a **Observation data**
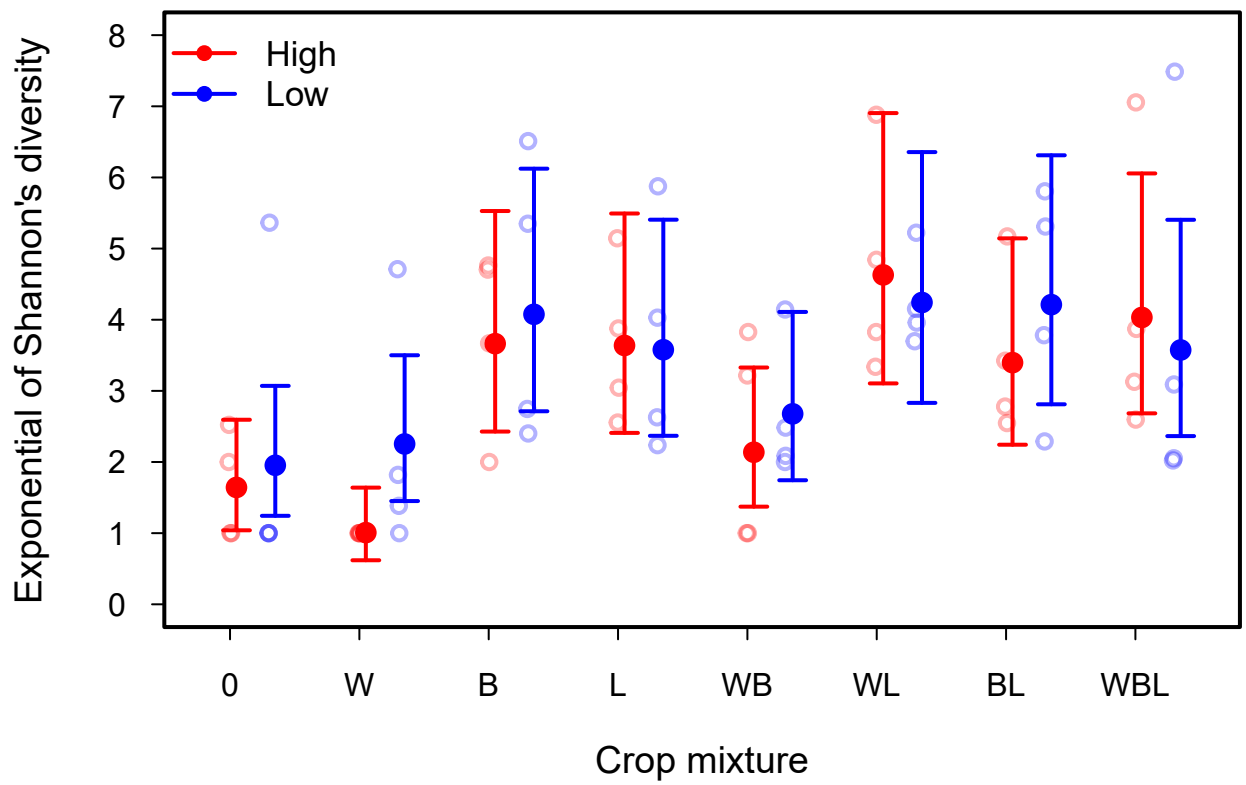
b **Pan trap data**