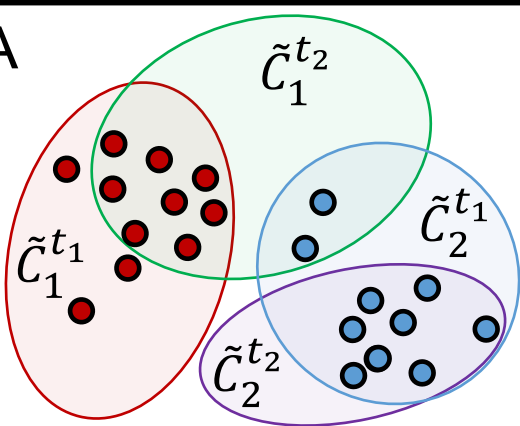
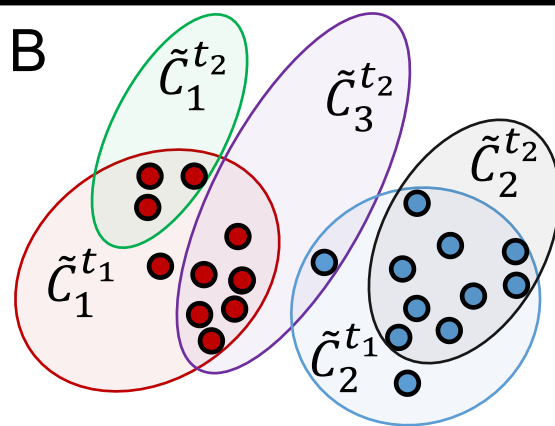


A



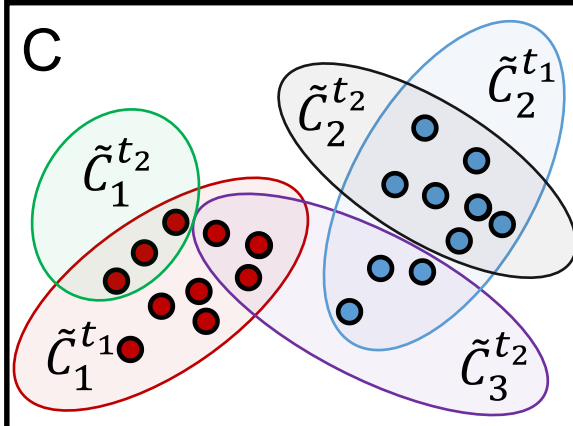
• $OS(C_1^{t_1})$ • $OS(C_2^{t_1})$

B



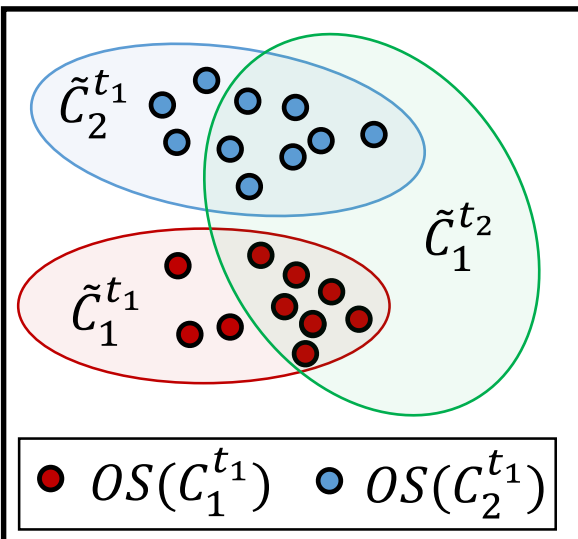
• $OS(C_1^{t_1})$ • $OS(C_2^{t_1})$

C

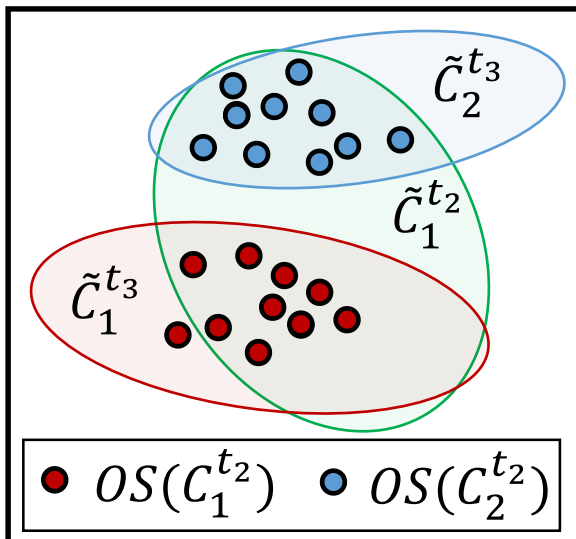


• $OS(C_1^{t_2})$ • $OS(C_2^{t_1})$

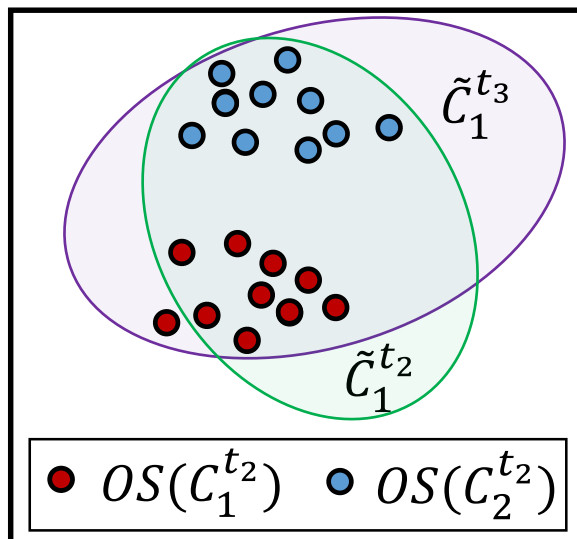
D



• $OS(C_1^{t_1})$ • $OS(C_2^{t_1})$



• $OS(C_1^{t_2})$ • $OS(C_2^{t_2})$



• $OS(C_1^{t_2})$ • $OS(C_2^{t_2})$