

Magnetoconvection in a Bidispersive Porous Media

G. Shiva Kumar Reddy, Ravi Ragoju

Department of Applied Sciences, National Institute of Technology Goa, Goa, India, 403401.

Abstract

Thermal instability of magnetoconvection in a horizontal bidispersive porous layer, uniformly heated from below, is analyzed. To study the linear stability theory, we perturbed the basic state with small-amplitude disturbances. Then, the governing dimensionless equations are solved using the normal modes. By employing the one-term Galerkin weighted residuals method, the critical values of Rayleigh numbers for the onset of stationary and oscillatory instability, have been determined. The effect of Chandrasekhar number on the system was analyzed.

Keywords: Bidispersive Porous Media, Thermal convection, Magnetic field, Linear stability analysis.

1. Introduction

Recently, many researchers are interested to study the convection bidispersive porous media (BDPM). A BDPM is an extension of a regular porous medium[1]. In general, a BDPM as a regular porous medium, where the solid phase is replaced by another porous medium. BDPM is composed of clusters of large particles that are agglomerations of small particles [1, 2]. In a BDPM, the voids between the clusters are known as macropores and the voids within the clusters are known as micropores. In other word, A BDPM is a porous medium in which fractures or tunnels have been introduced. In the present model, the f-phase and p-phase are represented by ‘fracture phase’ and ‘porous phase’ respectively.

Understanding convection in a BDPM is of considerable interest for geophysical applications [3, 4]. A general model for the convection in BDPM has received from

Nield & Kuznetsov [5] and Straughan [6]. In their analysis, they found that in a BDPM the critical values of Rayleigh number are much larger than that in the regular porous medium. Later, many research made an effort to investigate the convective instability in a BDPM. Very recently, Falsaperla, P., Mulone, G., and Straughan B [7] have investigated the linear and non linear stability analyses of Bidispersive-inclined convection. Gentile, M., and Straughan[8] have studied the problem of Bidispersive vertical convection. Straughan B. [9, 10] has investigated the double diffusive convection in a BDPM. Capone F, De Luca R, and Gentile M [11] have showed that the linear instability and nonlinear stability thresholds for a problem of thermal instability in a rotating BDPM. Later, Capone F and De Luca R [12] extended their work by considering inertia term and they showed that the effect of the Vadasz number can give rise to oscillatory motion at the loss of stability of thermal conduction solution.

In this paper, we reconsider the problem studied in [13], on taking into account the effect of an external magnetic field. The plan of the paper is as follows. Section 2 is devoted to the introduction of the mathematical problem. In Section 2, the governing dimensionless equations are solved using the normal modes to perform the linear stability analysis. The critical values of Rayleigh number at the onset of stationary and oscillatory convection, is determined by employing one-term Galerkin weighted residuals method. The paper ends with a Discussion and Conclusion section, which containing a table to show some examples in which stationary or oscillatory instability sets in and the figures showing the behavior of critical Rayleigh numbers and critical wave numbers for the steady and oscillatory instability versus Chandrasekhar number.

2. Mathematical formulation

Let us consider a horizontal BDPM of depth d . $T_L^0 C, T_U^0 C$ with $T_L > T_U > 0$ are the fixed temperatures at $z = 0$ and at $z = d$ respectively. V_i^f, V_i^p and T are the velocity of the fluid in the macro pores, the velocity of the fluid in the micro pores and the temperature. A constant magnetic field $H = (0, 0, H_0)$ is applied. The governing

equations are

$$\nabla \cdot \mathbf{V}^f = 0, \nabla \cdot \mathbf{V}^p = 0, \nabla \cdot H = 0, \quad (1)$$

$$-\frac{\mu}{\kappa_f} \mathbf{V}^f - \delta (\mathbf{V}^f - \mathbf{V}^p) - \nabla P^f + \rho_0 g \beta T \hat{e}_z + \frac{\mu_m}{\rho_0} (\nabla \times H) \times H = 0, \quad (2)$$

$$-\frac{\mu}{\kappa_p} \mathbf{V}^p - \delta (\mathbf{V}^p - \mathbf{V}^f) - \nabla P^p + \rho_0 g \beta T \hat{e}_z + \frac{\mu_m}{\rho_0} (\nabla \times H) \times H = 0, \quad (3)$$

$$\sigma \frac{\partial T}{\partial t} + (\mathbf{V}^f + \mathbf{V}^p) \cdot \nabla T = \alpha \nabla^2 T, \quad (4)$$

$$\frac{\partial H}{\partial t} + (\mathbf{V}^f + \mathbf{V}^p) \cdot \nabla H - H \cdot \nabla (\mathbf{V}^f + \mathbf{V}^p) = \eta \nabla^2 H. \quad (5)$$

Subject to the boundary conditions

$$\mathbf{V}^f \cdot \hat{e}_z = \mathbf{V}^p \cdot \hat{e}_z = 0, H = H_0 \text{ on } z = 0, d. \quad (6)$$

$$T(x, y, 0, t) = 1, T(x, y, d, t) = 0. \quad (7)$$

Here, $\hat{e}_z = (0, 0, 1)$, c_a , κ_f , κ_p , μ , δ , g , β , σ , α , μ_m are acceleration coefficient, permeability in the macro pores, permeability in the micro pores, dynamic viscosity, an interaction coefficient, gravity, coefficient of thermal expansion of the fluid, heat capacity ratio, thermal conductivity and magnetic permeability. In addition, ρ_0 is a reference density, ∇P^f , ∇P^p are the reduced pressures in the macro and micro pores, H_0 is the external magnetic field and k_m is the thermal conductivity. We introduce dimensionless quantities such that

$$\begin{aligned} x &= x^* d, & y &= y^* d, & z &= z^* d, \\ \mathbf{V}^f &= \frac{\alpha}{d} \mathbf{V}^{f*}, & \mathbf{V}^p &= \frac{\alpha}{d} \mathbf{V}^{p*}, & t &= \frac{\sigma d^2}{\alpha} t^*, \\ T &= \Delta T T^*, & H &= H_0 H^* \end{aligned}$$

The non-dimensional equations (after omitting the asterisks) governing the system are

$$\nabla \cdot \mathbf{V}^f = 0, \nabla \cdot \mathbf{V}^p = 0, \nabla \cdot H = 0, \quad (8)$$

$$-\mathbf{V}^f - \gamma(\mathbf{V}^f - \mathbf{V}^p) - \nabla P^f + RaT\hat{e}_z + QPm(\nabla \times H) \times H = 0, \quad (9)$$

$$-\kappa_r \mathbf{V}^p - \gamma(\mathbf{V}^p - \mathbf{V}^f) - \nabla P^p + RaT\hat{e}_z + QPm(\nabla \times H) \times H = 0, \quad (10)$$

$$\frac{\partial T}{\partial t} + (\mathbf{V}^f + \mathbf{V}^p) \cdot \nabla T = \nabla^2 T, \quad (11)$$

$$\frac{1}{\sigma} \frac{\partial H}{\partial t} + (\mathbf{V}^f + \mathbf{V}^p) \cdot \nabla H - H \cdot \nabla (\mathbf{V}^f + \mathbf{V}^p) = Pm \nabla^2 H, \quad (12)$$

$$\mathbf{V}^f \cdot \hat{e}_z = \mathbf{V}^p \cdot \hat{e}_z = 0, H = \hat{e}_z \text{ on } z = 0, 1, \quad (13)$$

$$T(x, y, 0, t) = 1, T(x, y, 1, t) = 0. \quad (14)$$

Where

$$Ra = \frac{\rho_0 \Delta T g \beta d \kappa_f}{\mu \alpha}, \quad \kappa_r = \frac{\kappa_f}{\kappa_p}, \quad \gamma = \frac{\delta \kappa_f}{\mu},$$

$$Q = \frac{\mu_m H_0^2 \kappa_f}{\rho_0 \mu \eta}, \quad Pm = \frac{\eta}{\alpha}.$$

Here Ra is the Rayleigh number, Q is the Chandrasekhar number, and Pm is the Magnetic Prandtl number.

2.1. Basic State

The basic stationary flow of Eqs. (8)-(12) is given by,

$$\mathbf{V}_b^f = 0, \mathbf{V}_b^p = 0, T_b = 1 - z, H_b = \hat{e}_z, \quad (15)$$

where the subscript b indicates for basic state. Let us introduce the perturbation of the basic state in the form of

$$\mathbf{V}^f = \mathbf{V}_b^f + \epsilon \mathbf{V}^{f'}, \mathbf{V}^p = \mathbf{V}_b^p + \epsilon \mathbf{V}^{p'}, P^f = P_b^f + P^{f'}, P^b = P_b^p + P^{p'},$$

$$T = T_b + \epsilon T', H = H_b + \epsilon H'. \quad (16)$$

where $\epsilon \ll 1$. By substituting Eq. (16) into Eqs. (8)-(14) and by neglecting terms $O(\epsilon^2)$ or higher, we obtain

$$\nabla \cdot \mathbf{V}^{f'} = 0, \nabla \cdot \mathbf{V}^{p'} = 0, \nabla \cdot H' = 0, \quad (17)$$

$$-\mathbf{V}^{f'} - \gamma \left(\mathbf{V}^{f'} - \mathbf{V}^{p'} \right) - \nabla P^{f'} + RaT' \hat{e}_z + QPm (\nabla \times H) \times \hat{e}_z = 0, \quad (18)$$

$$-\kappa_r \mathbf{V}^{p'} - \gamma \left(\mathbf{V}^{p'} - \mathbf{V}^{f'} \right) - \nabla P^{p'} + RaT' \hat{e}_z + QPm (\nabla \times H) \times \hat{e}_z = 0, \quad (19)$$

$$\frac{\partial T'}{\partial t} - \left(W^{f'} + W^{p'} \right) = \nabla^2 T', \quad (20)$$

$$\frac{1}{\sigma} \frac{\partial H'}{\partial t} = \frac{\partial}{\partial z} \left(\mathbf{V}^{f'} + \mathbf{V}^{p'} \right) + Pm \nabla^2 H'. \quad (21)$$

$$W^{f'} = W^{p'} = T' = \frac{\partial H'_z}{\partial z} = 0 \text{ on } z = 0, 1. \quad (22)$$

By taking the third component of double curl of Eqs. (18) and (19) and third component of Eq. (21), one obtains

$$\nabla \cdot \mathbf{V}^{f'} = 0, \nabla \cdot \mathbf{V}^{p'} = 0, \nabla \cdot H' = 0, \quad (23)$$

$$\nabla^2 W^{f'} + \gamma \left(\nabla^2 W^{f'} - \nabla^2 W^{p'} \right) - Ra \nabla_h^2 T' - QPm \frac{\partial}{\partial z} \nabla^2 H'_z = 0, \quad (24)$$

$$\kappa_r \nabla^2 W^{p'} + \gamma \left(\nabla^2 W^{p'} - \nabla^2 W^{f'} \right) - Ra \nabla_h^2 T' - QPm \frac{\partial}{\partial z} \nabla^2 H'_z = 0, \quad (25)$$

$$\frac{\partial T'}{\partial t} - \left(W^{f'} + W^{p'} \right) = \nabla^2 T', \quad (26)$$

$$\frac{1}{\sigma} \frac{\partial H'_z}{\partial t} = \frac{\partial}{\partial z} \left(W^{f'} + W^{p'} \right) + Pm \nabla^2 H'_z, \quad (27)$$

$$W^{f'} = W^{p'} = T' = \frac{\partial H'_z}{\partial z} = 0 \text{ on } z = 0, 1, \quad (28)$$

where $\nabla_h^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$ and $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$.

3. Linear Stability Analysis

Let us introduce the normal modes by writing the perturbations in the form of

$$\left(W^{f'}, W^{p'}, T', H'_z \right) = \left(w^f(z), w^p(z), \theta(z), h(z) \right) e^{i(lx + my - \omega t)}. \quad (29)$$

Substituting the above normal mode solution into the Eqs. (23)-(28),

$$(1 + \gamma) (D^2 - q^2) w^f - \gamma (D^2 - q^2) w^p + Raq^2\theta - QPmD (D^2 - q^2) h = 0, \quad (30)$$

$$(\kappa_r + \gamma) (D^2 - q^2) w^p - \gamma (D^2 - q^2) w^f + Raq^2\theta - QPmD (D^2 - q^2) h = 0, \quad (31)$$

$$(D^2 - q^2 + i\omega) \theta + (w^f + w^p) = 0, \quad (32)$$

$$Pm (D^2 - q^2) h + \frac{1}{\sigma} i\omega h + D (w^f + w^p) = 0, \quad (33)$$

$$w^f = w^p = \theta = Dh = 0 \text{ on } z = 0, 1, \quad (34)$$

where $D = \frac{d}{dz}$ and $q^2 = l^2 + m^2$. We assume the solution to w^f, w^p, θ and h in the form

$$\begin{pmatrix} w^f(z) \\ w^p(z) \\ \theta(z) \\ h(z) \end{pmatrix} = \begin{pmatrix} w_0^f \sin n\pi z \\ w_0^p \sin n\pi z \\ \theta_0 \sin n\pi z \\ h_0 \cos n\pi z \end{pmatrix}, \quad (35)$$

which satisfy the boundary conditions (34). On substituting Eq. (35) with $n = 1$ into Eqs. (30)-(33), one obtains

$$\begin{pmatrix} -\delta^2 (1 + \gamma) & \gamma\delta^2 & Raq^2 & -QPm\pi\delta^2 \\ \gamma\delta^2 & -\delta^2 (\kappa_r + \gamma) & Raq^2 & -QPm\pi\delta^2 \\ 1 & 1 & (-\delta^2 + i\omega) & 0 \\ \pi & \pi & 0 & (-Pm\delta^2 + \frac{i\omega}{\sigma}) \end{pmatrix} \begin{pmatrix} w_0^f \\ w_0^p \\ \theta_0 \\ h_0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad (36)$$

where $\delta^2 = \pi^2 + q^2$. For the nontrivial solution of the above matrix Eq. (36) the determinant of above matrix is zero, from which one can get the expression of the Rayleigh numbers Ra_{sc} and Ra_{oc} respectively for the stationary and also oscillatory

modes of convection in the form:

$$Ra_{sc} = \frac{\delta_{sc}^4 (\gamma + \kappa_r + \gamma\kappa_r)}{q_{sc}^2 (1 + \kappa_r + 4\gamma)} + \frac{Q\pi^2\delta^2}{q_{sc}^2}, \quad Ra_{oc} = \frac{I_1 + \omega^2 I_2}{q_{oc}^2 \chi_2 (\omega^2 + Pm^2 \delta_{oc}^4 \sigma^2)}, \quad (37)$$

where $I_1 = Pm^2 \delta_{oc}^6 (\chi_2 \pi^2 Q + \chi_1 \delta_{oc}^2) \sigma^2$, $I_2 = \delta_{oc}^2 (\chi_1 \delta_{oc}^2 + \chi_2 \pi^2 Pm Q \sigma)$, $\omega^2 = Pm \delta^2 \sigma (Pm \delta^2 \sigma + \frac{\chi_2}{\chi_1} \pi^2 Q (-1 + Pm \sigma))$, $\chi_1 = \kappa_r + \gamma + \gamma\kappa_r$ and $\chi_2 = 1 + \kappa_r + 4\gamma$.

and the subscripts *sc* and *oc* denote stationary and oscillatory convections.

In the absence of magnetic field, above stationary Rayleigh number reduces to

$$Ra_{sc} = \frac{\delta^4 (\gamma + \kappa_r + \gamma\kappa_r)}{q^2 (1 + \kappa_r + 4\gamma)}, \quad (38)$$

which is well agree with Eq. (31) in Gentile and Straughan [13].

4. Discussion and Conclusions

The numerical results and conclusions are presented in this section. Many theoretical and experimental studies have made an effort to model the convective instability problem that arises in the study of geophysical fluid dynamics. In the present analysis, a mathematical model of magnetoconvection in a bidispersive porous layer has been modeled to investigate the linear stability analysis. To the best of author's knowledge, this is the first study in the hydrodynamic stability. Darcy's law and the Oberbeck-Boussinesq approximation are adopted for modeling the buoyant flow. The one-term Galerkin weighted residuals method, has been employed to determine the critical Rayleigh numbers for the onset of stationary and oscillatory instability.

In the present analysis, we fix $\sigma = 1$ and $\gamma = 1$. In Table 1, some values of the physical parameters have been fixed, in order to show some examples in which stationary or oscillatory instability sets in. For example, when $Q = 5$, the onset of convection is more likely to be via oscillatory convection when $Pm < 0.82$, whereas the stationary convection dominates when $Pm \geq 0.82$. Furthermore, one can observe from this Table that Pm does not show any effect on Ra_{sc}^c , since Ra_{sc} is independent of Pm .

Q	Pm	Stationary		Oscillatory		Instability
		q_{sc}^c	Ra_{sc}^c	q_{oc}^c	Ra_{oc}^c	
5	0.4	6.82311	75.9007	4.58621	27.3207	Oscillatory
5	0.6	6.82311	75.9007	5.12303	43.5326	Oscillatory
5	0.81	6.82311	75.9007	5.65649	75.6315	Oscillatory
5	0.82	6.82311	75.9007	5.66515	76.4059	Stationary
5	1.2	6.82311	75.9007	5.91785	105.693	Stationary
5	1.4	6.82311	75.9007	6.01025	121.032	Stationary
10	0.4	8.06812	133.973	5.98167	69.5537	Oscillatory
10	0.6	8.06812	133.973	6.37327	97.2322	Oscillatory
10	0.81	8.06812	133.973	6.69704	132.775	Oscillatory
10	0.82	8.06812	133.973	6.70692	134.136	Stationary
10	1.2	8.06812	133.973	6.96666	178.9	Stationary
10	1.4	8.06812	133.973	7.07978	205.931	Stationary

Table 1: Onset of stationary and oscillatory instability for the fixed values of $\kappa_r = 0.1$.

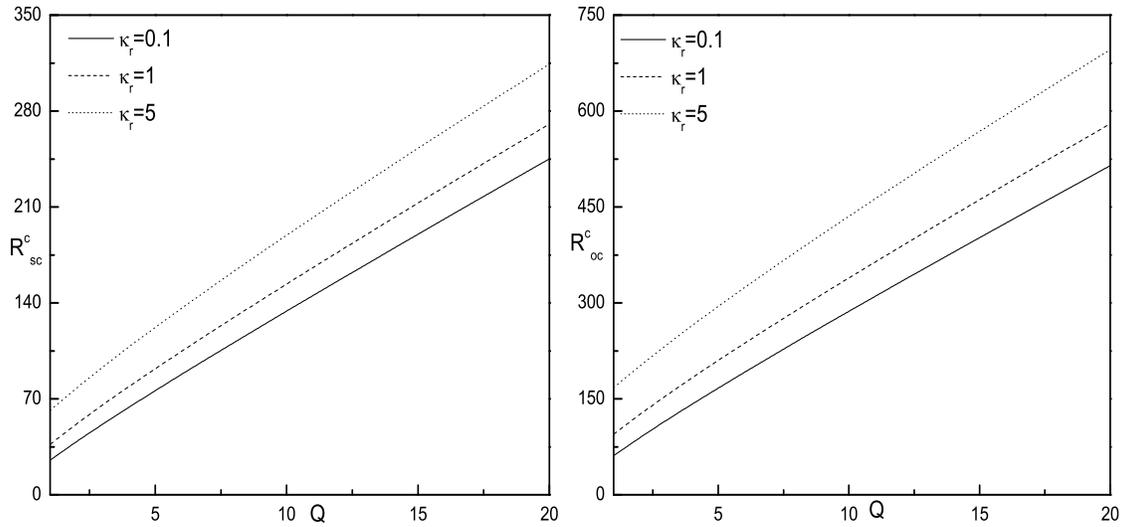


Figure 1: Variation of critical Rayleigh number with Q at the onset of (a) stationary convection and (b) oscillatory convection.

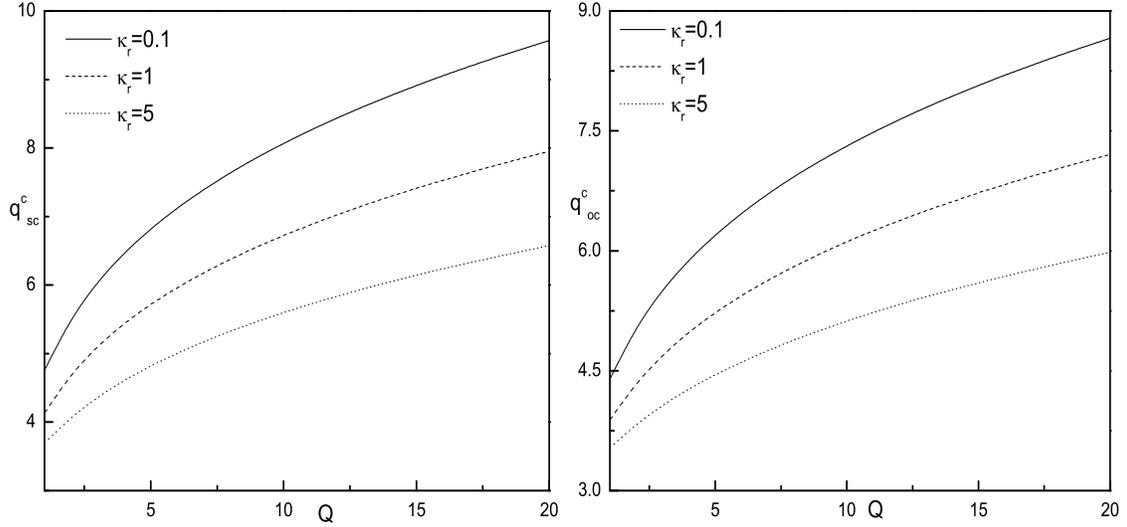


Figure 2: Variation of critical wave number with Q at the onset of (a) stationary convection and (b) oscillatory convection.

The effect of the Chandrasekhar number, Q , for the onset of steady and oscillatory convection, has been examined. In Fig. 1, the effect of the Chandrasekhar number, Q , on the onset of instability, is shown. The curves displayed are included in the range $1 \leq Q \leq 20$. Fig. 1 depicts an increasing trend of critical Rayleigh number at the onset of steady and oscillatory instability versus Q , and also a increasing function of κ_r . In other words, an increase in the value of Q makes the system stable.

Fig. 2 gives a variation of critical wave number (corresponding to critical Rayleigh number from Fig. 1) at the onset of steady and oscillatory convection versus Q for different values of κ_r . Fig. 2 depicts an increasing trend of critical wave number versus Q , and a decreasing function of κ_r .

The principal results found from the linear stability analysis can be summarized as follows:

- The eigenvalue problem for linear stability analysis is solved analytically by using normal mode technique.
- The critical Rayleigh number corresponding wave number are analyzed for the different values of other physical parameters at the onset of stationary and oscillatory convection.

latory convection.

- The Chandrasekhar number has a stabilizing effect on the stationary and oscillatory convection.
- κ_r has a stabilizing effect on the stationary and oscillatory convection.
- The critical wave number is an increasing function of Q and a decreasing function of κ_r at the onset of stationary and oscillatory convection.

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