

# Magnetic Hysteresis Properties of Magnetite: Trends with Particle Size and Shape

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## Key Points:

- Magnetic hysteresis is micromagnetically modeled for oblate, prolate and equant magnetite particles (50-195 nm).
- The reduced magnetization ( $M_{rs}/M_s$ ) is a very effective parameter for differentiating between magnetically single-domain and non-single-domain behavior.
- Transient magnetic hysteresis is a powerful tool for identifying stable remanent magnetizations, but is currently infrequently reported.

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**Abstract**

Magnetic hysteresis measurements are routinely made in the Earth and planetary sciences to identify geologically meaningful magnetic recorders, and to study variations in present and past environments. Interpreting magnetic hysteresis data in terms of domain state (particle size) and paleomagnetic stability are major motivations behind undertaking these measurements, but the interpretations remain fraught with challenges and ambiguities. To shed new light on these ambiguities, we have undertaken a systematic micromagnetic study to quantify the magnetic hysteresis behavior of room-temperature magnetite as a function of particle size (50-195 nm; equivalent spherical volume diameter) and shape (oblate, prolate and equant); our models span uniformly magnetized single domain (SD) to non-uniformly magnetized single vortex (SV) states. Within our models the reduced magnetization marks a clear boundary between SD ( $\geq 0.5$ ) and SV ( $< 0.5$ ) magnetite. We further identify particle sizes and shapes with unexpectedly low coercivity and coercivity of remanence. These low coercivity regions correspond to magnetite particles that typically have multiple possible magnetic domain states, which has been previously linked to a zone of unstable magnetic recorders. Of all hysteresis parameters investigated, transient hysteresis is most sensitive to particles that exhibit such domain state multiplicity, leading us to suggest that transient behavior be more routinely measured during rock magnetic investigations.

**Plain Language Summary**

Characterizing the magnetic properties and behavior of natural materials is key in Earth and planetary sciences to identifying reliable magnetic recorders and variations in the environment. One standard method for achieving this is through room-temperature magnetic hysteresis measurement. However, the interpretation of magnetic hysteresis data remains one of the most challenging aspects of rock magnetism. To improve our understanding of magnetic hysteresis data, we have systematically investigated how the hysteresis properties of distributions of randomly oriented magnetite change as a function of particle size and shape and how this can help us quantify the contents of natural materials and identify rocks that may give unreliable magnetic signals. We model prolate, oblate and equant magnetite particles in the size range 50-195 nm. We show that magnetic hysteresis defines a clear boundary between simple uniform magnetic structures and more complex non-uniform magnetic structures. We also identify sizes and morphologies of magnetic particles that are likely to have unstable remanent magnetizations. These unstable particles are associated with distinctive hysteresis behavior, suggesting hysteresis data can be used to easily identify rock samples dominated by such behavior.

## 52 1 Introduction

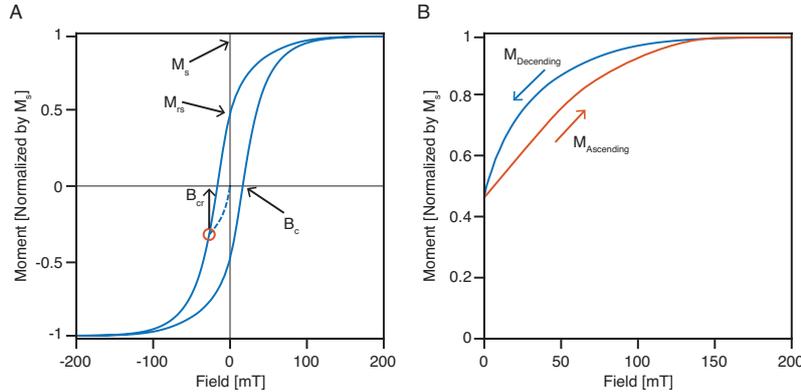
53 Due to the relative ease and rapidity of measurement, magnetic hysteresis is a widely used  
 54 technique in paleo-, rock, and environmental magnetic analysis and underpins assertions  
 55 around magnetic particle size and paleomagnetic stability (*e.g.*, Dunlop, 2002; Day et al.,  
 56 1977; Paterson et al., 2017). Despite the ease of measurement, processing and analyzing  
 57 hysteresis data can be complicated (*e.g.*, Jackson & Solheid, 2010; Paterson et al., 2018),  
 58 and the ubiquity of hysteresis data can lead to simplified or mis-interpretations of what  
 59 these data mean when dealing with magnetically complex materials (*e.g.*, Roberts et al.,  
 60 2018). Recent literature has highlighted the challenges of using hysteresis data for domain  
 61 state identification (*e.g.*, Roberts et al., 2018); however, other work has suggested that  
 62 hysteresis data have utility in quantifying the relative stability of paleomagnetic recorders  
 63 (*e.g.*, Paterson et al., 2017). Some hysteresis experiments, such as determining First Order  
 64 Reversal Curves, FORCs (Roberts et al., 1995a), are quite time consuming while others,  
 65 such as measuring only the outer loops or just the transient hysteresis (Fabian, 2003; Yu  
 66 & Tauxe, 2005), are fast. Hence, there is a trade-off between in-depth and time consuming  
 67 measurements and analyses to decompose bulk specimen properties and the more rapid  
 68 quantification of bulk hysteresis behavior and implications for other magnetic properties  
 69 that are measured on bulk specimens (*e.g.*, paleomagnetic directions or paleointensities).  
 70 Nevertheless, in both types of experiments, a comprehensive understanding of particle level  
 71 hysteresis behavior is required to be able to fully interpret hysteresis data.

72 Although extensive experimental observations of magnetic hysteresis in sized particles of  
 73 (nominally) magnetite have been made (*e.g.*, Day et al., 1977; Argyle & Dunlop, 1990; Krása  
 74 et al., 2009), there are challenges in constraining particle size distributions, maintaining a  
 75 single mineralogy, as well as preventing magnetostatic interactions between particles. There  
 76 also remains the unquantified, and highly variable, particle geometry of these synthetic  
 77 samples, which can play a notable role in their hysteresis properties (Williams et al., 2006).

78 Williams et al. (2006) and Yu & Tauxe (2008) explored hysteresis in magnetite as a function  
 79 of particle geometry, where configurational anisotropy has a large, or dominant, control on  
 80 the net anisotropy. They both illustrated that angular geometries tend to have higher  
 81 coercivities due to the “pinning” effect of sharp surface angles. Yu & Tauxe (2008) further  
 82 explored the influence of particle elongation (*i.e.*, shape anisotropy) for prolate cuboid and  
 83 octahedral particles that exhibited single vortex (SV) states when equidimensional. As  
 84 aspect ratio increases,  $B_c$  and  $M_{rs}/M_s$  initially increase due to a close balance between  
 85 magnetocrystalline and shape anisotropy. As aspect ratio increases further, above  $\sim 1.2$ ,  
 86 shape anisotropy dominates and both  $B_c$  and  $M_{rs}/M_s$  increase.

87 These works are based on low resolution finite difference models, whose domain structures  
 88 are indicative, but the coercivities are far more sensitive to model resolution and edge  
 89 effects. The characteristic hysteresis signals of isolated particles of varying size, shape,  
 90 and composition are therefore not comprehensively understood, neither experimentally, nor  
 91 micromagnetically.

92 In this work, we take a micromagnetic approach to systematically map out magnetic hys-  
 93 teresis behavior as a function of size and shape of isolated particles of magnetite. Unlike  
 94 Williams et al. (2006) and Yu & Tauxe (2008), we explore the effects of particle shape at  
 95 all particle sizes (up to 195 nm), and include oblate particle shapes, which were not part  
 96 of the previous works. We evaluate the relative changes of common hysteresis parameters  
 97 and what these mean in relation to magnetic domain states and magnetic stability of the  
 98 modeled particles. Before introducing our micromagnetic models, we start with an overview  
 99 of magnetic hysteresis and the main parameters derived from these data.



**Figure 1.** (A) Illustration of a hysteresis loop and associated parameters. The solid blue curve shows a hysteresis loop and the dashed blue curve is the back-field demagnetization curve used to determine the coercivity of remanence ( $B_{cr}$ ). See text for description of the remaining parameters. (B) Illustration of a transient hysteresis loop whereby the descending loop from saturation is terminated at zero field and the field is then increased back to saturation. The transient hysteresis of Fabian (2003) is twice the area between the two curves, which accounts for the transient behavior in the negative field half of the hysteresis loop.

## 100 2 Hysteresis Measurement and Derived Properties

101 A hysteresis loop is initiated by saturating a specimen's magnetization in a large field,  
 102 typically,  $> 300$  mT for magnetically soft materials or  $\gg 1$ -10 T for magnetically hard

103 materials (Figure 1A). From the saturated magnetization ( $M_s$ ) state, the field is gradually  
 104 reduced to the equivalent negative saturating field and swept back to positive saturation  
 105 to complete the loop. The magnetization at the zero-field point is known as the saturation  
 106 remanent magnetization ( $M_{rs}$ ).

107 During the field sweep, a single domain (SD) magnetic particle will experience a critical  
 108 switching of its magnetization to negative saturation as the field sweeps through a critical  
 109 field, known as the coercivity ( $B_c$ ). For larger particles, which do not have a uniform mag-  
 110 netic state, such as SV states (Schabes & Bertram, 1988; Williams & Dunlop, 1989), can  
 111 experience changing domain states with changing field and switching of the magnetization  
 112 may occur as a number of discrete steps caused by nucleation and denucleation of more  
 113 complicated magnetization structures like the single vortex (*e.g.*, Williams & Dunlop, 1995;  
 114 Lascu et al., 2018).

115 A number of other properties can be derived from a hysteresis loop by comparing the upper  
 116 and lower branches (*e.g.*, Rivas et al., 1981; Fabian, 2003). The average and the difference  
 117 of the upper and lower branches, are the induced and remanent hysteretic branches, respec-  
 118 tively (Rivas et al., 1981; von Dobeneck, 1996; Paterson et al., 2018). The fields at which  
 119 these curves fall to half of their peak values represent the median destructive field in the  
 120 induced and remanent branches,  $B_{ih}$  and  $B_{rh}$ , respectively (von Dobeneck, 1996; Fabian &  
 121 von Dobeneck, 1997).

122 Fabian (2003) quantified the shape of a hysteresis loop,  $\sigma_{hys}$ , which is the log of the ratio of  
 123 area of the loop to the area of the equivalent square hysteron for the observed  $M_s$  and  $B_c$ . A  
 124  $\sigma_{hys}$  value of zero indicates that the two loops have an equivalent area, hence, similar shape.  
 125 Positive values are indicative of “pot-bellied” loops and negative values indicative of “wasp-  
 126 waisted” loop (Tauxe et al., 1996). Deviations from a  $\sigma_{hys}$  of zero are often interpreted as  
 127 being indicative of particle populations with distinct coercivities arising from the mixing  
 128 of different particle sizes or different mineralogies (*e.g.*, Roberts et al., 1995a; Tauxe et al.,  
 129 1996).

130 In a typical suite of rock magnetic measurements, additional data are often acquired to  
 131 characterize the properties of a specimen. One such measurement is the back-field demag-  
 132 netization curve; also known as a DC demagnetization curve. In a back field measurement,  
 133 a specimen is initially in the positive remanent saturation state ( $M_{rs}$ ). A small negative field  
 134 is applied then removed and the magnetization is allowed to relax to a remanent state, which  
 135 should be partially demagnetized with respect to the initial positive remanent saturation  
 136 state. The negative, or back-field, is progressively increased until the specimen reaches the  
 137 negative remanent saturation state. The field at which the remanent magnetization falls to

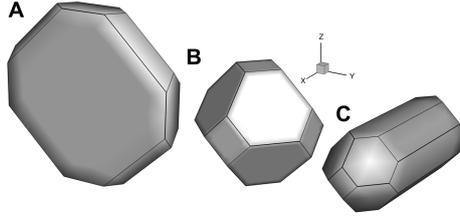
138 zero is called the coercivity of remanence ( $B_{cr}$ ). For an isolated SD particle switching of  
 139 remanence will occur in a single critical switching at  $B_{cr}$ . For non-SD particle the switch-  
 140 ing of remanence states can occur in multiple discrete switches linked to changing domain  
 141 structure.

142 An important point to note, is that while for SD particles,  $B_c$  and  $B_{cr}$  generally represent  
 143 critical switching fields, for SV states,  $B_{cr}$  is a critical switching field, but  $B_c$  may not be.  
 144 That is, application of  $B_{cr}$  field represents an irreversible switch in the magnetization, while  
 145 the magnetization at  $B_c$  may, in some case, be reversible.

146 Transient hysteresis,  $T_{hys}$  (Figure 1b, which takes a specimen from positive saturation to  
 147 the saturation remanent state (part of the major hysteresis branch) and then back to the  
 148 positive saturation state (a minor hysteresis curve), is the area mapped out by difference  
 149 in these two hysteresis branches (Fabian, 2003; Yu & Tauxe, 2005).  $T_{hys}$  is quantified as  
 150 the ratio of the transient area to the area of the whole hysteresis loop (Fabian, 2003). In  
 151 a uniformly magnetized SD particle, the field sweep has not passed the critical switching  
 152 field represented by  $B_c$ , so the magnetization from the remanence state back to saturation  
 153 is completely reversible. Hence, SD particles exhibit zero  $T_{hys}$ . In non-SD particles, the  
 154 progressive switching steps during the field sweep caused by domain states changes in the  
 155 return from remanence to saturation can be irreversible and result in substantial  $T_{hys}$ . In SV  
 156 domain states, transient hysteresis is caused by vortex nucleation and annihilation occurring  
 157 at different fields as the field is swept down from saturation and then back up, respectively  
 158 (Figure 1c) (Yu & Tauxe, 2005; Zhao et al., 2017).  $T_{hys}$  is, therefore, indicative of complex  
 159 and field history dependent domain state. Although straightforward and relatively quick  
 160 to measure, transient hysteresis is typically not measured in most suites of rock magnetic  
 161 measurements.

### 162 **3 Methods**

163 In this study we micromagnetically model hysteresis loops, transient hysteresis loops, and  
 164 back-field demagnetization curves as a function of particle size and aspect ratio ( $AR =$   
 165  $length/width$ ) for magnetite at room temperature ( $20^\circ C$ ). The models were generated using  
 166 the micromagnetic simulation software MERRILL v1.8.6p (Ó Conbhuí et al., 2018; Williams  
 167 et al., n.d.), with truncated-octahedral geometries created using Coreform Trellis 17.1 (Core-  
 168 form LLC, 2017), meshed at a resolution of 8 nm, which is below the exchange length of  
 169 magnetite (Rave et al., 1998). In total, we model 16 particle sizes between 45 and 195 nm  
 170 (expressed as the equivalent spherical volume diameter, ESVD) and aspect ratios between  
 171 0.17 (oblate) and 2.75 (prolate) (Figure 2). Prolate geometries were elongated along the  
 172  $\langle 100 \rangle$  axis and oblate geometries were shortened along  $\langle 100 \rangle$ .



**Figure 2.** Examples of the range of geometries modeled in this study. Particles with an ESVD of 45 nm representing (A) oblate ( $AR = 0.17$ ), (B) equant ( $AR = 1.00$ ), and (C) prolate ( $AR = 2.75$ ) geometries.

173 The simulated experiments were undertaken in fields between  $\pm 200$  mT at 1 mT resolution,  
 174 with hysteresis loops initiated at positive saturation. For hysteresis loops, only the upper  
 175 branches were simulated, but through rotational symmetry the lower branch can be deter-  
 176 mined. To represent a random assemblage of particles, all models were run using 29 field  
 177 directions evenly distributed over an octant of the unit sphere. Final simulation results are  
 178 the average of these directions.

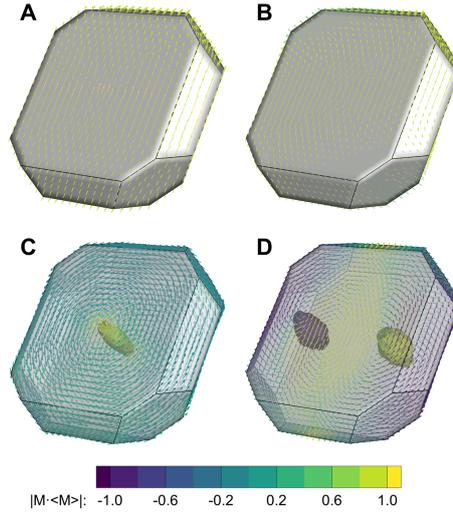
179 Transient hysteresis loop models were initiated from the zero field step of the major hysteresis  
 180 loop. The fields were swept back to 200 mT in step of 1 mT. Back-field demagnetization  
 181 curves were determined from the first-order reversal curve (FORC) simulations of (Nagy  
 182 et al., 2024), which were similarly simulated at 1 mT resolution. The zero-field steps of  
 183 reversal curves initiated at negative fields were taken as the remanence steps of the back-  
 184 field demagnetization curves (*e.g.*, Heslop, 2005).

185 Collectively, our hysteresis, transient and back-field models constitute  $\sim 4.8$  million micro-  
 186 magnetic solutions representing determinations of domain states under varying applied field  
 187 conditions. Classifying these domain states is not presently feasible and we therefore re-  
 188 strict domain our classification to the 6032  $M_{rs}$  states from the hysteresis loops (16 particle  
 189 sizes, 13 geometries, and 29 field directions from a Fibonacci distribution). Each of these  
 190 micromagnetic solutions was classified by visual inspection. Here, we make a distinction be-  
 191 tween “domain structure”, which refers to configuration of the magnetization vectors (*e.g.*,  
 192 uniformly magnetized, SD, versus SV), and “domain state”, which we restrict to refer to  
 193 an oriented domain structure (*e.g.*, a magnetocrystalline easy axis aligned SV versus a hard  
 194 aligned SV).

195 **4 Results**

196 **4.1 Domain Characterization**

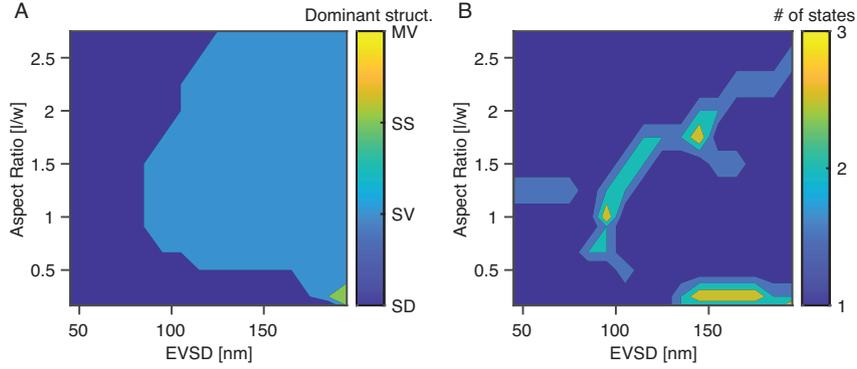
197 From our classification of remanence domain states we identify four main domain structures:  
 198 SD (uniformly magnetized, including flower structures), SV, s-shaped structures (SS), and  
 199 multi-vortex (MV). Examples of each of these structures are given in Figure 3.



**Figure 3.** Examples of the main domain structures observed in the remanence states of the hysteresis loop. All particles have an aspect ratio of 0.25. (A) A uniformly magnetized SD structure in a 135 nm particle; (B) An s-shaped structure in a 155 nm particle; (C) An SV structure in a 175 nm particle; (D) An MV structure in a 175 nm particle. The magnetization vectors are colored according to the dot product of the individual vector and the direction of the particles' net magnetization, where the individual vector are normalized unit vectors. In parts C and D, the vortex cores are highlighted by isosurface of relative helicity at 0.95 (yellow) and -0.95 (purple).

200 The domain structures in our models are predominantly SD and SV, with SS and MV  
 201 structures only occurring in the largest, most oblate particles. The most frequently occurring  
 202 domain structures for each of our size/shape combinations are shown in Figure 4A. For small  
 203 particles ( $\lesssim 80$  nm), all geometries are SD. At high elongations this extends up to  $\sim 120$  nm,  
 204 but for highly oblate particles, the SD region extends up to  $\sim 175$ -185 nm. SV structures  
 205 prevail above these sizes and SS structures occur for large oblate particles (Figure 4A).  
 206 We note that our models do not include thermal fluctuations, so it is likely that these SS  
 207 structures are meta-stable and are likely to rapidly collapse into a more stable structure,

208 which, for these particles, is an SV structure. MV states are only observed in a single model  
 209 of oblate particles (ESVD = 195 nm, aspect ratio = 0.250) .



**Figure 4.** Classification of hysteresis  $M_{rs}$  domain structures and states. (A) The most commonly occurring domain structure (SD - single domain, SV - single vortex, SS - s-shaped, MV - multi-vortex). (B) The number of unique domain states.

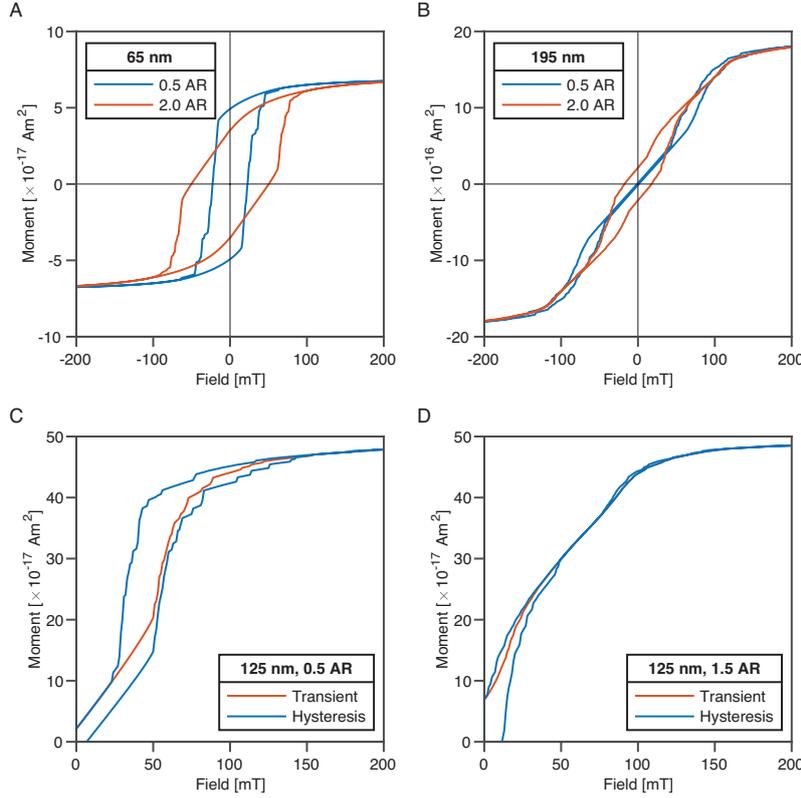
210 Within the SD region multiple orientations of magnetization, with respect to the magnetic  
 211 anisotropy, are observed, which represent different domain states (Figure 4B). For small  
 212 particles ( $\lesssim 80$  nm) and moderate elongations, the multiple domain states represents SD  
 213 structures oriented along either a shape or magnetocrystalline anisotropy easy axis and  
 214 represents instability in shapes where these anisotropy energies are closely balanced (*i.e.*,  
 215 aspect ratios  $\sim 1.2-1.3$ ).

216 For equant particles (aspect ratio of 1), as the particle size increases to 85-105 nm there is  
 217 a narrow band of particle size that exhibit multiple domains states at remanence (only our  
 218 95 nm model has multiple domain states; Figure 4B). This narrow size range corresponds to  
 219 the short relaxation time and low unblocking temperature unstable zone identified by Nagy  
 220 et al. (2017).

221 Across all the different particle geometries the competition between magnetocrystalline or  
 222 shape anisotropy controlled hard and easy aligned structures is responsible for this domain  
 223 state multiplicity (Figure 4B). In equant particles, this unstable zone coincides with the  
 224 transition between SD and SV structures, and is a result of the presence of hard and easy  
 225 aligned SV structures. For large prolate particles (upper right quadrant of Figure 4B), a large  
 226 region of domain state multiplicity is observed, with some particles capable of supporting  
 227 2-3 different domain states. This is similarly the result of both shape hard- and easy-aligned  
 228 SV structures. For large oblate particles domain state multiplicity arises from the presence  
 229 of shape-hard-aligned SV states and shape/magnetocrystalline easy aligned SD states.

## 230 4.2 Hysteresis Properties

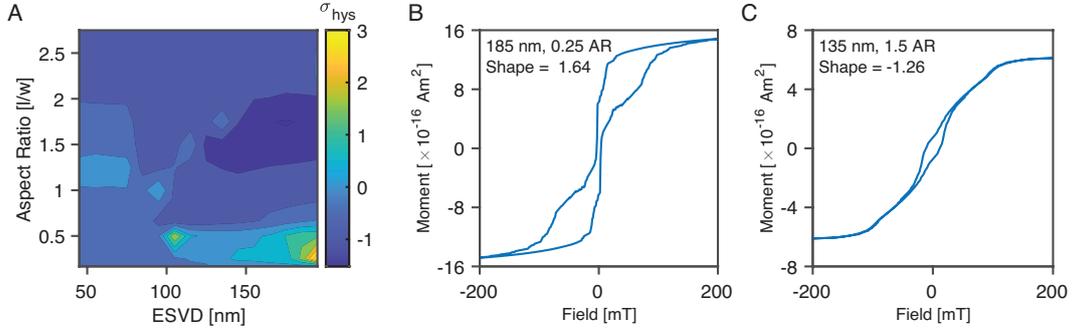
231 Our simulations exhibit a wide range of behavior characteristic of SD and SV particles  
 232 (Figure 5), and bears similarity to the range of behavior seen in hysteresis measurements  
 233 on natural materials (*e.g.*, Roberts et al., 1995b; Wang & Van der Voo, 2004; Paterson et  
 234 al., 2018; Nikolaisen et al., 2022).



**Figure 5.** Representative examples of the modeled hysteresis loops for individual particles. (A) Loops from small SD particles. (B) Loops from large SV dominated particles. Transient loop behavior from SV dominated (C) oblate and (D) prolate particles. For the hysteresis loops, only the upper branch was simulated, but was reflected to create a full hysteresis loop.

235 From our simulations we observe a wide range of hysteresis shapes from “wasp-waisted”  
 236 (Figure 6B) to “pot-bellied” (Figure 6C). There is a strong signal from large oblate particles  
 237 that have extremely wasp-waisted loops and large prolate particles with pot-bellied loops  
 238 (Figure 6A, B). In general, however, most particles have negative  $\sigma_{\text{hys}}$  indicative of pot-  
 239 bellied behavior, with the most pot-bellied loops coming from prolate particles ( $\text{AR} \approx 1.25$ –  
 240 2.00) larger than  $\approx 130$  nm (Figure 6A). Wasp-waistedness is predominantly found in small  
 241 ( $\lesssim 80$ – $90$  nm) prolate ( $\text{AR} \sim 1.25$ ) particles and larger ( $\gtrsim 120$  nm) oblate particles ( $\text{AR}$

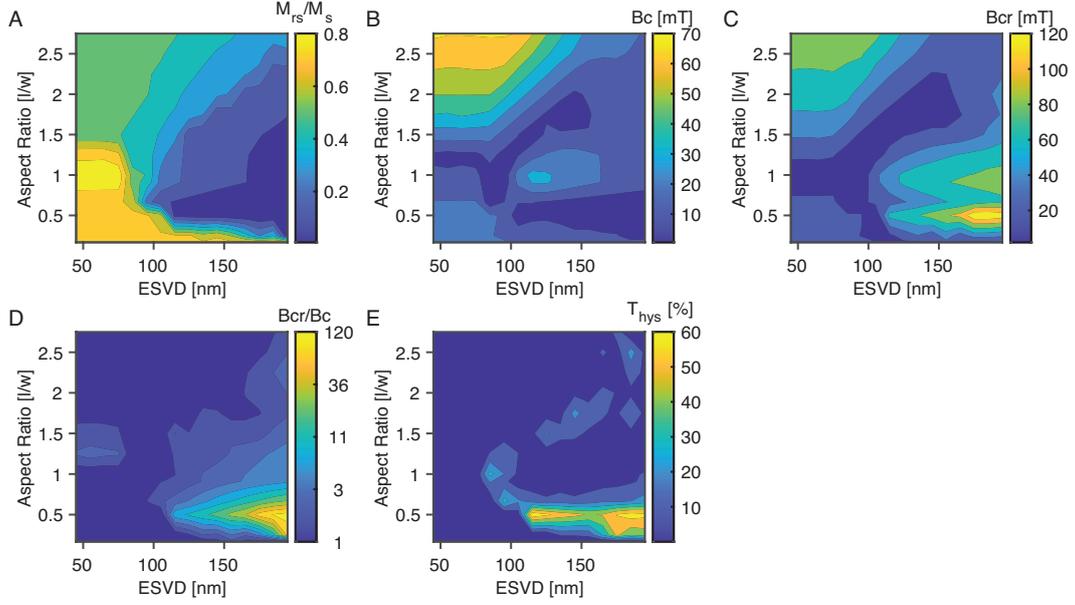
242  $\lesssim 0.5$ ). Despite the range of  $\sigma_{\text{hys}}$  observed, the median  $\sigma_{\text{hys}}$  of the 208 averaged hysteresis  
 243 loops is  $\approx -0.56$  (interquartile range of  $-0.74$  to  $-0.14$ ). This is broadly consistent with the  
 244 experimental observations of Fabian (2003) using sized powders of synthetic titanomagnetite  
 245 ( $\sigma_{\text{hys}} \approx -0.9$  to  $-0.5$ ).



**Figure 6.** Hysteresis loop  $\sigma_{\text{hys}}$  behavior. (A) Contour map of hysteresis  $\sigma_{\text{hys}}$  as function of particle size and aspect ratio. Examples of (B) “wasp-waisted” and (C) “pot-bellied” hysteresis loops.

246 In Figure 7 we show contour plots of hysteresis parameters as a function of particle size  
 247 and aspect ratio. Transects of these parameters at selected aspect ratios are shown in  
 248 Figure 8. Small ( $\lesssim 100$  nm) oblate, equant, and prolate particles have  $M_{\text{rs}}/M_{\text{s}}$  values  
 249 of 0.707, 0.866, and 0.5, respectively (Figure 7A), which are near the expected values for  
 250 random assemblages of uniformly magnetized particles dominated by biaxial, cubic, and  
 251 uniaxial magnetocrystalline anisotropy, respectively, (Dunlop & Özdemir, 1997; Williams  
 252 et al., 2023). As the particle size increases, prolate particles exhibit a relatively gradual  
 253 decrease in  $M_{\text{rs}}/M_{\text{s}}$  to  $\sim 0.1$  at 195 nm, with equant particles experiencing a slightly steeper  
 254 decrease (Figure 8A). Oblate particles show the largest decrease of  $M_{\text{rs}}/M_{\text{s}}$  with increasing  
 255 particle size (Figures 7A; 8A).

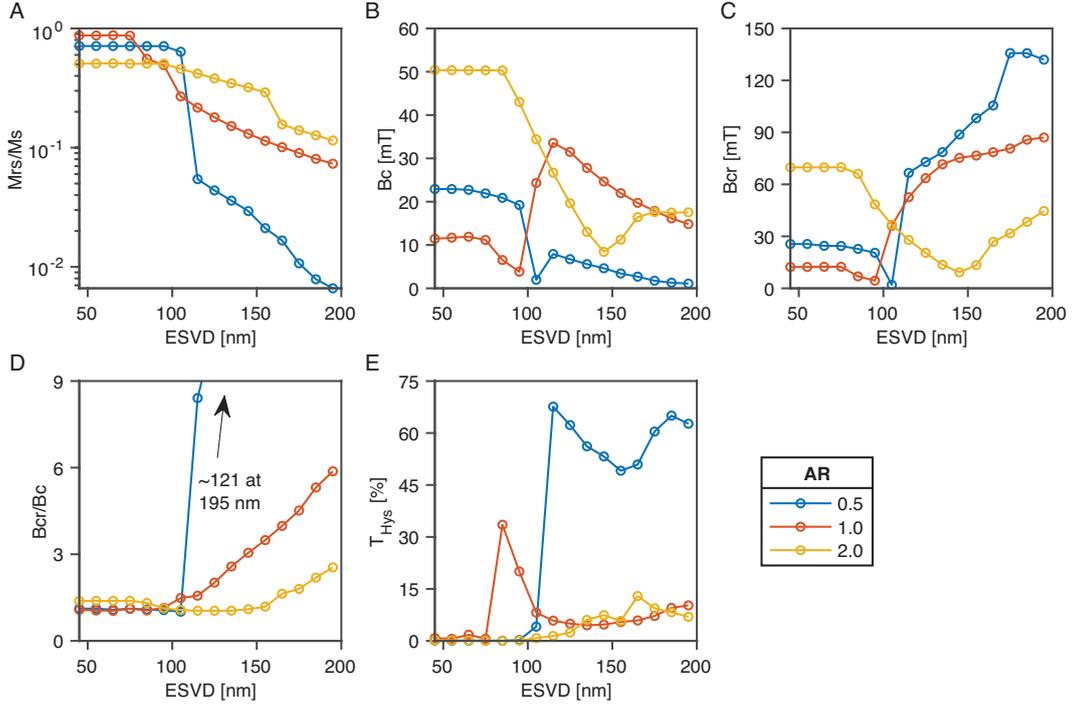
256 The coercivity ( $B_{\text{c}}$ ) of the models shows that, for both in the SD and SV states, coercivity in-  
 257 creases for increasing prolate particles, as is predicted from SD theory (Stoner & Wohlfarth,  
 258 1948) (Figure 7B). For equant particle of  $\sim 85$ – $95$  nm size, there is a dip in the coercivity  
 259 to values of  $\sim 5$  mT, coincident with particles that have low relaxation times (Nagy et al.,  
 260 2017). This dip in  $B_{\text{c}}$  is also seen at all prolate elongations, but occurs at larger particle  
 261 sizes with increasing elongation. For slightly oblate particles, this low coercivity zone exists  
 262 in  $\sim 85$ – $95$  nm particles. Highly oblate particles, however, have consistently low  $B_{\text{c}}$  above  
 263  $\sim 100$  nm, which corresponds to the presence on both SD and SV states in these particles.



**Figure 7.** Contour maps of hysteresis properties for random assemblages as function of particle size and aspect ratio. (A)  $M_{rs}/M_s$ , (B)  $B_c$ , (C)  $B_{cr}$ , (D)  $B_{cr}/B_c$ , and (E) Transient hysteresis.

264 Considering  $B_{cr}$  (Figure 7C), prolate particles with low  $B_{cr}$  values are associated with mul-  
 265 tiple domain states (Figure 4B); similar to the trend seen for coercivity (Figure 7B). For  
 266 oblate particles, however,  $B_{cr}$  increases with increasing particle size, with the highest values  
 267 corresponding to particles that are shape-hard-aligned SV in the remanence state. As a  
 268 result, variations in  $B_{cr}/B_c$  are dominated by these states found in oblate particles, which  
 269 have low  $B_c$  and high  $B_{cr}$  (Figures 7D). For equant and prolate particles,  $B_{cr}/B_c$  remains  
 270 less than  $\sim 5$ , but is consistently below 3 for the smallest particles ( $\lesssim 140$  nm; Figure 8D).

271 Transient hysteresis behavior is related to vortex states nucleating at relatively low fields  
 272 as the upper branch sweeps to zero-field, but denucleating at higher fields as the transient  
 273 branch sweeps back to saturation (Yu & Tauxe, 2005). Our SD models consistently have  
 274 transient loop areas ( $T_{hys}$ ) that are  $\ll 1\%$  of the major loop areas (related to numerical  
 275 noise and a small degree of flowering), while SV states typically have  $T_{hys} > 4\text{--}5\%$  (Figure  
 276 7E). For a consistent particle geometry,  $T_{hys}$  generally increases with increasing particle size  
 277 (Figure 8E). The most discernible feature of transient hysteresis behavior is the triangular  
 278 contour region of high  $T_{hys}$  (10-70%; Figures 7E and 8E). This occurs from oblate particles  
 279 across a wide range of sizes ( $\sim 100\text{--}195$  nm), but the size range varies with particle geometry  
 280 for prolate particles. Such large  $T_{hys}$  behavior is the result of highly variable SV nucleation  
 281 and denucleation fields and is an indication that the magnetization and domain state (see  
 282 Discussion) are strongly dependent on the particles' field pre-history.



**Figure 8.** Selected transects through the contours maps shown in Figure 7. (A)  $M_{rs}/M_s$ , (B)  $B_c$ , (C)  $B_{cr}$ , (D)  $B_{cr}/B_c$ , and (E) transient hysteresis. The selected aspect ratios are shown in the legend.

## 5 Discussion

### 5.1 Comparison with sized data

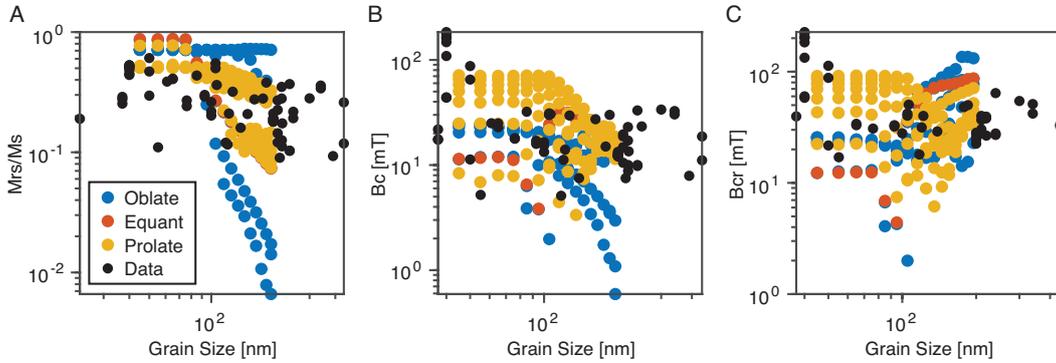
The effectiveness of the micromagnetic approach at predicting the observed domain structures from single particle microscopy observations has been well demonstrated (*e.g.*, Almeida et al., 2015, 2016; Khakhalova et al., 2018). Only recently, however, have micromagnetic studies been able to systematically model random assemblages of mono-dispersions of large (>100 nm) particles (Nikolaisen et al., 2020, 2022).

In Figure 9 we compare our model derived  $M_{rs}/M_s$ ,  $B_c$ , and  $B_{cr}$  values with published hysteresis properties from synthetic samples characterized as magnetite with nominal or known particle sizes. The aim is not to match exact values, but rather compare the range of our simulated results to that of experimental observations. The largest particle we model is 200 nm so the comparison is restricted to experimental data with a reported size <500 nm.

In general, the range of  $M_{rs}/M_s$ ,  $B_c$ , and  $B_{cr}$  values from our simulations compares well to those seen in the experimental measurements of sized magnetite particles, which most likely contain distributions of both size and shape (Figure 9). The largest discrepancy is for the

299 oblate particles with aspect ratios of  $\sim 0.5$ – $0.67$ , where the numerical models predict lower  
 300  $M_{rs}/M_s$  and  $B_c$  values (Figures 7A, B and 9A, B).  $B_c$  values show less discrepancy for the  
 301 oblate particles, but some equant and prolate models have lower  $B_c$  values that are not well  
 302 represented in the experimental data set.

303 Taking the area mapped out by our simulated results, we can determine the proportion of  
 304 experimental data that are consistent with our observations (*i.e.*, the 45–195 nm nominally  
 305 sized specimens that could be explained by a linear combination of one or more of our  
 306 simulations). For  $M_{rs}/M_s$  data,  $\sim 78\%$  fall with the area bounded by our simulations; for  
 307  $B_c$  and  $B_{cr}$ , this is  $\sim 85\%$   $\sim 67\%$ , respectively. This is a good indication that our model  
 308 predictions are consistent with experimental observations.

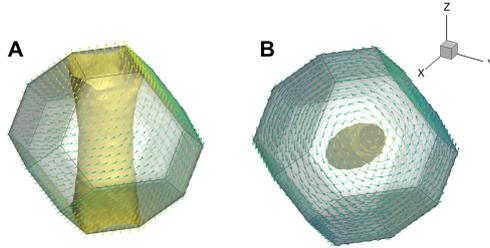


**Figure 9.** Comparison of model derived hysteresis properties with experimental results from synthetic powders characterized as magnetite with nominal particle sizes. (A)  $M_{rs}/M_s$ , (B)  $B_c$ , and (C)  $B_{cr}$ . Experimental data are for synthetic samples with reported sizes of  $< 500$  nm and are taken from Almeida et al. (2015); Argyle & Dunlop (1990); Dunlop (1983, 1986); Krása et al. (2003, 2009, 2011); Levi & Merrill (1978); Muxworthy (1999); Özdemir & Banerjee (1982); Özdemir & O’Reilly (1982); Özdemir et al. (2002); Schmidbauer & Keller (1996); Schmidbauer & Schembera (1987); Smirnov (2009); Yu et al. (2002).

## 309 5.2 Distinguishing Magnetic Characteristics

310 A comprehensive discussion of domain state analysis plots (*i.e.*, the Day plot; Day et al.,  
 311 1977) using these data, additional micromagnetic simulations, and a more extensive exper-  
 312 imental data set are presented in Williams et al. (2023). Here, we restrict the discussion to  
 313 salient features in whole loop hysteresis data and parameters, discussing the implications  
 314 for first-order characterization.

315 In terms of distinguishing dominant domain structure (*i.e.*, SD or SV),  $M_{rs}/M_s$  appears  
 316 to be the most effective parameter: The  $M_{rs}/M_s = 0.5$  contour closely follows the SD/SV  
 317 boundary (*cf.*, Figures 4a and 7A). Out of all sizes and aspect ratios that exhibit only SD  
 318 and/or SV remanence states (195 out of 208 simulations), only two are predominantly SV  
 319 with  $M_{rs}/M_s \geq 0.5$ ; the 85 nm particles with aspect ratios of 0.9091 and 1. These particles  
 320 exhibit only magnetocrystalline hard-axis-aligned vortex states (*e.g.*, Figure 10A), but the  
 321 vortex core is poorly defined and could also be classified as a twisting flower state (Hertel &  
 322 Kronmüller, 2002). As a consequence a larger proportion of magnetization is aligned with  
 323 the vortex core for these 85 nm particles than expected (*cf.* a well define SV state Figure  
 324 10B). These (near) equant particles fall directly in the unstable zone identified by Nagy  
 325 et al. (2017) and will have extremely short relaxation times; consequently, due to thermal  
 326 fluctuations  $M_{rs}/M_s \approx 0$  (*i.e.*, the particles are “superparamagnetic”).



**Figure 10.** Comparison of SV domain states in equant particles. (A) A hard-aligned vortex in  
 a 85 nm particle and (B) an easy-aligned vortex in a 105 nm particle. Colors are the same as in  
 Figure 3.

327 The diversity of hysteresis loop shapes is typically attributed to mixing of different parti-  
 328 cles with contrasting coercivities that arises from mixed mineralogy (*e.g.*, magnetite and  
 329 hematite) or mixed particle size (*e.g.*, SP and SD) (Roberts et al., 1995a; Tauxe et al.,  
 330 1996; Fabian, 2003; Frank & Nowaczyk, 2008). Our results, however, are from of magnetite  
 331 mono-dispersions, and do not contain mixed mineralogy or particle sizes. The diversity  
 332 of shapes is a result of vortex nucleation/annihilation and/or vortex switching at a range  
 333 of non-coercivity related fields that are dependent on the field orientation. Although the  
 334 most extreme shapes are only observed over narrow particle size and geometry ranges, this  
 335 serves as an important caveat when interpreting hysteresis shape in terms of mixed min-  
 336 eralogy. Similarly, the wide ranging values we observe for SD to SV states means that a  
 337 similar caution should be considered when interpreting shape in terms of mixing with SP  
 338 components.

## 339 6 Conclusions

340 In this study we have undertaken the most comprehensive micromagnetic investigation of  
 341 magnetic hysteresis in magnetite as a function of particle size and shape to date. The  
 342 range of behavior we observe is consistent with available experimental observations, giving  
 343 confidence in the robustness of the simulations.

344 Our models reveal that hysteresis loops from random mono-dispersions can exhibit varied  
 345 shapes that result from the variability of vortex nucleation and switching depending on the  
 346 orientation of the field with respect to particle geometry. This is a demonstration that mixed  
 347 mineralogy or mixed particle sizes are not required to create a diversity of loop shapes.

348 The size and shape range we model predominantly have SD and SV remanence domain struc-  
 349 tures. An  $M_{rs}/M_s$  value of 0.5 is the boundary between these structures. The SV structures  
 350 observed, exhibit both easy- and hard-aligned domain states, with the hard aligned states  
 351 corresponding to the unstable magnetic carriers identified by Nagy et al. (2017).

352 We have identified distinct size and shape combinations that yield low  $B_c$  and  $B_{cr}$ , indicating  
 353 low stability particles. These combinations, particularly for  $B_c$ , have a correspondence to  
 354 particles with a higher number of possible domain states, but this relation is less clear for  
 355 highly prolate particles larger than  $\sim 150$  nm.

356 The area of the transient hysteresis loop, which is rarely measured, has a strong relation to  
 357 particles that have multiple possible domain states. For transient hysteresis, however, the  
 358 contrast is more distinct than for  $B_c$  and  $B_{cr}$ , suggesting that it potentially offers a greater  
 359 discrimination of behavior likely responsible for unstable paleomagnetic recorders.

## 360 7 Open Research

361 All results reported here were generated using the open source micromagnetic modeling  
 362 code of Ó Conbhuí et al. (2018) and Williams et al. (n.d.). Source code for MERRILL is  
 363 available at <https://bitbucket.org/wynwilliams/merrill/> and is provided under a CC-  
 364 BY-SA 4.0 International license. Additional MERRILL resources are available at [https://](https://rockmag.org)  
 365 [rockmag.org](https://rockmag.org). All model data presented here and example MERRILL input scripts and  
 366 Treillis geometry generation scripts to reproduce these models are available at Paterson et  
 367 al. (2024).

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