

1 **Effects of weather variation on waterfowl migration: lessons from a continental-scale**  
2 **generalizable avian movement and energetics model**

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4 *Running title: Continental GAME model*

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15 **ABSTRACT**

16 We developed a nonbreeding period continental-scale energetics-based model of daily waterfowl  
17 movement to predict year-specific migration and overwinter occurrence. The model  
18 approximates energy-expensive movements and energy-gaining stopovers as functions of  
19 metabolism and weather, in terms of temperature and frozen precipitation (i.e., snow). The model  
20 is a Markov process operating at the population level and is parameterized through a review of  
21 literature. We examined model performance against 62 years of non-breeding period daily  
22 weather data. The average proportion of available habitat decreased as weather severity  
23 increased, with mortality decreasing as the proportion of available habitat increased. The most  
24 commonly used nodes during the course of the nonbreeding period were generally consistent  
25 across years, with the most inter-annual variation present in the overwintering area. Our model  
26 revealed that the distribution of birds on the landscape changed more dramatically when the  
27 variation in daily available habitat was greater. The main routes for avian migration in North  
28 America were predicted by our simulations: the Eastern, Central, and Western flyways. Our  
29 model predicted an average of 77.4% survivorship for the nonbreeding period across all years  
30 (range = 76.4 – 78.4%), with lowest survivorship during the fall, intermediate survivorship in the  
31 winter, and greatest survivorship in the spring. We provide the parameters necessary for  
32 exploration within and among other taxa to leverage the generalizability of this migration model  
33 to a broader expanse of bird species, and across a range of climate change and land use/land  
34 cover change scenarios.

35

36 *Key Words:* Avian, energetics, global climate change, migration, predictive modeling, waterfowl

37

38 **Introduction**

39

40 Migratory behavior of populations varies within an avian species as well as among individuals  
41 within a population (Newton 2006, Newton and Brockie 2008, Eichhorn et al. 2009, Stanley et  
42 al. 2012). This differential migratory behavior is influenced by environmental change operating  
43 over ecological and evolutionary time scales (Parmesan 2006, Louchart 2008). Wide plasticity in  
44 migratory behavior is demonstrated by some individuals of a species initiating habitual seasonal  
45 migrations, with some foregoing migration to remain sedentary (Atwell et al. 2011).  
46 Understanding the mechanistic reasons for this difference in behavioral outcomes is critical to  
47 predicting responses of migratory populations to a changing environment.

48       Efforts to model avian migration from an energetic perspective have necessarily been  
49 informed by empirical biological and physiological studies (see Malishev and Kramer-Schadt  
50 2021 for a review). For many species these empirical studies elucidated relationships between,  
51 for example: temperature and metabolism (e.g., Hartung 1967, Smith and Prince 1973, Klaassen  
52 1996), body mass and temperature (e.g., Baldwin and Kendeigh 1938, Boos et al. 2007), and  
53 flight velocity and duration and body fat content (e.g., Rayner 1990). Using systems of equations  
54 to connect one facet to the next generates a series of expectations for how migration is likely to  
55 unfold for a bird of a certain species and specific mass (e.g., Lonsdorf et al. 2016, Aagaard et al.  
56 2018). Connecting approaches for predicting environmental effects on migration-energetic  
57 dynamics with approaches evaluating the spatially explicit pattern of energetic-based migratory  
58 movements can reveal how migration is affected by the distribution of forage material on the  
59 landscape. It can also inform how migration is likely to proceed given the differential

60 expenditure of energy across the landscape and across temporally variable environmental  
61 conditions (Paxton et al. 2014).

62 While migration is a common term, we draw a distinction between it and movement and  
63 dispersal for consistency (Holloway and Miller 2017). Movement is any change in location over  
64 time. Dispersal is movement that occurs in spatially limited local communities without cyclical  
65 repetition (i.e., within a node, for our purposes; Ai et al. 2012). Migration is predictable or  
66 routine seasonal movement among two or more distinct and consistent habitats (Hansson and  
67 Åkesson 2014). Migratory birds are faced with several contrasting strategies along their journey  
68 relating to timing, distance, velocity, altitude, and stopover length (Alerstam and Lindström  
69 1990). These dilemmas are captured in three tradeoffs: avoiding predation or refueling, flying at  
70 a speed allowing for maximum power or maximum range, and departing on migration early (to  
71 avoid inhospitable weather) or late (to further increase fat reserves) as opposed to “on time”  
72 (Pennycuick 1975, Alerstam and Lindström 1990, Hedenström 1992, Bruderer and Boldt 2001,  
73 Drent et al. 2003, Pennycuick and Battley 2003, La Sorte et al. 2013, Pennycuick et al. 2013).  
74 Each trade-off can be thought of as choice between different energetic or physiological  
75 strategies, essentially boiling down to ‘full throttle’ or ‘fuel-efficient’ transport. An easy analogy  
76 can be made between migrants and automobile drivers (Kitamura and Sperling 1987); depending  
77 on the nature of the trip, a driver may choose to optimize for automobile velocity or fuel  
78 efficiency. Migratory birds must make similar tradeoffs during the course of their movements.  
79 For a more complete elaboration of the ecological processes of avian migration, see, for  
80 example, Alerstam and Lindström (1990), Drent et al. (2003), Alves et al. (2013) and Aagaard et  
81 al. (2018).

82 We extend existing energetics-based models of waterfowl movement (Lonsdorf et al. 2016,  
83 Aagaard et al. 2018) to construct a full nonbreeding period model of waterfowl movement and  
84 energetics. Our model is of the type described by Malishev and Kramer-Schadt (2021) and  
85 referred to as an energetics-based Individual Based Model (eIBM); we note that the irreducible  
86 unit of interest in our models are more precisely considered “agents” rather than “individuals”, as  
87 we follow subsets of the population but not discrete individuals. The model approximates  
88 energy-expensive movements and energy-gaining stopovers as functions of weather, in terms of  
89 air temperature, air density, and snow depth, which influence the timing and extent of waterfowl  
90 migration (Nichols et al. 1983). The model begins in the late summer/early autumn as birds are  
91 forced out of breeding habitat by inhospitable weather conditions. As in Lonsdorf et al. (2016)  
92 and Aagaard et al. (2018), we model bird movement as a function of the roosting quality and  
93 forage availability of each stopover site and the distance between the stopover site and departure  
94 site. We partition the population of birds into a set of body condition classes based on body mass  
95 and body fat. We transition birds among body condition classes based on differential movement  
96 and foraging, with the assumption of an inverse relationship between body condition and  
97 mortality risk.

98 We allow the bounds of the overwintering area to be an emergent property of the model  
99 rather than restrict it to static interpretations of historical overwintering grounds. We, therefore,  
100 add consideration of the distance from the stopover site to all other available stopover sites  
101 within an individual’s flight range into our approximation of bird movement. We also consider  
102 the consequences of a seasonally varying availability of forage by accommodating the  
103 consumption and natural decay of forage material. Additionally, we impose thresholds related to  
104 known waterfowl abundance-weather severity relations (e.g., Schummer et al. 2010) to bird

105 movement to restrict availability of the landscape to only those sites with hospitable conditions  
106 (Van Den Elsen 2016). Weather severity can be thought of as a propellant during the early  
107 portion of the nonbreeding period to “push” birds southward, while the breeding grounds serve  
108 as an attractant to “pull” birds northward. In this way, birds in this model tend to congregate  
109 along a weather-severity isocline, staying as close to breeding grounds as weather conditions and  
110 metabolic demands allow (e.g., Robinson et al. 2016).

111 While the model structure outlined here is generalizable to all birds, we use dabbling ducks  
112 as an example (specifically, we parameterize our model for a mallard-like, *Anas platyrhynchos*,  
113 dabbling duck). Mallards are exemplary model organisms in this context as they have been  
114 extensively studied in terms of their physiology and migratory dynamics (e.g., Prince 1979,  
115 Krementz et al. 2011, 2012, Pennycuick et al. 2013) and are of great conservation and  
116 management interest (e.g., Heitmeyer 2010).

117 A critical advancement of this model is development of over 50 years of migration  
118 trajectories using historical weather data to inform movement patterns, allowing sensitivity in  
119 input parameter values to approximate observed conditions. With this model, we seek to  
120 understand the influence of weather patterns and conditions on the nonbreeding period of the  
121 annual cycle of migratory dabbling ducks. A full evaluation of this first-principles exposition of  
122 avian migration requires broad-scale data revealing avian migration patterns associated with  
123 historical environmental data. In the absence of such data we can at least use our approach to  
124 determine if, all else being equal, variation present in a representative sample of observed  
125 historical environmental conditions facilitates demonstrable changes to avian migration patterns  
126 (Grim and Railsback 2012). Specifically, we expect (1) to determine explicitly and natively the  
127 overwintering habitat; (2) past environmental data to provide evidence that climate change has

128 led to increased available habitat over time (and less severe weather); (3) a reduction in  
129 nonbreeding period mortality concurrent with an decrease in weather severity; (4) to recover  
130 migratory routes (flyways); and (5) to discern differences between mild and severe years  
131 comparable to historical weather reports.

132

### 133 **Methods**

134

135 We discretized the landscape (North America) into 1036 km<sup>2</sup> stopover sites, or nodes. This  
136 spatial delineation is consistent with expectations that movement less than 16 km consists of  
137 dispersal (Lonsdorf et al. 2016). Data availability and computational advancements allow us to  
138 greatly increase the temporal scale of the model relative to that considered in Lonsdorf et al.  
139 (2016): rather than focus on migratory jumps we iterate across each day of the nonbreeding  
140 period. As such, our model begins after the molting stage of waterfowl (1 September of one  
141 calendar year) and terminates prior to the breeding period (31 May of the following calendar  
142 year). We use known values from the literature for physiological, anatomical, and metabolic  
143 dynamics to inform our model (Table 1).

144 The workflow to simulate daily movement was constructed to most closely approximate the  
145 actual processes of movement, dispersal, and migration while operating under the constraints of  
146 a sequential modeling framework. Our pattern proceeded as:

147 **Forage → Departure → Arrival → Mortality → Forage...**

148 Within each component of our model there were secondary procedures invoked, for example,  
149 to effectively allocate forage material among individuals within the population and to distribute  
150 individuals across the landscape according to the spatial pattern of high-quality habitat. The

151 overall workflow is depicted in Figure 1. R code (R Core Team 2018) is available in Supporting  
152 Materials File S1.

153 (1) *Forage*

154 A simulated day began with foraging, a weather- and body condition-dependent process,  
155 which transfers energy from forage material on the landscape into energy as fat to individual  
156 birds. Individuals in each node (distributed spatially according to NatureServe range maps  
157 [Ridgley et al. 2005] and breeding population survey data) were allocated among 21 body  
158 condition classes, with higher classes representing better body conditions. Body condition is a  
159 function of body fat; individuals falling below body condition class one (into class zero) had 0%  
160 body fat content (fatal). An individual's ability to accumulate forage—its rate of daily gain (*DG*)  
161 —was a function of disturbance (degree of urbanization in a node), fuel deposition rate (*FDR*, kJ  
162 per day), and temperature-dependent basal metabolic rate (Aagaard et al. 2018). We summed the  
163 fuel deposition of each individual to calculate the amount of energy removed from the landscape  
164 in each node as a result of active foraging.

165 To calculate the rate of natural decay (*D*) in forage material we multiplied the amount of  
166 forage material (*E*, kJ) present in each habitat type (shoreline, crop, wooded wetland, herbaceous  
167 wetland, Table 2) by a land cover-specific decay rate (*r*) to the power of the day of the  
168 nonbreeding period (*i*):

169 
$$D = E \times r^i.$$

170 We calculated the total forage available on the landscape in the next time step by subtracting the  
171 amount of forage material subject to decay and active foraging from the total amount of forage  
172 available (*F*) at the outset of day *i*,

173 
$$F_{i+1} = F_i - D - \sum FDR.$$

174 (2) *Departure*

175 Each day, individuals must decide whether to stay and continue foraging or depart from a  
 176 node. We assumed that individuals in poorer body condition experiencing mild weather nearest  
 177 to breeding nodes with potential for high rates of gain of body mass were less likely to leave a  
 178 node, instead remaining to continue foraging, while individuals in better body condition facing  
 179 severe weather far from breeding nodes with potential for low rates of gain of body mass were  
 180 highly likely to leave. The probability of individuals remaining in a given node or departing from  
 181 it depends on each individual's body condition (*BC*), the weather severity index (*WSI*) within the  
 182 node, the distance between the origin node and the nearest breeding node (*DB*), and the  
 183 disturbance-dependent daily gain in body mass (*DG*). The components were combined according  
 184 to the follow equation:

$$185 \quad \sum Pr(\text{depart}) = Pr(\text{depart}|WSI) + Pr(\text{depart}|BC) + Pr(\text{depart}|DB) + Pr(\text{depart}|DG)$$

186 Three of the four components, *BC*, *WSI*, and *DB*, were each calculated using a Monod function,  
 187 which produced a saturating curve for the target effect, with exponents applied to vary the shape  
 188 of the resulting curve. Daily Gain was calculated using a linear decreasing function. The discrete  
 189 probabilities of departure had the following forms:

$$190 \quad Pr(\text{depart}|WSI) = \left( \frac{(WSI + 7.5)^3}{(WSI + 7.5)^3 + (7.5)^3} \right),$$

$$191 \quad Pr(\text{depart}|BC) = \left( \frac{BC^8}{BC^8 + (N_{BC \text{ classes}} - 3)^8} \right),$$

$$192 \quad Pr(\text{depart}|DB) = \left( \frac{DB^5}{DB^5 + \text{flight range}^5} \right),$$

$$193 \quad Pr(\text{depart}|DG) = \left( \frac{1 - (FDR + 1)}{5} \right).$$

194 The values for the exponents in each of these three cases were selected to generate  
195 reasonable curves for each probability of departure component. We assessed what constitutes  
196 “reasonable” based on the reaction in the model to changes in these values. We expected that the  
197 curve for the body condition component should have a pronounced inflection point to represent a  
198 high probability of departure for birds in the highest body conditions (top three), and a relatively  
199 low probability of departure for birds in moderate to low body conditions. Weather severity, in  
200 contrast, should be relatively more linear. Thus, we set the exponents in body condition to be  
201 nearly three times as great as those in *WSI*.

202 More formally, we calculated the number of individuals departing each node as the product  
203 of the abundance per node,  $i$ , on day,  $k$ , and the proportion of individuals in each  $BC, j$ ; this  
204 product was then multiplied by the  $BC$ -dependent probability of departure:

205

206  $i$

207

### 208 (3) *Arrival*

209 Once individuals choose to depart, they must decide how far to fly and where to land. How far  
210 birds can fly is a function of body condition (mass, body fat proportion), flight cost, and flight  
211 velocity. Using the relations set forth in the program Flight (for Windows, version 1.25  
212 [<http://www.bio.bristol.ac.uk/people/pennycuick.htm>]; Pennycuick 2008), we calculated the  
213 chemical power, velocity for maximum range, and effective lift-to-drag ratio for birds from a  
214 distribution of available body masses, wing spans, wing areas, and at various air densities, across  
215 a range of potential true air speeds. These calculations led to the ultimate output of the flight cost  
216 (kg of fat metabolized per km) and flight velocity (km per hr), for the input range of

217 morphometric features. The code used to generate these calculations is included in Supporting  
218 Material File S4.

219 Birds determine where to land based on *WSI*, forage availability, roosting habitat, and  
220 distance to breeding grounds. On average, birds will tend to select more attractive nodes, that is,  
221 nodes with low winter severity (*WSI*) and higher air density (*AD*), plentiful forage availability  
222 and roosting habitat (*R*), nearer to breeding grounds, and within the flight range (defined as a  
223 node-specific gamma movement probability, *G*; the cumulative probability of moving from a  
224 node to all other nodes in the landscape based on the distance between each pair of nodes). We  
225 used a Cobb-Douglas function to combine these factors.

226 We restricted movement to nodes in which the *WSI* was below the empirically derived  
227 threshold (7.5; Schummer et al. 2010). The remaining four components of the arrival function  
228 (forage, roosting, breeding ground distance, gamma movement probability) were individually  
229 weighted to allow for the differential significance of particular parameters ( $w_f$ , forage  
230 availability;  $w_a$ , air density;  $w_r$ , roosting quality;  $w_b$  distance to nearest breeding node; and  $w_g$ ,  
231 node-specific gamma movement probability). We also assumed variable relative importance of  
232 each component over time (Figure 2). We assumed that distance to the nearest breeding node  
233 was the most important consideration for migrants proximal to the breeding period (i.e., early  
234 and late in the nonbreeding period). We assumed that forage availability and roosting quality  
235 increased in importance up to the mid-winter period of the nonbreeding period—with forage  
236 increasing more so than roosting—and then decreased to initial values again by the end of the  
237 nonbreeding period. We held the node-specific gamma movement marginal probability steady  
238 across the nonbreeding period because the probability of moving between any given pair of  
239 nodes (depending only on the distance between them) should not vary temporally.

240 Input values for the component weights were, for  $w_f$ , 0.45 ,  $w_a$ , 0.3,  $w_r$ , 0.2, and  $w_g$ , 0.05.

241 The weight for the distance to breeding grounds,  $w_b$ , was set to the sum of the daily weights for  
242 all other components subtracted from one. To establish the structure of the weights for the  
243 components assumed to have non-linear dynamics we randomly selected a date during the mid-  
244 winter phase of the nonbreeding period (between 31 December and 31 January) to serve as our  
245 inflection point. We then generated a sequence of values,  $c$ , from 1 to 0.1 to 1, with an inflection  
246 occurring on the specified day of the nonbreeding period,  $d$ , for use in a function to calculate the  
247 corresponding weights for each component:

$$248 \quad w_f = - \left( 0.9 \times \left( \left( c_d - \left( \frac{c_d}{n} \right) \right)^2 \right) \right) + 0.45$$

$$249 \quad w_a = - \left( 0.6 \times \left( \left( c_d - \left( \frac{c_d}{n} \right) \right)^2 \right) \right) + 0.3$$

$$250 \quad w_r = - \left( 0.4 \times \left( \left( c_d - \left( \frac{c_d}{n} \right) \right)^2 \right) \right) + 0.2$$

$$251 \quad w_g = 0.05$$

$$252 \quad w_b = 1 - \sum (w_f, w_a, w_r, w_g),$$

253 where  $n$  is the length of the nonbreeding period in days.

254 Using this process to generate the daily weights, the full Cobb-Douglas function for the  
255 probability of arrival in a given node was defined as:

$$256 \quad A = F^{w_f} \times AD^{w_a} \times R^{w_r} \times DB^{w_b} \times G^{w_g}.$$

257 Each of these components was normalized to a 0-1 scale, using  $\frac{x - \min(x)}{\max(x) - \min(x)}$ ; the node with

258 the greatest amount of forage availability on a given day was assigned a normalized forage

259 availability score of 1; we repeated this calculation for roosting quality, distance to nearest  
260 breeding node, and node-specific gamma movement probability.

261 *(4) Mortality*

262 We assumed that individuals in poorer body conditions had higher daily rates of mortality than  
263 individuals in better body conditions—in keeping with the assumption of increased mortality  
264 with increased energy deficits (e.g., Lonsdorf et al. 2016). Each day we multiplied the  
265 survivorship associated with a given body condition by the number of individuals in that body  
266 condition class.

267

268 *Daily Abundance* – We redistributed individuals across the landscape and among body condition  
269 classes according to their probabilities to stay/depart and arrive. We calculated the following  
270 day’s abundance in a node as the product of the total number of individuals departing all nodes  
271 and the probability of arrival in the node:

272

273 
$$\dot{i} = \dot{i}_s,$$

274

275 added to the difference of the current abundance and the number of individuals departing the  
276 node.

277 We computed the number of individuals departing a node in each body condition and the  
278 number of individuals remaining in a node in each body condition. We decremented the body  
279 condition of departing individuals according to the distance between origin-node and destination-  
280 node, using established relations for the mass-dependent cost of flight per unit distance (e.g., see  
281 Aagaard et al. 2018). This decrement-function informed the number of individuals arriving in

282 each node in each body condition, which we used to calculate the number of individuals in each  
283 node in each body condition class on the following day.

284 The final abundance for a given node on the following day was the abundance in that node  
285 on the current day minus the number of individuals that died in that node on that day. Taken  
286 together with *Arrival*, this produced:

287

288 
$$i.$$

289

290 *Parameterization* – For some parameters in our model there is a lack of empirical evidence to  
291 inform their value. We defined these parameters probabilistically, as a function of body  
292 condition, to allow for sensitivity in the model (Table 1; see also Appendix S1 for definitions of  
293 parameters and distributions). These included daily survivorship, flight power components, and  
294 energetic costs of flight. We also allowed parameters with known individual variation to vary  
295 within the population, such as flight velocity, body mass, and proportion of body mass composed  
296 of metabolizable lipids. We applied these distributions to the starting population of ~20 million  
297 birds and updated the fluctuating variables according to incurred energetic costs (body mass,  
298 available metabolizable lipids). This arrangement allowed us to capture a realistic representation  
299 of the distribution of realized values for each parameter in the model without unreasonably  
300 increasing computing time. We varied the parameter values associated with the prior  
301 distributions for morphological features to evaluate their effects on the model (monitoring  
302 estimated survivorship as a comparison point), including daily survivorship, flight power  
303 components, morphological components, and energetic components.

304 (1) *Daily Survivorship*

305 Daily survivorship ranged from 0.99620 to 0.99984, from the second body condition bin to the  
306 optimal body condition bin (body condition bin 1 represented dead individuals, survivorship =  
307 0). We assumed birds that exceeded some critical mass would experience heightened mortality as  
308 a result of increase predation risk (or decreased predation avoidance ability), in keeping with  
309 optimal body mass theory (Lima 1986). We therefore set the optimal body mass to be that of a  
310 1.625 kg bird (~0.134 kg of fat), about the maximum of observed mallard body masses in the  
311 field (Owen and Cook 1977; while noting and allowing for the rare occurrence of heavier birds).

### 312 (2) *Flight power components*

313 Air density was informed by measured and interpolated air pressure values, as detailed in  
314 Appendix S1. The absolute range in air density across the period of sampled data was 0.95 to 1.3

315  $\frac{kg}{m^3}$ . The true air speed – that is, the velocity at which molecules *appear* to move past a moving

316 body from the perspective of the body in motion – ranged from 10 to 25  $\frac{m}{s}$ . Flight velocity (the  
317 actual velocity of the body in motion) ranged from 75.92 to 87.37, according to relations laid out  
318 in Flight (for Windows, version 1.25 [<http://www.bio.bristol.ac.uk/people/pennycuick.htm>];  
319 Pennycuick 2008).

### 320 (3) *Morphological components*

321 Body mass, wing span, and wing area were all modeled to follow skew-normal distributions with  
322  $\mu = 1.2$  and  $\sigma = 1.21$  [body mass],  $\mu = 0.95$  and  $\sigma = 1$  [wing span], and  $\mu = 0.1$  and  $\sigma = 0.1$  [wing  
323 area] (Owen and Cook 1977; assuming most individuals begin migration only when closer to  
324 optimal body condition). The proportion of body mass composed of metabolizable lipids (*kg*)  
325 was set to 11%, and was subsequently allowed to vary from 8 to 14% (using values from Dabbert

326 et al. 1997, Boos et al. 2007). Lipids account for ~81% to 84% of metabolizable energy (Boos et  
327 al. 2007). Not all lipids are available for metabolic processes (some retained for other purposes,  
328 not detailed; Boos et al. 2002, 2007). We assume the ~16% to 19% of metabolizable energy  
329 provided by sources other than lipids is used for processes other than flight (basal metabolic rate,  
330 reproductive organs, cellular replacement, etc.). Therefore, we assume that all energy directed  
331 toward powered flight relies on lipids as its source exclusively, and not all the ~10% to 16% of  
332 body mass comprised of lipids is available for powered flight processes.

333 Body mass had a mean of 1.2 *kg* (Owen and Cook 1977, Pennycuick 2008). This resulted in a  
334 distribution with a range of 0.5 to 2 *kg*. Wing span and wing area had ranges of 0.75 to 1.15 *m*  
335 and 0.09 to 0.11 *m*<sup>2</sup> (respectively; Bruderer and Boldt 2001).

#### 336 (4) *Energetic components*

337 The cost (*kg* of body fat) per unit distance flown (*km*) ranged from  $2.1 \times 10^{-5}$  to  $1.6 \times 10^{-4}$ ,  
338 according to relations laid out in Flight (Pennycuick 2008). Without clear guidance from the  
339 literature to inform a consistent relationship between fuel deposition rate and climatic factors, we  
340 defined the coefficient of fuel deposition rate as a multiple of body mass and set it to 1.1%  
341 initially, and subsequently set it to 0.5 and 2 to represent low and high values. This arrangement  
342 is in line with values presented by Lindström (2003), in which the maximum fuel deposition rate  
343 for a ~1 *kg* non-passerine bird caps out at 2% of the lean mass, with a minimum of 0.3%.

344

345 *Migration paths* – For each year of the simulation we recorded a migration “path” – an  
346 approximation of the median route taken by the population during the nonbreeding period. We  
347 computed the abundance-weight center-of-mass for the population on each day; given the spatial  
348 distribution of individuals within nodes across the landscape, we identified the point representing

349 the centroid of the population (Figure 3). By tracking the latitude of this point each day we  
350 assembled a trajectory representing the latitudinal and longitudinal shift of the centroid of the  
351 population throughout the nonbreeding period. Evaluating the nadir of the latitudinal shift across  
352 years informs potential temporal patterns in migration and overwintering dynamics. For  
353 example, one might expect a general northward regression of the southern-most point of the  
354 population center-of-mass through time as average global atmospheric temperatures increase  
355 (Aagaard et al. 2018). Alternatively, the southern-most point might be more closely related to  
356 weather severity, with a changing climate leading to increasingly variable weather patterns from  
357 one year to the next; as such, there may not be a consistent decrease in severe weather but rather  
358 more frequent extremes (more unusually mild and unusually severe weather years). By  
359 regressing the southern-most point of the population center-of-mass with year and *WSI* we can  
360 potentially parse this difference.

361 We calculated the mean distance between all consecutive population centers-of-mass, as well  
362 as the distance between the northern-most and southern-most population centers-of-mass. These  
363 metrics informed the mean distance moved by the population from one day to the next, as well as  
364 the separation between breeding grounds and overwintering habitat. We identified the most  
365 commonly used nodes during the course of the nonbreeding period by measuring the total  
366 abundance in each node on each day to compute the top 2% most populated nodes per day. We  
367 used these metrics to produce animations for each year of the record showing the daily,  
368 normalized (0-1) abundance for each node in the landscape.

369

370 *Data sources* – Our model takes as input six data layers relating to habitat state and weather  
371 conditions. There are five layers relating to habitat state; the first was derived from National

372 Land Cover Database (NLCD) 2006 for the USA (Fry et al. 2011) and the CSC2000v for Canada  
373 (*available online*; see Appendix S2) to estimate roosting and foraging quality. We used  
374 NatureServe range maps (Ridgley et al. 2005) to identify potential starting locations among  
375 which to distribute birds at the onset of the nonbreeding period. We used these input layers in  
376 conjunction with breeding population survey data (U.S. Fish and Wildlife Service 2013) to  
377 establish abundance at breeding sites by weighting the total number of birds by the quality of  
378 habitat within the site and the breeding population survey results for the area. We relied on daily  
379 climate data from the National Oceanic and Atmospheric Association's National Centers for  
380 Environmental Prediction National Center for Atmospheric Research Reanalysis Project (NOAA  
381 NCEP; Kalnay et al. 1996).

382 We considered sites with a higher proportional area of shoreline, herbaceous wetlands, and  
383 wooded wetlands to be of higher quality for roosting. In this fashion, breeding sites of high  
384 quality aligning with large numbers of birds from the breeding population survey hosted the  
385 greatest numbers of individuals. We estimated mean forage availability per site (in 0.1 GJ units)  
386 at the outset of the nonbreeding period based on an evaluation of land cover using a range of  
387 parameter estimates. Further details of this process, and the values used for the forage  
388 availability parameter estimates, are available in Lonsdorf et al. (2016).

389

390 *Landscape generation* – Mallards have documented preferences for wetlands with shallow water  
391 (5–20 cm) in which to forage and near which to roost (Colwell and Taft 2000, Guillemain et al.  
392 2000). We classified shoreline cover as optimal roosting habitat (i.e., with a value of 1, while all  
393 other cover types are 0), and calculated the proportion of each node occupied by shoreline cover.

394 Multiplying this proportion by the area of the focal node yielded the value of roosting quality  
395 provided by that node.

396 We multiplied the amount of forage provided by each land cover type represented within the  
397 node (using food-habit information from the literature; see Lonsdorf et al. 2016) by the  
398 proportion of the node classified as each land cover type. We multiplied this value by the  
399 proportion of forage *available* in a node, based on the distance to the nearest roosting site. Areas  
400 in which forage and roosting habitat were nearby had greater proportions of their forage  
401 available for consumption to account for a decrease in net energy extracted from a node given  
402 the increased distance traveled to the foraging sites within the node. We multiplied this roosting  
403 distance- and area-dependent forage availability measure by the area of the node to calculate the  
404 quantity of forage available in each node (Pearse et al. 2012, Beatty et al. 2014).

405

406 *Winter severity* – To quantify the severity of the weather in a given node (and thus the  
407 probability that birds will occupy that node), we followed the framework of Schummer et al.  
408 (2010) wherein a weather severity index (*WSI*) was calculated based on the depth of snow in a  
409 node ( $S$ , cm), the number of consecutive days with snow depth  $\geq 2.54$  cm ( $S_{days}$ ), the temperature  
410 in a node ( $T$ , °C), and the number of consecutive days with temperature  $< 0$  ( $T_{freeze}$ ). The  
411 formulation follows:

$$412 \quad WSI = (S \times 0.394) + S_{days} + (-T) + T_{freeze}.$$

413 Schummer et al. (2010) found that the rate of change of the relative abundance at a location  
414 switched from positive to negative when  $WSI = 7.5$ ; we invoked this value as the threshold below  
415 which individuals were expected to remain in a node and above which individuals were expected  
416 to depart.

417

418 *Model evaluation* – We monitored a suite of metrics as we iterated our simulation across years to  
419 evaluate the degree to which migratory patterns differed annually. We monitored nonbreeding  
420 period mortality ( $N_0 - N_n$ ;  $n$  is the last day of the nonbreeding period). We also monitored  
421 landscape availability, based on the number of nodes in which the *WSI* was less than the  
422 threshold each day. We calculated the mean availability (and standard deviation) of habitat, as  
423 well as the minimum availability at any point during the nonbreeding period. These values  
424 informed the average weather severity across the nonbreeding period, and the severity of the  
425 weather during the least hospitable portion of the nonbreeding period. We ran the model in R (R  
426 Core Team 2018).

427

## 428 **Results**

429

430 *Objectives* – As expected, we observed weather patterns and conditions effecting the  
431 nonbreeding period of the annual cycle of migratory birds. We were able to discern  
432 overwintering habitat as an emergent property of the model (Figure 3). The average proportion  
433 of available habitat ( $WSI < 7.5$ ) across the landscape increased as winter weather severity  
434 decreased (Figure 4A), and mortality decreased as the proportion of available habitat increased  
435 (Figure 4B). Unexpectedly, mortality did not demonstrate any correlative trend with weather  
436 severity (Figure 4C), perhaps because birds flew beyond the range of the affected area.

437 Importantly, whereas we summarized weather severity across the entire landscape, there was  
438 spatial heterogeneity in the variation of weather severity. The summarized *WSI* in the available  
439 habitat showed a slight increase over time, with a few years of above-average weather severity

440 later in the record (especially 2009-2010 and 2010-2011). However, the summarized *WSI* across  
441 the entire landscape decreased more dramatically over the same timeframe (even 2009-2010 and  
442 2010-2011 produced below-average *WSI* scores) (Figure 5). We plotted the standard deviation of  
443 the mean annual *WSI* for each node across the period of record to demonstrate this point (Figure  
444 6).

445 We were successful in our attempt to recover the primary avenues for migration (Figure 7  
446 and File S4): a heavily-used central flyway along the Mississippi River, a well-defined Atlantic  
447 Flyway east of the Appalachian Mountains, and a disjointed Pacific Flyway along the west coast.  
448 The flyways tended to converge within the Prairie Potholes Region and along the southern shore  
449 of Hudson Bay (which is the NatureServe defined breeding region). The most commonly used  
450 nodes during the course of the nonbreeding period were generally consistent across years (Figure  
451 7). The center-of-mass of the population during the migratory periods were similarly consistent  
452 across years, while the overwintering period showed more inter-annual variation (Figure 7).  
453 Finally, the model yielded strong evidence of the effect of *WSI* on the distribution of birds on the  
454 landscape. The mean distance among all daily center-of-mass locations was highly correlated  
455 with the standard deviation of available habitat (adj.- $R^2 = 0.86$ ; Figure 8), suggesting that the  
456 distribution of birds on the landscape changed more dramatically when the variation in daily  
457 available habitat was greater.

458 Temporally, we were able to distinguish between severe and mild years by their mean daily  
459 *WSI* values across the landscape, and the years identified as severe or cohered to historical  
460 weather anecdotes. We found that years with severe weather yielded correspondingly reduced  
461 available habitat during the winter months (Figure 10). Finally, we found that as *WSI* increased,

462 the population moved farther south during the nonbreeding period as available habitat was  
463 reduced (Figure 10, and see Appendix S3).

464

465 *Validation* – Our model predicted an average survivorship of 77.4% for the nonbreeding period  
466 across all years (range = 76.4 – 78.4%). This value is decomposed into an average survivorship  
467 rate of 91.3% for the autumn migratory period (1 September to 30 November; 90.5 – 92.1%),  
468 91.8% for the overwintering period (1 December to 28 February; 91.1 – 92.6%), and 92.4% for  
469 the spring migratory period (1 March to 31 May; 91.5 – 92.9%). Mean daily mortality across the  
470 period of record ranged from 13,100 to 21,000 birds (Figure 9). These estimates are  
471 commensurate with literature-derived mortality estimates (Zimmer et al. 2010, Davis et al.  
472 2011).

473

474 *Parameter sensitivity* – The proportion of birds in different body condition bins varied most  
475 strongly at lower classes, with a two-order of magnitude increase in the proportion of birds in the  
476 lowest body condition (starvation) over the nonbreeding period, and a 20% reduction in birds in  
477 the top body condition. Decreasing the proportion of metabolizable body fat to 8% resulted in  
478 survivorship (averaged across all years) of 86.72% (85.87 – 87.37%), whereas increasing it to  
479 14% metabolizable body fat yielded survivorship of 50.66% (50 – 51.35%). Increasing the  
480 coefficient for the fuel deposition rate to 2 increased survivorship to 89.15% (89.05 – 89.22%),  
481 whereas decreasing it to 0.5 decreased survivorship to 41.03% (39.99 – 41.95%) (while holding  
482 the proportion of metabolizable body fat steady at 11%).

483

484 **Discussion**

485

486 We elaborated an energetics-based model of avian migration to more fully realize the stochastic  
487 variation in migration induced by daily weather. Our model was able to recreate documented  
488 North American avian migration routes (La Sorte et al. 2014a, La Sorte et al. 2014b, Lonsdorf et  
489 al. 2016) and recover expected rates of survivorship (Lonsdorf et al. 2016;  $90.5 \pm 1.35\%$  [mean  $\pm$   
490 confidence interval] survivorship in autumn,  $93.6 \pm 1.1\%$  survivorship in spring) based on  
491 nothing more than first-principle arrangements of dabbling duck energetics and behavior. With a  
492 thorough literature review and carefully considered parameterization, the model we present here  
493 can be generalized to any migratory bird species. Extending the model to the entirety of the  
494 nonbreeding period is a crucial step on the path to developing a generalizable energetics-based  
495 full-annual-cycle model (Marra et al. 2015). We included consideration of weather severity on  
496 the movement patterns of migrants, allowing us to form initial expectations about the role  
497 climate and climate change can play in altering physiology and subsequent migration behavior  
498 (Notaro et al. 2016). We introduced a refined forage availability scheme by allowing for  
499 consumption and natural decay of forage material during the nonbreeding period.

500

501 *Interpreting results* – Our model suggests that the milder conditions across North America  
502 resulting from climate change (Appendix S3; Schummer et al. 2017) are increasing the  
503 proportion of habitat available to dabbling ducks which has led to decreased environmentally  
504 induced mortality. This result is evident in the decrease in *WSI* over time across the continent,  
505 demonstrating generally less severe winters over the period of record. This result is also  
506 evidenced in the relationship between *WSI* and the minimum proportion of available habitat, with  
507 less available habitat in years with greater *WSI*.

508 Walther et al. (2002) indicated that freeze-free periods were lengthening and that snow cover  
509 has decreased since the 1960s. If these trends continue, as recent studies suggest (Notaro et al.  
510 2014), we may expect to see more northerly overwintering (Abraham et al. 2005, Link et al.  
511 2006, Tingley et al. 2009, Notaro et al. 2016). Taken to the extreme, this development may  
512 suggest that mallard-like dabbling ducks could be approaching a cessation of migration (Moore  
513 2011, Notaro et al. 2016, Aagaard et al. 2018). Recent studies investigating the changing patterns  
514 of avian migration under the influence of climate change provide corroborating evidence of this  
515 possibility (Walther et al. 2002, La Sorte and Thompson 2007); American black ducks (*Anas*  
516 *rubripes*), for instance, have shown a tendency to remain in the region in which they breed  
517 during migration, and some occasionally move in directions antithetical to conventional  
518 migratory movements (Brook et al. 2009, Robinson et al. 2016). Whether this movement  
519 represents inexperienced birds or the influence of climate or land use/land cover change has not  
520 been decisively determined, but mounting evidence of similar patterns paired with the findings of  
521 this and other simulation models suggest it is the latter.

522 By varying the proportion of available metabolizable body fat we were able to identify  
523 sensitivity within the model. The effect of modifying the proportion of available metabolizable  
524 body fat was counterintuitive; increasing body fat functionally increases available fuel and  
525 should decrease time spent migrating, the most energy expensive aspect of the nonbreeding  
526 period. However, the proportion of body fat does not influence the cost of flight, so two  
527 individuals of the same body mass but different body fat proportions will be subjected to the  
528 same energetic costs. The individual with a greater proportion of body fat will be able to travel  
529 farther, decreasing its body mass more substantially and (based on the structure of our model)

530 subsequently transitioning into a lower body condition class with a lower associated daily  
531 survivorship.

532       Given the harsher conditions and limited habitat availability during the overwintering period  
533 (see Appendix S3), the lower survivorship is expected. In autumn, we expect greater forage  
534 availability on the landscape than in winter (and possibly even spring), as seed and waste grain  
535 has not yet decayed (Hagy and Kaminski 2012), so we expected higher survivorship during this  
536 period. However, the timing of energy expensive migration fell in the autumn period (1  
537 September to 30 November), which led to greater reductions in body condition and therefore  
538 generally greater mortality rates. The higher mean survivorship rate of spring is likely a result of  
539 less intense weather severity than in either the fall or nonbreeding periods.

540       When reviewing extreme weather events within the period of record we considered, there is  
541 appreciable concordance with *WSI* and observed extremes (e.g., deep freezes in the south, as in  
542 1957-1958, and 1961-1962). Events such as these, coupled with our model results, offer support  
543 for the claim that poor weather tends to push birds farther south in search of hospitable habitat  
544 (Figure 9). Conversely, mild years (such as 2015-2017) provide more available habitat across the  
545 landscape (Figure 9), likely leading to the population generally staying closer to the breeding  
546 grounds and demonstrating more willingness to withstand brief inclement weather, with the  
547 expectation that more hospitable conditions await after it quickly passes. As climatic conditions  
548 increase in variability this change could have dramatic effects on migratory dynamics, as some  
549 years may see birds move only a short distance from the breeding grounds, while in other years,  
550 comprised of extreme weather events, birds may be pushed relatively far south. If the tendency  
551 of waterfowl is to remain sedentary as extreme events pass through, and if these events end up  
552 lasting longer, this sedentary inclination could lead to unusually high mortality events in some

553 years. Historical data show a clear divergence in the spatial variation in weather severity,  
554 consistent with expectations of increasingly extreme weather as the climate changes, so  
555 predictions of general trends will necessarily be obscured by these spatially inconsistent weather  
556 pattern changes.

557 Waterfowl enthusiasts (e.g., birders and hunters, Cooper et al. 2015) contribute >\$100  
558 million annually to the economies of Canada and the U.S. (Mattsson et al. 2018, 2020). Should  
559 migration distance continue to shorten and sedentary behavior increase, the availability of  
560 waterfowl to birders and hunters would likely be affected, potentially leading to decreased  
561 funding in support of wetland habitat conservation (Grado et al. 2001, Cooper et al. 2015, López-  
562 Hoffman et al. 2017). If hunter behavior were to change in response to differing migratory  
563 patterns, the distribution of monetary resources would likely change as well (López-Hoffman et  
564 al. 2017, Bagstad et al. 2018, Mattsson et al. 2020).

565

566 *Future research directions* – Our model has many important strengths in terms of advancing our  
567 understanding of avian nonbreeding movement patterns within the context of energetics and  
568 weather. We sought to maintain flexibility in the model for ease of adding components that  
569 might increase the power of the model. We did not add these components in the present iteration  
570 because, in some cases, there remain critical gaps in our knowledge requiring further research.  
571 For example, while we included a placeholder for harvest-induced mortality, an important aspect  
572 of migration dynamics (Klaassen et al. 2005, Vaananen 2001), we lacked access to data at the  
573 relevant spatial scale to inform the effect of this source of mortality across the landscape. Efforts  
574 to aggregate such data for inclusion in future iterations of this model would be extremely useful.

575 Because waterfowl migration is mediated on a daily time-step via weather, predicting waterfowl  
576 availability on time horizons useful to hunters could be possible.

577 While we used pertinent land cover data to inform forage availability across the landscape,  
578 we are aware of limitations in converting land cover classes into available kilojoules, as well as  
579 grouping potentially distinct land cover classes into broad categories (Malishev and Kramer-  
580 Schadt 2021). Targeted research into the seasonally varying availability of accessible forage  
581 (including invertebrates) in various land cover classes is necessary to better inform this aspect of  
582 the model (e.g., Fredrickson and Reid 1988, Kaminski et al. 2003, Bishop and Vrtiska 2008,  
583 Beatty et al. 2017). Improving the reliability of spatial data layers is of particular importance to  
584 eIBMs, given the significance of this input on the resulting dynamics predicted by the model  
585 (Malishev and Kramer-Schadt 2021). Similarly, despite formatting our model with an agent-  
586 based rather than individual-based framework, we ignored another main challenge eIBMs face  
587 (Malishev and Kramer-Schadt 2021): accounting for complex behavior and movement (e.g.,  
588 sociality and predation avoidance). Refining our understanding of the probabilistic tendencies of  
589 individuals to alter movement dynamics as a function of social dynamics or predation threat  
590 would greatly improve our approximation of especially small-scale (short-distance) movement.

591 In other cases, we omitted potentially important components because the complexity they  
592 add to the model significantly inflates computational time. We foresee a framework for adding in  
593 additional components in a serial, stepwise process. That is, we first developed a generalizable  
594 energetics-based landscape model for avian migration (Lonsdorf et al. 2016), then laid the  
595 foundation for the interaction between temperature and migration energetics (Aagaard et al.  
596 2018), and now merge those efforts to generate a generalizable continental-scale energetics-  
597 based landscape model of avian migration accounting for variable temperature and weather

598 severity and their effects on migratory dynamics. By building toward the ultimate goal of a fully  
599 generalizable and energetics-based *animal* movement model one block at a time we provide a  
600 cogent work flow and fully elaborate the logic at each step. Thus, we have for now ignored the  
601 effect of some aspects such as wind direction on avian migration dynamics, a component known  
602 to be predictive of movement patterns (La Sorte et al. 2014b). Adding model functions and data  
603 relating to daily wind currents and velocity would likely improve the realism of our model and  
604 provide refined predictions for migration routes and critical habitat areas (Gutierrez Illan et al.  
605 2017).

606 We also excluded competition (Eichhorn et al. 2009, Stirnemann et al. 2012) and  
607 epidemiological effects (Gilbert et al. 2006) from the model. While we found that *WSI* has  
608 generally increased over time and led to decreased mortality, it is possible that altered disease  
609 dynamics may counteract these gains in survivorship (i.e., as the climate becomes milder, disease  
610 transmission may increase; Harvell et al. 2002), while decreased competition may provide the  
611 opposite influence. Developing techniques to account for these dynamics in the model would be  
612 beneficial. As with all models, we must balance realism in the model with the usefulness of the  
613 general trends and predictions of the model.

614 Lastly, we made preliminary connections between the body condition of birds at the end of  
615 the nonbreeding period and the energy available for reproduction during the breeding period.  
616 Assuming an energy conversion of 39,700 kJ per kg of body fat (Rayner 1990), and an energy  
617 content of 400 to 636 kJ per egg (636 kJ in Ricklefs 1977; 487 kJ in Sotherland and Rahn 1987;  
618 400 kJ in Alisauskas and Ankney 1992), we estimate that, for 400 kJ per egg, only birds with  
619 body mass greater than 0.725 kg and above would have sufficient fat reserves available at the  
620 outset of the breeding period to lay at least one egg, and for 636 kJ per egg, only birds with body

621 mass greater than 0.8 kg would be able to lay at least one egg (see Krapu 1981 for discussion of  
622 body condition and breeding period success). Given a clutch size range for mallards of eight to  
623 13 eggs (Drilling et al. 2020), we estimate that only birds with body mass over 1.4 kg (for 400 kJ  
624 per egg) or over 1.625 kg would lay a full clutch of eggs at the beginning of the breeding period.  
625 Birds in lower body conditions would need more time to forage to restock fat reserves  
626 sufficiently to produce a full clutch size. The modeled distribution of birds in each body  
627 condition at the end of the nonbreeding period indicates that approximately 3% (for 636 kJ per  
628 egg) to 15% (for 400 kJ per egg) of the population could effectively lay a standard size clutch of  
629 eggs at the beginning of the breeding period, also allowing for the possibility of a second clutch  
630 (depending on the size of each) later in the breeding period given a rapid enough rate of fuel  
631 deposition.

632

633 *Conclusions* – Accelerating change to land cover and climate is eroding avian migration as we  
634 know it. Merging environmental conditions with spatially explicit models of energetics-based  
635 migratory movements is helping to inform how the landscape affects migration patterns. Our  
636 model approximates avian migration during the nonbreeding period and the movement occurring  
637 among local stopovers along the way. Our results indicate that available habitat during the non-  
638 breeding period has likely increased over time, indicative of milder conditions as a product of a  
639 changing climate, ultimately leading to decreased (environmentally induced) mortality. This  
640 finding has important ramifications: if migration distance continues to diminish and the tendency  
641 for sedentary behavior increases, we may see altered hunter harvest across the landscape.  
642 Additionally, if sedentary behavior in the face of extreme events continues then birds may  
643 experience unusually high mortality events in some years. All these possibilities underscore the

644 need for continued advancements in the vein of this model to further illuminate the consequences  
645 of a changing environment on avian migration.

646

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653

#### 654 **Data Accessibility**

655 All data are stored in publicly available repositories as cited in the paper (e.g., weather data  
656 comes from the National Oceanic and Atmospheric Administration’s National Centers for  
657 Environmental Prediction). We provide all code as Supporting Information, and the code has  
658 annotated references to each data set.

659

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913 **Tables**914 **Table 1.** Definition, values, and units for each parameter used in the model.

<b>Parameter</b>	<b>Definition</b>	<b>Value</b>	<b>Units</b>
$d$	Local movement distance	3,000	m
$v$	Mean flight velocity	76 – 86	km/hr
$e$	Energetic cost of flight (per hr)	0.042 – 0.076	kJ/hr
$w$	Weather Severity Index threshold	7.5	—
$r$	Flight range	2,253	km
$n$	Node size	32.187	km
$N_0$	Initial population size	19,856,514	individuals
$m$	Body mass	800 – 1,300	grams
$LCT$	Lower Critical Temperature	$47.2 \times (m \times 1000)^{-0.18}$	°C
$s_d$	Daily survivorship range	0.9975 – 0.9997	—
$f$	Proportional body fat range	0 – 0.13	—

915

916 **Table 2.** Values assigned to the weights for natural forage decay rates in available land cover  
917 classes.

<b>Land cover class</b>	<b>Weight</b>
Shoreline	0.9998
Crops	0.9970
Woody wetlands	0.9965
Herbaceous wetlands	0.9910

918

919 **Figure Legends**

920 **Figure 1.** Graphical representation of the order of operations of the model. We initiated (1)  
921 foraging activity (i.e., the loss of forage material from the habitat as a result of active foraging  
922 and natural decay and the subsequent acquisition of the actively foraged material to augment  
923 body condition, **BC**) prior to (2) departure, the probability of which was dictated by the node-  
924 specific weather severity index (*WSI*), class-specific **BC**, distance between a focal node and the  
925 nearest breeding node (distance to breeding grounds, **DB**), and the node-specific air density  
926 (**AD**). Arrival of individuals (3) followed, informed by node-specific forage quantity (**F**),  
927 roosting habitat quality (**R**), cumulative gamma-movement probability (the probability of  
928 moving between each pair of nodes on the landscape, given the distance between them; **G**), as  
929 well as **AD** and **DB**. Individuals were then redistributed among **BC** classes according to energy  
930 expended in flight and were redistributed spatially based on to-from node flights. Finally, the  
931 population incurred mortality (4) according to survivorship rates related to each **BC**. We  
932 calculated the number of individuals per body condition after mortality and arrival, as well as the  
933 number of individuals per node, for the following day.

934

935 **Figure 2.** Graphical representation of exponential weights for each of the four components of the  
936 Cobb-Douglas function used to define node attractiveness over time: amount of forage  
937 availability, air density, proportion of roosting habitat in each node, distance to the nearest  
938 breeding node, and a cumulative probability of moving to a node from all other nodes based on a  
939 gamma function.

940

941 **Figure 3.** An example of the abundance-weighted center-of-mass for the population on the 50<sup>th</sup>  
942 day of migration, represented by the black dot. The gray shaded areas represent the top 2% most  
943 populace nodes on day 50.

944

945 **Figure 4.** (A) Normalized  $\left(\frac{x_i - \bar{x}}{sd(x)}\right)$  minimum available habitat on the landscape as a function of  
946 normalized weather severity index (*WSI*); (B) Normalized mortality during the nonbreeding  
947 period (September to May) as a function of normalized minimum available habitat; and (C)  
948 Normalized mortality as a function of normalized *WSI*. Black lines indicate the line of best fit of  
949 a generalized linear model and associated standard error (gray shaded area).

950

951 **Figure 5.** (A) Mean weather severity index (*WSI*; Schummer et al. 2010) within the available  
952 habitat (areas with *WSI* < 7.5) and (B) across the entire landscape showed differing patterns over  
953 time.

954

955 **Figure 6.** The standard deviation in the annual mean weather severity index (*WSI*) over the  
956 period of record (1957 – 2019) for each node in North America. Mid-latitude and above areas  
957 were subject to greater variation in weather severity over time than southerly areas, which are  
958 more consistently incorporated in “available habitat” (areas with *WSI* < 7.5).

959

960 **Figure 7.** Map showing the 2% most populace nodes, in gray, across the nonbreeding period  
961 (September to May) for all years (1957 – 2019). The darker the gray the more often a node  
962 occurred within the 2% most populace nodes across the record. The 2% most populace nodes  
963 were similar across most years, hence the consistent patches. Lines represent the path of the

964 abundance-weighted population center of mass, or migration route, across years, with the mean  
965 of all years in black.

966

967 **Figure 8.** The mean distance among all abundance-weighted center-of-mass locations for the  
968 population on each day increased as the standard deviation of the daily proportion of available  
969 habitat (weather severity index  $< 7.5$ ) increased.

970

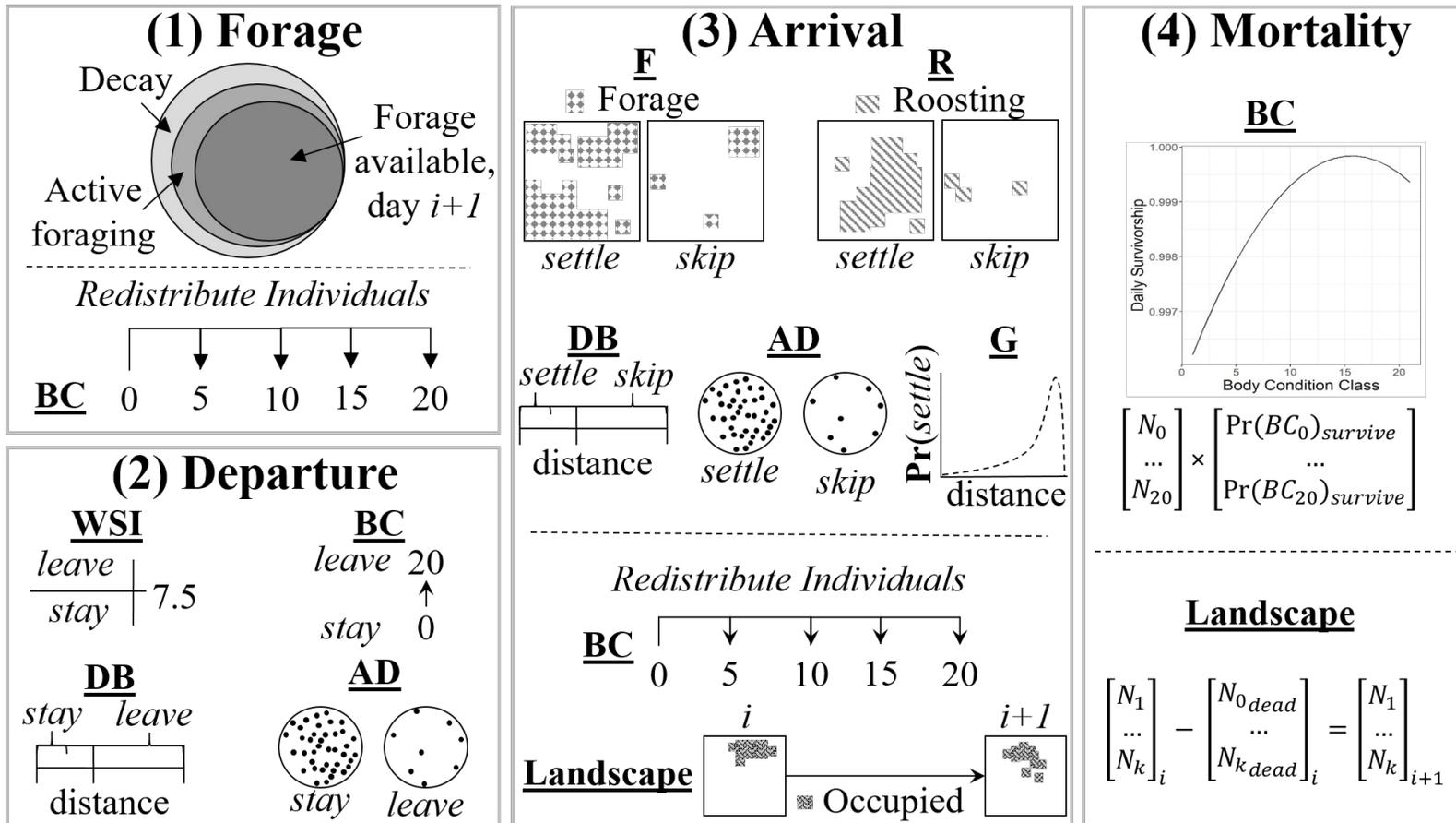
971 **Figure 9.** Mean daily mortality (total number of dead birds) on each day of the non-breeding  
972 period across the period of record (1957 – 2019).

973

974 **Figure 10.** Comparison of mean daily proportion of available habitat during the nonbreeding  
975 period for years in the highest quartile of mean annual weather severity index values (“Severe”;  
976 1961, 1964, 1966, 1971, 1972, 1974, 1975, 1977, 1978, 1981, 1982, 1984, 1993, 1995, 1996,  
977 2013) and for years in the lower quartile (“Mild”; 1979, 1980, 1997, 1998, 1999, 2001, 2003,  
978 2004, 2005, 2006, 2009, 2011, 2015, 2016, 2017).

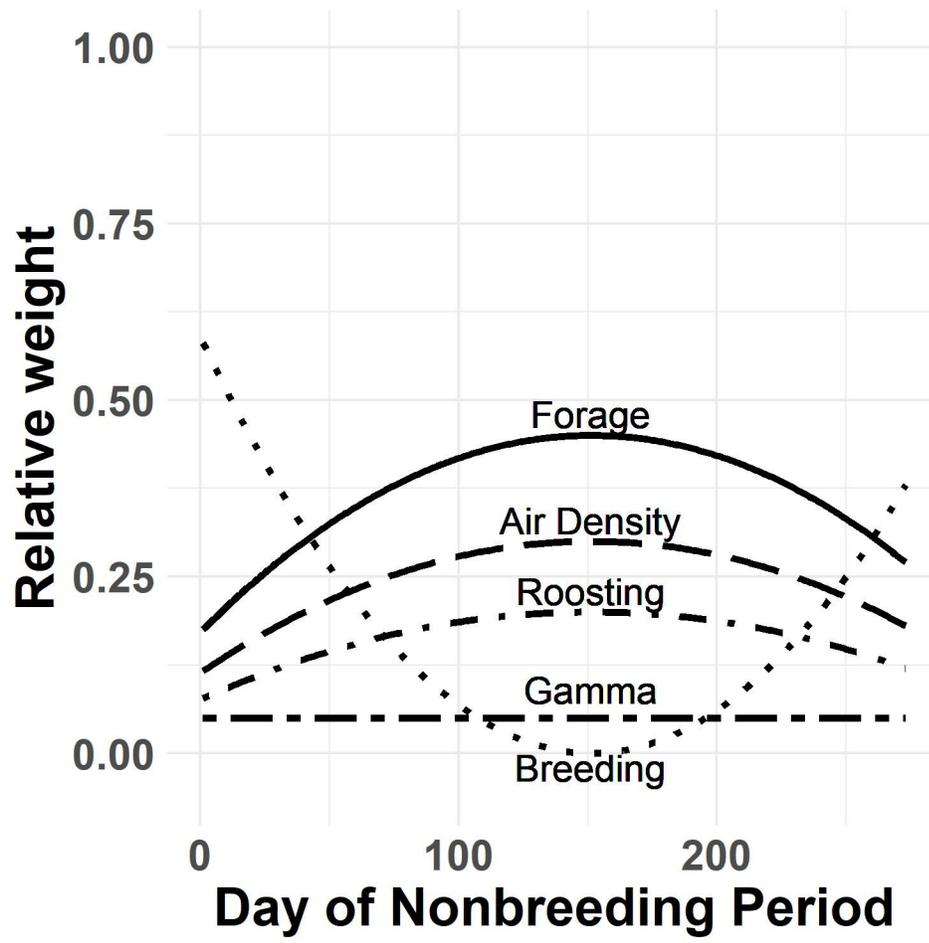
979

980 **Figure 1.**



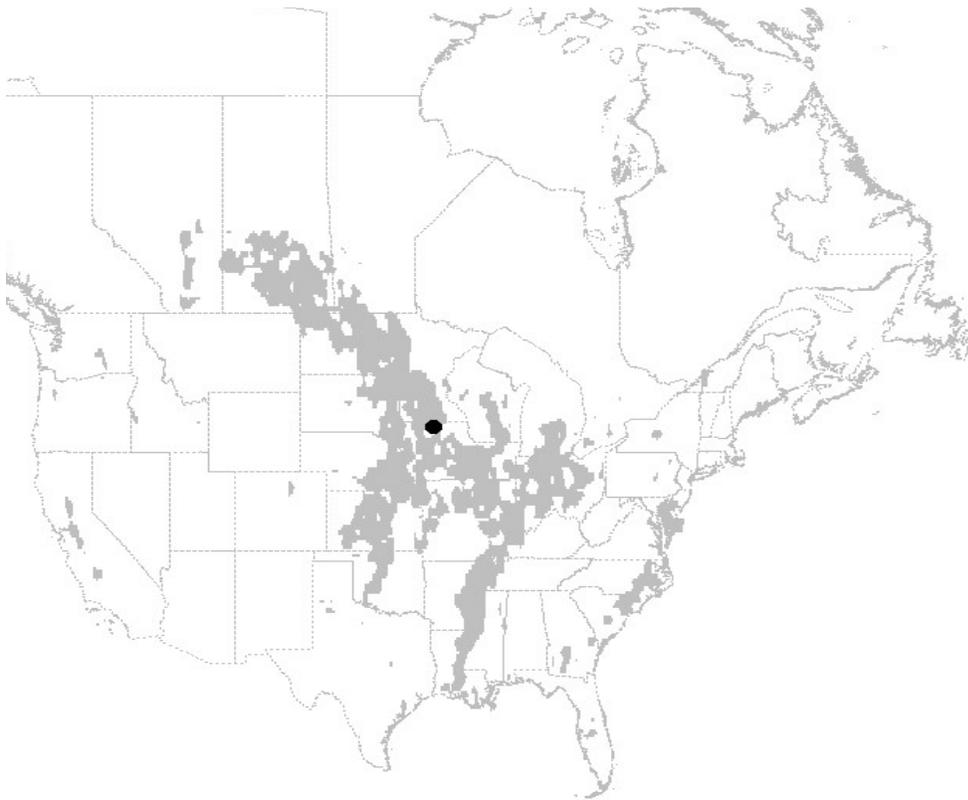
981

982 **Figure 2.**



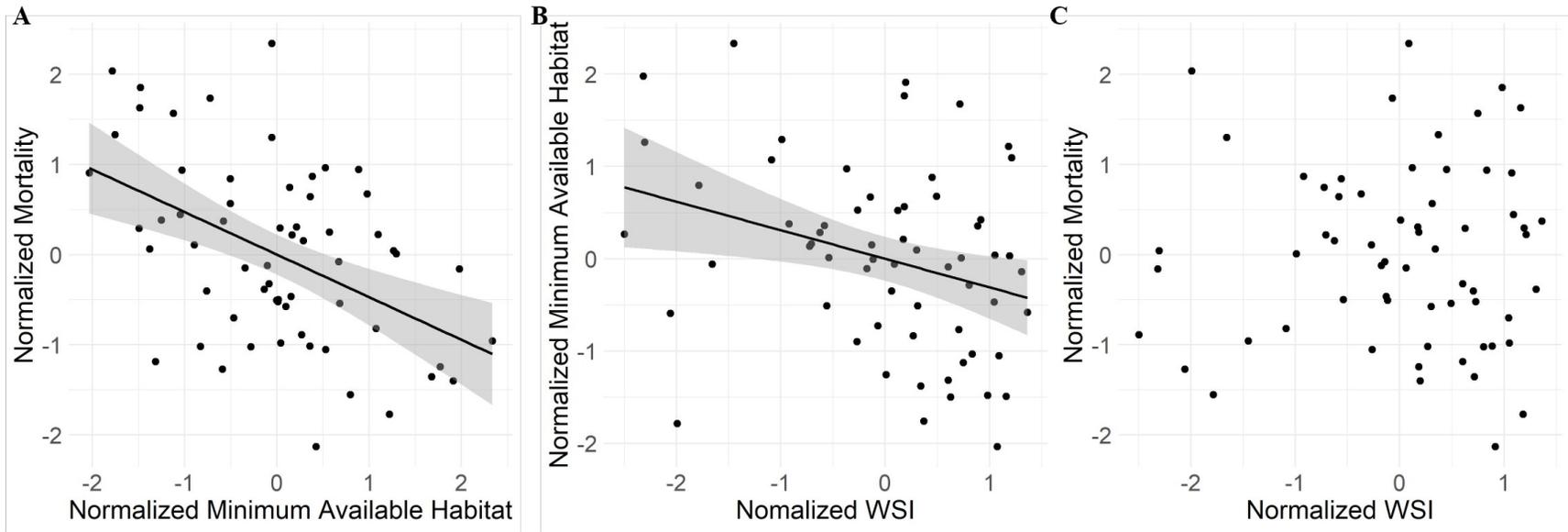
983

984 **Figure 3.**



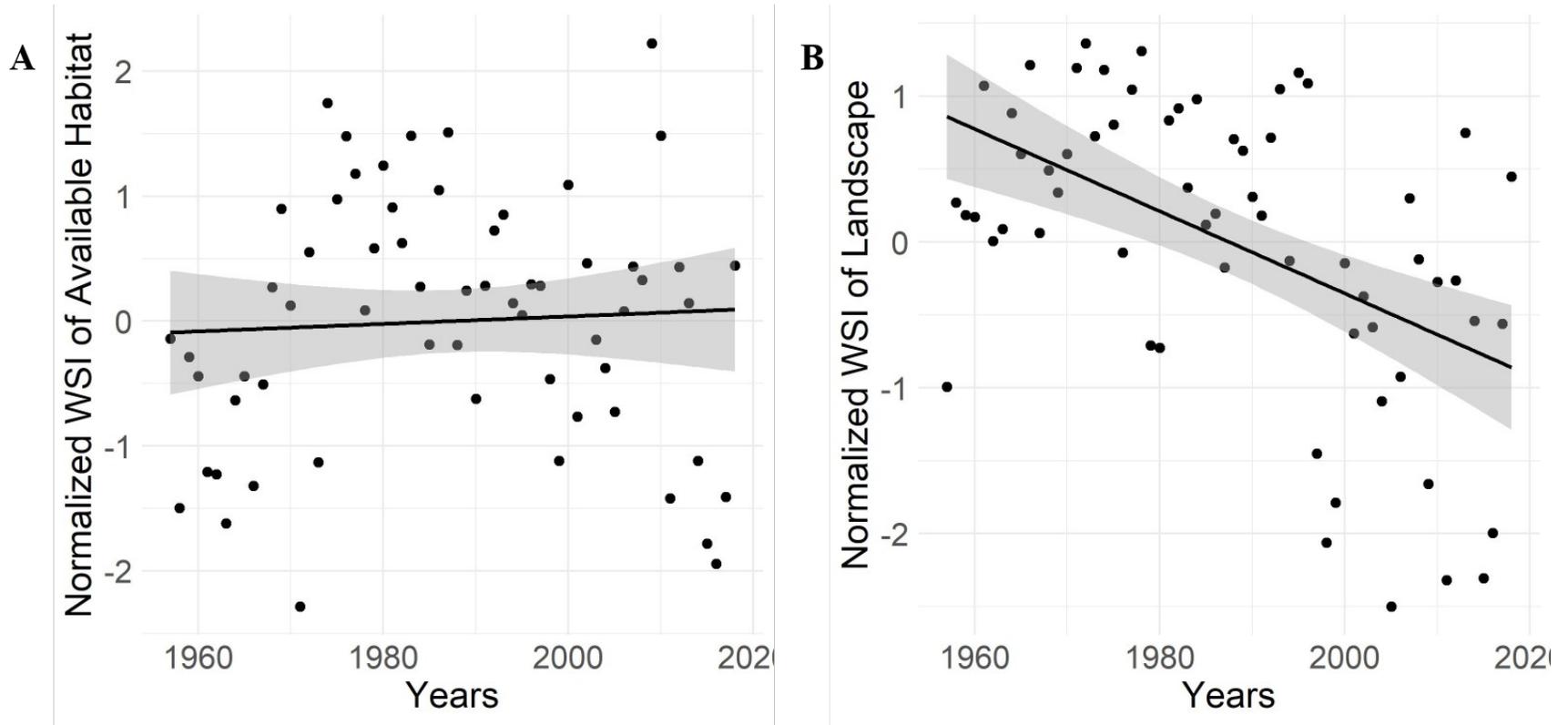
985

986 **Figure 4.**

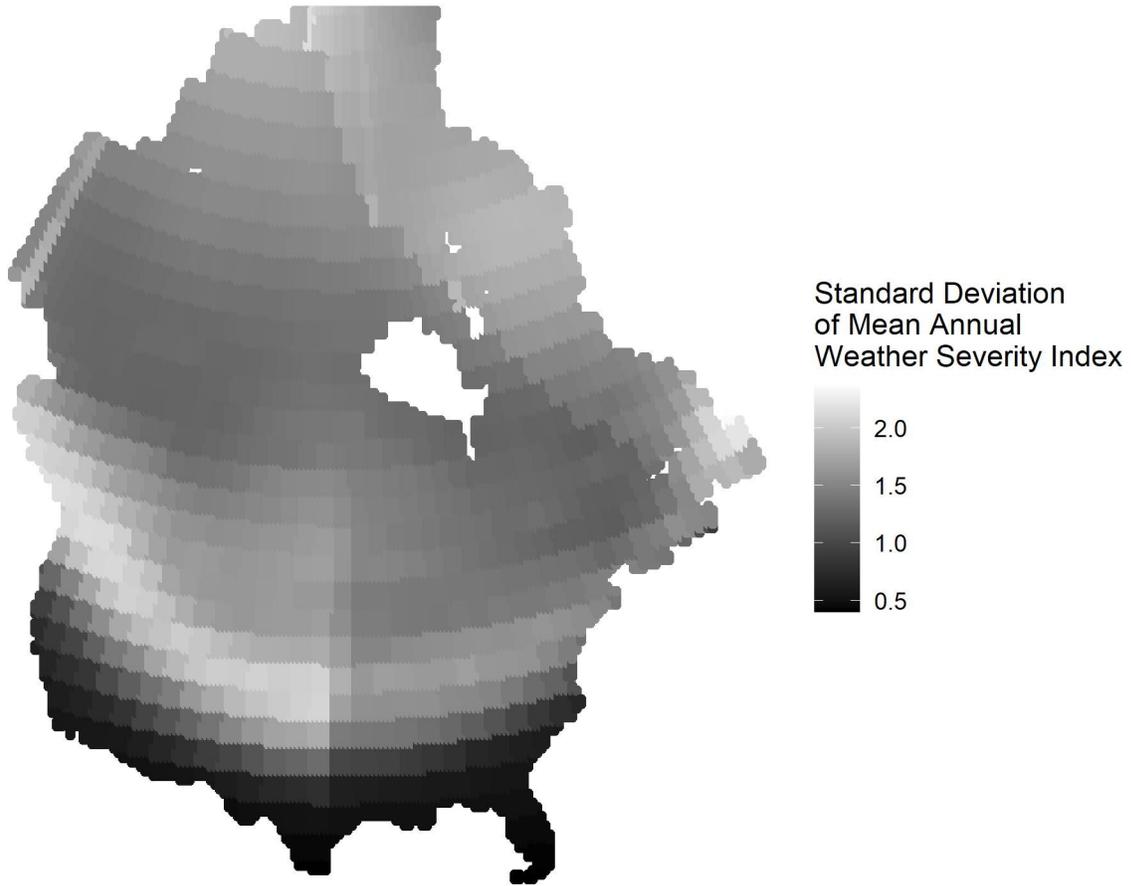


987

988



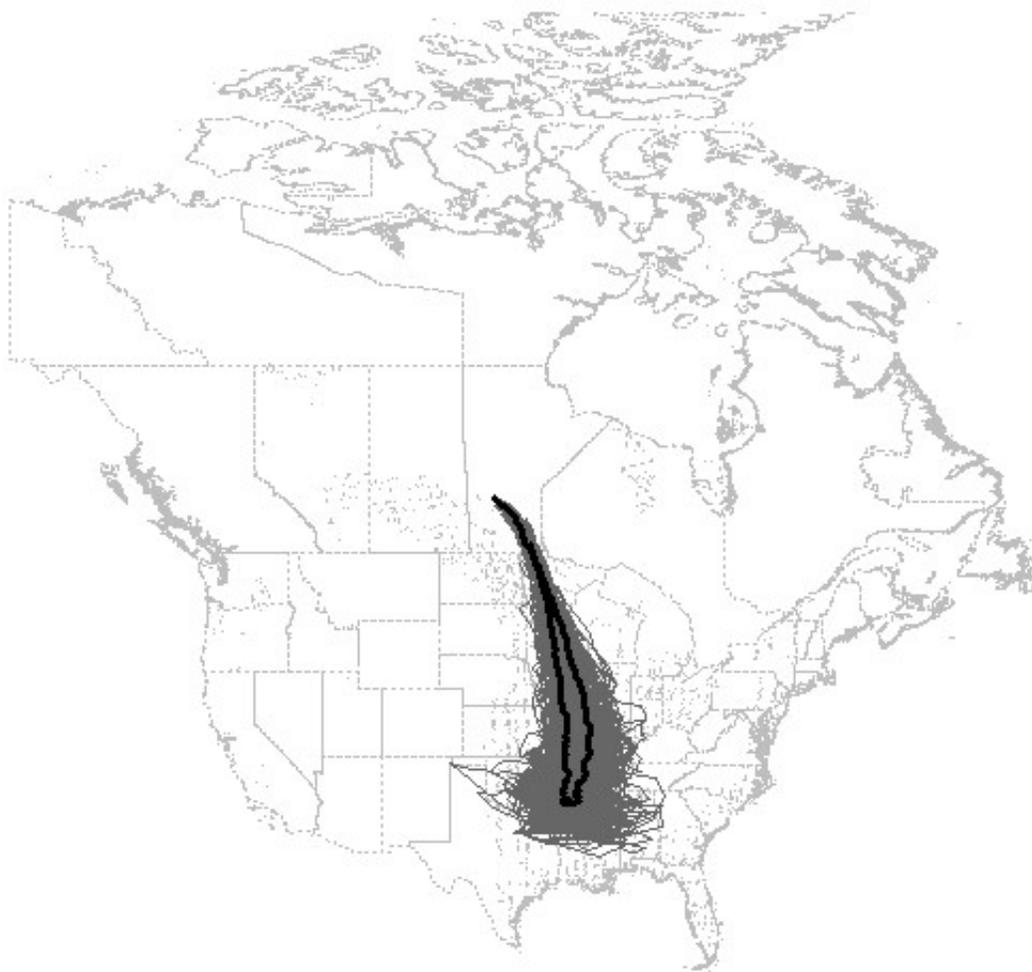
991 **Figure 6.**



992

993

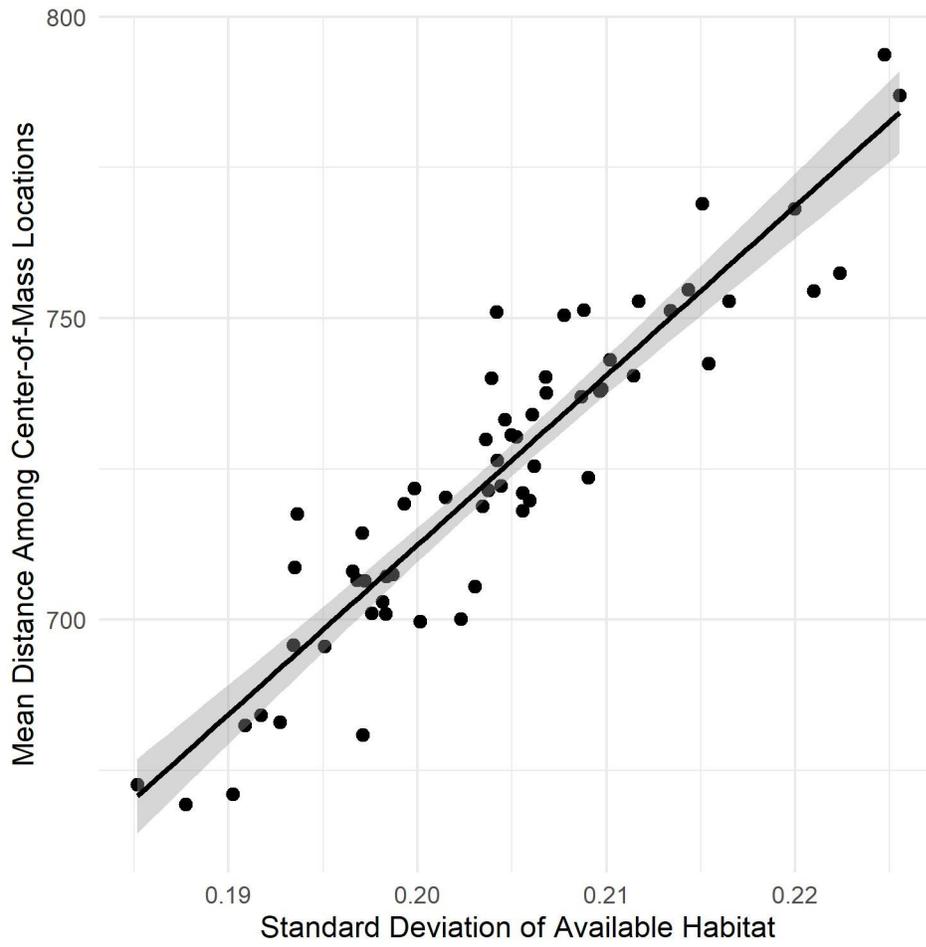
994 **Figure 7.**



995

996

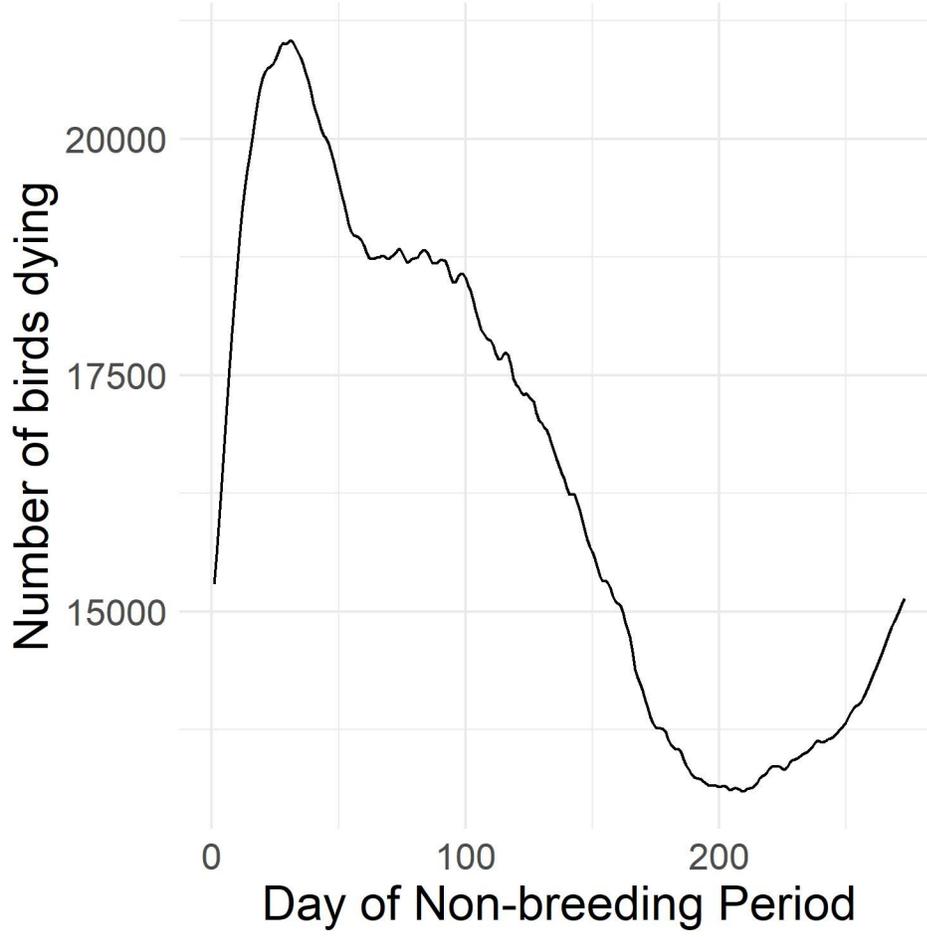
997 **Figure 8.**



998

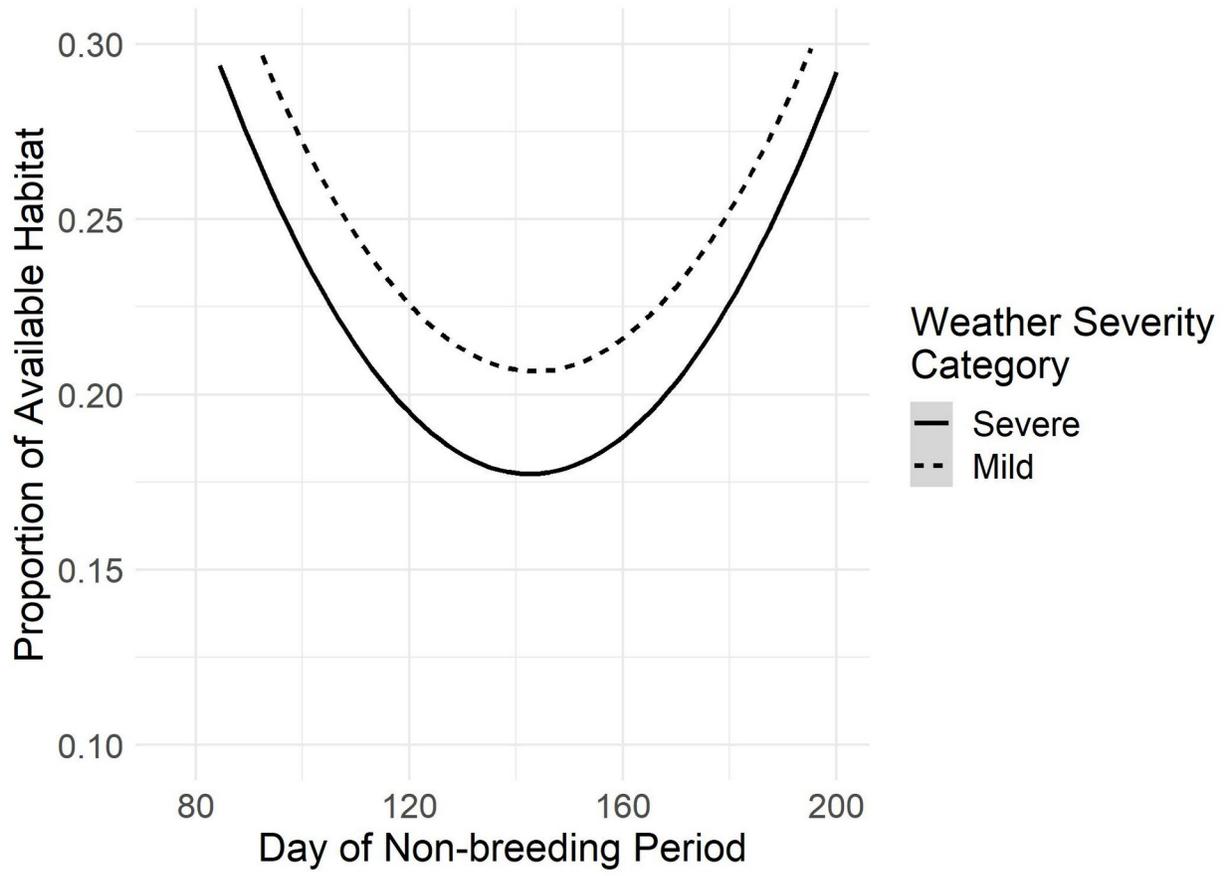
999

1000 **Figure 9.**



1001

1002 **Figure 10.**



1003

1004

1005 **Supporting Material**

1006 We provide several files of supporting material for visualization of our results and replication of  
1007 our methods.

1008 **File S1.** (game\_distrib.R) – R script used to apply the model and generate the results.

1009 **File S3.** (weather\_severity\_index.R) – R script used to acquire the data and perform the  
1010 calculations to generate the weather severity index for each day of the simulations.

1011 **File S4.** (DailyAbundance\_2013.gif) – A video showing the daily abundance per node across the  
1012 landscape, normalized on a zero-to-one scale. White to gray dots depict the population-weighted  
1013 center of mass on each day of migration to demonstrate an estimate of the population-level  
1014 “migration path”.

1015 **Appendix S1. Details of the cleaning, conversion, and projection of the weather data from**  
1016 **the National Oceanic and Atmospheric Administration’s National Centers for**  
1017 **Environmental Prediction.**

1018 We used the RNCEP package (R-connection to National Centers for Environmental  
1019 Prediction data; Kemp et al. 2012) to gather and manipulate the target climate data, which  
1020 included data for each day between 1957 and 2019. We gathered air temperature ( $^{\circ}\text{K}$  at 2 m  
1021 above surface level), water equivalent of snow depth ( $\frac{\text{kg}}{\text{m}^2}$  at surface level), and air pressure  
1022 (Pascals at low cloud bottom) data sampled on a T62 Gaussian grid. We restricted data to the  
1023 nonbreeding period, from 1 July of one calendar year to 31 May of the next (ignoring leap days).  
1024 We converted air temperature to  $^{\circ}\text{C}$  and water equivalent of snow depth to meters. To convert air  
1025 pressure to density ( $\frac{\text{kg}}{\text{m}^3}$ ), we divided the pressure by the product of the specific gas constant for  
1026 dry air ( $287.058 \frac{\text{J}}{\text{kg} * \text{km}}$ ) and air temperature.

1027 The water equivalent of snow depth (or, snow-water equivalent, SWE) measures the amount  
1028 of water that would be released by a volume of snow melting. It is calculable as the product of  
1029 snow depth and snow density. To acquire snow depth (in m) given SWE, we took the quotient of  
1030 SWE ( $\frac{\text{kg}}{\text{m}^2}$ ) and snow density ( $\frac{\text{kg}}{\text{m}^3}$ ). Snow density varies with temperature, and pressure (or depth,  
1031 with snow deeper in a column being more compacted and thus denser). Snow density ranges  
1032 from 10 to  $400 \frac{\text{kg}}{\text{m}^3}$  in our conditions (i.e., the temperatures observed across the focal landscape);

1033 we assume a constant snow density of  $400 \frac{kg}{m^3}$  across the landscape to convert SWE to snow  
1034 depth.

1035

1036 **References**

1037 Kemp, M. U., E. Emiel van Loon, J. Shamoun-Baranes, and W. Bouten. 2012. RNCEP: global  
1038 weather and climate data at your fingertips. *Methods in Ecology and Evolution* 3:65–70.

1039 **Appendix S2. Cross-walk of Canada (CSC2000v, Center for Topographic Information,**  
 1040 **Earth Sciences Sector and Natural Resources Canada 2009) and U.S. (National Land**  
 1041 **Cover Database 2006, Fry et al. 2011) land cover.**

CSC Value	CSC Class	NLCD Value	NLCD Class
0	No Data	No Data	
10	Unclassified	No Data	
11	Cloud	No Data	
12	Shadow	No Data	
20	Water	11	Open Water
30	Barren	31	Barren Land
31	Snow/Ice	12	Perennial Ice/Snow
32	Rock/Rubble	31	Barren Land
33	Exposed Land	31	Barren Land
34	Developed	23	Developed, Medium Intensity
35	Sparsely vegetated bedrock	31	Barren Land
36	Sparsely vegetated till-colluvium	31	Barren Land
37	Bare soil with cryptogam crust - frostboils	31	Barren Land
40	Bryoids	74	Moss
50	Shrubland	52	Shrub/Scrub
51	Shrub -Tall	52	Shrub/Scrub
52	Shrub - Low	51	Dwarf Scrub
53	Prostrate dwarf shrub	51	Dwarf Scrub

80	Wetland	95	Emergent Herbaceous Wetlands
81	Wetland Treed	90	Wood Wetlands
82	Wetland Shrub	90	Wood Wetlands
83	Wetland Herb	95	Emergent Herbaceous Wetlands
100	Herb	71	Grassland/Herbaceous
101	Tussock graminoid tundra	72	Sedge/Herbaceous
102	Wet sedge	72	Sedge/Herbaceous
103	Moist to dry non-tussock graminoid/dwarf shrub tussock	51	Dwarf Scrub
104	Dry graminoid prostrate dwarf shrub tundra	51	Dwarf Scrub
110	Grassland	71	Grassland/Herbaceous
120	Cultivated agricultural land	82	Cultivated Crops
121	Annual crops	82	Cultivated Crops
122	Perennial crops and Pasture	81	Pasture/Hay
210	Coniferous	42	Evergreen Forest
211	Coniferous - Dense	42	Evergreen Forest
212	Coniferous - Open	42	Evergreen Forest
213	Coniferous - Sparse	42	Evergreen Forest
220	Broad Leaf	41	Deciduous Forest
221	Broad Leaf - Dense	41	Deciduous Forest
222	Broad Leaf - Open	41	Deciduous Forest
223	Broad Leaf - Sparse	41	Deciduous Forest

230	Mixed Wood	43	Mixed Forest
231	Mixed Wood - Dense	43	Mixed Forest
232	Mixed Wood - Open	43	Mixed Forest
233	Mixed Wood - Sparse	43	Mixed Forest

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1044 **References**

1045 Center for Topographic Information, Earth Sciences Sector and Natural Resources Canada. 2009.

1046 Land cover, circa 2000-vector: Feature catalogue, edition 1.0. Geobase,

1047 <http://www.geobase.ca/geobase/en/data/landcover/csc2000v/description.html>.

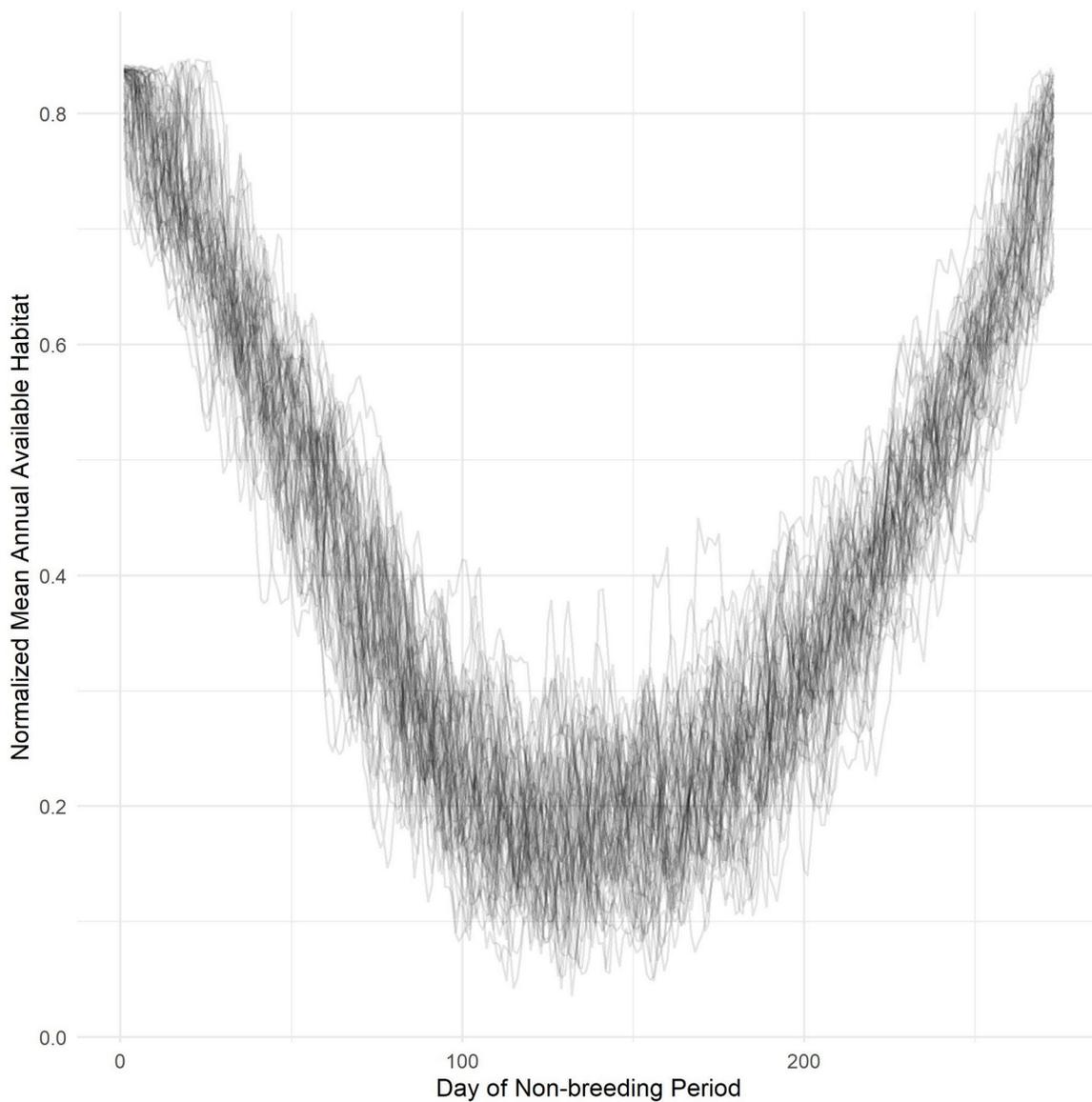
1048 Fry, J., G. Xian, S. Jin, J. Dewitz, C. Homer, L. Yang, C. Barnes, N. Herold, and J. Wickham.

1049 2011. Completion of the 2006 National Land Cover Database for the Conterminous United

1050 States. *Photogrammetric Engineering and Remote Sensing* 77:858–864.

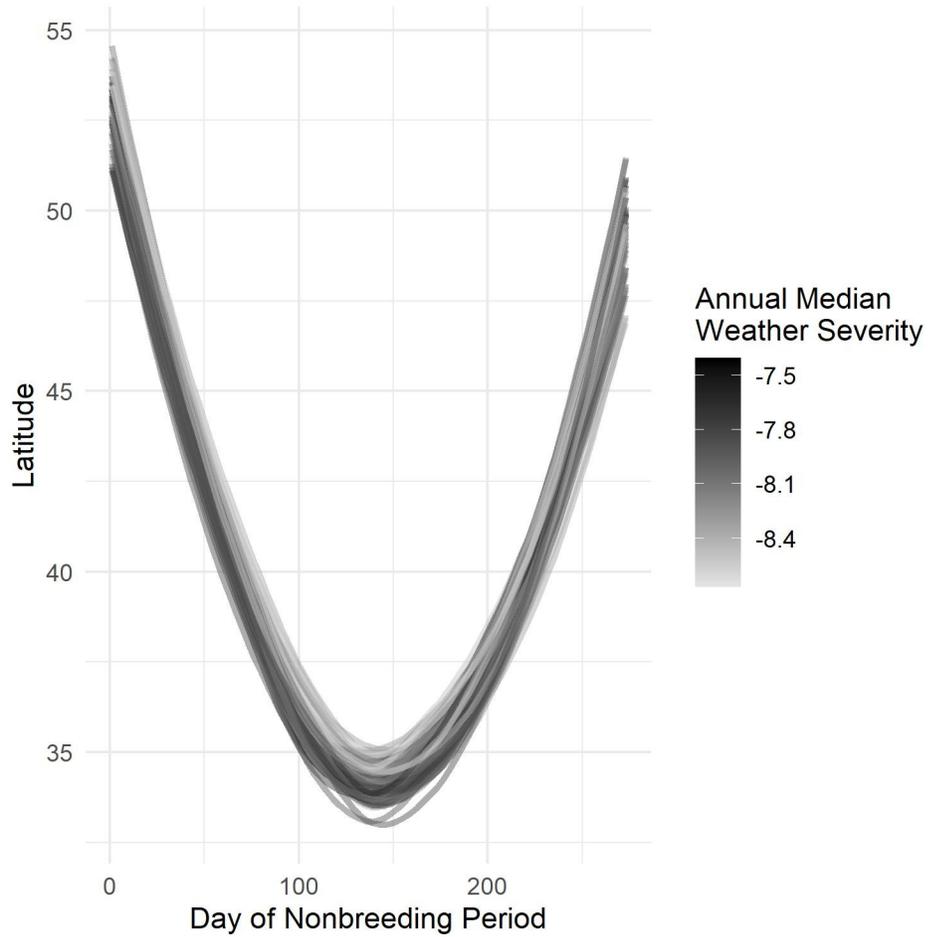
1051 **Appendix S3. Here we report several results and findings relevant to the change in weather**  
1052 **severity over time and the subsequent effects of this change on the nadir of the latitudinal**  
1053 **reach of the population each year.**

1054 **Figure S3.1.** The proportion of the landscape available for individuals to occupy on each day of  
1055 the nonbreeding period, according to the weather severity index (*WSI*) in that node. *WSI* values  
1056 above 7.5 trigger departure and inhibit arrival. This metric is normalized to a 0 to 1 scale for  
1057 comparison across all years in the record (1957 – 2019).



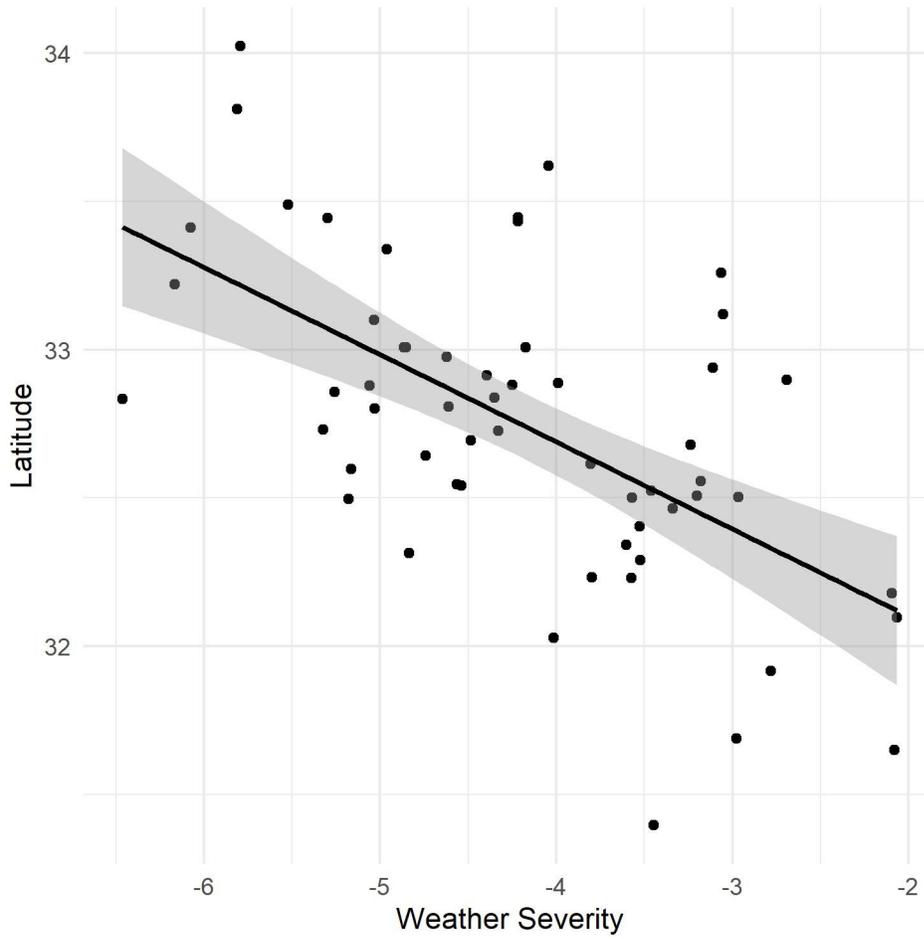
1058

1059 **Figure S3.2.** Change in the southernmost latitude achieved by the abundance-weighted center-  
1060 of-mass of the population over time, with corresponding annual median weather severity index.  
1061 Years of less severe weather (lighter curves) demonstrated less southerly minimum latitudes.



1062

1063 **Figure S3.3.** Change in the southernmost latitude achieved by the abundance-weighted center-  
1064 of-mass of the population with varying annual median weather severity index values.



1065  
1066