

REGULARITY OF THE ATTRACTOR FOR A COUPLED NONLINEAR KLEIN-GORDON-SCHRÖDINGER SYSETEM IN \mathbb{R}^3

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ABSTRACT. The main goal of this paper is to study the asymptotic behavior of a coupled Klein-Gordon-Schrödinger system in three dimensional unbounded domain. We prove the existence of a global attractor of the systems of the nonlinear Klein-Gordon-Schrödinger (KGS) equations in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$ and more particularly that this attractor is in fact a compact set of $H^2(\mathbb{R}^3) \times H^2(\mathbb{R}^3) \times H^1(\mathbb{R}^3)$.

1. INTRODUCTION. The dissipative Klein-Gordon-Schrödinger (KGS) system take the following form:

$$iu_t + \Delta u + i\nu u + \nu u = f, \quad (1)$$

$$v_{tt} + \gamma v_t - \Delta v + v - |u|^2 = g, \quad (2)$$

where u (respectively, v) is a complex (respectively, real) valued function, ν and γ are positive parameters, f and g are driving terms. This system describes the interaction of a nucleon field u and a meson field v through the Yukawa coupling. The terms νu and γv_t model the dissipative effect. The global well-posedness of system (1)-(2) was studied by several authors. For instance, one can see the works of Fukuda and Tsutsumi [8, 9], Bachelot [3], Hayashi and von Wahl [13]. The long time behavior was studied by Biler [4], Lu and Wang [14], Guo and Li [11] where the authors proved the existence of a global attractor in different phase spaces. These results were improved by Abounouh and *al.* [2], where the authors have established the so called asymptotic smoothing effect of dynamical system of (1)-(2) on $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$. That is, they obtained that the global attractor in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$; is in fact a compact set embedded into $H^2(\mathbb{R}^3) \times H^2(\mathbb{R}^3) \times H^1(\mathbb{R}^3)$. The same kind of results was firstly established by Goubet in [12] for Nonlinear Schrödinger equations .

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In this paper, we are going to study the long-time behavior of solutions for the nonlinear generalized dissipative Klein-Gordon-Schrödinger systems (NLKGS) in the whole space \mathbb{R}^3 . This model reads,

$$iu_t + \Delta u + i\nu u + i|u|^2 u + vu = f, \quad (3)$$

$$v_{tt} + \gamma v_t - \Delta v + v + v^2 - |u|^2 = g. \quad (4)$$

We supplement (3)-(4) with initial data

$$(u(0), v(0), v_t(0)) = (u_0, v_0, v_1) \in H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3), \quad (5)$$

and we suppose that the driving terms $f, g \in L_x^2(\mathbb{R}^3)$ are time independent. The global well-posedness in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$ of (3)-(5) can be obtained in a standard way as in [3]. It's worth to signal that M.M. Cavalcanti and V.N. Domingos Cavalcanti [7] studied the existence, uniqueness and the uniform decay for the solutions of the homogenous system associate to (3)-(5).

The existence of global attractor \mathcal{A} for (3)-(5) (in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$) can be obtained by proceeding like in [14] for (1)-(2).

In this article, we aim to prove that this global attractor is in fact included and compact in $H^2(\mathbb{R}^3) \times H^2(\mathbb{R}^3) \times H^1(\mathbb{R}^3)$.

The issue of the regularity of the attractor is classical in the study of infinite-dimensional dissipative systems. We refer to [21] for the general framework and for numerous applications.

Our main task here is to establish that this attractor \mathcal{A} is regular. Namely, we prove the following

Theorem 1.1. *The semigroup $(S(t))_t$ associated to the system (3)-(5), has a global attractor \mathcal{A} in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$. Moreover, \mathcal{A} is a compact set of $H^2(\mathbb{R}^3) \times H^2(\mathbb{R}^3) \times H^1(\mathbb{R}^3)$.*

Throught this article, we refer to H^1 or H_x^1 for the usual Sobolev spaces $H^1(\mathbb{R}^3)$, for $x \in \mathbb{R}^3$. L^p or L_x^p stand also for the space of measurable functions u such that u^p is integrable over \mathbb{R}_x^3 ($p < +\infty$) and L^∞ or L_x^∞ is the usual space of (essentially) bounded functions, we set

$$E_1 = H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3), \quad E_2 = H^2(\mathbb{R}^3) \times H^2(\mathbb{R}^3) \times H^1(\mathbb{R}^3),$$

and we denote by $(u, v) = \operatorname{Re} \int_{\mathbb{R}^3} u(x) \overline{v(x)} dx$, the usual inner product on $L^2(\mathbb{R}^3)$.

We recall the following Gagliardo-Nirenberg inequalities which will be used frequently later:

$$\|D^j u\|_p \leq C \|u\|_q^{1-a} \|D^m u\|_r^a, \quad u \in L^p(\mathbb{R}^n) \cap H^{m,r}(\mathbb{R}^n),$$

where

$$\frac{1}{p} = \frac{j}{n} + a \left(\frac{1}{r} - \frac{m}{n} \right) + \frac{1-a}{q},$$

$$1 \leq q, r \leq \infty, j \text{ is an integer}, 0 \leq j \leq m, \frac{j}{m} \leq a \leq 1.$$

If $m - j - \frac{n}{r}$ is a nonnegative integer, then the inequality holds for $\frac{j}{m} \leq a < 1$.

Hereafter, we denote by C and K any positive constants which may change from one line to another.

This article is organized as follows: in Section 2, we derive a priori estimates on the solutions of system (3)-(4) which will be useful for constructing a bounded absorbing set and to justify the existence of the global attractor. Section 3 is devoted to proof

the main theorem, following the idea of [2] we show the regularity of the attractor where we will prove the result thus reported in a few steps.

2. Existence of a global attractor.

2.1. A priori estimates. The aim of this section is to derive a priori estimates of solutions for (3)-(5), that are essential to establish a bounded absorbing set in E_1 . We set $w = v_t + \delta v$ and change (3)-(5) equivalently to the following

$$iu_t + i\nu u + \Delta u + i|u|^2 u + vu = f \quad (6)$$

$$v_t + \delta v = w, \quad (7)$$

$$w_t + (\gamma - \delta)w - \Delta v + (1 - \delta(\gamma - \delta))v + v^2 - |u|^2 = g, \quad (8)$$

$$u(0, x) = u_0(x), \quad v(0, x) = v_0(x), \quad w(0, x) = w_0(x), \quad x \in \mathbb{R}^3, \quad (9)$$

where δ is a small positive constant which will be specified later. We are now in a position to derive the estimates for regular solutions of problem (6)-(9). We start with the first estimate on u in $L^2(\mathbb{R}^3)$.

Proposition 1. *Let $R > 0$. There exists $C_0 = C_0(\nu, \|f\|_2)$ and $t_0 = t_0(\nu, R, \|f\|_2)$ such that*

$$\|u(t)\|_2 \leq C_0, \quad \forall t \geq t_0, \quad (10)$$

whenever $\|u_0\|_2 \leq R$.

Proof. Multiplying (6) by \bar{u} , integrating over \mathbb{R}^3 and then taking imaginary parts, we obtain

$$\frac{1}{2} \frac{d}{dt} \|u\|_2^2 + \nu \|u\|_2^2 + \|u\|_4^4 = \text{Im} \int f \bar{u}. \quad (11)$$

Obviously, in the right-hand side of (11) we use the Cauchy-Schwarz and the Young inequalities to get

$$\frac{d}{dt} \|u\|_2^2 + \nu \|u\|_2^2 \leq \frac{1}{\nu} \|f\|_2^2. \quad (12)$$

Applying Gronwall lemma in (12), we obtain

$$\|u(t)\|_2^2 \leq \|u(0)\|_2^2 e^{-\nu t} + \frac{1}{\nu^2} \|f\|_2^2 (1 - e^{-\nu t}) \leq e^{-\nu t} R^2 + \frac{1}{\nu^2} \|f\|_2^2.$$

It's easy to see that for $t \geq t_0 = \frac{1}{\nu} \log(\frac{\nu^2 R^2}{\|f\|_2^2})$, we get

$$\|u(t)\|_2^2 \leq \frac{2}{\nu^2} \|f\|_2^2. \quad (13)$$

which concludes the proof of the Proposition 1. \square

In the following we give the second estimate on solutions (u, v, w) of (6)-(9) in E_1 .

Proposition 2. *Let $R > 0$. There exists $M = M(\nu, \gamma, \delta, f, g)$, $t_1 = t_1(R) \geq t_0$ and $\delta_1 > 0$ such that for all $0 < \delta \leq \delta_1$*

$$\|u(t)\|_{H^1} + \|v(t)\|_{H^1} + \|w(t)\|_2 \leq M, \quad \forall t \geq t_1, \quad (14)$$

whenever $\|(u_0, v_0, w_0)\|_{E_1} \leq R$.

Proof. Multiplying (6) by $\Delta \bar{u}$, integrating over \mathbb{R}^3 , using the Green formula and then taking imaginary parts, we obtain

$$\frac{1}{2} \frac{d}{dt} \|\nabla u(t)\|_2^2 + \nu \|\nabla u(t)\|_2^2 - \operatorname{Re} \int |u|^2 u \Delta \bar{u} dx - \operatorname{Im} \int v u \Delta \bar{u} dx = -\operatorname{Im} \int f \Delta \bar{u} dx, \quad (15)$$

Using,

$$-\operatorname{Re} \int |u|^2 u \Delta \bar{u} dx = 2 \int |\nabla u|^2 |u|^2 dx + \operatorname{Re} \int (\nabla u)^2 (\bar{u})^2 dx, \quad (16)$$

so we get

$$-\operatorname{Re} \int |u|^2 u \Delta \bar{u} dx = \int |\nabla u|^2 |u|^2 dx + 2 \int [\operatorname{Re}(\nabla u \bar{u})]^2 dx, \quad (17)$$

since $2[\operatorname{Re}(z_1 \bar{z}_2)]^2 = |z_1|^2 |z_2|^2 + \operatorname{Re}[(z_1 \bar{z}_2)^2]$.

By (6) a gain, we have on one hand,

$$\begin{aligned} -\operatorname{Im} \int f \Delta \bar{u} dx &= \operatorname{Im} \int \Delta u \bar{f} dx \\ &= -\operatorname{Re} \int u_t \bar{f} dx - \nu \operatorname{Re} \int u \bar{f} dx - \operatorname{Re} \int |u|^2 u \bar{f} dx \\ &\quad -\operatorname{Im} \int v u \bar{f} dx, \end{aligned} \quad (18)$$

and on the other hand,

$$\frac{1}{4} \frac{d}{dt} \|u(t)\|_4^4 + \nu \|u(t)\|_4^4 + \|u(t)\|_6^6 + \operatorname{Im} \int \Delta u |u|^2 \bar{u} dx = \operatorname{Im} \int f |u|^2 \bar{u} dx. \quad (19)$$

After substituting (17) and (18) in (15), and adding the resulting equation to (19) we obtain

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \{ \|\nabla u(t)\|_2^2 + 2 \operatorname{Re} \int f \bar{u} dx + \frac{1}{2} \|u(t)\|_4^4 \} \\ &+ \nu \{ \|\nabla u(t)\|_2^2 + \operatorname{Re} \int f \bar{u} dx + \|u(t)\|_4^4 \} \\ &+ \|u(t)\|_6^6 + \int |\nabla u|^2 |u|^2 dx + 2 \int [\operatorname{Re}(\nabla u \bar{u})]^2 dx \\ &= \operatorname{Im} \int f v \bar{u} dx + \operatorname{Im} \int \nabla v \cdot \nabla u \bar{u} dx + \operatorname{Im} \int (\nabla u \bar{u})^2 dx \\ &+ \operatorname{Im} \int f |u|^2 \bar{u} dx - \operatorname{Re} \int f |u|^2 \bar{u} dx. \end{aligned} \quad (20)$$

Taking the inner product of (8) with w in $L^2(\mathbb{R}^3)$, we have

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \{ \|w(t)\|_2^2 + (\gamma - \delta) \|w(t)\|_2^2 - \int_{\mathbb{R}^3} w \Delta v + (1 - \delta(\gamma - \delta)) \int_{\mathbb{R}^3} v w + \int_{\mathbb{R}^3} v^2 w \} \\ &= \int_{\mathbb{R}^3} |u|^2 w + \int_{\mathbb{R}^3} g w. \end{aligned} \quad (21)$$

Using (9), we get from (21) that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \{ \|w(t)\|_2^2 + (1 - \delta(\gamma - \delta)) \|v(t)\|_2^2 + \|\nabla v(t)\|_2^2 + \frac{2}{3} \|v(t)\|_3^3 \} + (\gamma - \delta) \|w(t)\|_2^2 \\ & + \delta(1 - \delta(\gamma - \delta)) \|v(t)\|_2^2 + \delta \|\nabla v(t)\|_2^2 + \delta \|v(t)\|_3^3 = \int_{\mathbb{R}^3} |u|^2 w + \int_{\mathbb{R}^3} g w. \end{aligned} \quad (22)$$

Adding (20) to (22), we obtain after making some arrangements

$$\frac{d}{dt} E(t) + \delta E(t) = F(t), \quad (23)$$

where

$$\begin{aligned} E(t) = & \|w(t)\|_2^2 + (1 - \delta(\gamma - \delta)) \|v(t)\|_2^2 + \|\nabla v(t)\|_2^2 + \delta \|\nabla u(t)\|_2^2 \\ & + 2\delta \operatorname{Re} \int_{\mathbb{R}^3} f \bar{u} dx + \frac{\delta}{4} \|u(t)\|_4^4, \end{aligned} \quad (24)$$

and

$$\begin{aligned} F(t) = & 2 \int_{\mathbb{R}^3} g w + 2 \int_{\mathbb{R}^3} w |u|^2 + 2\delta \operatorname{Im} \int_{\mathbb{R}^3} f v \bar{u} dx + 2\delta \operatorname{Im} \int_{\mathbb{R}^3} \nabla v \cdot \nabla u \bar{u} dx \\ & + \delta \operatorname{Im} \int_{\mathbb{R}^3} f |u|^2 \bar{u} dx - 2\delta \operatorname{Re} \int_{\mathbb{R}^3} f |u|^2 \bar{u} dx + \delta \operatorname{Im} \int_{\mathbb{R}^3} (\nabla u \bar{u})^2 dx \\ & - [\delta(2\nu - \delta) \|\nabla u\|_2^2 + 2\delta(\nu - \delta) \operatorname{Re} \int_{\mathbb{R}^3} f \bar{u} dx + (2\gamma - 3\delta) \|w\|_2^2 \\ & + \delta(\nu - \frac{\delta}{4}) \|u\|_4^4 + \delta \|u\|_6^6 + 2\delta \int_{\mathbb{R}^3} |\nabla u|^2 |u|^2 dx + 4\delta \int_{\mathbb{R}^3} [\operatorname{Re}(\nabla u \bar{u})]^2 dx \\ & + \delta(1 - \delta(\gamma - \delta)) \|v(t)\|_2^2 + \delta \|\nabla v(t)\|_2^2 + \frac{4\delta}{3} \|v(t)\|_3^3]. \end{aligned} \quad (25)$$

In order to establish an upper bound for $E(t)$ we estimate the last terms of $F(t)$. Using Cauchy-Schwarz and Young inequalities, we have

$$\begin{aligned} \left| \int_{\mathbb{R}^3} g w \right| & \leq \|g\|_2 \|w\|_2 \\ & \leq K_\epsilon + \frac{\epsilon}{2} \|w\|_2^2, \end{aligned} \quad (26)$$

where $\epsilon > 0$ to be chosen later. By Hölder inequality, the Proposition 1, the Gagliardo-Nirenberg and Young inequalities, we get,

$$\begin{aligned} \left| \int_{\mathbb{R}^3} w |u|^2 \right| & \leq \|w\|_2 \|u\|_3 \|u\|_6 \\ & \leq C \|w\|_2 \|\nabla u\|_2^{\frac{1}{2}} \|\nabla u\|_2^{\frac{1}{2}} \|u\|_6 \\ & \leq K_\epsilon + \frac{\epsilon}{2} \|w\|_2^2 + \epsilon \|\nabla u\|_2^2 + \frac{\epsilon}{6} \|u\|_6^6. \end{aligned} \quad (27)$$

Using again Cauchy-Schwarz and Young inequalities, we obtain

$$\begin{aligned} |\operatorname{Im} \int_{\mathbb{R}^3} \nabla v \nabla u \bar{u} dx| &\leq \int |\nabla v| |\nabla u| |u| dx \\ &\leq \frac{1}{2} \|\nabla v\|_2^2 + \frac{1}{2} \int |\nabla u|^2 |u|^2 dx, \end{aligned} \quad (28)$$

and

$$\begin{aligned} |\delta \operatorname{Im} \int_{\mathbb{R}^3} f |u|^2 \bar{u} dx - 2\delta \operatorname{Re} \int_{\mathbb{R}^3} f |u|^2 \bar{u} dx| &\leq 3 \|f\|_2 \|u\|_6^3 \\ &\leq K_\epsilon + \frac{\epsilon}{3} \|u\|_6^6. \end{aligned} \quad (29)$$

Moreover, for the same reasons, we get

$$\begin{aligned} |\delta \operatorname{Im} \int_{\mathbb{R}^3} f v \bar{u} dx| &\leq C \|f\|_2 \|v\|_3 \|u\|_6 \\ &\leq K_\epsilon + \frac{\epsilon}{2} \|v\|_3^3 + \frac{\epsilon}{6} \|u\|_6^6, \end{aligned} \quad (30)$$

where the constant $K_\epsilon = K(f, g, \gamma, \nu, \delta, \epsilon)$. Let δ small enough such that

$$\delta < \min(\gamma, 2\nu), \quad \gamma - \frac{3}{2}\delta > 0, \quad 1 - \delta(\gamma - \delta) > 0, \quad (31)$$

and then consider $\epsilon > 0$ also small enough such that

$$\epsilon < \min(\gamma - \frac{3}{2}\delta, \frac{\delta}{2}(2\nu - \delta), \delta). \quad (32)$$

Finally, using again Cauchy-Schwarz inequality and Proposition 1 we obtain

$$\begin{aligned} |\delta(\nu - \delta) \operatorname{Re} \int_{\mathbb{R}^3} f \bar{u} dx| &\leq C \|f\|_2 \|u\|_2 \\ &\leq K, \end{aligned} \quad (33)$$

where $K = K(f, \nu, \delta)$.

Moreover, for the same reasons and thanks to (33), we get $\forall t \geq t_0$,

$$E(t) \leq C \|(u(t), v(t), w(t))\|_{E_1} + K. \quad (34)$$

With the choices (31)-(32) and using (26)-(30) and (33) in (25), we obtain $\forall t \geq t_0$, $F(t) \leq K_\epsilon$ and hence (23) becomes

$$\frac{d}{dt} E(t) + \delta E(t) \leq K_\epsilon,$$

which yields by Gronwall Lemma, for all $t \geq t_0$,

$$E(t) \leq e^{-\delta(t-t_0)} E(t_0) + \frac{K_\epsilon}{\delta} (1 - e^{-\delta(t-t_0)}). \quad (35)$$

Thus, from (34) and (35), we deduce that there exist $t_1 \geq t_0$ and $M = M(\nu, \gamma, \delta, f, g) > 0$ such that $\forall t \geq t_1$

$$E(t) \leq M, \quad (36)$$

whenever $\|(u(t_0), v(t_0), w(t_0))\|_{E_1} \leq R$.

For a lower bound to $E(t)$; we use

$$2\delta \operatorname{Re} \int_{\mathbb{R}^3} f \bar{u} dx \geq -K, \quad (37)$$

and hence we get

$$E(t) \geq C[\|\nabla u(t)\|_2^2 + (1 - \delta(\gamma - \delta))\|v(t)\|_2^2 + \|\nabla v(t)\|_2^2 + \|w(t)\|_2^2] - K. \quad (38)$$

Gathering (36) and (38) together, we easily get (14). \square

2.2. Global attractor. For the global well-posedness of (3)-(5), one can obtain the existence and uniqueness of solutions in $H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$ from standard method using the Propositions 1 and 2. The continuity property of solutions with respect to initial data is rather long to establish and can be obtained in a similar way as in the work of Lu and Wang [14], so we omit it here. Hence, we can define a dynamical system $S(t)$ on $H^1 \times H^1 \times L^2$. Again, thanks to Proposition 2, there exists a bounded absorbing set $\mathcal{B} \subset H^1(\mathbb{R}^3) \times H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$ for $(S(t))_t$, that is, for all $R > 0$, there exists $t_1 > 0$ such that if $\|(u(0), v(0), w(0))\|_{E_1} \leq R$ then for all $t \geq t_1$, $(u(t), v(t), w(t)) \in \mathcal{B}$. By proceeding as in [14], the asymptotic compactness of $S(t)$ can be achieved essentially by energy equation method and hence the existence of the global attractor

$$\mathcal{A} = \omega(\mathcal{B}) = \bigcap_{t \in \mathbb{R}} \overline{\bigcup_{s \geq t} S(s)\mathcal{B}}^{E_1}$$

follows accordingly to an abstract theorem [21, Theorem 1.4].

3. Proof of the main theorem.

3.1. Asymptotic smoothing effect for dissipative wave equation. Introduce $\Lambda = Id - \Delta$ in L^2 whose domain is $H^2(\mathbb{R}^3)$. Let a be a nonnegative real number. Define $X_{2a} = C_b(\mathbb{R}, D(\Lambda^a))$ as the set of continuous and bounded function into the domain of Λ^a . Let us set $H^{2a} = D(\Lambda^a)$.

We consider the following problem

$$\phi_{tt} + \gamma \phi_t - \Delta \phi + \phi = f, \quad (39)$$

$$(\phi(0, x), \phi_t(0, x)) = (\phi_0(x), \phi_1(x)). \quad (40)$$

Then we recall from [10]

Proposition 3. *Let $T > 0$. If $(\phi_0, \phi_1) \in H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$, then $\exists! (\phi, \phi_t) \in C([0, T]; H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3))$ a solution of (39)-(40)*

In the following we will establish the smoothing effect for the dissipative wave equation (39).

Proposition 4. *If the function $f = f(t, x)$ belongs to X_a . Then every solution $(\phi, \phi_t) \in X_a \times X_{a-1}$ of (39)-(40) belongs to $X_{a+1} \times X_a$.*

For demonstrations and some details, we refer to [10] and to the references therein.

3.2. An iteration argument: first step. The objective of this step is to establish that,

$$(v, v_t) \in X_{\frac{3}{2}} \times X_{\frac{1}{2}},$$

In order to obtain this, we will use the following lemma that was stated and proved by T. Runst and W. Sickel in their paper [19].

Lemma 3.1. *Let $s_1, s_2 < \frac{d}{2}$. If $u_1 \in H^{s_1}(\mathbb{R}^d), u_2 \in H^{s_2}(\mathbb{R}^d)$ then $u_1 u_2 \in H^{s_1+s_2-\frac{d}{2}}(\mathbb{R}^d)$.*

Thanks to Lemma 3.1 and $(u, v) \in (H^1(\mathbb{R}^3))^2$, we get

Corollary 1. *There exist C_1 and C_2 such that*

$$\|u\bar{u}\|_{H^{\frac{1}{2}}} \leq C_1 \|u\|_{H^1}^2, \quad \|v^2\|_{H^{\frac{1}{2}}} \leq C_1 \|v\|_{H^1}^2. \quad (41)$$

We consider a complete trajectory $(u(t), v(t), v_t(t))$ that belongs to the global attractor \mathcal{A} . So we have the following result

Lemma 3.2. *Let (u, v, v_t) a complete trajectory of \mathcal{A} , then we have*

$$(v, v_t) \in X_{\frac{3}{2}} \times X_{\frac{1}{2}}. \quad (42)$$

Proof. If (u, v, v_t) is a complete trajectory of \mathcal{A} , then $(u, v, v_t) \in C_b(\mathbb{R}^+, H^1 \times H^1 \times L^2)$ so $(u, v) \in X_1^2 = (C_b(\mathbb{R}^+, H^1))^2$.

Since $g \in L^2$ is known to exist v^* as

$$v^* - \Delta v^* = g. \quad (43)$$

If we set $\tilde{v} = v - v^*$, then from (3) and (43) we obtain

$$\tilde{v}_{tt} + \gamma \tilde{v}_t - \Delta \tilde{v} + \tilde{v} = |u|^2 - v^2. \quad (44)$$

Through Corollary 1 we apply Proposition 3 in (44), we obtain

$$(\tilde{v}, \tilde{v}_t) \in X_{\frac{3}{2}} \times X_{\frac{1}{2}}. \quad (45)$$

So we conclude the proof of the Corollary 1 since $v^* \in H^2$. \square

3.3. An iteration argument: second step. Let (u, v, v_t) a complete trajectory of \mathcal{A} , we know that the Lemma 3.2 gives a sort of regularity for v . In this step we will show that u is more regular, for this we will approximate u the solution of (3) per u^m (m a natural integer) solution of:

$$iu_t^m + i\nu u^m + i|u^m|^2 u^m + \Delta u^m + \nu u^m = f, \quad (46)$$

under the initial condition (at $t = -m$)

$$u^m(-m) = 0. \quad (47)$$

First we have the estimates of u^m

Proposition 5. *It exists $C_1 = C_1(\nu, f)$ such that, for all $t \geq -m$, we have*

$$\|u^m(t)\|_2 \leq C_1. \quad (48)$$

Moreover, for all $\epsilon > 0$ there exists $C_2 = C_2(f, \nu, \epsilon)$ such that, for all $t \geq -m$, we have

$$\|\nabla u^m(t)\|_2 \leq C_2. \quad (49)$$

Proof. On one hand it is easy to prove (48), indeed it is a classic result, for example we can repeat the proof of Proposition 1 (associated with u^m). On the other hand using the same approach in the proof of Proposition 2 (associated with the problem (46)-(47)), we obtain after making some arrangements

$$\begin{aligned}
& \frac{1}{2} \frac{d}{dt} \{ \|\nabla u^m(t)\|_2^2 + 2\operatorname{Re} \int f \overline{u^m} dx + \frac{1}{2} \|u^m(t)\|_4^4 - \int v |u^m|^2 dx \} \\
& + \nu \{ \|\nabla u^m(t)\|_2^2 + \operatorname{Re} \int f \overline{u^m} dx + \|u^m(t)\|_4^4 - \int v |u^m|^2 dx \} \\
& = \int v |u^m|^4 dx + \operatorname{Im} \int f |u^m|^2 \overline{u^m} dx - \operatorname{Re} \int f |u^m|^2 \overline{u^m} dx \\
& - \|u^m\|_6^6 - \int |\nabla u^m|^2 |u^m|^2 dx - 2 \int [\operatorname{Re}(\nabla u^m \overline{u^m})]^2 dx,
\end{aligned} \tag{50}$$

and hence, we have

$$\frac{1}{2} \frac{d}{dt} E_m(t) + \frac{\nu}{2} E_m(t) = F_m(t), \tag{51}$$

where

$$E_m(t) = \|\nabla u^m(t)\|_2^2 + 2\operatorname{Re} \int f \overline{u^m} dx + \frac{1}{2} \|u^m(t)\|_4^4 - \int v |u^m|^2 dx, \tag{52}$$

and

$$\begin{aligned}
F_m(t) &= \frac{\nu}{2} \int v |u^m|^2 dx + \frac{1}{2} \int v_t |u^m|^2 dx + \int v |u^m|^4 dx + \operatorname{Im} \int f |u^m|^2 \overline{u^m} dx \\
&- \operatorname{Re} \int f |u^m|^2 \overline{u^m} dx - \frac{3}{4} \nu \|u^m(t)\|_4^4 - \|u^m\|_6^6 - \int |\nabla u^m|^2 |u^m|^2 dx \\
&- 2 \int [\operatorname{Re}(\nabla u^m \overline{u^m})]^2 dx.
\end{aligned} \tag{53}$$

In order to establish an upper bound of E_m , we estimate the last terms of F_m . Using Hölder, Gagliardo-Nirenberg and Young inequalities, we have

$$\begin{aligned}
\left| \frac{\nu}{2} \int v |u^m|^2 dx \right| &\leq C \|v\|_2 \|u^m\|_4^2 \\
&\leq C \|u^m\|_4^2 \text{ (thanks to (42))} \\
&\leq \varepsilon \|u^m\|_4^4 + C_\varepsilon,
\end{aligned} \tag{54}$$

$$\begin{aligned}
\left| \frac{1}{2} \int v_t |u^m|^2 dx \right| &\leq C \|v_t\|_3 \|u^m\|_3^2 \\
&\leq C \|v_t\|_3 \|u^m\|_2 \|\nabla u^m\|_2 \\
&\leq C \|\nabla u^m\|_2 \text{ (thanks to (42) and (48))} \\
&\leq \varepsilon \|\nabla u^m\|_2^2 + C_\varepsilon,
\end{aligned} \tag{55}$$

$$\begin{aligned}
\left| \int v |u^m|^4 dx \right| &\leq C \|v\|_3 \|u^m\|_6^4 \\
&\leq C \|u^m\|_6^4 \text{ (thanks to (42))} \\
&\leq \varepsilon \|u^m\|_6^6 + C_\varepsilon,
\end{aligned} \tag{56}$$

and

$$\begin{aligned}
\left| \operatorname{Im} \int f |u^m|^2 \overline{u^m} dx - \operatorname{Re} \int f |u^m|^2 \overline{u^m} dx \right| &\leq C \|f\|_2 \|u^m\|_6^3 \\
&\leq C \|u^m\|_6^3 \\
&\leq \varepsilon \|u^m\|_6^6 + C_\varepsilon,
\end{aligned} \tag{57}$$

where $C_\varepsilon = C(\varepsilon, \nu, f)$. Then we have

$$\begin{aligned}
&\frac{1}{2} \frac{d}{dt} E_m(t) + \frac{\nu}{2} E_m(t) + \frac{\nu}{2} (1 - 2\varepsilon) \|\nabla u^m(t)\|_2^2 + \frac{3\nu}{4} (1 - \frac{4\varepsilon}{3}) \|u^m(t)\|_4^4 \\
&+ (1 - 2\varepsilon) \|u^m\|_6^6 + \int |\nabla u^m|^2 |u^m|^2 dx + 2 \int [\operatorname{Re}(\nabla u^m \overline{u^m})]^2 dx \leq C.
\end{aligned} \tag{58}$$

Finally, if we consider $\varepsilon > 0$ small enough such that $\varepsilon < \frac{1}{2}$ we obtain from (58)

$$\frac{d}{dt} (e^{\nu t} E_m(t)) \leq C e^{\nu t}, \tag{59}$$

then integrating (60) on $[-m, t]$, we have for all $t \geq -m$

$$E_m(t) \leq C(1 - e^{-\nu(m+t)}) \leq C. \tag{60}$$

A gain thanks to previous estimates, we can conclude

$$E_m(t) \geq (\frac{1}{2} - \varepsilon) \|u^m(t)\|_4^4 - C. \tag{61}$$

Gathering (60) and (61) we deduce (48) which concludes the proof of the Proposition 5.

□

Now we will show that $(u^m)_m$ is bounded in X_2 and for all $T > 0$ it converges strongly to u in $L^\infty(0; T; L^2(\mathbb{R}^3))$. To show this result, we will establish the following lemma.

Lemma 3.3. *There exists a numerical constant $C > 0$ such that for all $t \geq -m$*

$$\|u^m(t) - u(t)\|_2 \leq C \exp(-\nu(t+m)), \tag{62}$$

where $C = C(\nu, f, u_0)$.

Proof. Subtract (46) from (3) and multiply the equation obtained by $\overline{u^m - u}$ and integrate the imaginary part on \mathbb{R}^3 we obtain

$$\frac{1}{2} \frac{d}{dt} \|u^m(t) - u(t)\|_2^2 + \nu \|u^m(t) - u(t)\|_2^2 + \operatorname{Re} \int (|u^m|^2 u^m - |u|^2 u) (\overline{u^m - u}) dx = 0. \tag{63}$$

Then, using the fact that

$$\begin{aligned}
& \operatorname{Re}[(|z_1|^2 z_1 - |z_2|^2 z_2)(\overline{z_1 - z_2})] \\
&= [|z_1|^4 + |z_2|^4 - (|z_1|^2 + |z_2|^2) \operatorname{Re}(z_1 \overline{z_2})] \\
&\geq [|z_1|^4 + |z_2|^4 - (|z_1|^3 |z_2| + |z_2|^3 |z_1|)] \\
&= (|z_1|^3 - |z_2|^3)(|z_1| - |z_2|) \\
&\geq (|z_1| - |z_2|)^2 (|z_1|^2 + |z_1| |z_2| + |z_2|^2),
\end{aligned} \tag{64}$$

we obtain

$$\frac{1}{2} \frac{d}{dt} \|u^m(t) - u(t)\|_2^2 + \nu \|u^m(t) - u(t)\|_2^2 \leq 0, \tag{65}$$

which equivalent to

$$\frac{d}{dt} (\|u^m(t) - u(t)\|_2^2 e^{2\nu t}) \leq 0. \tag{66}$$

Then we integrate (66) between $-m$ and t we get for all $t \geq -m$

$$\|u^m(t) - u(t)\|_2 \leq \|u(-m)\|_2 \exp(-\nu(m+t)) \leq C \exp(-\nu(m+t)), \tag{67}$$

from where you get (62). \square

Proposition 6. *The sequence $(u^m)_m$ is bounded uniformly in X_2 .*

Proof. According to (46), we have

$$\Delta u^m = -i u_t^m + \mathcal{R}(u^m, f, v), \tag{68}$$

where $\mathcal{R}(u^m, f, v) = f - v u^m - i \nu u^m - i |u^m|^2 u^m$.

So, as $\mathcal{R}(u^m, f, v)$ belongs to L^2 it is enough to find an estimate of u_t^m in L^2 . For this, we see that $\mathcal{U} = u_t^m$ is solution of

$$i \mathcal{U}_t + \Delta \mathcal{U} + i \nu \mathcal{U} + v \mathcal{U} + v_t u^m + 2i |u^m|^2 \mathcal{U} + i (u^m)^2 \overline{\mathcal{U}} = 0, \tag{69}$$

$$\mathcal{U}(-m) = u_t^m(-m) = -i f \in L^2. \tag{70}$$

Multiplying (69) by $\overline{\mathcal{U}}$, integrating over \mathbb{R}^3 and taking the imaginary part to obtain

$$\frac{1}{2} \frac{d}{dt} \|\mathcal{U}\|_2^2 + \nu \|\mathcal{U}\|_2^2 + 2 \int |u^m|^2 |\mathcal{U}|^2 dx - \operatorname{Re} \int (u^m \overline{\mathcal{U}})^2 dx = -\operatorname{Im} \int v_t u^m \overline{\mathcal{U}} dx. \tag{71}$$

Using $2[\operatorname{Re}(z_1 \overline{z_2})]^2 = |z_1|^2 |z_2|^2 + \operatorname{Re}[(z_1 \overline{z_2})^2]$ in (71), we have

$$\frac{1}{2} \frac{d}{dt} \|\mathcal{U}\|_2^2 + \nu \|\mathcal{U}\|_2^2 + 3 \int |u^m|^2 |\mathcal{U}|^2 dx - 2 \int [\operatorname{Re}(u^m \overline{\mathcal{U}})]^2 dx = -\operatorname{Im} \int v_t u^m \overline{\mathcal{U}} dx, \tag{72}$$

and thanks to $[\operatorname{Re}(z_1 \overline{z_2})]^2 \leq |z_1|^2 |z_2|^2$, we get

$$\frac{1}{2} \frac{d}{dt} \|\mathcal{U}\|_2^2 + \nu \|\mathcal{U}\|_2^2 \leq -\operatorname{Im} \int v_t u^m \overline{\mathcal{U}} dx. \tag{73}$$

Thanks to Hölder and Young inequalities, the Sobolev injections $H^{\frac{1}{2}} \subset L^3$, $H^1 \subset L^6$, Lemma 3.3 and the Proposition 6 we have

$$\begin{aligned} |\operatorname{Im} \int v_t u^m \bar{\mathcal{U}} dx| &\leq \|v_t\|_3 \|u^m\|_6 \|\mathcal{U}\|_2 \\ &\leq C \|\mathcal{U}\|_2 \\ &\leq \frac{\nu}{2} \|\mathcal{U}\|_2^2 + C. \end{aligned} \tag{74}$$

According to (73) and (74), the lemma of Gronwall can be applied in the resulting equation to have for all $t \geq -m$

$$\|\mathcal{U}(t)\|_2^2 \leq C(1 - e^{-\nu(m+t)}) \leq C, \tag{75}$$

where C is m independent, which completes the proof of the Proposition 6. \square

3.4. Conclusion.

Proposition 7.

$$u \in X_2. \tag{76}$$

Proof. On the one hand, thanks to the Proposition 6 there exist a subsequence still noted $(u^m)_m$ which converge weak - star to \tilde{u} in X_2 . On the other hand by lemma 3.3, we have

$$u^m \rightarrow u \text{ in } L^\infty(0, T; L^2). \tag{77}$$

By uniqueness of the limit we deduce that $u \in X_2$. \square

Proposition 8.

$$(v, v_t) \in X_2 \times X_1. \tag{78}$$

Proof. On the one hand, as a consequence of Proposition 7, we have

$$|u|^2 \in X_2, \tag{79}$$

because $H^2(\mathbb{R}^3)$ is an algebra. On the other hand, by Lemma 3.1 and Lemma 3.2 we get

$$v^2 \in X_{\frac{3}{2}-}. \tag{80}$$

Using (79) and (80) we deduce

$$|u|^2 - v^2 \in X_{\frac{3}{2}-}, \tag{81}$$

which allows us to use Proposition 4 to

$$(\tilde{v}, \tilde{v}_t) \in X_{\frac{5}{2}-} \times X_{\frac{3}{2}-}. \tag{82}$$

Then we can easily obtain (78). \square

From Proposition 7 and Proposition 8 it is deduced that \mathcal{A} is a subset of E_2 . The remainder of the proof (of the main theorem) is devoted to establishing the compactness of \mathcal{A} into E_2 .

Proposition 9. \mathcal{A} is a compact subset of E_2 .

Proof. Let $(u^n, v^n, v_t^n)_n$ is a sequence of the attractor \mathcal{A} . On one hand there exist a subsequence again noted $(u^n, v^n, v_t^n)_n$ which converges (strongly) towards $(u; v; v_t)$ in E_1 (since \mathcal{A} is an attractor in E_1). On the other hand, the fact that \mathcal{A} is bounded in E_2 even if to extract a subsequence (of the previous subsequence) we can assume that $(u^n, v^n, v_t^n)_n$ converges weakly towards $(u; v; v_t)$ in E_2 (by uniqueness of the limit).

Based on the proof of Proposition 8 we have $(v^n - \tilde{v}; v_t^n) \in X_{\frac{5}{2}-} \times X_{\frac{3}{2}-}$, then by interpolation we obtain the strong convergence of $(v^n; v_t^n)$ in $H^2 \times H^1$.

Either $T > 0$ and either $0 \leq t \leq T$, lets show that $u^n(t)$ converges strongly towards $u(t)$ in H^2 which is equivalent to showing that

$$\|u_t^n(t)\|_2 \rightarrow \|u_t(t)\|_2. \quad (83)$$

Next, we differentiate the analogous equation of (3) (verified by u^n and v^n) and we multiply the resulting equation by $\overline{u_t^n}$ then we integrate the imaginary part on \mathbb{R}^3 and proceeding as above, we get

$$\frac{d}{dt} \|u_t^n(t)\|_2^2 + 2\nu \|u_t^n(t)\|_2^2 \leq -2\text{Im} \int_{\mathbb{R}^3} v_t^n(t) u^n(t) \overline{u_t^n(t)} dx. \quad (84)$$

So we integrate (84) on $[0, t]$, we'll have

$$\|u_t^n(t)\|_2^2 \leq \|u_t^n(0)\|_2^2 e^{-2\nu t} - 2\text{Im} \int_0^t \int_{\mathbb{R}^3} e^{2\nu(s-t)} v_t^n(s) u^n(s) \overline{u_t^n(s)} dx ds. \quad (85)$$

By analogy we have

$$\|u_t(t)\|_2^2 \leq \|u_t(0)\|_2^2 e^{-2\nu t} - 2\text{Im} \int_0^t \int_{\mathbb{R}^3} e^{2\nu(s-t)} v_t(s) u(s) \overline{u_t(s)} dx ds. \quad (86)$$

The same goes for

$$\begin{aligned} \|u_t^n(t)\|_2^2 &\leq \|u_t^n(t-T)\|_2^2 e^{-2\nu T} \\ &\quad - 2\text{Im} \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t^n(s-T) u^n(s-T) \overline{u_t^n(s-T)} dx ds. \end{aligned} \quad (87)$$

$$\begin{aligned} \|u_t(t)\|_2^2 &\leq \|u_t(t-T)\|_2^2 e^{-2\nu T} \\ &\quad - 2\text{Im} \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t(s-T) u(s-T) \overline{u_t(s-T)} dx ds. \end{aligned} \quad (88)$$

Lemma 3.4.

$$\begin{aligned} &\int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t^n(s-T) u^n(s-T) \overline{u_t^n(s-T)} dx ds \\ &\xrightarrow{n \rightarrow +\infty} \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t(s-T) u(s-T) \overline{u_t(s-T)} dx ds. \end{aligned} \quad (89)$$

Proof. First of all we notice that

$$\int_{\mathbb{R}^3} v_t^n u^n \overline{u_t^n} - \int_{\mathbb{R}^3} v_t u \overline{u_t} = \int_{\mathbb{R}^3} v_t^n u^n \overline{u_t^n} - \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t u \overline{u_t^n} + \int_{\mathbb{R}^3} v_t u \overline{u_t^n} - \int_{\mathbb{R}^3} v_t u \overline{u_t}.$$

On one hand, by Proposition 6 and the Sobolev embedding $H_x^1 \subset L_x^4$ we have

$$\begin{aligned}
\left| \int_{\mathbb{R}^3} v_t^n u^n \overline{u_t^n} - \int_{\mathbb{R}^3} v_t u \overline{u_t} \right| &\leq \|v_t^n u^n - v_t u\|_2 \|u_t^n\|_2 \\
&\leq C(\|v_t^n u^n - v_t u^n\|_2 + \|v_t u^n - v_t u\|_2) \\
&\leq C(\|v_t^n - v_t\|_4 \|u^n\|_4 + \|v_t\|_4 \|u^n - u\|_4) \\
&\leq C(\|v_t^n - v_t\|_{H^1} + \|u^n - u\|_{H^1}),
\end{aligned} \tag{90}$$

hence by the strong convergence $u^n \rightarrow u$ and $v_t^n \rightarrow v_t$ (in H^1), we get

$$\left| \int_{\mathbb{R}^3} v_t^n u^n \overline{u_t^n} - \int_{\mathbb{R}^3} v_t u \overline{u_t} \right| \xrightarrow{n \rightarrow +\infty} 0. \tag{91}$$

On the other hand, by the weak convergence $(u^n, v^n, v_t^n) \rightharpoonup (u, v, v_t)$ in E_2 , we obtain

$$u_t^n \rightharpoonup u_t \text{ in } L^2, \tag{92}$$

so we get

$$\int_{\mathbb{R}^3} v_t u \overline{u_t^n} \xrightarrow{n \rightarrow +\infty} \int_{\mathbb{R}^3} v_t u \overline{u_t}. \tag{93}$$

Thanks to (91) and (93), we obtain

$$\int_{\mathbb{R}^3} v_t^n u^n \overline{u_t^n} \xrightarrow{n \rightarrow +\infty} \int_{\mathbb{R}^3} v_t u \overline{u_t}. \tag{94}$$

Thanks to the dominated convergence theorem and (93) one deduces (89) and the proof Lemma 3.4 will be completed. \square

The weak convergence (92) makes it possible to have

$$\liminf_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 \geq \|u_t(t)\|_2^2. \tag{95}$$

To finish the proof we will establish that

$$\limsup_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 \leq \|u_t(t)\|_2^2. \tag{96}$$

At this stage, the classical argument of J. Bull is used (see [22] and the references therein). By (87), lemma 3.4 and Lebesgue's convergence theorem we have

$$\begin{aligned}
&\limsup_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 \\
&\leq \limsup_{n \rightarrow +\infty} \|u_t^n(t - T)\|_2^2 e^{-2\nu T} \\
&\quad - 2\operatorname{Im} \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t^n(s - T) u^n(s - T) \overline{u_t^n(s - T)} dx ds \\
&\leq \limsup_{n \rightarrow +\infty} \|u_t^n(t - T)\|_2^2 e^{-2\nu T} \\
&\quad + 2 \left| \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t^n(s - T) u^n(s - T) \overline{u_t^n(s - T)} dx ds \right|.
\end{aligned} \tag{97}$$

Thanks to (88), we have

$$\begin{aligned}
& 2 \left| \int_0^T \int_{\mathbb{R}^3} e^{2\nu(s-T)} v_t^n(s-T) u^n(s-T) \overline{u_t^n(s-T)} dx ds \right| \\
& \leq \|u_t(t-T)\|_2^2 e^{-2\nu T} - \|u_t(t)\|_2^2 \\
& \leq \|u_t(t-T)\|_2^2 e^{-2\nu T} + \|u_t(t)\|_2^2.
\end{aligned} \tag{98}$$

By substituting (98) in (97), we will have

$$\begin{aligned}
2 \limsup_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 & \leq \limsup_{n \rightarrow +\infty} \|u_t^n(t-T)\|_2^2 e^{-2\nu T} \\
& \quad + \|u_t(t-T)\|_2^2 e^{-2\nu T} + \|u_t(t)\|_2^2 \\
& \leq (\limsup_{n \rightarrow +\infty} \|u_t^n(t-T)\|_2^2 \\
& \quad + \|u_t(t-T)\|_2^2) e^{-2\nu T} + \|u_t(t)\|_2^2.
\end{aligned} \tag{99}$$

As $u_t^n(t-T)$ is bounded in L^2 and $u_t(t-T)$ in L^2 , then there exist C (independent of n and T) such that

$$\limsup_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 \leq C e^{-2\nu T} + \|u_t(t)\|_2^2. \tag{100}$$

Letting $T \rightarrow +\infty$ into (100). Using the resulting inequality, it is easy to prove that in fact

$$\limsup_{n \rightarrow +\infty} \|u_t^n(t)\|_2^2 \leq \|u_t(t)\|_2^2, \tag{101}$$

which finish the proof of the Proposition 9. \square

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