., *Bramson et al., 2015*) though such low dielectric constants are measured in non-porous dacite (e.g., 7.54 for Mount Meager - Ring Creek dacite samples, *Rust et al. (1999)*). In this study, we applied $\varepsilon_{rock} = 14.9$ (an average of 14.768 and 14.955 for Mauna Ulu basaltic lava basalt with no voids; *Rust et al. (1999)*), since most of the observed rock on Mars has low-SiO₂ components, which are comparable to basalt and andesite (*McSween et al., 2009*). Using these equations and parameters, we estimated the plausible component materials in layers above identified subsurface reflectors (Fig.1D).

From SHARAD observation data, we obtained the two-way delay time (Δt) of subsurface reflectors and calculated their depths (d) by assigning a range of dielectric constants (ε : 2 to 16) as

$$d = \frac{\Delta t \times c}{2} \times \frac{1}{\sqrt{\varepsilon_{bulk}}} \quad (3)$$

where c is the speed of light in a vacuum (3.0×10^8 m/s).

3 Results

We identified subsurface reflectors in four areas (I, II, III, and IV) of eastern Coprates and northern Capri Chasmata (Fig.2). Areas I, II, and III are located at the edge of the chasma plateau. Areas II and III are close to tiny tributary chasmata (Figs.2,S2). Area IV is located south of the Saravan crater. Though there are many RSLs that have been found in eastern Coprates and Capri Chasmata (*Chojnacki et al., 2016; Stillman et al., 2017*), their distribution pattern is not correlated with the subsurface reflector identified in this study. In this region, RSLs are located on Nectaris Montes inside the chasmata; a difficult place to see subsurface on SHARAD data due to its relatively small area and rough surface. The coverage of the four areas as concave hulls of subsurface reflector-identified places is $0.3 - 1.1 \times 10^4$ km² in total and Table 1 shows the value for each one. The average delay times of the subsurface echoes for these four areas is $0.67 \mu s$ and those for each area are shown in Table 1.

At point 1 in area II, we identified several stratigraphic layers (Fig.3A,B). The uppermost fine layer (1-1) is 16.5 m thick, and the very coarse layer (1-2) has 11.6 m thickness. Beneath these layers, a 31.9 m thick fine layer (1-3) and a 2.1 m thick very coarse subsurface layer (1-4) exist. Layer 1-4 corresponds to the strong layer described by *Beyer and McEwen (2005)*. As noted in *Bramson et al., 2015*, shallow reflectors within ~ 30 m depth from the surface are obscured by sidelobes. Therefore we regarded the delays of the subsurface echoes ($0.73 \mu s$ in average of area II) as representing bulk information of the dielectric constant above the reflectors (i.e., layers 1-1, 1-2, and 1-3). At point 1, the plausible bulk dielectric constant of the layers above the subsurface reflectors (delay time of the echoes from them: $0.73 \mu s$), which corresponds to the boundaries between the fine and coarse layers at a depth of 60.0 m (bottom of layer 1-3 = top of layer 1-4), is estimated to be 3.4 (Fig.1A). Regarding the error of reading for depth/thickness on a DTM as ± 5 m, the range of plausible bulk dielectric constant is 2.6 to 4.2. Since the other remote sensing data

Table 1. Average two-way delay time of the subsurface echoes and coverage of the subsurface reflectors in each area. Area name corresponds to Fig.2. The coverage was calculated as a convex hull of the identified points in Fig.2.

Area name	Average delay time (μs)	Area (km^2) ¹
I	0.58	782.5 – 1411.8
II	0.73	846.4 – 1998.5
III	0.66	925.1 – 5259.0
IV	0.67	153.2 – 2251.5
Total		2707.2 – 10920.7

¹ Minimum: only for main clusters of subsurface echo-identified points in shadow convex hulls of Fig.2. Maximum: for whole subsurface echo-identified points in hatched convex hulls of Fig.2

such as HiRISE color images and CRISM absorptions does not show strong features for water-ice on the chasma wall, layers 1-1, 1-2, and 1-3 are believed to be a pore-filling ice regime, not an excess ice regime (*Bramson et al.*, 2015). Assuming that these layers are pore-filling ice regime, the value of the calculated dielectric constant (~ 3.4) is consistent with a rock-air mixture with 46.1 % porosity and a rock-air-ice mixture, for which the range of volume fraction of water-ice is 0 – 7.8 % (Fig.1D).

At point 2 in area III, the uppermost fine layer (2-1) has 7.8 m thickness, and the very coarse subsurface layer (2-2) has 6.6 m thickness (Fig.S2). Beneath these layers, a 32.6 m thick fine layer (2-3) and 20.0 m thick very coarse layer (2-4) exist. Layer 2-4 corresponds to the strong layer described by *Beyer and McEwen* (2005). The bulk dielectric constant of the layers above the subsurface reflectors (average delay time in area III: 0.66 μs), which corresponds to the boundary between the fine and coarse layers at a depth of 46.9 m (bottom of layer 2-3 = top of layer 2-4), is estimated to be 4.0 (range of 3.3 to 5.1, considering the error of depth/thickness reading)(Fig.1B). This value is consistent with 39.3 % porosity for the rock-air mixture and up to 21.2 % of the volume fraction of ice for the rock-air-ice mixture (Fig.1D).

4 Discussion and conclusion

From the analysis of radar sounding data, high-resolution images and topographic data, we found that eastern Coprates and Capri Chasmata have areas with relatively low dielectric constants. The calculated bulk dielectric constant (3.4–4.0) suggests that the layers are composed of a rock-air mixture with up to ~ 46.1 % porosity and a rock-ice-air mixture with up to ~ 21.2 % volume fraction of water-ice. In the equatorial region, it has been estimated that water-ice is unstable due to the sublimation and thus a cryosphere does not currently exist (*Schorghofer and Aharonson*, 2005). Considering the instability of ice, the layers with low bulk dielectric constant should be a porous rock layer without water-ice. It is certainly true that ~ 46 % of the calculated porosity in this study is possible for general geologic materials such as those of aeolian, fluvial, and volcanic origins (*Todd and Mays*, 2005), which possibly exist in eastern Coprates and Capri Chasmata. However, orbital simulations have suggested that the obliquity of Mars oscillates periodically. In this case, water could be transported to the low-latitude region at the high obliquity stage. *Head et al.* (2003) evaluates that the last high obliquity stage occurred ~ 0.4 Myr ago. *Bryson et al.* (2008) performed the experiments on the sublimation rate of water-ice beneath regolith, and their conclusion suggests that ~ 1 m-thick water-

ice can be maintained for 0.4 Myr under ~ 2 m-thick regolith. Although the age of the low dielectric constant layer is uncertain, if ice was deposited in the layer ~ 0.4 Myr ago, the existence of water-ice at the depth in which the reflector was identified (~ 60 m) cannot be ruled out. From crater counting, the age of water-ice detected by radar sounding in the mid-latitude area is evaluated to be ~ 20 Myr (*Viola et al.*, 2015). Thus, if the layers in the equatorial area contain water-ice, the time when water-ice was deposited should differ between mid-latitude and low-latitude regions. In addition to the preservation of water-ice at a time of high-obliquity, the accumulation of water-ice in the pores by thermal contraction is also suggested (*Fisher*, 2005), which may be the another origin of pore water-ice in eastern Coprates and Capri Chasmata.

If the layer is composed of a rock-ice-air mixture, using the estimated water-ice volume fraction in a layer of a specific thickness, the possible amount of water-ice can be calculated. In area II, assuming a layer 846.4 to 1998.5 km² that is 60.0 m thick with 7.8 % volume fraction of water-ice, 4.0 to 9.4 km³ of putative water-ice would exist. However, considering the emplacement of water-ice in 0.4 Ma by snowfall (e.g., *Christensen*, 2003), it is natural to think a host layer of water-ice is located above the strong layer, which is described as a Hesperian lava flow (*Witbeck et al.*, 1991). This stratigraphic setting (water-ice can exist in the topmost layer) leads to the volume fraction of putative water-ice in the topmost layer being 29 %. This calculation can be applied to 925 to 5258 km² of the subsurface reflectors region in area III. Based on the analysis of radar sounding data, in point 2 in area III, the plausible water-ice volume fraction of a 46.9 m thick layer is 21.2 %. Although this condition simply leads to a volume range of putative water-ice from 9.2 to 52.4 km³, the volume of putative water-ice in area III would be less than 7.2 km³ assuming a pore-filling water-ice regime (less than 50 % water-ice content) in the 5259.0 km²-extent of a 7.8 m-thick topmost layer. Therefore, a maximum of 16.6 km³ of putative water-ice may exist in the plateau of eastern Coprates and northern Capri Chasmata. On the gamma-ray spectrum, eastern Coprates and Capri Chasmata do not show a strong hydrogen concentration (*Boynton et al.*, 2007). Since the detection depth of the hydrogen is approximately 1 m (*Feldman et al.*, 2004), the water-ice layers in these regions are thought to be undetectable by the gamma-ray spectrum. The surface echo power analyses of radar sounding data by the Mars Advanced Radar for Subsurface and Ionospheric Sounding instrument (MARSIS) showed the dielectric constant property at a few decameters below the surface (*Mouginot et al.*, 2010). On their dielectric map, dielectric constants in eastern Coprates and Capri Chasmata decrease from southwest to northeast. This suggests drastic variation in the shallow subsurface environment, such as from dry to ice-rich or the increase of porosity in these areas. Thus, although deducing accumulation mechanisms is still challenging, our analyses imply the possible existence of a subsurface ice-contained layer in eastern Coprates and northern Capri Chasmata, i.e., even in the equatorial region.

In this work, from the bulk dielectric constant evaluated from the delay time of radar sounding and plausible corresponding depth at the stratigraphic exposure, we could only constrain the upper limit of the water-ice fraction. Thus, considering the current instability of water-ice in low-latitude terrain, further studies and discussions are required to determine the existence of water-ice and, if water-ice actually exists, for the mechanism to maintain it within low-latitude terrain.

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