

Prueba de Referencias

Abraham Contreras

PRUEBA DE REFERENCIAS

[1]

[2]

[3]

[4]

[5]

[6]

[7]

[8]

[9]

[10]

[11]

[12]

REFERENCES

- [1] N. Salameh, G. Challita, S. Mousset, A. Bensrhair, and S. Ramaswamy, "Collaborative positioning and embedded multi-sensors fusion cooperation in advanced driver assistance system," *Transportation Research Part C: Emerging Technologies*, vol. 29, pp. 197–213, apr 2013. [Online]. Available: <https://doi.org/10.1016%2Ftrc.2012.05.004>
- [2] H. Vahdat-Nejad, A. Ramazani, T. Mohammadi, and W. Mansoor, "A survey on context-aware vehicular network applications," *Vehicular Communications*, vol. 3, pp. 43–57, jan 2016. [Online]. Available: <https://doi.org/10.1016%2Fvehcom.2016.01.002>
- [3] S. Al-Sultan, M. M. Al-Doori, A. H. Al-Bayatti, and H. Zedan, "A comprehensive survey on vehicular Ad Hoc network," *Journal of Network and Computer Applications*, vol. 37, pp. 380–392, jan 2014. [Online]. Available: <https://doi.org/10.1016%2Fj.jnca.2013.02.036>
- [4] B. Krogh and C. Thorpe, "Integrated path planning and dynamic steering control for autonomous vehicles," in *Proceedings. 1986 IEEE International Conference on Robotics and Automation*. Institute of Electrical and Electronics Engineers. [Online]. Available: <https://doi.org/10.1109%2Frobot.1986.1087444>
- [5] B. Kim and B. Park, "Robust Control for the Segway with Unknown Control Coefficient and Model Uncertainties," *Sensors*, vol. 16, no. 12, p. 1000, jun 2016. [Online]. Available: <https://doi.org/10.3390%2Fs16071000>
- [6] J. Ashurst and B. Wagner, "Injuries Following Segway Personal Transporter Accidents: Case Report and Review of the Literature," *Western Journal of Emergency Medicine*, vol. 16, no. 5, pp. 693–695, sep 2015. [Online]. Available: <https://doi.org/10.5811%2Fwestjem.2015.7.26549>
- [7] J.-C. Junqua, "The influence of acoustics on speech production: A noise-induced stress phenomenon known as the Lombard reflex," *Speech Communication*, vol. 20, no. 1-2, pp. 13–22, nov 1996. [Online]. Available: <https://doi.org/10.1016%2Fs0167-6393%2896%2900041-6>
- [8] "SRF05 Technical Documentation," <https://www.robot-electronics.co.uk/htm/srf05tech.htm>, accessed on Mon, March 12, 2018. [Online]. Available: <https://www.robot-electronics.co.uk/htm/srf05tech.htm>
- [9] "Sharp Distance Measuring Sensor unit 20 to 150 cm - GP2Y0A02YK0F - Robu.in — Indian Online Store — RC Hobby — Robotics," <https://robu.in/product/sharp-distance-measuring-sensor-unit-20-150-cm-gp2y0a02yk0f/>, accessed on Mon, March 12, 2018. [Online]. Available: <https://robu.in/product/sharp-distance-measuring-sensor-unit-20-150-cm-gp2y0a02yk0f/>
- [10] J. Roberts and T. D. Roberts, "Use of the Butterworth low-pass filter for oceanographic data," *Journal of Geophysical Research*, vol. 83, no. C11, p. 5510, 1978. [Online]. Available: <https://doi.org/10.1029%2Fjc083ic11p05510>
- [11] E. S. Gardner, "Exponential smoothing: The state of the art," *Journal of Forecasting*, vol. 4, no. 1, pp. 1–28, 1985. [Online]. Available: <https://doi.org/10.1002%2Ffor.3980040103>
- [12] "6.4.3.3. Double Exponential Smoothing," <http://www.itl.nist.gov/div898/handbook/pmc/section4/pmc433.htm>, accessed on Mon, March 12, 2018. [Online]. Available: <http://www.itl.nist.gov/div898/handbook/pmc/section4/pmc433.htm>