

**Effects of weather variation on waterfowl migration: lessons from a continental-scale
generalizable avian movement and energetics model**

Running title: Continental GAME model

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ABSTRACT

We developed a nonbreeding period continental-scale energetics-based model of daily waterfowl movement to predict year-specific migration and overwinter occurrence. The model approximates energy-expensive movements and energy-gaining stopovers as functions of metabolism and weather, in terms of temperature and frozen precipitation (i.e., snow). The model is a Markov process operating at the population level and is parameterized through a review of literature. We examined model performance against 62 years of non-breeding period daily weather data. The average proportion of available habitat decreased as weather severity increased, with mortality decreasing as the proportion of available habitat increased. The most commonly used nodes during the course of the nonbreeding period were generally consistent across years, with the most inter-annual variation present in the overwintering area. Our model revealed that the distribution of birds on the landscape changed more dramatically when the variation in daily available habitat was greater. The main routes for avian migration in North America were predicted by our simulations: the Eastern, Central, and Western flyways. Our model predicted an average of 77.4% survivorship for the nonbreeding period across all years (range = 76.4 – 78.4%), with lowest survivorship during the fall, intermediate survivorship in the winter, and greatest survivorship in the spring. We provide the parameters necessary for exploration within and among other taxa to leverage the generalizability of this migration model to a broader expanse of bird species, and across a range of climate change and land use/land cover change scenarios.

Key Words: Avian, energetics, global climate change, migration, predictive modeling, waterfowl

Introduction

Migratory behavior of populations varies within an avian species as well as among individuals within a population (Newton 2006, Newton and Brockie 2008, Eichhorn et al. 2009, Stanley et al. 2012). This differential migratory behavior is influenced by environmental change operating over ecological and evolutionary time scales (Parmesan 2006, Louchart 2008). Wide plasticity in migratory behavior is demonstrated by some individuals of a species initiating habitual seasonal migrations, with some foregoing migration to remain sedentary (Atwell et al. 2011). Understanding the mechanistic reasons for this difference in behavioral outcomes is critical to predicting responses of migratory populations to a changing environment.

Efforts to model avian migration from an energetic perspective have necessarily been informed by empirical biological and physiological studies (see Malishev and Kramer-Schadt 2021 for a review). For many species these empirical studies elucidated relationships between, for example: temperature and metabolism (e.g., Hartung 1967, Smith and Prince 1973, Klaassen 1996), body mass and temperature (e.g., Baldwin and Kendeigh 1938, Boos et al. 2007), and flight velocity and duration and body fat content (e.g., Rayner 1990). Using systems of equations to connect one facet to the next generates a series of expectations for how migration is likely to unfold for a bird of a certain species and specific mass (e.g., Lonsdorf et al. 2016, Aagaard et al. 2018). Connecting approaches for predicting environmental effects on migration-energetic dynamics with approaches evaluating the spatially explicit pattern of energetic-based migratory movements can reveal how migration is affected by the distribution of forage material on the landscape. It can also inform how migration is likely to proceed given the differential

expenditure of energy across the landscape and across temporally variable environmental conditions (Paxton et al. 2014).

While migration is a common term, we draw a distinction between it and movement and dispersal for consistency (Holloway and Miller 2017). Movement is any change in location over time. Dispersal is movement that occurs in spatially limited local communities without cyclical repetition (i.e., within a node, for our purposes; Ai et al. 2012). Migration is predictable or routine seasonal movement among two or more distinct and consistent habitats (Hansson and Åkesson 2014). Migratory birds are faced with several contrasting strategies along their journey relating to timing, distance, velocity, altitude, and stopover length (Alerstam and Lindström 1990). These dilemmas are captured in three tradeoffs: avoiding predation or refueling, flying at a speed allowing for maximum power or maximum range, and departing on migration early (to avoid inhospitable weather) or late (to further increase fat reserves) as opposed to “on time” (Pennycuick 1975, Alerstam and Lindström 1990, Hedenström 1992, Bruderer and Boldt 2001, Drent et al. 2003, Pennycuick and Battley 2003, La Sorte et al. 2013, Pennycuick et al. 2013). Each trade-off can be thought of as choice between different energetic or physiological strategies, essentially boiling down to ‘full throttle’ or ‘fuel-efficient’ transport. An easy analogy can be made between migrants and automobile drivers (Kitamura and Sperling 1987); depending on the nature of the trip, a driver may choose to optimize for automobile velocity or fuel efficiency. Migratory birds must make similar tradeoffs during the course of their movements. For a more complete elaboration of the ecological processes of avian migration, see, for example, Alerstam and Lindström (1990), Drent et al. (2003), Alves et al. (2013) and Aagaard et al. (2018).

We extend existing energetics-based models of waterfowl movement (Lonsdorf et al. 2016, Aagaard et al. 2018) to construct a full nonbreeding period model of waterfowl movement and energetics. Our model is of the type described by Malishev and Kramer-Schadt (2021) and referred to as an energetics-based Individual Based Model (eIBM); we note that the irreducible unit of interest in our models are more precisely considered “agents” rather than “individuals”, as we follow subsets of the population but not discrete individuals. The model approximates energy-expensive movements and energy-gaining stopovers as functions of weather, in terms of air temperature, air density, and snow depth, which influence the timing and extent of waterfowl migration (Nichols et al. 1983). The model begins in the late summer/early autumn as birds are forced out of breeding habitat by inhospitable weather conditions. As in Lonsdorf et al. (2016) and Aagaard et al. (2018), we model bird movement as a function of the roosting quality and forage availability of each stopover site and the distance between the stopover site and departure site. We partition the population of birds into a set of body condition classes based on body mass and body fat. We transition birds among body condition classes based on differential movement and foraging, with the assumption of an inverse relationship between body condition and mortality risk.

We allow the bounds of the overwintering area to be an emergent property of the model rather than restrict it to static interpretations of historical overwintering grounds. We, therefore, add consideration of the distance from the stopover site to all other available stopover sites within an individual’s flight range into our approximation of bird movement. We also consider the consequences of a seasonally varying availability of forage by accommodating the consumption and natural decay of forage material. Additionally, we impose thresholds related to known waterfowl abundance-weather severity relations (e.g., Schummer et al. 2010) to bird

105 movement to restrict availability of the landscape to only those sites with hospitable conditions
106 (Van Den Elsen 2016). Weather severity can be thought of as a propellant during the early
107 portion of the nonbreeding period to “push” birds southward, while the breeding grounds serve
108 as an attractant to “pull” birds northward. In this way, birds in this model tend to congregate
109 along a weather-severity isocline, staying as close to breeding grounds as weather conditions and
110 metabolic demands allow (e.g., Robinson et al. 2016).

111 While the model structure outlined here is generalizable to all birds, we use dabbling ducks
112 as an example (specifically, we parameterize our model for a mallard-like, *Anas platyrhynchos*,
113 dabbling duck). Mallards are exemplary model organisms in this context as they have been
114 extensively studied in terms of their physiology and migratory dynamics (e.g., Prince 1979,
115 Krementz et al. 2011, 2012, Pennycuick et al. 2013) and are of great conservation and
116 management interest (e.g., Heitmeyer 2010).

117 A critical advancement of this model is development of over 50 years of migration
118 trajectories using historical weather data to inform movement patterns, allowing sensitivity in
119 input parameter values to approximate observed conditions. With this model, we seek to
120 understand the influence of weather patterns and conditions on the nonbreeding period of the
121 annual cycle of migratory dabbling ducks. A full evaluation of this first-principles exposition of
122 avian migration requires broad-scale data revealing avian migration patterns associated with
123 historical environmental data. In the absence of such data we can at least use our approach to
124 determine if, all else being equal, variation present in a representative sample of observed
125 historical environmental conditions facilitates demonstrable changes to avian migration patterns
126 (Grim and Railsback 2012). Specifically, we expect (1) to determine explicitly and natively the
127 overwintering habitat; (2) past environmental data to provide evidence that climate change has

led to increased available habitat over time (and less severe weather); (3) a reduction in nonbreeding period mortality concurrent with an decrease in weather severity; (4) to recover migratory routes (flyways); and (5) to discern differences between mild and severe years comparable to historical weather reports.

Methods

We discretized the landscape (North America) into 1036 km² stopover sites, or nodes. This spatial delineation is consistent with expectations that movement less than 16 km consists of dispersal (Lonsdorf et al. 2016). Data availability and computational advancements allow us to greatly increase the temporal scale of the model relative to that considered in Lonsdorf et al. (2016): rather than focus on migratory jumps we iterate across each day of the nonbreeding period. As such, our model begins after the molting stage of waterfowl (1 September of one calendar year) and terminates prior to the breeding period (31 May of the following calendar year). We use known values from the literature for physiological, anatomical, and metabolic dynamics to inform our model (Table 1).

The workflow to simulate daily movement was constructed to most closely approximate the actual processes of movement, dispersal, and migration while operating under the constraints of a sequential modeling framework. Our pattern proceeded as:

Forage → Departure → Arrival → Mortality → Forage...

Within each component of our model there were secondary procedures invoked, for example, to effectively allocate forage material among individuals within the population and to distribute individuals across the landscape according to the spatial pattern of high-quality habitat. The

overall workflow is depicted in Figure 1. R code (R Core Team 2018) is available in Supporting Materials File S1.

(1) Forage

A simulated day began with foraging, a weather- and body condition-dependent process, which transfers energy from forage material on the landscape into energy as fat to individual birds. Individuals in each node (distributed spatially according to NatureServe range maps [Ridgley et al. 2005] and breeding population survey data) were allocated among 21 body condition classes, with higher classes representing better body conditions. Body condition is a function of body fat; individuals falling below body condition class one (into class zero) had 0% body fat content (fatal). An individual's ability to accumulate forage—its rate of daily gain (DG)—was a function of disturbance (degree of urbanization in a node), fuel deposition rate (FDR , kJ per day), and temperature-dependent basal metabolic rate (Aagaard et al. 2018). We summed the fuel deposition of each individual to calculate the amount of energy removed from the landscape in each node as a result of active foraging.

To calculate the rate of natural decay (D) in forage material we multiplied the amount of forage material (E , kJ) present in each habitat type (shoreline, crop, wooded wetland, herbaceous wetland, Table 2) by a land cover-specific decay rate (r) to the power of the day of the nonbreeding period (i):

$$D = E \times r^i.$$

We calculated the total forage available on the landscape in the next time step by subtracting the amount of forage material subject to decay and active foraging from the total amount of forage available (F) at the outset of day i ,

$$F_{i+1} = F_i - D - \sum FDR.$$

(2) Departure

Each day, individuals must decide whether to stay and continue foraging or depart from a node. We assumed that individuals in poorer body condition experiencing mild weather nearest to breeding nodes with potential for high rates of gain of body mass were less likely to leave a node, instead remaining to continue foraging, while individuals in better body condition facing severe weather far from breeding nodes with potential for low rates of gain of body mass were highly likely to leave. The probability of individuals remaining in a given node or departing from it depends on each individual's body condition (BC), the weather severity index (WSI) within the node, the distance between the origin node and the nearest breeding node (DB), and the disturbance-dependent daily gain in body mass (DG). The components were combined according to the following equation:

$$\sum Pr(\text{depart}) = Pr(\text{depart}|WSI) + Pr(\text{depart}|BC) + Pr(\text{depart}|DB) + Pr(\text{depart}|DG).$$

Three of the four components, BC , WSI , and DB , were each calculated using a Monod function, which produced a saturating curve for the target effect, with exponents applied to vary the shape of the resulting curve. Daily Gain was calculated using a linear decreasing function. The discrete probabilities of departure had the following forms:

$$Pr(\text{depart}|WSI) = \left(\frac{(WSI + 7.5)^3}{(WSI + 7.5)^3 + (7.5)^3} \right),$$

$$Pr(\text{depart}|BC) = \left(\frac{BC^8}{BC^8 + (N_{BC \text{ classes}} - 3)^8} \right),$$

$$Pr(\text{depart}|DB) = \left(\frac{DB^5}{DB^5 + \text{flight range}^5} \right),$$

$$Pr(\text{depart}|DG) = \left(\frac{1 - (FDR + 1)}{5} \right).$$

The values for the exponents in each of these three cases were selected to generate reasonable curves for each probability of departure component. We assessed what constitutes “reasonable” based on the reaction in the model to changes in these values. We expected that the curve for the body condition component should have a pronounced inflection point to represent a high probability of departure for birds in the highest body conditions (top three), and a relatively low probability of departure for birds in moderate to low body conditions. Weather severity, in contrast, should be relatively more linear. Thus, we set the exponents in body condition to be nearly three times as great as those in *WSI*.

More formally, we calculated the number of individuals departing each node as the product of the abundance per node, i , on day, k , and the proportion of individuals in each BC, j ; this product was then multiplied by the BC -dependent probability of departure:

↳

(3) Arrival

Once individuals choose to depart, they must decide how far to fly and where to land. How far birds can fly is a function of body condition (mass, body fat proportion), flight cost, and flight velocity. Using the relations set forth in the program Flight (for Windows, version 1.25 [<http://www.bio.bristol.ac.uk/people/pennycuick.htm>]; Pennycuick 2008), we calculated the chemical power, velocity for maximum range, and effective lift-to-drag ratio for birds from a distribution of available body masses, wing spans, wing areas, and at various air densities, across a range of potential true air speeds. These calculations led to the ultimate output of the flight cost (kg of fat metabolized per km) and flight velocity (km per hr), for the input range of

217 morphometric features. The code used to generate these calculations is included in Supporting
218 Material File S4.

219 Birds determine where to land based on WSI , forage availability, roosting habitat, and
220 distance to breeding grounds. On average, birds will tend to select more attractive nodes, that is,
221 nodes with low winter severity (WSI) and higher air density (AD), plentiful forage availability
222 and roosting habitat (R), nearer to breeding grounds, and within the flight range (defined as a
223 node-specific gamma movement probability, G ; the cumulative probability of moving from a
224 node to all other nodes in the landscape based on the distance between each pair of nodes). We
225 used a Cobb-Douglas function to combine these factors.

226 We restricted movement to nodes in which the WSI was below the empirically derived
227 threshold (7.5; Schummer et al. 2010). The remaining four components of the arrival function
228 (forage, roosting, breeding ground distance, gamma movement probability) were individually
229 weighted to allow for the differential significance of particular parameters (w_f , forage
230 availability; w_a , air density; w_r , roosting quality; w_b distance to nearest breeding node; and w_g ,
231 node-specific gamma movement probability). We also assumed variable relative importance of
232 each component over time (Figure 2). We assumed that distance to the nearest breeding node
233 was the most important consideration for migrants proximal to the breeding period (i.e., early
234 and late in the nonbreeding period). We assumed that forage availability and roosting quality
235 increased in importance up to the mid-winter period of the nonbreeding period—with forage
236 increasing more so than roosting—and then decreased to initial values again by the end of the
237 nonbreeding period. We held the node-specific gamma movement marginal probability steady
238 across the nonbreeding period because the probability of moving between any given pair of
239 nodes (depending only on the distance between them) should not vary temporally.

240 Input values for the component weights were, for w_f , 0.45 , w_a , 0.3, w_r , 0.2, and w_g , 0.05.

241 The weight for the distance to breeding grounds, w_b , was set to the sum of the daily weights for
242 all other components subtracted from one. To establish the structure of the weights for the
243 components assumed to have non-linear dynamics we randomly selected a date during the mid-
244 winter phase of the nonbreeding period (between 31 December and 31 January) to serve as our
245 inflection point. We then generated a sequence of values, c , from 1 to 0.1 to 1, with an inflection
246 occurring on the specified day of the nonbreeding period, d , for use in a function to calculate the
247 corresponding weights for each component:

$$248 \quad w_f = - \left(0.9 \times \left(\left(c_d - \left(\frac{c_d}{n} \right) \right)^2 \right) \right) + 0.45$$

$$249 \quad w_a = - \left(0.6 \times \left(\left(c_d - \left(\frac{c_d}{n} \right) \right)^2 \right) \right) + 0.3$$

$$250 \quad w_r = - \left(0.4 \times \left(\left(c_d - \left(\frac{c_d}{n} \right) \right)^2 \right) \right) + 0.2$$

$$251 \quad w_g = 0.05$$

$$252 \quad w_b = 1 - \sum (w_f, w_a, w_r, w_g),$$

253 where n is the length of the nonbreeding period in days.

254 Using this process to generate the daily weights, the full Cobb-Douglas function for the
255 probability of arrival in a given node was defined as:

$$256 \quad A = F^{w_f} \times AD^{w_a} \times R^{w_r} \times DB^{w_b} \times G^{w_g}.$$

257 Each of these components was normalized to a 0-1 scale, using $\frac{x - \min(x)}{\max(x) - \min(x)}$; the node with

258 the greatest amount of forage availability on a given day was assigned a normalized forage

259 availability score of 1; we repeated this calculation for roosting quality, distance to nearest
260 breeding node, and node-specific gamma movement probability.

261 (4) *Mortality*

262 We assumed that individuals in poorer body conditions had higher daily rates of mortality than
263 individuals in better body conditions—in keeping with the assumption of increased mortality
264 with increased energy deficits (e.g., Lonsdorf et al. 2016). Each day we multiplied the
265 survivorship associated with a given body condition by the number of individuals in that body
266 condition class.

267

268 *Daily Abundance* – We redistributed individuals across the landscape and among body condition
269 classes according to their probabilities to stay/depart and arrive. We calculated the following
270 day’s abundance in a node as the product of the total number of individuals departing all nodes
271 and the probability of arrival in the node:

272

$$273 \quad \hat{I} = \hat{I}_d,$$

274

275 added to the difference of the current abundance and the number of individuals departing the
276 node.

277 We computed the number of individuals departing a node in each body condition and the
278 number of individuals remaining in a node in each body condition. We decremented the body
279 condition of departing individuals according to the distance between origin-node and destination-
280 node, using established relations for the mass-dependent cost of flight per unit distance (e.g., see
281 Aagaard et al. 2018). This decrement-function informed the number of individuals arriving in

each node in each body condition, which we used to calculate the number of individuals in each node in each body condition class on the following day.

The final abundance for a given node on the following day was the abundance in that node on the current day minus the number of individuals that died in that node on that day. Taken together with *Arrival*, this produced:

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Parameterization – For some parameters in our model there is a lack of empirical evidence to inform their value. We defined these parameters probabilistically, as a function of body condition, to allow for sensitivity in the model (Table 1; see also Appendix S1 for definitions of parameters and distributions). These included daily survivorship, flight power components, and energetic costs of flight. We also allowed parameters with known individual variation to vary within the population, such as flight velocity, body mass, and proportion of body mass composed of metabolizable lipids. We applied these distributions to the starting population of ~20 million birds and updated the fluctuating variables according to incurred energetic costs (body mass, available metabolizable lipids). This arrangement allowed us to capture a realistic representation of the distribution of realized values for each parameter in the model without unreasonably increasing computing time. We varied the parameter values associated with the prior distributions for morphological features to evaluate their effects on the model (monitoring estimated survivorship as a comparison point), including daily survivorship, flight power components, morphological components, and energetic components.

(1) *Daily Survivorship*

Daily survivorship ranged from 0.99620 to 0.99984, from the second body condition bin to the optimal body condition bin (body condition bin 1 represented dead individuals, survivorship = 0). We assumed birds that exceeded some critical mass would experience heightened mortality as a result of increase predation risk (or decreased predation avoidance ability), in keeping with optimal body mass theory (Lima 1986). We therefore set the optimal body mass to be that of a 1.625 kg bird (~0.134 kg of fat), about the maximum of observed mallard body masses in the field (Owen and Cook 1977; while noting and allowing for the rare occurrence of heavier birds).

(2) *Flight power components*

Air density was informed by measured and interpolated air pressure values, as detailed in Appendix S1. The absolute range in air density across the period of sampled data was 0.95 to 1.3

$\frac{kg}{m^3}$. The true air speed – that is, the velocity at which molecules *appear* to move past a moving

body from the perspective of the body in motion – ranged from 10 to $25 \frac{m}{s}$. Flight velocity (the actual velocity of the body in motion) ranged from 75.92 to 87.37, according to relations laid out in Flight (for Windows, version 1.25 [<http://www.bio.bristol.ac.uk/people/pennycuick.htm>]; Pennycuick 2008).

(3) *Morphological components*

Body mass, wing span, and wing area were all modeled to follow skew-normal distributions with $\mu = 1.2$ and $\sigma = 1.21$ [body mass], $\mu = 0.95$ and $\sigma = 1$ [wing span], and $\mu = 0.1$ and $\sigma = 0.1$ [wing area] (Owen and Cook 1977; assuming most individuals begin migration only when closer to optimal body condition). The proportion of body mass composed of metabolizable lipids (*kg*) was set to 11%, and was subsequently allowed to vary from 8 to 14% (using values from Dabbert

et al. 1997, Boos et al. 2007). Lipids account for ~81% to 84% of metabolizable energy (Boos et al. 2007). Not all lipids are available for metabolic processes (some retained for other purposes, not detailed; Boos et al. 2002, 2007). We assume the ~16% to 19% of metabolizable energy provided by sources other than lipids is used for processes other than flight (basal metabolic rate, reproductive organs, cellular replacement, etc.). Therefore, we assume that all energy directed toward powered flight relies on lipids as its source exclusively, and not all the ~10% to 16% of body mass comprised of lipids is available for powered flight processes.

Body mass had a mean of 1.2 *kg* (Owen and Cook 1977, Pennycuick 2008). This resulted in a distribution with a range of 0.5 to 2 *kg*. Wing span and wing area had ranges of 0.75 to 1.15 *m* and 0.09 to 0.11 *m*² (respectively; Bruderer and Boldt 2001).

(4) *Energetic components*

The cost (*kg* of body fat) per unit distance flown (*km*) ranged from 2.1×10^{-5} to 1.6×10^{-4} , according to relations laid out in Flight (Pennycuick 2008). Without clear guidance from the literature to inform a consistent relationship between fuel deposition rate and climatic factors, we defined the coefficient of fuel deposition rate as a multiple of body mass and set it to 1.1% initially, and subsequently set it to 0.5 and 2 to represent low and high values. This arrangement is in line with values presented by Lindström (2003), in which the maximum fuel deposition rate for a ~1 *kg* non-passerine bird caps out at 2% of the lean mass, with a minimum of 0.3%.

Migration paths – For each year of the simulation we recorded a migration “path” – an approximation of the median route taken by the population during the nonbreeding period. We computed the abundance-weight center-of-mass for the population on each day; given the spatial distribution of individuals within nodes across the landscape, we identified the point representing

the centroid of the population (Figure 3). By tracking the latitude of this point each day we assembled a trajectory representing the latitudinal and longitudinal shift of the centroid of the population throughout the nonbreeding period. Evaluating the nadir of the latitudinal shift across years informs potential temporal patterns in migration and overwintering dynamics. For example, one might expect a general northward regression of the southern-most point of the population center-of-mass through time as average global atmospheric temperatures increase (Aagaard et al. 2018). Alternatively, the southern-most point might be more closely related to weather severity, with a changing climate leading to increasingly variable weather patterns from one year to the next; as such, there may not be a consistent decrease in severe weather but rather more frequent extremes (more unusually mild and unusually severe weather years). By regressing the southern-most point of the population center-of-mass with year and *WSI* we can potentially parse this difference.

We calculated the mean distance between all consecutive population centers-of-mass, as well as the distance between the northern-most and southern-most population centers-of-mass. These metrics informed the mean distance moved by the population from one day to the next, as well as the separation between breeding grounds and overwintering habitat. We identified the most commonly used nodes during the course of the nonbreeding period by measuring the total abundance in each node on each day to compute the top 2% most populated nodes per day. We used these metrics to produce animations for each year of the record showing the daily, normalized (0-1) abundance for each node in the landscape.

Data sources – Our model takes as input six data layers relating to habitat state and weather conditions. There are five layers relating to habitat state; the first was derived from National

372 Land Cover Database (NLCD) 2006 for the USA (Fry et al. 2011) and the CSC2000v for Canada
373 (*available online*; see Appendix S2) to estimate roosting and foraging quality. We used
374 NatureServe range maps (Ridgley et al. 2005) to identify potential starting locations among
375 which to distribute birds at the onset of the nonbreeding period. We used these input layers in
376 conjunction with breeding population survey data (U.S. Fish and Wildlife Service 2013) to
377 establish abundance at breeding sites by weighting the total number of birds by the quality of
378 habitat within the site and the breeding population survey results for the area. We relied on daily
379 climate data from the National Oceanic and Atmospheric Association's National Centers for
380 Environmental Prediction National Center for Atmospheric Research Reanalysis Project (NOAA
381 NCEP; Kalnay et al. 1996).

382 We considered sites with a higher proportional area of shoreline, herbaceous wetlands, and
383 wooded wetlands to be of higher quality for roosting. In this fashion, breeding sites of high
384 quality aligning with large numbers of birds from the breeding population survey hosted the
385 greatest numbers of individuals. We estimated mean forage availability per site (in 0.1 GJ units)
386 at the outset of the nonbreeding period based on an evaluation of land cover using a range of
387 parameter estimates. Further details of this process, and the values used for the forage
388 availability parameter estimates, are available in Lonsdorf et al. (2016).

389

390 *Landscape generation* – Mallards have documented preferences for wetlands with shallow water
391 (5–20 cm) in which to forage and near which to roost (Colwell and Taft 2000, Guillemain et al.
392 2000). We classified shoreline cover as optimal roosting habitat (i.e., with a value of 1, while all
393 other cover types are 0), and calculated the proportion of each node occupied by shoreline cover.

394 Multiplying this proportion by the area of the focal node yielded the value of roosting quality
395 provided by that node.

396 We multiplied the amount of forage provided by each land cover type represented within the
397 node (using food-habit information from the literature; see Lonsdorf et al. 2016) by the
398 proportion of the node classified as each land cover type. We multiplied this value by the
399 proportion of forage *available* in a node, based on the distance to the nearest roosting site. Areas
400 in which forage and roosting habitat were nearby had greater proportions of their forage
401 available for consumption to account for a decrease in net energy extracted from a node given
402 the increased distance traveled to the foraging sites within the node. We multiplied this roosting
403 distance- and area-dependent forage availability measure by the area of the node to calculate the
404 quantity of forage available in each node (Pearse et al. 2012, Beatty et al. 2014).

405

406 *Winter severity* – To quantify the severity of the weather in a given node (and thus the
407 probability that birds will occupy that node), we followed the framework of Schummer et al.
408 (2010) wherein a weather severity index (*WSI*) was calculated based on the depth of snow in a
409 node (S , cm), the number of consecutive days with snow depth ≥ 2.54 cm (S_{days}), the temperature
410 in a node (T , °C), and the number of consecutive days with temperature < 0 (T_{freeze}). The
411 formulation follows:

$$412 \quad WSI = (S \times 0.394) + S_{days} + (-T) + T_{freeze}.$$

413 Schummer et al. (2010) found that the rate of change of the relative abundance at a location
414 switched from positive to negative when $WSI = 7.5$; we invoked this value as the threshold below
415 which individuals were expected to remain in a node and above which individuals were expected
416 to depart.

417

418 *Model evaluation* – We monitored a suite of metrics as we iterated our simulation across years to
419 evaluate the degree to which migratory patterns differed annually. We monitored nonbreeding
420 period mortality ($N_0 - N_n$; n is the last day of the nonbreeding period). We also monitored
421 landscape availability, based on the number of nodes in which the *WSI* was less than the
422 threshold each day. We calculated the mean availability (and standard deviation) of habitat, as
423 well as the minimum availability at any point during the nonbreeding period. These values
424 informed the average weather severity across the nonbreeding period, and the severity of the
425 weather during the least hospitable portion of the nonbreeding period. We ran the model in R (R
426 Core Team 2018).

427

428 **Results**

429

430 *Objectives* – As expected, we observed weather patterns and conditions effecting the
431 nonbreeding period of the annual cycle of migratory birds. We were able to discern
432 overwintering habitat as an emergent property of the model (Figure 3). The average proportion
433 of available habitat ($WSI < 7.5$) across the landscape increased as winter weather severity
434 decreased (Figure 4A), and mortality decreased as the proportion of available habitat increased
435 (Figure 4B). Unexpectedly, mortality did not demonstrate any correlative trend with weather
436 severity (Figure 4C), perhaps because birds flew beyond the range of the affected area.
437 Importantly, whereas we summarized weather severity across the entire landscape, there was
438 spatial heterogeneity in the variation of weather severity. The summarized *WSI* in the available
439 habitat showed a slight increase over time, with a few years of above-average weather severity

later in the record (especially 2009-2010 and 2010-2011). However, the summarized *WSI* across the entire landscape decreased more dramatically over the same timeframe (even 2009-2010 and 2010-2011 produced below-average *WSI* scores) (Figure 5). We plotted the standard deviation of the mean annual *WSI* for each node across the period of record to demonstrate this point (Figure 6).

We were successful in our attempt to recover the primary avenues for migration (Figure 7 and File S4): a heavily-used central flyway along the Mississippi River, a well-defined Atlantic Flyway east of the Appalachian Mountains, and a disjointed Pacific Flyway along the west coast. The flyways tended to converge within the Prairie Potholes Region and along the southern shore of Hudson Bay (which is the NatureServe defined breeding region). The most commonly used nodes during the course of the nonbreeding period were generally consistent across years (Figure 7). The center-of-mass of the population during the migratory periods were similarly consistent across years, while the overwintering period showed more inter-annual variation (Figure 7). Finally, the model yielded strong evidence of the effect of *WSI* on the distribution of birds on the landscape. The mean distance among all daily center-of-mass locations was highly correlated with the standard deviation of available habitat ($\text{adj.-}R^2 = 0.86$; Figure 8), suggesting that the distribution of birds on the landscape changed more dramatically when the variation in daily available habitat was greater.

Temporally, we were able to distinguish between severe and mild years by their mean daily *WSI* values across the landscape, and the years identified as severe or cohered to historical weather anecdotes. We found that years with severe weather yielded correspondingly reduced available habitat during the winter months (Figure 10). Finally, we found that as *WSI* increased,

the population moved farther south during the nonbreeding period as available habitat was reduced (Figure 10, and see Appendix S3).

Validation – Our model predicted an average survivorship of 77.4% for the nonbreeding period across all years (range = 76.4 – 78.4%). This value is decomposed into an average survivorship rate of 91.3% for the autumn migratory period (1 September to 30 November; 90.5 – 92.1%), 91.8% for the overwintering period (1 December to 28 February; 91.1 – 92.6%), and 92.4% for the spring migratory period (1 March to 31 May; 91.5 – 92.9%). Mean daily mortality across the period of record ranged from 13,100 to 21,000 birds (Figure 9). These estimates are commensurate with literature-derived mortality estimates (Zimmer et al. 2010, Davis et al. 2011).

Parameter sensitivity – The proportion of birds in different body condition bins varied most strongly at lower classes, with a two-order of magnitude increase in the proportion of birds in the lowest body condition (starvation) over the nonbreeding period, and a 20% reduction in birds in the top body condition. Decreasing the proportion of metabolizable body fat to 8% resulted in survivorship (averaged across all years) of 86.72% (85.87 – 87.37%), whereas increasing it to 14% metabolizable body fat yielded survivorship of 50.66% (50 – 51.35%). Increasing the coefficient for the fuel deposition rate to 2 increased survivorship to 89.15% (89.05 – 89.22%), whereas decreasing it to 0.5 decreased survivorship to 41.03% (39.99 – 41.95%) (while holding the proportion of metabolizable body fat steady at 11%).

Discussion

485

486 We elaborated an energetics-based model of avian migration to more fully realize the stochastic
487 variation in migration induced by daily weather. Our model was able to recreate documented
488 North American avian migration routes (La Sorte et al. 2014a, La Sorte et al. 2014b, Lonsdorf et
489 al. 2016) and recover expected rates of survivorship (Lonsdorf et al. 2016; $90.5 \pm 1.35\%$ [mean \pm
490 confidence interval] survivorship in autumn, $93.6 \pm 1.1\%$ survivorship in spring) based on
491 nothing more than first-principle arrangements of dabbling duck energetics and behavior. With a
492 thorough literature review and carefully considered parameterization, the model we present here
493 can be generalized to any migratory bird species. Extending the model to the entirety of the
494 nonbreeding period is a crucial step on the path to developing a generalizable energetics-based
495 full-annual-cycle model (Marra et al. 2015). We included consideration of weather severity on
496 the movement patterns of migrants, allowing us to form initial expectations about the role
497 climate and climate change can play in altering physiology and subsequent migration behavior
498 (Notaro et al. 2016). We introduced a refined forage availability scheme by allowing for
499 consumption and natural decay of forage material during the nonbreeding period.

500

501 *Interpreting results* – Our model suggests that the milder conditions across North America
502 resulting from climate change (Appendix S3; Schummer et al. 2017) are increasing the
503 proportion of habitat available to dabbling ducks which has led to decreased environmentally
504 induced mortality. This result is evident in the decrease in *WSI* over time across the continent,
505 demonstrating generally less severe winters over the period of record. This result is also
506 evidenced in the relationship between *WSI* and the minimum proportion of available habitat, with
507 less available habitat in years with greater *WSI*.

Walther et al. (2002) indicated that freeze-free periods were lengthening and that snow cover has decreased since the 1960s. If these trends continue, as recent studies suggest (Notaro et al. 2014), we may expect to see more northerly overwintering (Abraham et al. 2005, Link et al. 2006, Tingley et al. 2009, Notaro et al. 2016). Taken to the extreme, this development may suggest that mallard-like dabbling ducks could be approaching a cessation of migration (Moore 2011, Notaro et al. 2016, Aagaard et al. 2018). Recent studies investigating the changing patterns of avian migration under the influence of climate change provide corroborating evidence of this possibility (Walther et al. 2002, La Sorte and Thompson 2007); American black ducks (*Anas rubripes*), for instance, have shown a tendency to remain in the region in which they breed during migration, and some occasionally move in directions antithetical to conventional migratory movements (Brook et al. 2009, Robinson et al. 2016). Whether this movement represents inexperienced birds or the influence of climate or land use/land cover change has not been decisively determined, but mounting evidence of similar patterns paired with the findings of this and other simulation models suggest it is the latter.

By varying the proportion of available metabolizable body fat we were able to identify sensitivity within the model. The effect of modifying the proportion of available metabolizable body fat was counterintuitive; increasing body fat functionally increases available fuel and should decrease time spent migrating, the most energy expensive aspect of the nonbreeding period. However, the proportion of body fat does not influence the cost of flight, so two individuals of the same body mass but different body fat proportions will be subjected to the same energetic costs. The individual with a greater proportion of body fat will be able to travel farther, decreasing its body mass more substantially and (based on the structure of our model)

subsequently transitioning into a lower body condition class with a lower associated daily survivorship.

Given the harsher conditions and limited habitat availability during the overwintering period (see Appendix S3), the lower survivorship is expected. In autumn, we expect greater forage availability on the landscape than in winter (and possibly even spring), as seed and waste grain has not yet decayed (Hagy and Kaminski 2012), so we expected higher survivorship during this period. However, the timing of energy expensive migration fell in the autumn period (1 September to 30 November), which led to greater reductions in body condition and therefore generally greater mortality rates. The higher mean survivorship rate of spring is likely a result of less intense weather severity than in either the fall or nonbreeding periods.

When reviewing extreme weather events within the period of record we considered, there is appreciable concordance with *WSI* and observed extremes (e.g., deep freezes in the south, as in 1957-1958, and 1961-1962). Events such as these, coupled with our model results, offer support for the claim that poor weather tends to push birds farther south in search of hospitable habitat (Figure 9). Conversely, mild years (such as 2015-2017) provide more available habitat across the landscape (Figure 9), likely leading to the population generally staying closer to the breeding grounds and demonstrating more willingness to withstand brief inclement weather, with the expectation that more hospitable conditions await after it quickly passes. As climatic conditions increase in variability this change could have dramatic effects on migratory dynamics, as some years may see birds move only a short distance from the breeding grounds, while in other years, comprised of extreme weather events, birds may be pushed relatively far south. If the tendency of waterfowl is to remain sedentary as extreme events pass through, and if these events end up lasting longer, this sedentary inclination could lead to unusually high mortality events in some

years. Historical data show a clear divergence in the spatial variation in weather severity, consistent with expectations of increasingly extreme weather as the climate changes, so predictions of general trends will necessarily be obscured by these spatially inconsistent weather pattern changes.

Waterfowl enthusiasts (e.g., birders and hunters, Cooper et al. 2015) contribute >\$100 million annually to the economies of Canada and the U.S. (Mattsson et al. 2018, 2020). Should migration distance continue to shorten and sedentary behavior increase, the availability of waterfowl to birders and hunters would likely be affected, potentially leading to decreased funding in support of wetland habitat conservation (Grado et al. 2001, Cooper et al. 2015, López-Hoffman et al. 2017). If hunter behavior were to change in response to differing migratory patterns, the distribution of monetary resources would likely change as well (López-Hoffman et al. 2017, Bagstad et al. 2018, Mattsson et al. 2020).

Future research directions – Our model has many important strengths in terms of advancing our understanding of avian nonbreeding movement patterns within the context of energetics and weather. We sought to maintain flexibility in the model for ease of adding components that might increase the power of the model. We did not add these components in the present iteration because, in some cases, there remain critical gaps in our knowledge requiring further research. For example, while we included a placeholder for harvest-induced mortality, an important aspect of migration dynamics (Klaassen et al. 2005, Vaananen 2001), we lacked access to data at the relevant spatial scale to inform the effect of this source of mortality across the landscape. Efforts to aggregate such data for inclusion in future iterations of this model would be extremely useful.

Because waterfowl migration is mediated on a daily time-step via weather, predicting waterfowl availability on time horizons useful to hunters could be possible.

While we used pertinent land cover data to inform forage availability across the landscape, we are aware of limitations in converting land cover classes into available kilojoules, as well as grouping potentially distinct land cover classes into broad categories (Malishev and Kramer-Schadt 2021). Targeted research into the seasonally varying availability of accessible forage (including invertebrates) in various land cover classes is necessary to better inform this aspect of the model (e.g., Fredrickson and Reid 1988, Kaminski et al. 2003, Bishop and Vrtiska 2008, Beatty et al. 2017). Improving the reliability of spatial data layers is of particular importance to eIBMs, given the significance of this input on the resulting dynamics predicted by the model (Malishev and Kramer-Schadt 2021). Similarly, despite formatting our model with an agent-based rather than individual-based framework, we ignored another main challenge eIBMs face (Malishev and Kramer-Schadt 2021): accounting for complex behavior and movement (e.g., sociality and predation avoidance). Refining our understanding of the probabilistic tendencies of individuals to alter movement dynamics as a function of social dynamics or predation threat would greatly improve our approximation of especially small-scale (short-distance) movement.

In other cases, we omitted potentially important components because the complexity they add to the model significantly inflates computational time. We foresee a framework for adding in additional components in a serial, stepwise process. That is, we first developed a generalizable energetics-based landscape model for avian migration (Lonsdorf et al. 2016), then laid the foundation for the interaction between temperature and migration energetics (Aagaard et al. 2018), and now merge those efforts to generate a generalizable continental-scale energetics-based landscape model of avian migration accounting for variable temperature and weather

severity and their effects on migratory dynamics. By building toward the ultimate goal of a fully generalizable and energetics-based *animal* movement model one block at a time we provide a cogent work flow and fully elaborate the logic at each step. Thus, we have for now ignored the effect of some aspects such as wind direction on avian migration dynamics, a component known to be predictive of movement patterns (La Sorte et al. 2014b). Adding model functions and data relating to daily wind currents and velocity would likely improve the realism of our model and provide refined predictions for migration routes and critical habitat areas (Gutierrez Illan et al. 2017).

We also excluded competition (Eichhorn et al. 2009, Stirnemann et al. 2012) and epidemiological effects (Gilbert et al. 2006) from the model. While we found that *WSI* has generally increased over time and led to decreased mortality, it is possible that altered disease dynamics may counteract these gains in survivorship (i.e., as the climate becomes milder, disease transmission may increase; Harvell et al. 2002), while decreased competition may provide the opposite influence. Developing techniques to account for these dynamics in the model would be beneficial. As with all models, we must balance realism in the model with the usefulness of the general trends and predictions of the model.

Lastly, we made preliminary connections between the body condition of birds at the end of the nonbreeding period and the energy available for reproduction during the breeding period. Assuming an energy conversion of 39,700 kJ per kg of body fat (Rayner 1990), and an energy content of 400 to 636 kJ per egg (636 kJ in Ricklefs 1977; 487 kJ in Sotherland and Rahn 1987; 400 kJ in Alisauskas and Ankney 1992), we estimate that, for 400 kJ per egg, only birds with body mass greater than 0.725 kg and above would have sufficient fat reserves available at the outset of the breeding period to lay at least one egg, and for 636 kJ per egg, only birds with body

mass greater than 0.8 kg would be able to lay at least one egg (see Krapu 1981 for discussion of body condition and breeding period success). Given a clutch size range for mallards of eight to 13 eggs (Drilling et al. 2020), we estimate that only birds with body mass over 1.4 kg (for 400 kJ per egg) or over 1.625 kg would lay a full clutch of eggs at the beginning of the breeding period. Birds in lower body conditions would need more time to forage to restock fat reserves sufficiently to produce a full clutch size. The modeled distribution of birds in each body condition at the end of the nonbreeding period indicates that approximately 3% (for 636 kJ per egg) to 15% (for 400 kJ per egg) of the population could effectively lay a standard size clutch of eggs at the beginning of the breeding period, also allowing for the possibility of a second clutch (depending on the size of each) later in the breeding period given a rapid enough rate of fuel deposition.

Conclusions – Accelerating change to land cover and climate is eroding avian migration as we know it. Merging environmental conditions with spatially explicit models of energetics-based migratory movements is helping to inform how the landscape affects migration patterns. Our model approximates avian migration during the nonbreeding period and the movement occurring among local stopovers along the way. Our results indicate that available habitat during the nonbreeding period has likely increased over time, indicative of milder conditions as a product of a changing climate, ultimately leading to decreased (environmentally induced) mortality. This finding has important ramifications: if migration distance continues to diminish and the tendency for sedentary behavior increases, we may see altered hunter harvest across the landscape. Additionally, if sedentary behavior in the face of extreme events continues then birds may experience unusually high mortality events in some years. All these possibilities underscore the

need for continued advancements in the vein of this model to further illuminate the consequences of a changing environment on avian migration.

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Data Accessibility

All data are stored in publicly available repositories as cited in the paper (e.g., weather data comes from the National Oceanic and Atmospheric Administration's National Centers for Environmental Prediction). We provide all code as Supporting Information, and the code has annotated references to each data set.

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913 **Tables**

914 **Table 1.** Definition, values, and units for each parameter used in the model.

Parameter	Definition	Value	Units
d	Local movement distance	3,000	m
v	Mean flight velocity	76 – 86	km/hr
e	Energetic cost of flight (per hr)	0.042 – 0.076	kJ/hr
w	Weather Severity Index threshold	7.5	—
r	Flight range	2,253	km
n	Node size	32.187	km
N_0	Initial population size	19,856,514	individuals
m	Body mass	800 – 1,300	grams
LCT	Lower Critical Temperature	$47.2 \times (m \times 1000)^{-0.18}$	°C
s_d	Daily survivorship range	0.9975 – 0.9997	—
f	Proportional body fat range	0 – 0.13	—

915

916 **Table 2.** Values assigned to the weights for natural forage decay rates in available land cover
917 classes.

Land cover class	Weight
Shoreline	0.9998
Crops	0.9970
Woody wetlands	0.9965
Herbaceous wetlands	0.9910

918

919 **Figure Legends**

920 **Figure 1.** Graphical representation of the order of operations of the model. We initiated (1)
921 foraging activity (i.e., the loss of forage material from the habitat as a result of active foraging
922 and natural decay and the subsequent acquisition of the actively foraged material to augment
923 body condition, **BC**) prior to (2) departure, the probability of which was dictated by the node-
924 specific weather severity index (*WSI*), class-specific **BC**, distance between a focal node and the
925 nearest breeding node (distance to breeding grounds, **DB**), and the node-specific air density
926 (**AD**). Arrival of individuals (3) followed, informed by node-specific forage quantity (**F**),
927 roosting habitat quality (**R**), cumulative gamma-movement probability (the probability of
928 moving between each pair of nodes on the landscape, given the distance between them; **G**), as
929 well as **AD** and **DB**. Individuals were then redistributed among **BC** classes according to energy
930 expended in flight and were redistributed spatially based on to-from node flights. Finally, the
931 population incurred mortality (4) according to survivorship rates related to each **BC**. We
932 calculated the number of individuals per body condition after mortality and arrival, as well as the
933 number of individuals per node, for the following day.

934

935 **Figure 2.** Graphical representation of exponential weights for each of the four components of the
936 Cobb-Douglas function used to define node attractiveness over time: amount of forage
937 availability, air density, proportion of roosting habitat in each node, distance to the nearest
938 breeding node, and a cumulative probability of moving to a node from all other nodes based on a
939 gamma function.

940

Figure 3. An example of the abundance-weighted center-of-mass for the population on the 50th day of migration, represented by the black dot. The gray shaded areas represent the top 2% most populace nodes on day 50.

Figure 4. (A) Normalized $\left(\frac{x_i - \bar{x}}{sd(x)}\right)$ minimum available habitat on the landscape as a function of normalized weather severity index (*WSI*); (B) Normalized mortality during the nonbreeding period (September to May) as a function of normalized minimum available habitat; and (C) Normalized mortality as a function of normalized *WSI*. Black lines indicate the line of best fit of a generalized linear model and associated standard error (gray shaded area).

Figure 5. (A) Mean weather severity index (*WSI*; Schummer et al. 2010) within the available habitat (areas with *WSI* < 7.5) and (B) across the entire landscape showed differing patterns over time.

Figure 6. The standard deviation in the annual mean weather severity index (*WSI*) over the period of record (1957 – 2019) for each node in North America. Mid-latitude and above areas were subject to greater variation in weather severity over time than southerly areas, which are more consistently incorporated in “available habitat” (areas with *WSI* < 7.5).

Figure 7. Map showing the 2% most populace nodes, in gray, across the nonbreeding period (September to May) for all years (1957 – 2019). The darker the gray the more often a node occurred within the 2% most populace nodes across the record. The 2% most populace nodes were similar across most years, hence the consistent patches. Lines represent the path of the

964 abundance-weighted population center of mass, or migration route, across years, with the mean
965 of all years in black.

966

967 **Figure 8.** The mean distance among all abundance-weighted center-of-mass locations for the
968 population on each day increased as the standard deviation of the daily proportion of available
969 habitat (weather severity index < 7.5) increased.

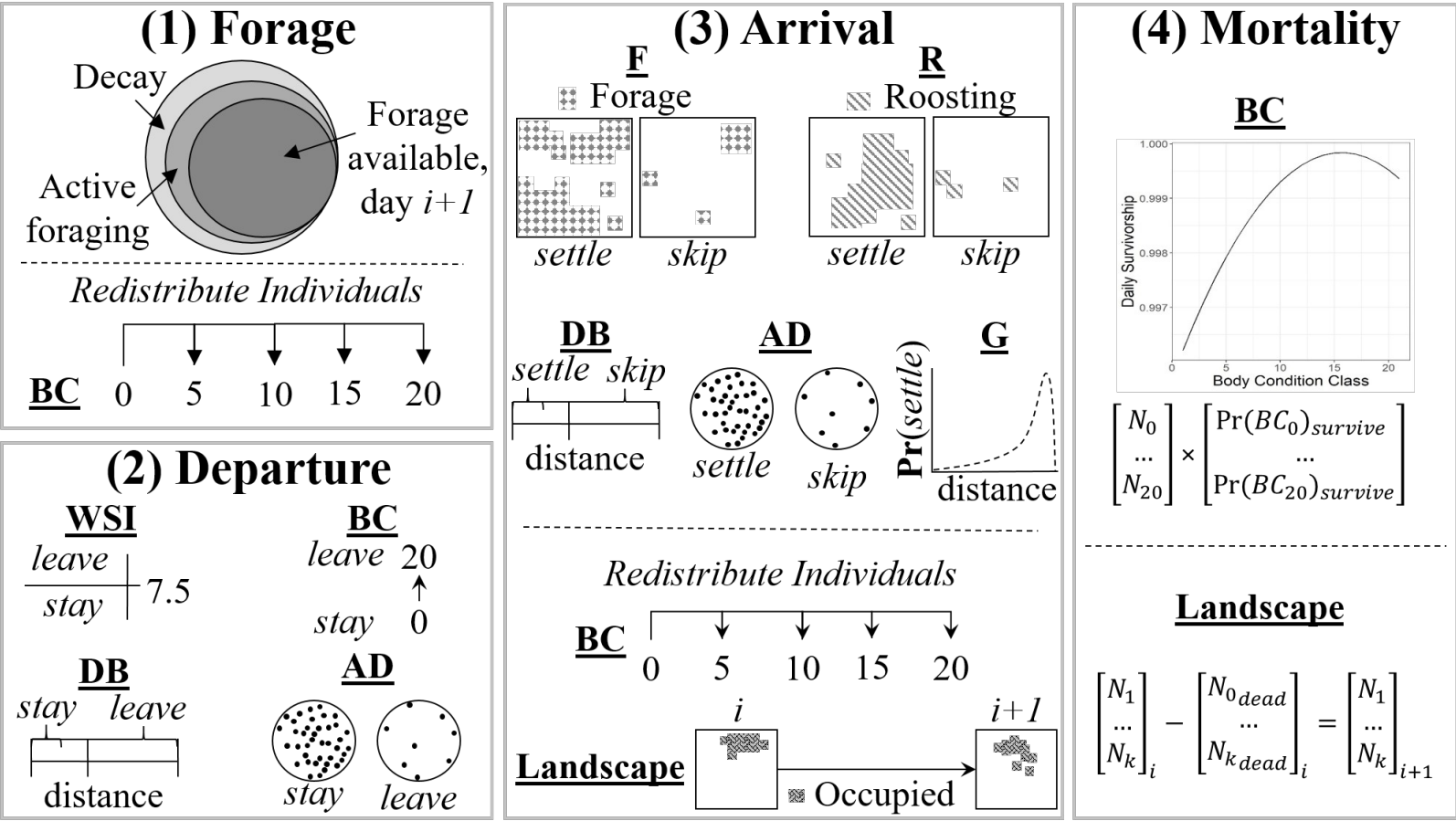
970

971 **Figure 9.** Mean daily mortality (total number of dead birds) on each day of the non-breeding
972 period across the period of record (1957 – 2019).

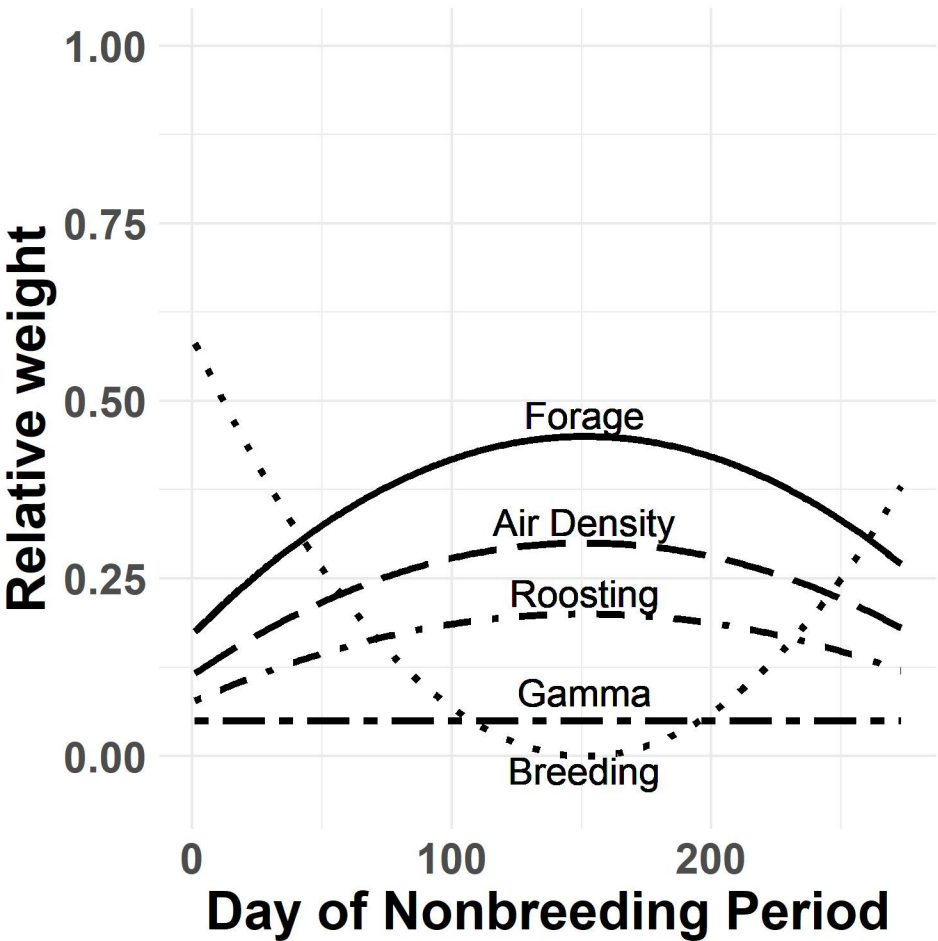
973

974 **Figure 10.** Comparison of mean daily proportion of available habitat during the nonbreeding
975 period for years in the highest quartile of mean annual weather severity index values (“Severe”;
976 1961, 1964, 1966, 1971, 1972, 1974, 1975, 1977, 1978, 1981, 1982, 1984, 1993, 1995, 1996,
977 2013) and for years in the lower quartile (“Mild”; 1979, 1980, 1997, 1998, 1999, 2001, 2003,
978 2004, 2005, 2006, 2009, 2011, 2015, 2016, 2017).

979

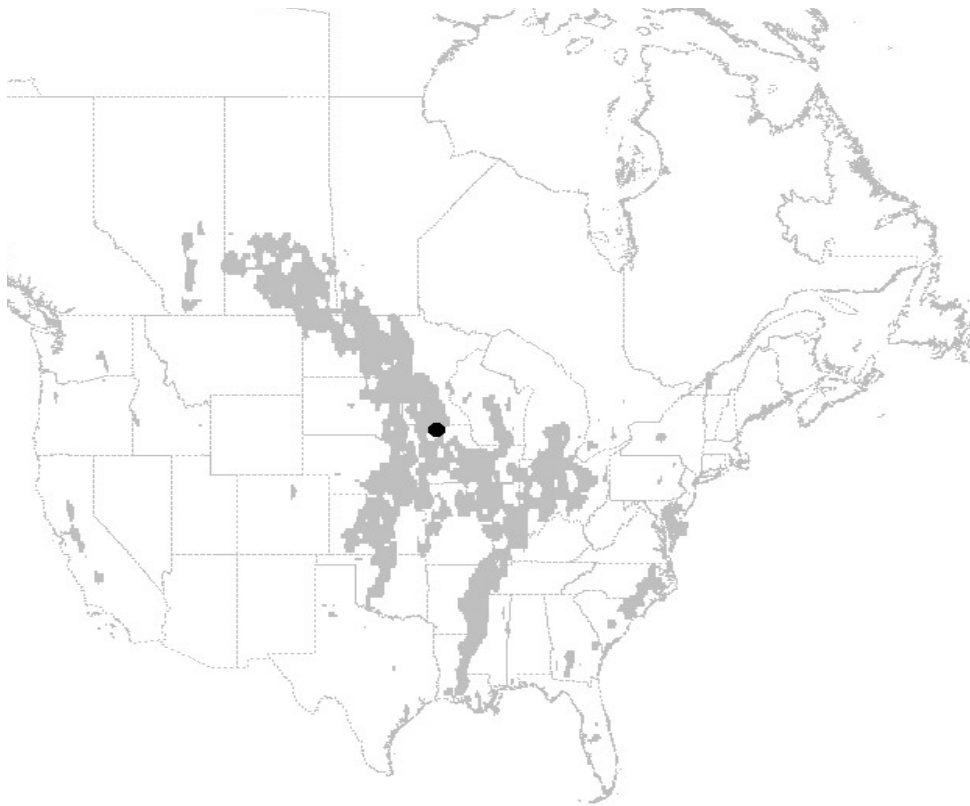


982 **Figure 2.**



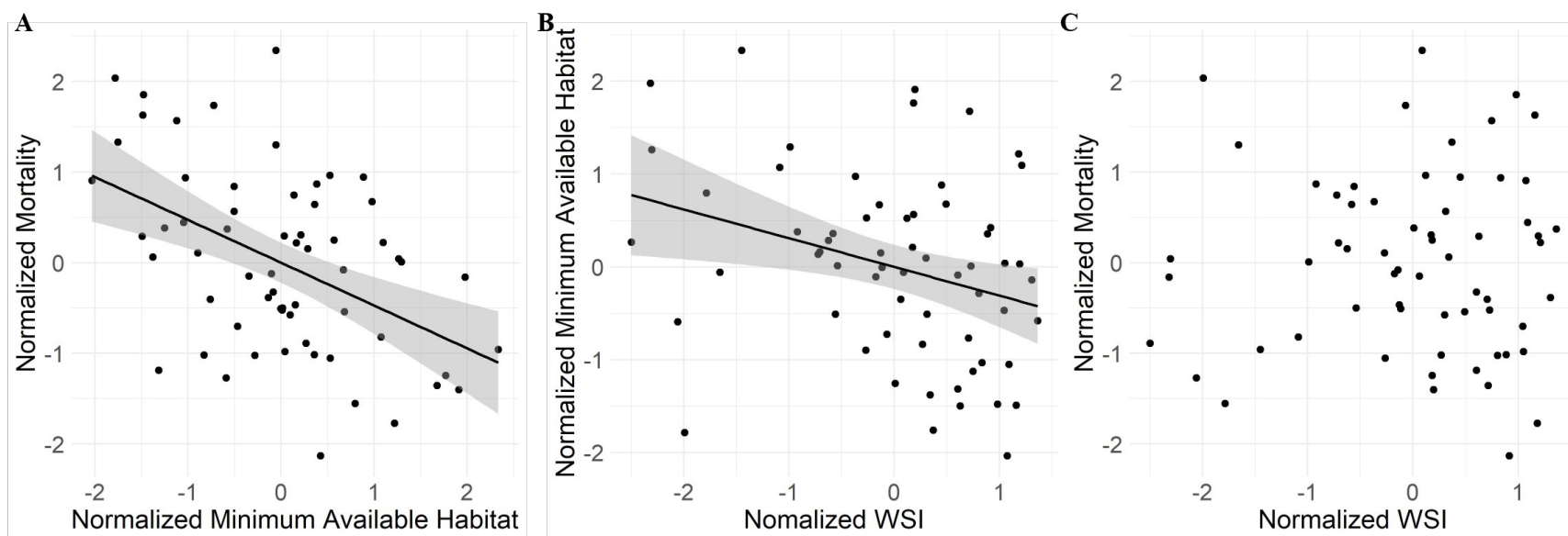
983

984 **Figure 3.**

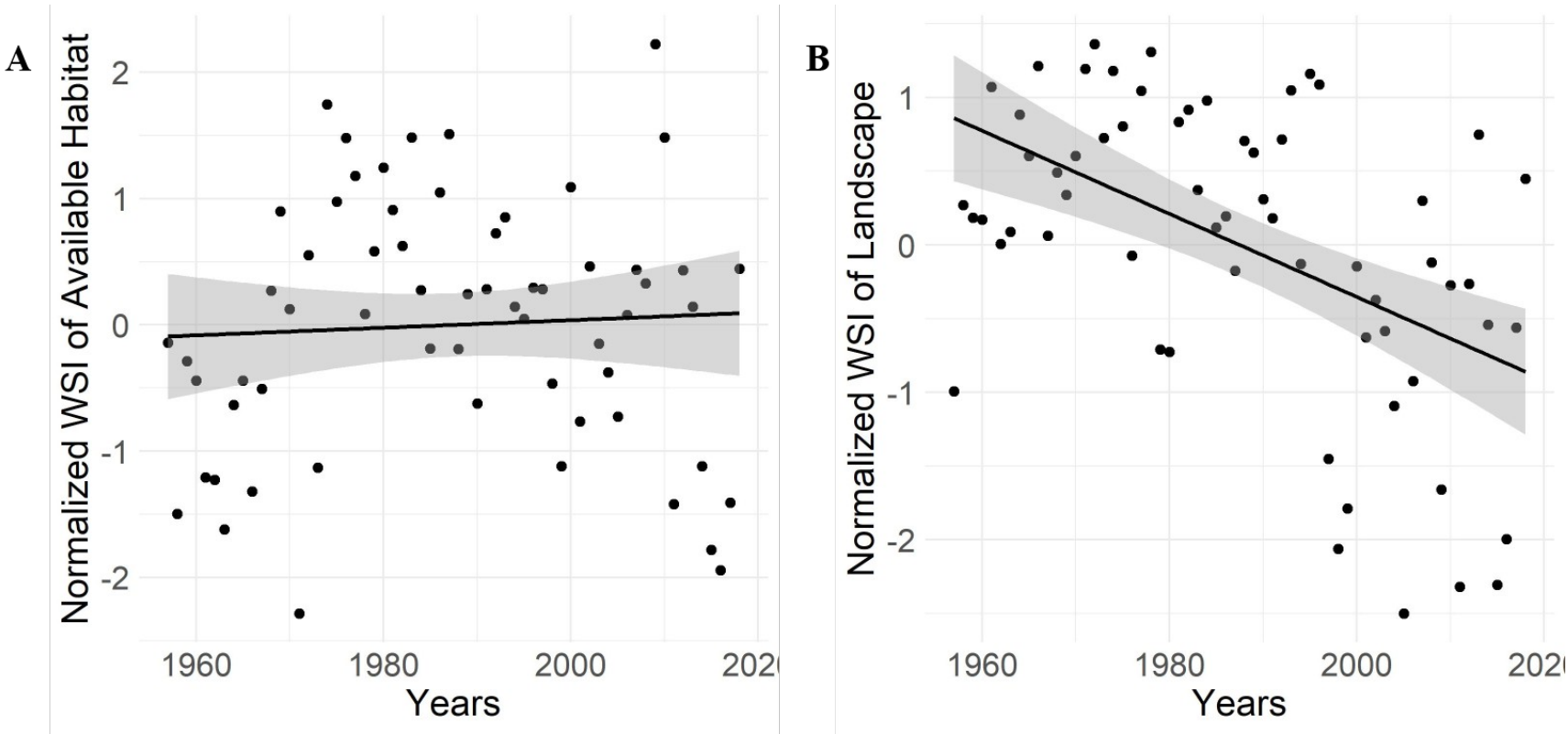


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986 **Figure 4.**

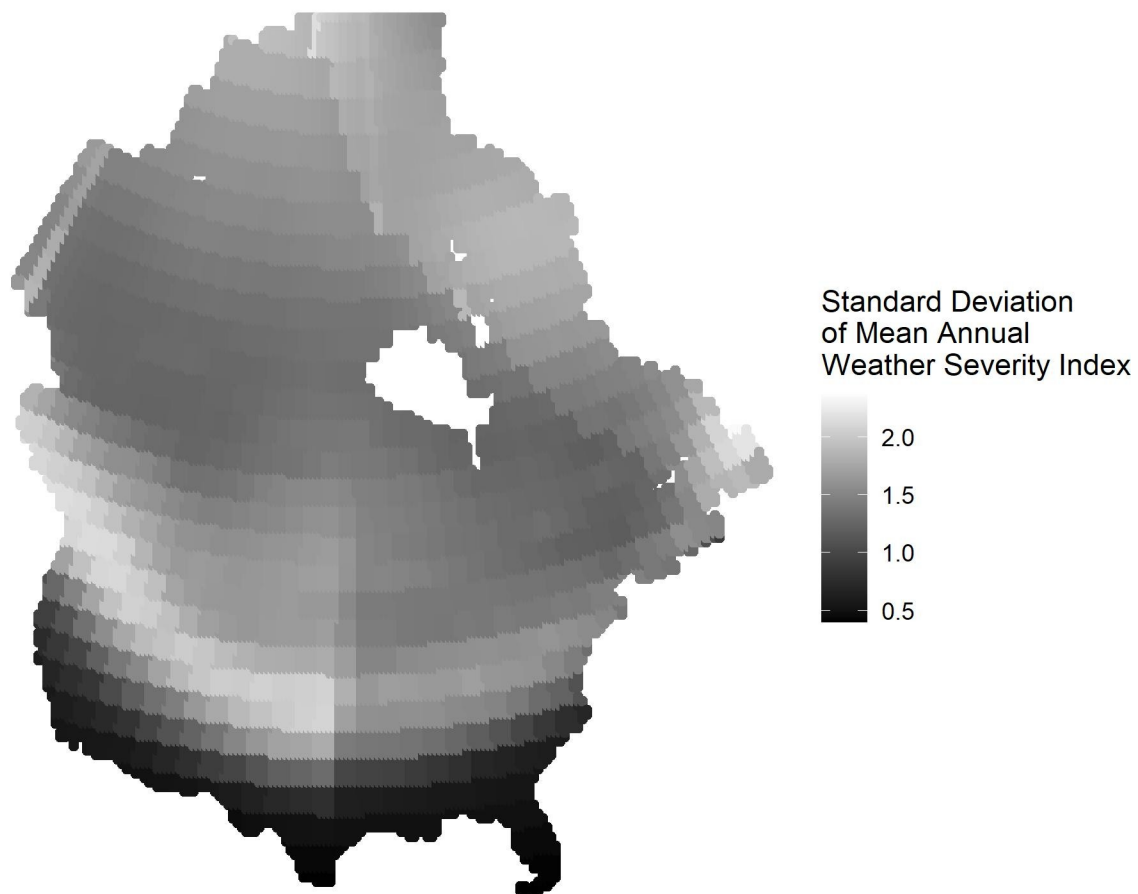


989 **Figure 5.**



990

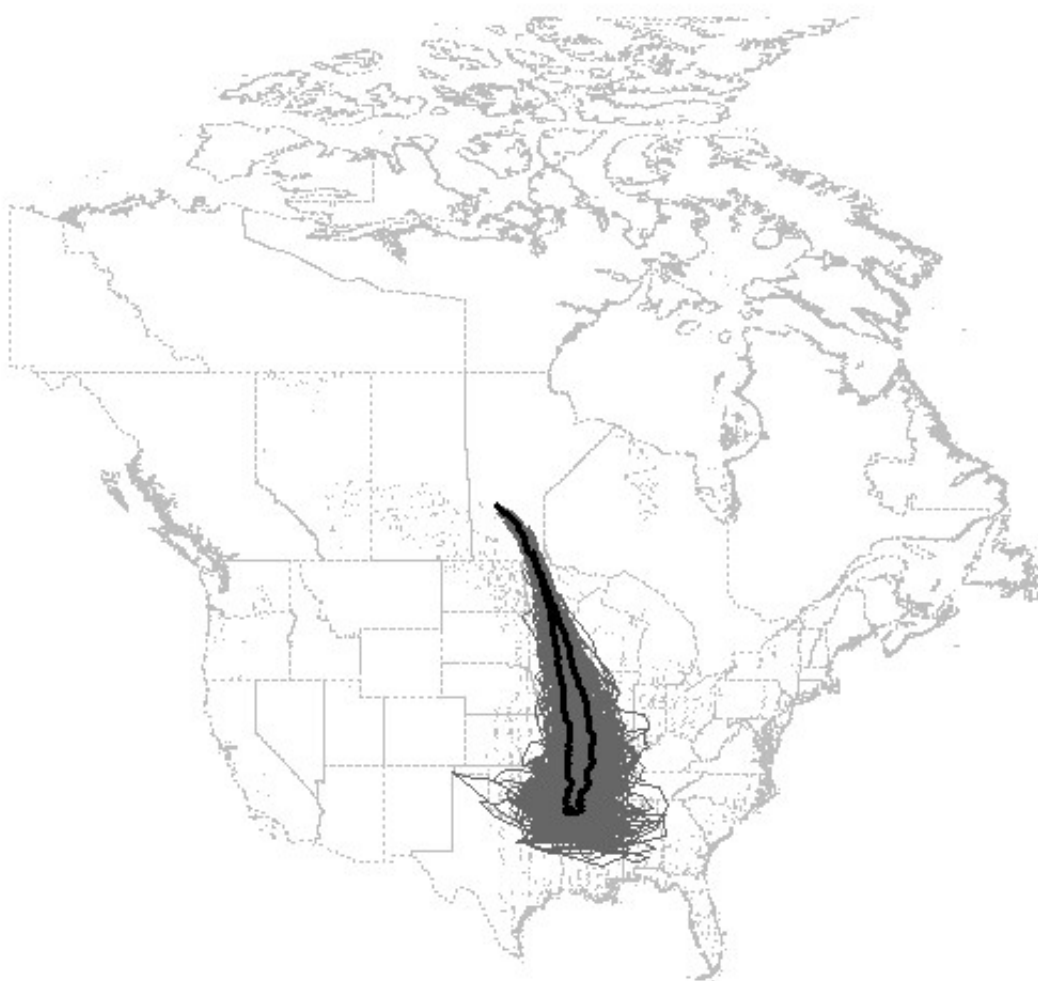
991 **Figure 6.**



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993

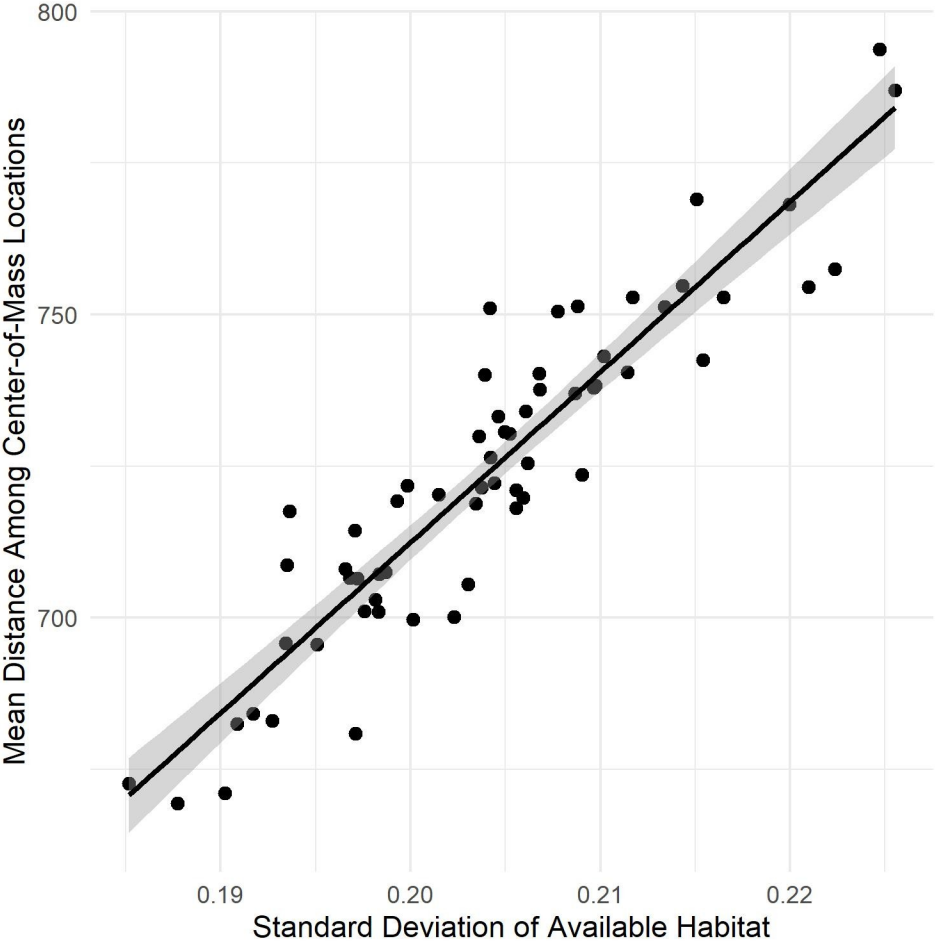
994 **Figure 7.**



995

996

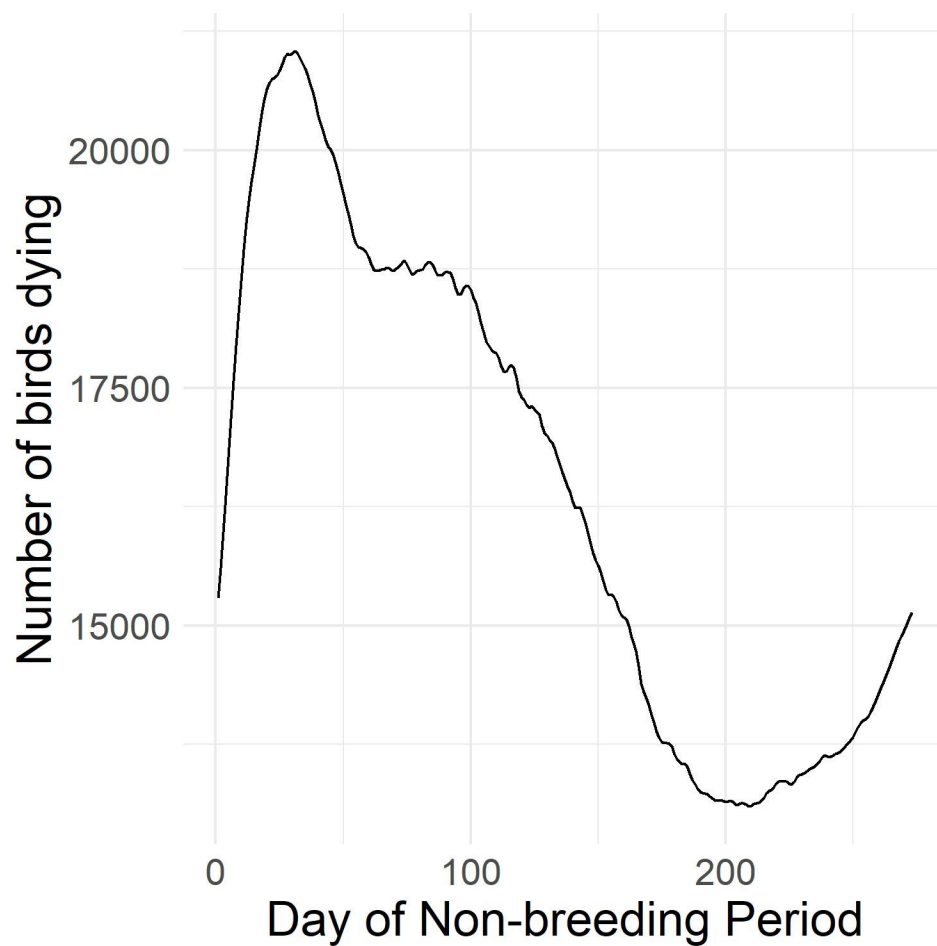
997 **Figure 8.**



998

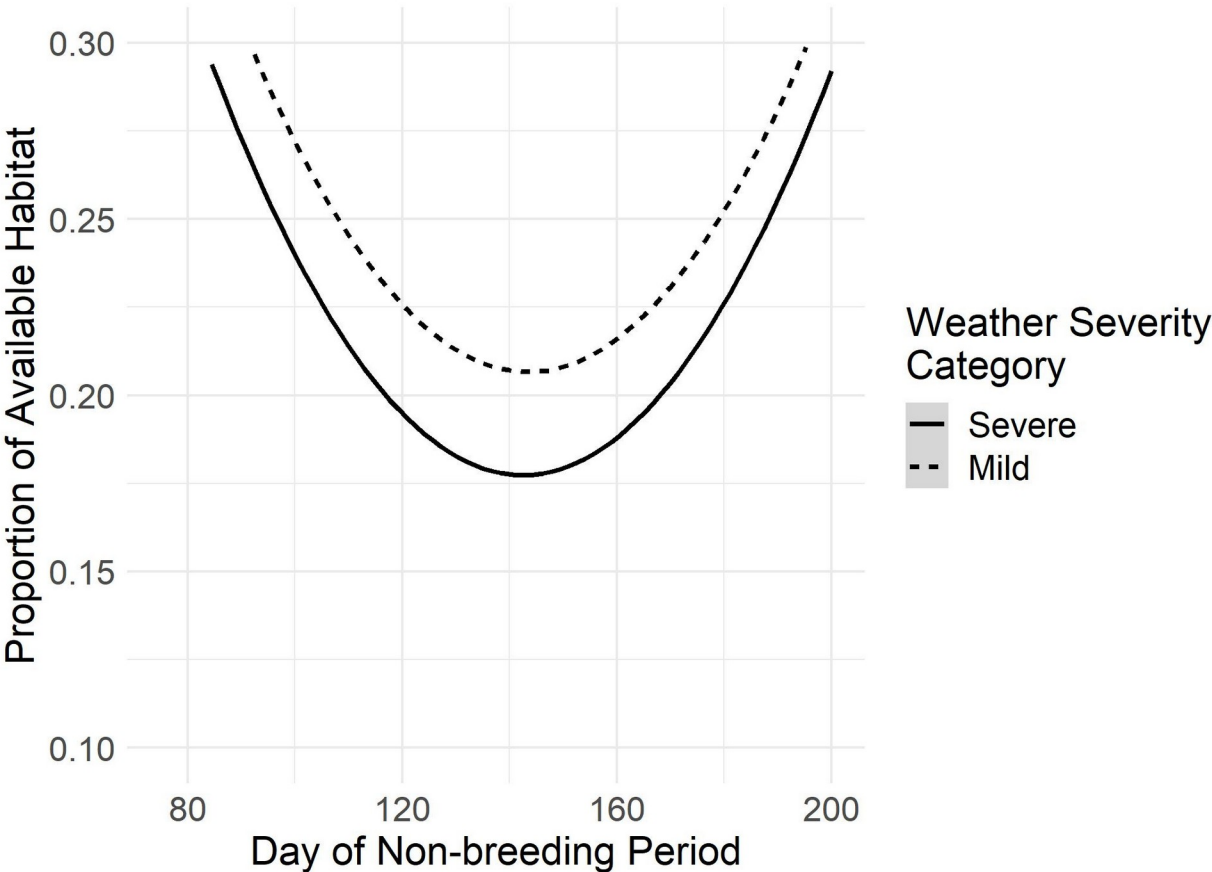
999

1000 **Figure 9.**



1001

1002 **Figure 10.**



1003
1004

1005 **Supporting Material**

1006 We provide several files of supporting material for visualization of our results and replication of
1007 our methods.

1008 **File S1.** (game_distrib.R) – R script used to apply the model and generate the results.

1009 **File S3.** (weather_severity_index.R) – R script used to acquire the data and perform the
1010 calculations to generate the weather severity index for each day of the simulations.

1011 **File S4.** (DailyAbundance_2013.gif) – A video showing the daily abundance per node across the
1012 landscape, normalized on a zero-to-one scale. White to gray dots depict the population-weighted
1013 center of mass on each day of migration to demonstrate an estimate of the population-level
1014 “migration path”.

1015 **Appendix S1. Details of the cleaning, conversion, and projection of the weather data from**
1016 **the National Oceanic and Atmospheric Administration’s National Centers for**
1017 **Environmental Prediction.**

1018 We used the RNCEP package (R-connection to National Centers for Environmental
1019 Prediction data; Kemp et al. 2012) to gather and manipulate the target climate data, which
1020 included data for each day between 1957 and 2019. We gathered air temperature ($^{\circ}\text{K}$ at 2 m
1021 above surface level), water equivalent of snow depth ($\frac{\text{kg}}{\text{m}^2}$ at surface level), and air pressure
1022 (Pascals at low cloud bottom) data sampled on a T62 Gaussian grid. We restricted data to the
1023 nonbreeding period, from 1 July of one calendar year to 31 May of the next (ignoring leap days).
1024 We converted air temperature to $^{\circ}\text{C}$ and water equivalent of snow depth to meters. To convert air
1025 pressure to density ($\frac{\text{kg}}{\text{m}^3}$), we divided the pressure by the product of the specific gas constant for
1026 dry air ($287.058 \frac{\text{J}}{\text{kg} * \text{K}}$) and air temperature.

1027 The water equivalent of snow depth (or, snow-water equivalent, SWE) measures the amount
1028 of water that would be released by a volume of snow melting. It is calculable as the product of
1029 snow depth and snow density. To acquire snow depth (in m) given SWE, we took the quotient of
1030 SWE ($\frac{\text{kg}}{\text{m}^2}$) and snow density ($\frac{\text{kg}}{\text{m}^3}$). Snow density varies with temperature, and pressure (or depth,
1031 with snow deeper in a column being more compacted and thus denser). Snow density ranges
1032 from 10 to $400 \frac{\text{kg}}{\text{m}^3}$ in our conditions (i.e., the temperatures observed across the focal landscape);

1033 we assume a constant snow density of $400 \frac{kg}{m^3}$ across the landscape to convert SWE to snow
1034 depth.

1035

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1039 **Appendix S2. Cross-walk of Canada (CSC2000v, Center for Topographic Information,**
 1040 **Earth Sciences Sector and Natural Resources Canada 2009) and U.S. (National Land**
 1041 **Cover Database 2006, Fry et al. 2011) land cover.**

CSC Value	CSC Class	NLCD Value	NLCD Class
0	No Data	No Data	
10	Unclassified	No Data	
11	Cloud	No Data	
12	Shadow	No Data	
20	Water	11	Open Water
30	Barren	31	Barren Land
31	Snow/Ice	12	Perennial Ice/Snow
32	Rock/Rubble	31	Barren Land
33	Exposed Land	31	Barren Land
34	Developed	23	Developed, Medium Intensity
35	Sparsely vegetated bedrock	31	Barren Land
36	Sparsely vegetated till-colluvium	31	Barren Land
37	Bare soil with cryptogam crust - frostboils	31	Barren Land
40	Bryoids	74	Moss
50	Shrubland	52	Shrub/Scrub
51	Shrub -Tall	52	Shrub/Scrub
52	Shrub - Low	51	Dwarf Scrub
53	Prostrate dwarf shrub	51	Dwarf Scrub

80	Wetland	95	Emergent Herbaceous Wetlands
81	Wetland Treed	90	Wood Wetlands
82	Wetland Shrub	90	Wood Wetlands
83	Wetland Herb	95	Emergent Herbaceous Wetlands
100	Herb	71	Grassland/Herbaceous
101	Tussock graminoid tundra	72	Sedge/Herbaceous
102	Wet sedge	72	Sedge/Herbaceous
103	Moist to dry non-tussock graminoid/dwarf shrub tussock	51	Dwarf Scrub
104	Dry graminoid prostrate dwarf shrub tundra	51	Dwarf Scrub
110	Grassland	71	Grassland/Herbaceous
120	Cultivated agricultural land	82	Cultivated Crops
121	Annual crops	82	Cultivated Crops
122	Perennial crops and Pasture	81	Pasture/Hay
210	Coniferous	42	Evergreen Forest
211	Coniferous - Dense	42	Evergreen Forest
212	Coniferous - Open	42	Evergreen Forest
213	Coniferous - Sparse	42	Evergreen Forest
220	Broad Leaf	41	Deciduous Forest
221	Broad Leaf - Dense	41	Deciduous Forest
222	Broad Leaf - Open	41	Deciduous Forest
223	Broad Leaf - Sparse	41	Deciduous Forest

230	Mixed Wood	43	Mixed Forest
231	Mixed Wood - Dense	43	Mixed Forest
232	Mixed Wood - Open	43	Mixed Forest
233	Mixed Wood - Sparse	43	Mixed Forest

1042

1043

1044 **References**

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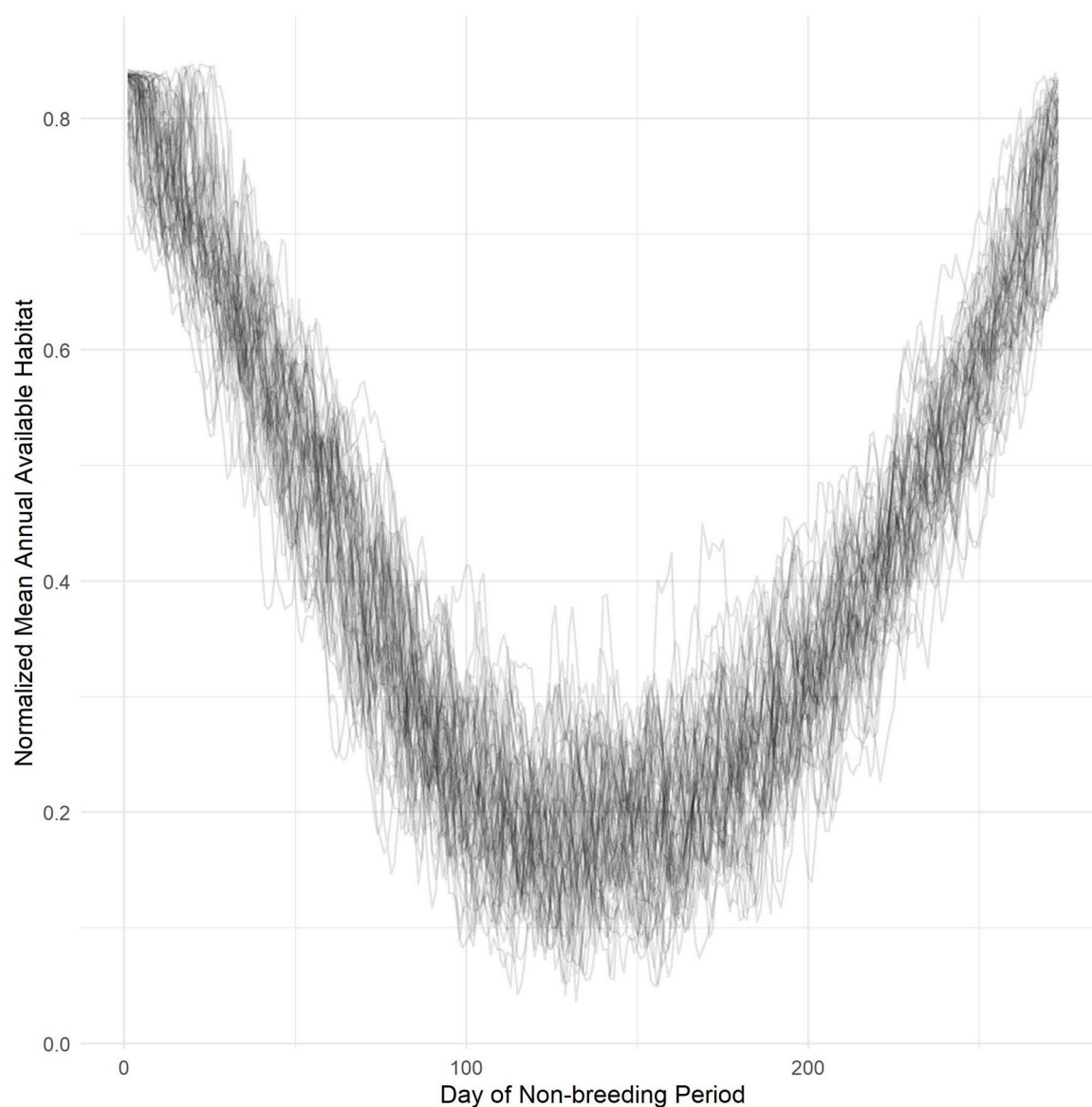
1048 Fry, J., G. Xian, S. Jin, J. Dewitz, C. Homer, L. Yang, C. Barnes, N. Herold, and J. Wickham.

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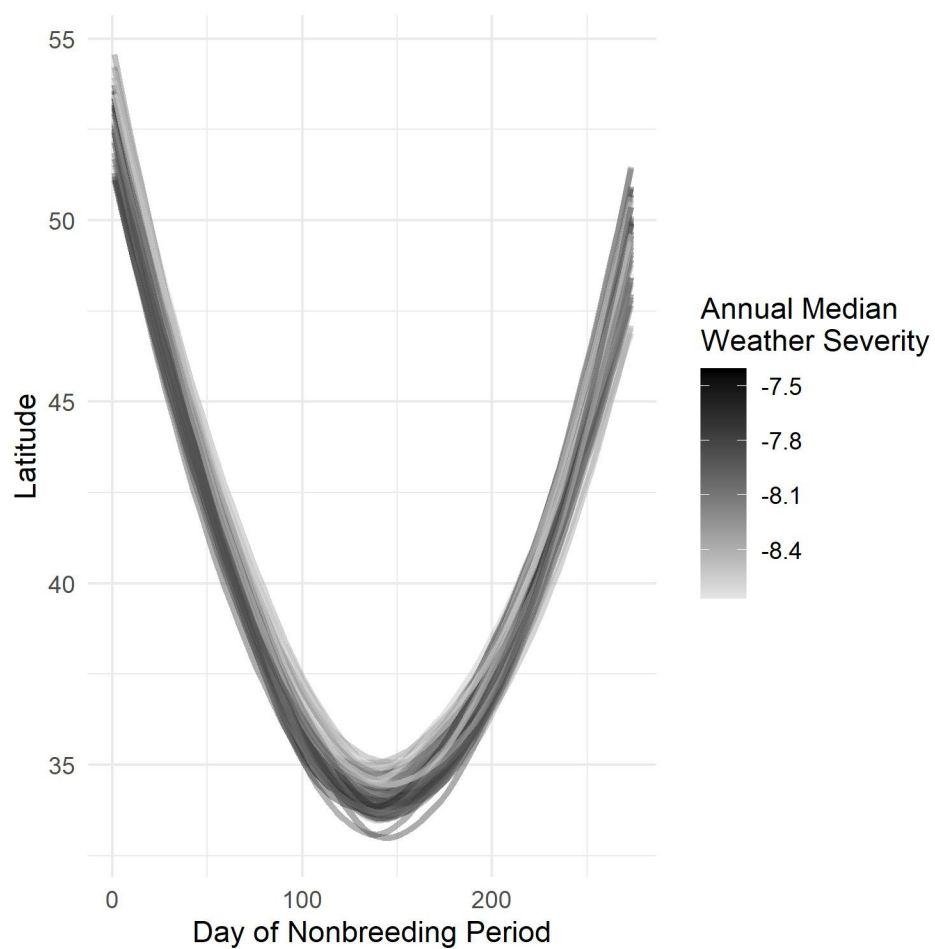
1050 States. Photogrammetric Engineering and Remote Sensing 77:858–864.

Appendix S3. Here we report several results and findings relevant to the change in weather severity over time and the subsequent effects of this change on the nadir of the latitudinal reach of the population each year.

Figure S3.1. The proportion of the landscape available for individuals to occupy on each day of the nonbreeding period, according to the weather severity index (*WSI*) in that node. *WSI* values above 7.5 trigger departure and inhibit arrival. This metric is normalized to a 0 to 1 scale for comparison across all years in the record (1957 – 2019).

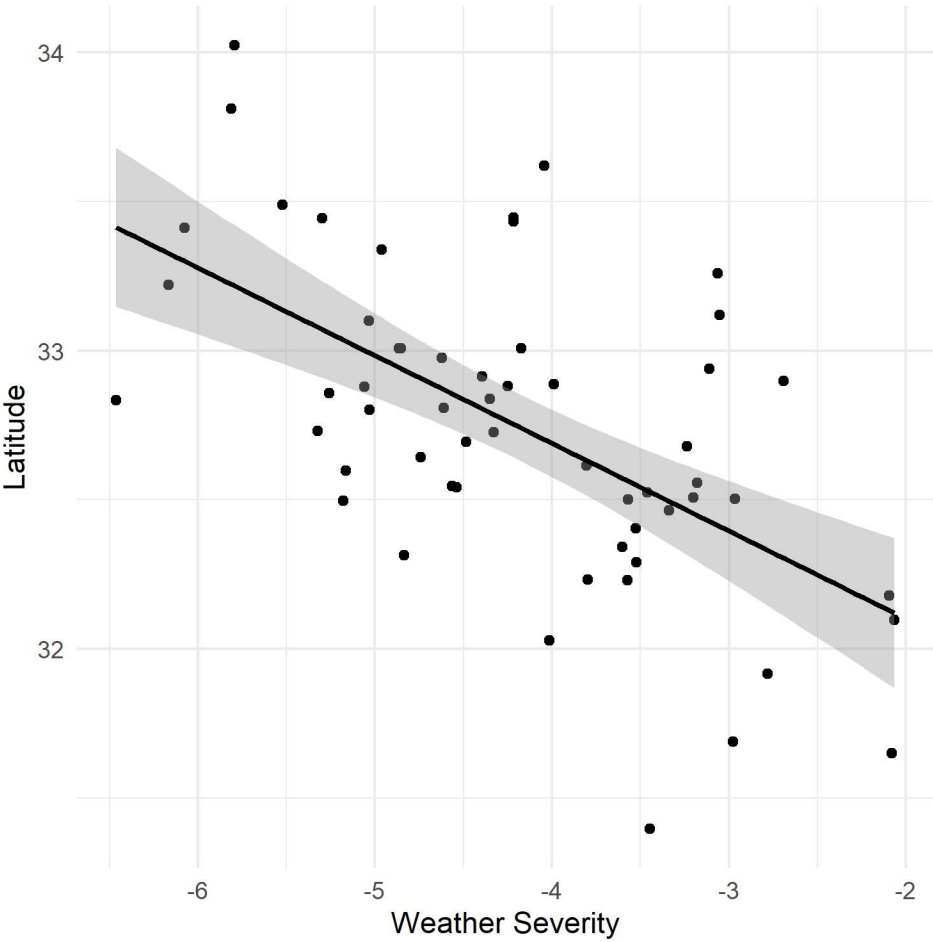


1059 **Figure S3.2.** Change in the southernmost latitude achieved by the abundance-weighted center-
1060 of-mass of the population over time, with corresponding annual median weather severity index.
1061 Years of less severe weather (lighter curves) demonstrated less southerly minimum latitudes.



1062

1063 **Figure S3.3.** Change in the southernmost latitude achieved by the abundance-weighted center-
1064 of-mass of the population with varying annual median weather severity index values.



1065
1066