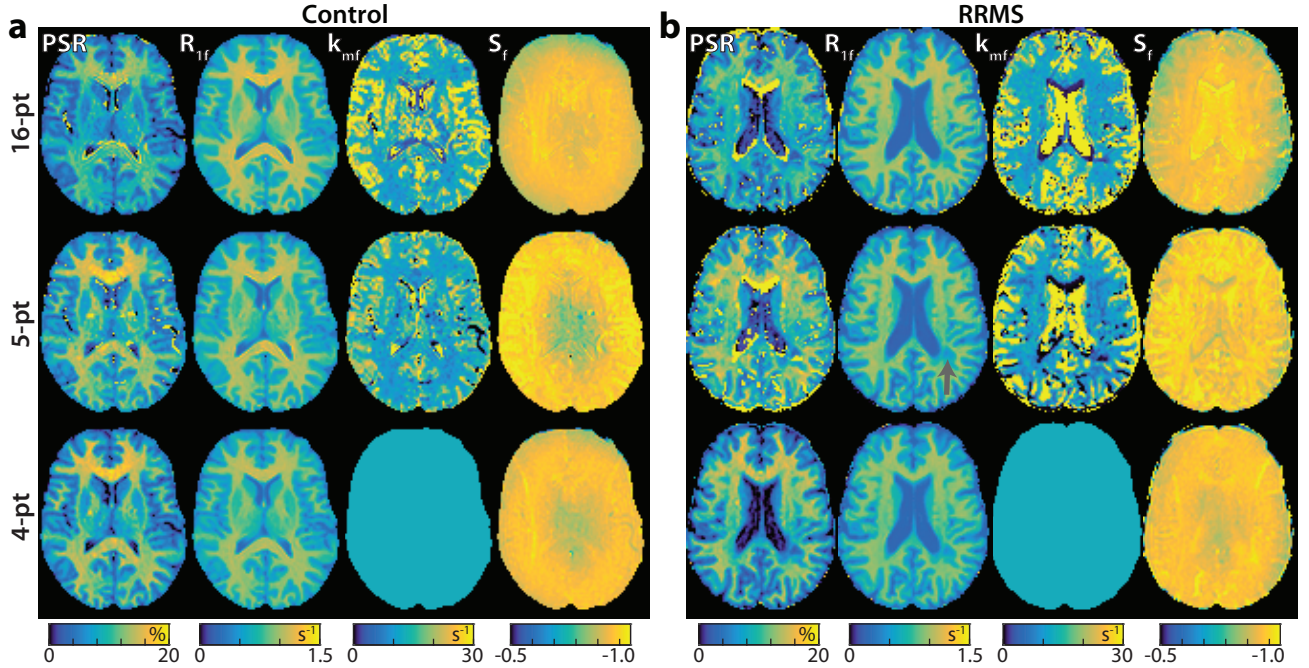
a
Control
b
RRMS
PSR
R_{1f}
k_{mf}
S_f
16-pt
5-pt
4-pt
%
0
20
s^{-1}
0
1.5
s^{-1}
0
30
-0.5
-1.0