Cycles-L: A coupled, 3-D, land surface, hydrologic, and agroecosystem landscape model

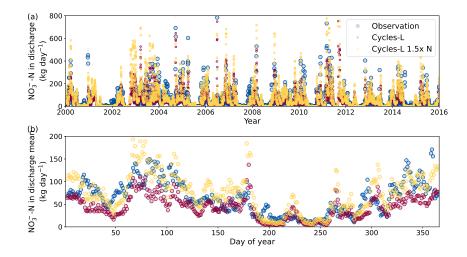
Yuning Shi¹, Felipe Montes², and Armen R Kemanian²

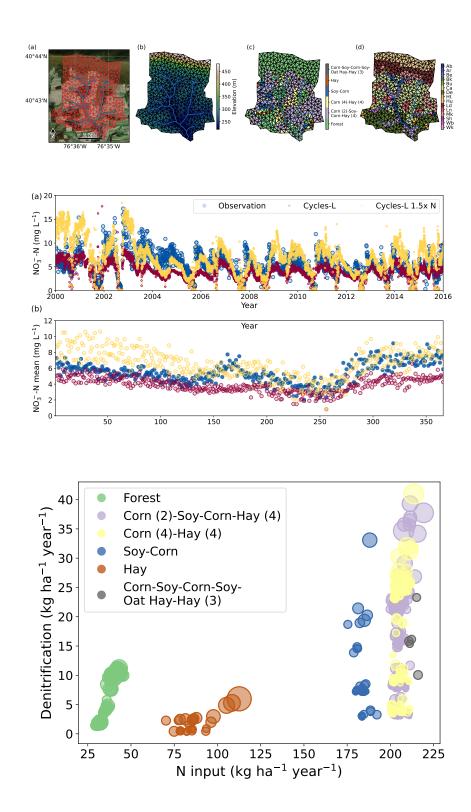
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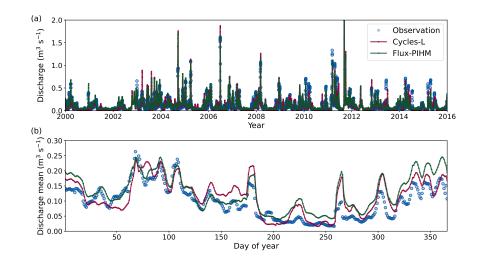
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Abstract

Managing landscapes to increase agricultural productivity and environmental stewardship requires spatially distributed models that can integrate data and operate at spatial and temporal scales that are intervention-relevant. This paper presents Cycles-L, a landscape-scale, coupled agroecosystem hydrologic modeling system. Cycles-L couples a 3-D land surface hydrologic model, Flux-PIHM, with a 1-D agroecosystem model, Cycles. Cycles-L takes the landscape and hydrology structure from Flux-PIHM and most agroecosystem processes from Cycles. Consequently, Cycles-L can simulate landscape level processes affected by topography, soil heterogeneity, and management practices, owing to its physically-based hydrologic component and ability to simulate horizontal and vertical transport of mineral nitrogen (N) with water. The model was tested at a 730-ha agricultural experimental watershed within the Mahantango Creek watershed in Pennsylvania. Cycles-L simulated well stream water discharge and N exports (Nash-Sutcliffe coefficient 0.55 and 0.58, respectively), and grain crop yield (root mean square error 1.01 Mg ha⁻¹), despite some uncertainty in the accuracy of survey-based input data. Cycles-L outputs are as good if not better than those obtained with the uncoupled Flux-PIHM (water discharge) and Cycles (crop yield) models. Model predicted spatial patterns of N fluxes clearly show the combined control of crop management and topography. Cycles-L spatial and temporal resolution fills a gap in the availability of analytical models at an operational scale relevant to evaluate costly strategic and tactical interventions *in silico*, and can become a core component of tools for applications in precision agriculture, precision conservation, and artificial intelligence-based decision support systems.







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5	Key Points:
6	• Cycles-L is a coupled agroecosystem hydrologic modeling system that couples an
7	agroecosystem model with a 3-D land surface hydrologic model
8	• Cycles-L simulated well stream discharge, grain crops yield, and nitrogen exports
9	in the stream at a 730-ha agricultural experimental watershed
10	• Cycles-L can simulate landscape level processes affected by topography, soil het-
11	erogeneity, and management practices

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12 Abstract

Managing landscapes to increase agricultural productivity and environmental steward-13 ship requires spatially distributed models that can integrate data and operate at spa-14 tial and temporal scales that are intervention-relevant. This paper presents Cycles-L, a 15 landscape-scale, coupled agroecosystem hydrologic modeling system. Cycles-L couples 16 a 3-D land surface hydrologic model, Flux-PIHM, with a 1-D agroecosystem model, Cv-17 cles. Cycles-L takes the landscape and hydrology structure from Flux-PIHM and most 18 agroecosystem processes from Cycles. Consequently, Cycles-L can simulate landscape 19 level processes affected by topography, soil heterogeneity, and management practices, ow-20 ing to its physically-based hydrologic component and ability to simulate horizontal and 21 vertical transport of mineral nitrogen (N) with water. The model was tested at a 730-ha 22 agricultural experimental watershed within the Mahantango Creek watershed in Penn-23 sylvania. Cycles-L simulated well stream water discharge and N exports (Nash-Sutcliffe 24 coefficient 0.55 and 0.58, respectively), and grain crop yield (root mean square error 1.01 Mg ha⁻¹), 25 despite some uncertainty in the accuracy of survey-based input data. Cycles-L outputs 26 are as good if not better than those obtained with the uncoupled Flux-PIHM (water dis-27 charge) and Cycles (crop yield) models. Model predicted spatial patterns of N fluxes clearly 28 show the combined control of crop management and topography. Cycles-L spatial and 29 temporal resolution fills a gap in the availability of analytical models at an operational 30 scale relevant to evaluate costly strategic and tactical interventions in silico, and can be-31 come a core component of tools for applications in precision agriculture, precision con-32 servation, and artificial intelligence-based decision support systems. 33

34 1 Introduction

Managing landscapes to increase agricultural productivity and environmental stew-35 ardship requires understanding and representing landscape attributes with ever increas-36 ing fidelity. The ability to represent in silico the spatial variability and temporal dynam-37 ics of water and nutrient flows in such landscapes through modeling tools can help sig-38 nificantly in the design of cost-effective interventions in the realms of precision agricul-39 ture, precision conservation, or watershed management (Beaujouan et al., 2001; Booker 40 et al., 2014; Stöckle et al., 2014). These modeling tools are known as spatially distributed. 41 Two features are critical for these models to be applicable. First, they must integrate 42 the wealth of real-time data incoming from *in situ* sensors, proximal sensing from un-43 manned aerial vehicles (UAVs) and terrestrial vehicles (UTVs), remote sensing from satel-44 lites, and constantly refined terrain and surface data (e.g., the Soil Survey Geographic 45 Database or SSURGO, and the National Land Cover Database or NLCD), and mete-46 orological data such as the Global Land Data Assimilation System (GLDAS; Rodell et 47 al., 2004) and Europe's World Climate Research Program Coordinated Regional Down-48 scaling Experiment (EURO-CORDEX; Jacob et al., 2014). Second, these models must 49 operate at a scale of relevance to represent interventions and with minimal supervision, 50 so that they do not become "mathematical marionettes" (Kirchner, 2006). There are to 51 our knowledge only partial efforts at integrating models and data in this fashion. This 52 paper presents the model Cycles-L, where L stands for landscape. Cycles-L integrates 53 Flux-PIHM (Shi et al., 2013), a 3-D energy and hydrology model, and the Cycles agroe-54 cosystem model (Kemanian et al., 2022). 55

One-dimensional cropping system models are established tools for planning and de-56 cision making in agriculture systems with low spatial variability and high quality input 57 data (e.g., Boote et al., 2010; Stöckle & Kemanian, 2020; Zhai et al., 2020). Applications 58 of these 1-D models in precision agriculture lag behind their promise (Stafford, 2000) be-59 cause, among other limitations (Zhai et al., 2020), the representation of both static and 60 dynamic properties that vary spatially is limited. Although these models are often used 61 in a gridded way in an attempt to represent spatial heterogeneity (e.g., Saarikko, 2000; 62 Batchelor et al., 2002; Basso et al., 2007), their 1-D nature and lack of lateral water and 63

nutrient transport among grids significantly limits their ability to represent nonlinear ities in water and nutrient availability caused by topography and soil heterogeneity. An
 additional impedance is that using these models in a way that enriches decision-making
 requires substantial competence (Confalonieri et al., 2016).

There have been, however, efforts at developing models that represent spatial and 68 temporal variability in a semi-distributed fashion in non-agricultural (Tague & Band, 69 2004) and agricultural landscapes without resorting to costly numerical solutions of wa-70 ter flow in landscapes. For example, the Soil Water Assessment Tool (SWAT; Arnold et 71 al., 1998) and the Agricultural Policy EXtender (APEX; Gassman et al., 2010) divide 72 the model domain into subareas (e.g., Hydrological Response Units, or HRUs) by ter-73 rain or soil attributes. Within HRUs, processes are simulated using the core of the 1-D 74 EPIC model (J. R. Williams, 1990). In the SWAT model, HRUs do not interact; an HRU's 75 water, nutrient, and sediment runoff contributions to the corresponding watershed out-76 let are represented through HRU-specific delivery ratios. However, sediment generation 77 and delivery, for example, are not equally scaled to the HRU area, which causes output 78 variations solely dependent on the HRU generation scheme (E. Chen & Mackay, 2004). 79 In the APEX model, the HRUs (or subareas) are hydrologically connected, but the land-80 scape segmentation methodology is ad hoc (Kemanian et al., 2009), calibration require-81 ments are substantial (X. Wang et al., 2011), and the calibration parameters are not nec-82 essarily robust (Francesconi et al., 2014; Van Liew et al., 2017). These challenges are not 83 unique to these modeling systems but are easily overlooked and difficult to grasp with-84 out substantial training, as alluded to in general by Confalonieri et al. (2016). Further-85 more, models that aggregate large spatial scales can represent some processes very well 86 (Arnold et al., 1998; Koch et al., 2016), but cannot represent highly non-linear processes 87 controlled by within-subarea heterogeneity in topography, soil, and landcover. Both Stöckle 88 and Kemanian (2020) and Tenreiro et al. (2020) concluded that among the most promis-89 ing areas for improvement of current cropping system models is the representation of land-90 scape processes that affect surface inflow and subsurface lateral flows of water and other 91 constituents. Although efforts in this direction have been underway for decades (e.g. Beau-92 jouan et al., 2001), the usage of spatially-distributed models remains limited. A robust, 93 scale-independent formulation of routing is desirable to dispel uncertainty and to reduce 94 dependence on local calibration. 95

Advances in computational power and modeling techniques have paved the way to 96 the development of coupled agroecosystem hydrologic models. The Precision Agricultural-97 Landscape Modeling System (PALMS; Molling et al., 2005) combines an enhanced 2-D 98 diffusive wave runoff model with a 1-D biophysical model based on the Integrated BIo-99 sphere Simulator (IBIS; Foley et al., 1996; Kucharik et al., 2000). PALMS has been used 100 to simulate crop and erosion processes (e.g., Molling et al., 2005; Bonilla et al., 2007, 2008), 101 and connected to other crop models (Booker et al., 2014, 2015). Although the PALMS 102 grids are hydrologically connected at the surface, horizontal distribution of subsurface 103 water is empiric and subsurface lateral flow is not explicitly simulated. Ward et al. (2018) 104 presented a spatially distributed and 3-D hydrologic cropping system model, CropSyst-Microbasin 105 (CS-MB), which added the Soil Moisture Routing model-based subsurface lateral flow 106 to CropSyst. The model was tested in a 10.9-ha watershed growing rainfed wheat in the 107 Inland Pacific Northwest, USA, showing promising potential to simulate field-scale spa-108 tial variability of water distribution and grain yield. The kinematic assumption used by 109 this model, i.e., the hydraulic gradient for subsurface water flow follows the land slope 110 rather than the water table slope, limits its application on gentle slopes (Wigmosta & 111 Lettenmaier, 1999). 112

While crop production is a primary target in landscape management, more comprehensive models are needed to track dynamic processes that reshape the landscape such as soil and sediments erosion and deposition (Pineux et al., 2017) and changes in soil organic carbon stocks (Baker et al., 2007), as well as to represent the provision of ecosys-

tem services determined by landscape diversity (Frank et al., 2012). Processes need to 117 be represented along the continuum of soil, groundwater, and streams. For example, ni-118 trogen (N) is both a critical plant macronutrient needed to reach high crop yield and a 119 source of pollution (McLellan et al., 2018). Within the Chesapeake Bay Watershed (CBW), 120 Ator and Garcia (2016) estimated that of the total N input to the CBW as fertilizer, bi-121 ological N fixation, and N deposition, up to 18% is delivered to tidal waters or stored 122 in the stream, 19% is harvested, and 45% is lost as denitrification. Most N losses occur 123 when there is a large mismatch between N extraction in harvest and N applied as fer-124 tilizer (Woodbury et al., 2018; McLellan et al., 2018). Furthermore, high N losses as den-125 itrification point to potentially high and unreported losses of N_2O if denitrification is in-126 complete (Saha et al., 2021). Opportunities exist therefore to reduce N losses in a cost-127 effective and environmentally friendly fashion, and taking advantage of these opportu-128 nities can greatly benefit from robust modeling and diagnostic tools. 129

The objectives of this paper are to present Cycles-L, a coupled agroecosystem hy-130 drologic modeling system, and to demonstrate its use through a case study. We tested 131 Cycles-L at an agricultural experimental watershed, WE-38, that is nested in the larger 132 watershed of the Mahantango Creek in Pennsylvania. The long-term records of discharge 133 and water quality, together with the surveys of crop rotations, make WE-38 an ideal site 134 for testing Cycles-L. We evaluate and discuss the simulated discharge, stream NO_3^- -N 135 concentrations, and crop yield with observations and county-level surveys, to showcase 136 the degree of fidelity and utility of Cycles-L for landscape level analysis. 137

¹³⁸ 2 Cycles-L Components Description

2.1 Flux-PIHM

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Flux-PIHM is a spatially distributed land surface hydrologic model that integrates 140 the Penn State Integrated Hydrologic Model (PIHM; Qu & Duffy, 2007; Bhatt et al., 2014) 141 and the Noah land surface model component (F. Chen & Dudhia, 2001; Ek et al., 2003). 142 Flux-PIHM simulates 3-D soil, groundwater, and river hydrology, along with the surface 143 energy balance with high spatial resolution, representing land surface and hydrological 144 variability resulting from soil, landcover, and topographic heterogeneity (Shi et al., 2015). 145 Flux-PIHM is the core of other terrestrial biogeochemistry (Shi et al., 2018; Zhi et al., 146 2022) and reactive transport models (Bao et al., 2017). 147

In Flux-PIHM, the land surface is decomposed into unstructured triangular grids 148 for optimal representation of local heterogeneities (topography, soil, and land cover), river 149 channels, and watershed boundaries. River channels are represented by rectangular el-150 ements (Tarboton et al., 1991). Water transport between soil, ground, and river follows 151 PIHM (Qu & Duffy, 2007). PIHM uses de Saint-Venant (1871) equations to compute 152 channel (1-D) and surface (2-D) water flow. Infiltration at the air-soil interface is cal-153 culated using the properties of the top 10 cm of soil following Darcy's law. In the sub-154 surface, the prismatic and triangular volume is divided into water saturated and unsat-155 urated zones. Unsaturated water transport only occurs vertically. In the saturated zone, 156 groundwater flow is horizontal with dynamic coupling to the unsaturated zone across the 157 water table, governed by Darcy's law. The hydrologic equations at each model grid are 158 discretized to ordinary differential equations (ODEs), which are assembled within the 159 boundaries of the domain, and solved simultaneously using the CVODE ODE solver (Hindmarsh 160 et al., 2005). The land surface component of Flux-PIHM is adapted from the Noah land 161 surface model (F. Chen & Dudhia, 2001; Ek et al., 2003), and is coupled to PIHM by 162 exchanging water table depth, infiltration rate, water table position, net precipitation 163 rate, and evapotranspiration rate between the two components. The land surface com-164 ponent simulates surface energy balance, snow melt, interception, and drip. In the land 165 surface component, the subsurface is divided into layers with fixed thickness. By default, 166 the soil layer thickness increases from 0.11 m for the first layer to 0.38 m for the 10th 167

layer (Shi et al., 2015). The number of soil layers can be reduced, and the thickness of 168 the deepest layer can be adjusted to match the depth to bedrock. If the bedrock is deeper 169 than the total thickness of 10 soil layers, one additional layer is added as needed. While 170 PIHM only simulates infiltration rate, lateral subsurface flow rate, and position of wa-171 ter table for all model grids, these variables are used as boundary conditions by the land 172 surface model to calculate transport within the unsaturated zone using the Richards equa-173 tion. A recent development is adding a topographic solar radiation module to Flux-PIHM 174 (Shi et al., 2018). Flux-PIHM is now the core landscape hydrology model for multiple 175 modeling systems. Detailed descriptions of PIHM and Flux-PIHM are provided by Qu 176 and Duffy (2007), and Shi et al. (2013, 2014, 2018). 177

2.2 Cycles

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Cycles is a one-dimensional process-based multi-year and multi-species agroecosys-179 tem model (Kemanian et al., 2022). Cycles evolved from C-Farm (Kemanian & Stöckle, 180 2010) and shares biophysical modules with CropSyst (Stöckle et al., 2014). Cycles sim-181 ulates the water and energy balance, the coupled cycling of carbon (C) and N, and plant 182 growth at daily time steps. Evapotranspiration is calculated based on the Penman-Monteith 183 equation. Transpiration is modulated by temperature, crop root distribution, soil wa-184 ter potential, and plant hydraulic properties (Campbell, 1985). Plant development is de-185 termined by thermal time, and plant growth is based on solar radiation interception (light 186 limited) or the realized transpiration (water limited) based on stomatal optimization the-187 ory (Cowan, 1978, 1982; Katul et al., 2009). Soil organic C and N cycling are based on 188 saturation theory (Kemanian & Stöckle, 2010; Pravia et al., 2019). The model can sim-189 ulate a wide range of perturbations of biogeochemical processes caused by management 190 practices such as tillage, irrigation, organic and inorganic nutrient additions, annual and 191 perennial crop selections, crop harvests as grain or forages, polycultures, relay cropping, 192 and grazing. Cycles can simulate unlimited plant species as specified by the user. 193

2.3 Cycles-L

Cycles-L (Fig. 1) takes the landscape and hydrology structure from Flux-PIHM and 195 most agroecosystem processes from Cycles. The surface energy balance and soil hydrol-196 ogy are simulated as in Flux-PIHM, except for plant water uptake, hydraulic lifting, and 197 the water balance of surface plant residues, which use Cycles' algorithms. Hydrologic pro-198 cesses are simulated with a sub-daily time step (usually $\sim 10^0$ minute, dynamic). Fol-199 lowing Cycles, each soil layer has texture- and organic matter-dependent hydraulic properties. However, when activating landscape hydrology, the properties of the soil profile 201 are averaged preserving total soil mass and porosity to allow solving for vertical and lat-202 eral fluxes using Flux-PIHM. Biogeochemical processes are simulated with a daily time 203 step independently for each soil layer. Tillage operations allow mixing all components of the soil layers affected by tillage. The one-dimensional Cycles model is integrated into 205 every Flux-PIHM model grid, therefore each model grid can be assigned with a unique 206 land cover or crop rotation. 207

A solute transport module is used to simulate subsurface nutrient transport. This model is the same as the subsurface transport in Flux-PIHM-BGC (Shi et al., 2018), and is used to calculate total solute flowing in or out of a model grid:

$$V_i \frac{\mathrm{d}}{\mathrm{d}t} \left(\Theta_i C_i\right) = \sum_j \left(-q_{ij} C_{ij}\right) + F,\tag{1}$$

where V_i is the subsurface prism volume of grid i (m³), C_i is the subsurface mineral N concentration (kg m⁻³), Θ_i is the volumetric soil water content (m³ m⁻³), q_{ij} is the lateral water flow at the subsurface between grid i and its neighbor at edge j (m³ s⁻¹), and F is a source/sink term of the corresponding solute (kg s⁻¹). In Cycles-L, the source/sink

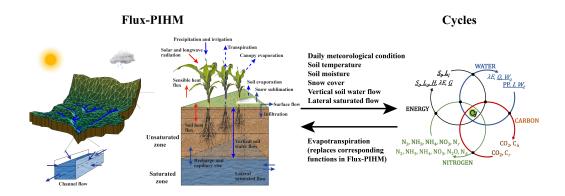


Figure 1. Schematic illustration of land surface and hydrologic processes simulated by Flux-PIHM; energy, water, carbon (C) and nitrogen (N) cycles simulated by Cycles with fluxes in and out for each component; and the coupling between Flux-PIHM and Cycles. For Cycles, the nodes at the arrows' intersections represent interactions between cycles; S_t and L_i are incoming shortwave and longwave radiation, S_r and L_o are outgoing shortwave and longwave radiation, H, λE , and G are sensible, latent, and ground heat fluxes, PP is precipitation, I is irrigation, W_t is capillary rise, Q is runoff, W_o is soil percolation or lateral flow, C_r and N_r are C and N changes caused by soil amendments, and C_h and N_h are harvested C and N. When coupled, the processes represented by dashed arrows in Flux-PIHM are simulated by Cycles, and the fluxes with underlines in Cycles are calculated by Flux-PIHM.

²¹⁶ terms for mineral N are:

and

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$$\frac{d}{dt}NH_{4}^{+}-N = NH_{4}^{+}-N_{f} + NH_{4}^{+}-N_{d} + NH_{4}^{+}-N_{\min} - NH_{4}^{+}-N_{nit} - NH_{4}^{+}-N_{min} - NH_{4}^{+}-N_{pup} - NH_{3}-N_{vol} - NH_{4}^{+}-N_{l} - NH_{4}^{+}-N_{r}$$
(2b)

(2a)

 $\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t}\mathrm{NO}_3^-\mathrm{N} &= \mathrm{NO}_3^-\mathrm{N}_f + \mathrm{NO}_3^-\mathrm{N}_d + \mathrm{NO}_3^-\mathrm{N}_{\mathrm{nit}} + \mathrm{NO}_3^-\mathrm{N}_{\mathrm{imm}} \\ &- \mathrm{NO}_3^-\mathrm{N}_{\mathrm{dnit}} - \mathrm{NO}_3^-\mathrm{N}_{\mathrm{pup}} - \mathrm{NO}_3^-\mathrm{N}_l - \mathrm{NO}_3^-\mathrm{N}_r \end{aligned}$

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where subscript f is for fertilizer, d for deposition, nit for nitrification, imm for microbial immobilization or microbial uptake, pup for plant uptake, dnit for denitrification, 223 l for leaching or percolation, r for runoff, min for mineralization of organic compounds 224 with N (many), and vol for volatilization as NH_3 -N. Note that $NO_3^--N_{nit}$ and $NH_4^+-N_{nit}$ 225 are the same, and NH_4^+ and NO_3^- are just N species identifiers. If the net water flow from 226 a grid is outward (net efflux from grid i to grid j) then the mineral N concentration (C_{ij}) 227 of the water flow (q_{ij}) is that of grid *i*: $C_{ij} = C_i$; otherwise, $C_{ij} = C_j$. In Flux-PIHM, 228 horizontal water flow is restricted to the saturated zone. But this horizontal flow is cal-229 ibrated to include the representation of lateral perched flow above unsaturated layers and 230 that flow can drag mineral N (M. R. Williams et al., 2015) or other solutes. This is dif-231 ficult to predict because it depends on the mixing between water flowing through macro-232 pores and water in the non-macropore soil matrix and the distribution of mineral N. To 233 account empirically for that transport, we tentatively assigned a weight function that 234 allows for mineral N transport from unsaturated layers. The weighting function is $\frac{K_r}{D-d_z}$. 235 where K_r is the relative hydraulic conductivity (hydraulic conductivity divided by sat-236 urated hydraulic conductivity), D is the total soil depth, and d_z is the depth of the cor-237 responding soil layer. This function is applied to all soil layers when calculating the av-238 erage concentration of soil mineral N, to emulate the horizontal transport of mineral N 239

in the shallower depths with higher hydraulic conductivities. Due to the very low hydraulic conductivity of dry layers, they contribute little to mineral N transport.

At the beginning of each simulation day, land surface processes are calculated first 242 using the Noah land surface model. Note that in Cycles-L, Noah LSM evapotranspira-243 tion functions are replaced by the corresponding Cycles functions. Cycles then applies 244 management operations and simulates vegetation, residue, and soil C and N processes, 245 using as input the daily meteorological conditions, soil temperature, soil moisture, and 246 snow cover informed by Flux-PIHM. Cycles passes evapotranspiration rate and N fluxes 247 as source/sink terms in water and N transport. Then, Flux-PIHM calculates the trans-248 port of water and N for the entire domain using sub-daily time steps. 249

²⁵⁰ 3 Site and data

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3.1 Description of the WE-38 watershed

The WE-38 watershed is a 7.3 km² first-order watershed within the Mahantango 252 Creek Watershed in Pennsylvania's Northumberland county (Fig. 2a). Elevation ranges 253 from 503 m at the northernmost ridge to about 214 m near the southern outlet. The land 254 cover comprises cultivated land (55%), followed by forests (40%), pasture (3%), and de-255 veloped area (2%). The watershed contains more than 300 farm fields. Surveys and in-256 terviews were used to obtain field-specific operations (Veith et al., 2015) that documented 257 crop species, planting and harvesting dates, tillage tools and operation dates, and syn-258 thetic fertilizer and animal manure application rates and dates. The watershed has been 259 the focus of rigorous research on agricultural management and monitoring of water qual-260 ity (Pionke et al., 2000; Bryant et al., 2011; Buda et al., 2011; Church et al., 2011; Lu 261 et al., 2015; Veith et al., 2015), and long-term discharge and water quality measurements, 262 including NO_3^- -N and NH_4^+ -N, are publicly available. 263

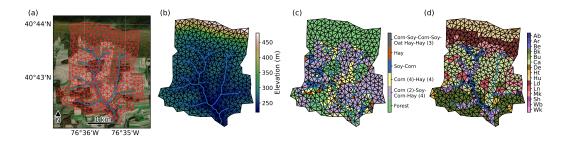


Figure 2. (a) WE-38 model domain projected onto an aerial photograph of the watershed. The red triangles represent the model grids and the blue lines represent river segments. (b) Surface elevation map of the WE-38 model domain. (c) Land use and crop rotations in the WE-38 model grids. (d) SSURGO soil map projected onto WE-38 model grids, with each color representing one unique soil type. The soil series are Albrights silt loam (Ab), Alvira silt loam (Ar), Bedington silt loam (Be), Berks channery silt loam (Bk), Buchanan channery loam (Bu), Calvin-Klinesville shaly silt loams (Ca), Dekalb very channery sandy loam (De), Hartleton channery silt loam (Ht), Hazleton and Clymer extremely stony sandy loams (Hu), Laidig and Meckesville extremely stony soils (Ld), Leck kill shaly silt loam (Ln), Meckesville silt loam (Mk), Shelmadine silt loam (Sh), Watson silt loam (Wb), and Weikert and Klinesville shaly silt loams (Wk).

3.2 Domain and model setup

The Cycles-L WE-38 model physical domain consists of 114 segments represent-265 ing the stream network (average 98-m long) and 883 triangular grids (average 0.83 ha), 266 of which 522 triangular grids are cropland (Fig. 2). The watershed drainage network was 267 mapped using the Terrain Analysis Using Digital Elevation Models tool (TauDEM; Tar-268 boton et al., 2009; Tarboton, 2015) on a digital elevation model (DEM) obtained from 269 light detection and ranging (lidar) data and color orthophotography at horizontal and 270 vertical resolutions of 0.5 and 0.15 m, respectively (Bryant et al., 2011). Afterwards, the 271 drainage network was updated by overlapping the TauDEM analysis results with a geo-272 referenced orthomosaic of the watershed obtained from the Pennsylvania Spatial Data 273 Access (PASDA, 2022). 274

To represent field operations, we converted the database used for WE-38 in Hirt 275 et al. (2020) to Cycles-L inputs. This database aggregates field operations history by crop 276 in the rotation. These rotations and associated field operations were projected on the 277 Cycles-L WE-38 model domain (Fig. 2c). Model grids were assigned to one of six land 278 uses: deciduous forest, a corn (2 years)-soybean-corn-hay (4 years) rotation, a corn (4 years)-279 hay (4 years) rotation, a soybean-corn rotation, a hay rotation, and a corn-soybean-corn-280 soybean-oat hay-hay (3 years) rotation. Hay was simulated as a mixture of 1/3 alfalfa 281 and 2/3 orchardgrass. Deciduous forest is the most common land use type, while the corn 282 (2 years)-soybean-corn-hay (4 years) rotation is the most common crop rotation. The 283 operations for each crop are listed in Table 1. 284

To prevent an unrealistic rotation synchrony in grids with the same rotation, we randomly assigned a different starting point in the rotation to each grid within the assigned rotation. For example, for the model grids with the soybean-corn rotation, we randomly assigned half of those grids to start with soybean, and the other half to start with corn.

The soil properties texture, organic matter, and bulk density (by layer) were extracted from the SSURGO database projected to the model domain (Fig. 2d); 15 unique soil series were identified for the watershed. The meteorological forcing (precipitation, air temperature, humidity, wind speed, downward solar radiation, downward longwave radiation, and air pressure) were obtained from the North American Land Data Assimilation System Phase 2 (NLDAS-2; Xia et al., 2012) forcing data, which provides data at hourly time-step and is suitable for hydrologic simulations.

For model testing, annual crop yields were downloaded from the The United States Department of Agriculture (USDA) National Agricultural Statistics Service (NASS) at county level (Northumberland county) and compared with both Cycles 1-D and Cycles-L for the entire watershed.

The simulation period was 16 years from 0000 UTC 1 January 2000 to 0000 UTC 301 1 January 2016. Setting up the model requires spin-up to stabilize hydrological and bio-302 geochemical soil properties. The spin-up process was divided into two, one for hydrol-303 ogy and one for soil variables. Because running Cycles-L is more computationally ex-304 pensive than Flux-PIHM, we first ran Flux-PIHM for land surface hydrological param-305 306 eter calibration and hydrological state spin-up. When running Flux-PIHM, the forest was simulated as the deciduous forest NLCD land cover type, the hay rotation was sim-307 ulated as the pasture/hay land cover type, and all other crop rotations were simulated 308 as the cultivated crop land cover type. The leaf area index (LAI) forcing was prescribed 309 monthly climatological LAI that depends on land cover types. Flux-PIHM hydrologic 310 and land surface parameters were manually calibrated using the observed discharge data 311 from 2000 to 2011. Model parameters that affect horizontal flow and key parameters iden-312 tified from Flux-PIHM sensitivity analyses (Shi et al., 2014; Xiao et al., 2019) were ad-313 justed, including vertical and horizontal saturated hydraulic conductivities, vertical and 314

Opearation	Day of year	Fertilizer mass (kg ha^{-1})	Fertilizer N-P-K
	Co	rn	
Manure fertilizer	100	3500	03-01-00
Tillage moldboard	101		
Tillage disking	102		
Planting	121		
Fertilization	121	100	10-20-20
Fertilization	152	100	33-00-00
Harvest and kill crop			
	\mathbf{Soyb}	ean	
Manure fertilizer	100	1875	03-01-00
Tillage disking	102		
Planting	121		
Harvest and kill			
	Oat fo	r hay	
Tillage chisel $+$ cultivator	92		
Planting	97		
Fertilization	97	300	03 - 15 - 48
Fertilization	166	100	33-00-00
Harvest and kill	219		
Hay (a	alfalfa + orch	nardgrass for hay)	
Tillage (year 1)	101		
Planting (year 1)	105		
Fertilization manure (year 1)	100	3500	03-01-00
Fertilization (year 1)	259	100	02-11-45
Clipping and having (4 times)	Various		
Fertilization all years (4 times)	Various	100	02-11-45
Kill (year 4)	303		

Table 1. Field operations for crops in the rotation. The N-P-K refers to the proportion of N, P, and K in the dry mass. For manure, 25% of N is added as NH_4^+ and 75% as organic N with C:N ratio of 14. For hay, fertilization follows after a clipping and having event.

horizontal saturated macropore hydraulic conductivities, macropore depth, soil porosity, van Genuchten parameters, and canopy stomatal conductance. After calibration, land
surface and hydrological states were spun up by recycling the meteorological forcing. Hydrological states are considered steady when the change of watershed average groundwater storage is lower than 1 cm between the beginning and end of a simulation cycle.
Steady state condition was reached in 32 years, which required recycling the meteorological forcing twice.

The land surface hydrological state variables after the spin-up were used to initialize the Cycles-L spin-up process. The Cycles-L model was run repeatedly by recycling the 16-year meteorological forcing and prescribed farm operations until the change of soil profile organic carbon was lower than 0.01 Mg ha⁻¹. Cycles-L reached steady state conditions after 11 simulation cycles, i.e., 167 simulation years.

We calibrated the crop model using the USDA-NASS survey corn yield by adjust-327 ing crop ecophysiological parameters that are site-dependent (rooting depth) and two 328 related parameters that regulate growth potential, the radiation use efficiency (g of biomass 329 accrued per MJ of radiation intercepted) and transpiration use efficiency (g of biomass 330 accrued per kg of water transpired). The last two parameters were reduced to 2/3 of their 331 default values, to represent in a simplified way limitations to growth not accounted for 332 in the input data (shallower soils or compacted layers) or in the model (deficient root 333 exploration due to rocks); the watershed soils can have locally high rock content (Saha 334 et al., 2017). Overestimating yields can severely alter outputs mostly by increasing nu-335 trient extraction in harvested grain or forage. 336

Uncoupled Cycles simulations were performed to compare with Cycles-L outputs. 337 The Cycles 1-D simulations used the most dominant soil type Calvin-Klinesville shaly 338 silt loams (Ca), and the most prevailing crop rotation [corn (2 years)-soybean-corn-hay 339 (4 years)]. As in Cycles-L, we ran four Cycles simulations, starting with different crops 340 in the rotation, i.e., a corn (2 years)-soybean-corn-hay (4 years) simulation, a soybean-341 corn-hay (4 years)-corn (2 years) simulation, a hay (4 years)-corn (2 years)-soybean-corn 342 simulation, and a hay (2 years)-corn (2 years)-soybean-corn-hay (2 years) simulation. Re-343 sults from the four simulations were averaged to be compared with Cycles-L. 344

345 4 Results

346

4.1 Simulation of stream discharge

Model simulation results from 2000 to 2015 after spin-up are presented below, and evaluated using field measurements or surveys.

Cycles-L captured the interannual variability of discharge, and accurately predicted 349 the timing of most discharge events. The base flow rate predicted by Cycles-L compared 350 well with observations. The Nash-Sutcliffe coefficient (NSE) of daily discharge for the 351 entire simulation period was 0.55. The NSE, however, varied from year to year, and was 352 as high as 0.85 in 2005. Discharge from multiple years was also averaged to each day of 353 year to glean within-year patterns of measured and modeled discharge (Fig. 3b). The 354 model captured the seasonal wet-dry cycles, and the predicted magnitude of discharge 355 generally agreed well with observation. Cycles-L slightly overestimated discharge, ex-356 cept for late winter and spring. The NSE for the predicted multi-year average discharge 357 was 0.68. 358

Flux-PIHM prediction was similar to Cycles-L (Fig. 3a) because both of them share the same hydrologic component but canopy cover is endogenous in Cycles-L and a forcing in Flux-PIHM. The NSE for Flux-PIHM daily discharge prediction was 0.60, which was slightly higher than Cycles-L (0.55). It should be noted that the land surface and hydrologic parameters in Cycles-L were calibrated by running Flux-PIHM, which may

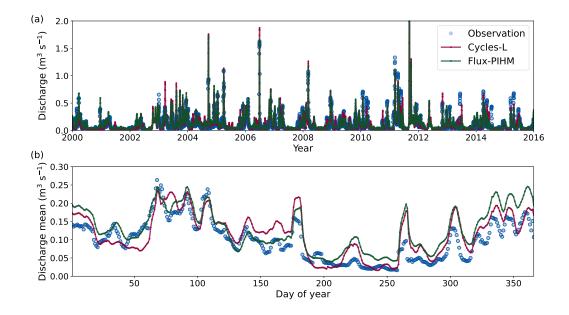


Figure 3. (a) Comparison of daily discharge between observations and outputs from Cycles-L and Flux-PIHM, from 1 Jan 2000 to 31 Dec 2015. (b) Comparison of daily discharge when averaged to each day of year.

cause Flux-PIHM to yield slightly better performance than Cycles-L. When averaged to
 each day of year, Flux-PIHM also tended to overestimate discharge. Compared to Cy cles-L, Flux-PIHM produced higher predictions of discharge in spring, and lower predic tions in other seasons.

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4.2 Simulation of grain yield

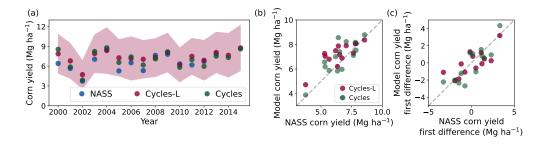


Figure 4. (a) Temporal variation of USDA-NASS survey corn yield and both Cycles-L and Cycles 1-D predicted annual average corn yield from 2000 to 2015. The USDA-NASS survey is for Northumberland County, PA. The shaded area represents the standard deviations of corn yield in space. (b) Cycles-L and Cycles 1-D predicted annual average corn yield versus USDA-NASS survey annual corn yield. (c) First difference of Cycles-L and Cycles 1-D predicted annual average corn yield versus first difference of USDA-NASS survey annual corn yield.

³⁶⁹ On average, both Cycles-L and Cycles captured the corn yield variation well (Fig. 4), ³⁷⁰ with R^2 of 0.66 for Cycles-L and 0.65 for Cycles, and root mean square error (RMSE) ³⁷¹ of 1.01 and 0.90 Mg ha⁻¹ for Cycles-L and Cycles, respectively. When comparing the

first differences of corn yield, which detrend yield increases with time due to technology, 372 the R^2 for Cycles-L decreased to 0.58 and that for Cycles increased to 0.72. Cycles-L 373 tended to underestimate the interannual variability compared to Cycles (Fig. 4c). The 374 shaded area in Fig. 4(a) illustrates the spatial variation of corn grain yield predicted by 375 Cycles-L. The spatial variation of corn yield was larger when yield was higher, and smaller 376 when yield was lower. The standard deviations of corn yield in space varied between 2.2 377 and 3.5 Mg ha^{-1} . The USDA-NASS survey reported yields were always within the pre-378 dicted one-standard-deviation (Fig. 4a). 379

4.3 Simulation of mineral nitrogen discharge

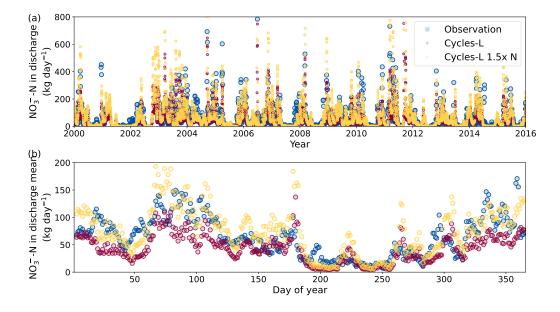


Figure 5. (a) Comparison of daily nitrate-N discharge between the observations and two Cycles-L simulations (1x N and 1.5x N), from 1 Jan 2000 to 31 Dec 2015. (b) Comparison of daily nitrate-N discharge when averaged to each day of year. When averaged to each day of year, a 3-day moving average was applied to both observations and predictions to better reveal the temporal patterns.

We focused on the N exported at the watershed outlet, where comparisons with measurements allow a reality-bounded assessment of the impact of changing N fertilization rates. The temporal patterns of water discharge (Fig. 3) and N discharge (Fig. 5) are similar, because N discharge is controlled by water discharge. Accordingly, the N discharge pattern was correctly simulated by Cycles-L with an NSE of 0.58, but the N mass discharged through the stream was consistently underestimated compared with measurements (Fig. 5). The observed and predicted average NO₃⁻-N discharge were 63.8 and 46.1 kg day⁻¹.

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4.4 Simulation of mineral nitrogen concentration in the stream

Because the stream discharge was slightly overestimated and NO_3^- -N underestimated, the concentration of NO_3^- -N was also underestimated, as was the seasonal variation in NO_3^- -N concentration (Fig. 6). The average observed NO_3^- -N concentration in the stream was 5.4 mg L⁻¹, with a pronounced W-shaped seasonal pattern with highs in early summer and in winter, and lows in spring and autumn (Fig. 6b). Interannual variability was also noticeable. The simulations consistently underestimated the concentration of NO_3^- -N,

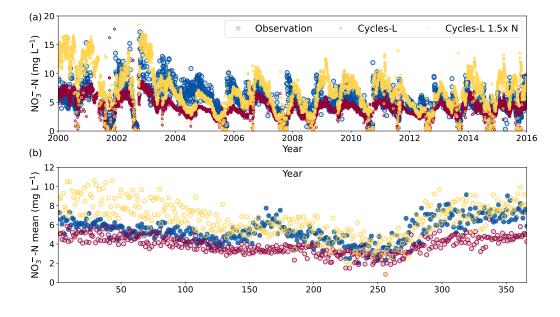


Figure 6. (a) Comparison of daily stream nitrate-N concentrations between observations and two Cycles-L simulations (1x N and 1.5x N), from 1 Jan 2000 to 31 Dec 2015. (b) Comparison of daily nitrate-N concentrations when averaged to each day of year.

on average by about 30%, and significantly underestimated the magnitude of seasonal variations.

4.5 Spatial pattern of simulated nitrogen fluxes

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Table 2. Simulated and observed nitrogen fluxes. All fluxes are watershed annual average.

N flux	Cycles-L	Cycles-L 1.25xN (kg ha ⁻		Observed
Fixation and deposition	45.0	41.9	38.7	N/A
Fertilization (manure)	54.8	68.4	82.2	N/A
Fertilization (synthetic)	30.2	37.8	45.3	N/A
Volatilization	9.4	10.6	11.8	N/A
Denitrification	8.4	10.7	13.3	N/A
N_2O emission from nitrification	0.5	0.6	0.7	N/A
N in Harvest	77.3	83.7	89.1	N/A
N in discharge	22.7	29.9	38.8	31.4

Since the model has been run to steady state, the change of N storage in the system was low. On average, most N removals other than discharge occurred through N harvest, NH₃-N volatilization, and NO_3^- -N denitrification (Table 2).

Due to the distribution of the cropland and forestland, N inputs had a marked spatial distribution (Fig. 7). Yet, the spatial patterns of N losses were also shaped by topography and soils that alter hydrology. The spatial pattern of N input was clearly controlled by crop management. Forests and the areas with the hay rotation have low N in-

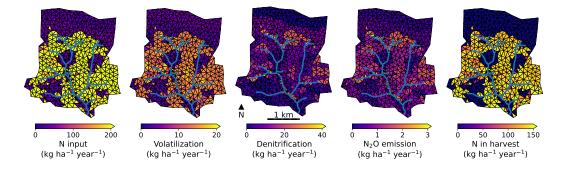


Figure 7. Spatial patterns of nitrogen fluxes (nitrogen input, nitrogen volatilization, denitrification, N_2O emission, and nitrogen in harvest) as predicted by Cycles-L. For each model grid, the fluxes were averaged over the whole simulation period. The dotted areas represent the forests and areas with the hay rotation. The blue lines represent river segments.

put because there was no fertilization but only deposition and biological fixation. The 405 spatial pattern of NH₃-N volatilization was highly correlated with the pattern of fertil-406 ization. The spatial patterns of denitrification and N_2O emission demonstrate the complex interactions between crop management and topography. The forests had a lower den-408 itrification rate (and N_2O emission) compared to areas with crop rotations. For the ar-409 eas with crop rotations, denitrification rates (and N_2O emission) were higher in head-410 waters and some regions of convergent flow or flat terrain near the stream (but not all), 411 where soil water content was higher. Nitrogen harvest was largest in areas with a high 412 frequency of corn and soybean. 413

$_{414}$ 5 Discussion

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5.1 Simulating hydrology

Cycles-L captured the interannual variability of discharge, and accurately predicted 416 the timing of peak discharge events and base flow rates with minimum manual calibra-417 tion. This is in line with the high fidelity of the PIHM family models demonstrated for 418 multiple watersheds (Shi et al., 2013, 2015; Jepsen et al., 2016; Crow et al., 2018; Zhang 419 et al., 2018; Xiao et al., 2019; Zheng et al., 2021). Among the desirable future improve-420 ments are to represent explicitly perched water movement on top of Bt horizons, which 421 would allow lateral water transport overlaying unsaturated soil layers. Currently, this 422 process is lumped in the lateral flow calibration parameters. While modeling it explic-423 itly may not improve the overall accuracy of discharge predictions, it may affect min-424 eral N (and other constituents) transport. Similar considerations apply to modeling water flux through tile drains, with the practical caveat that the location of tile drains is 426 often unknown. When the tile drain network is well mapped it can be explicitly simu-427 lated although at the cost of a very dense grid (De Schepper et al., 2015). Nonetheless, 428 while the model performs well in its current formulation, future developments should in-429 clude an explicit representation of tile drains as submerged channels that interact with 430 groundwater. 431

Compared with other spatially distributed agroecosystem hydrological systems, which
usually have rigid rectangular model grids, the unstructured triangular grids of Cycles-L
provides both computational efficiency and optimal representations of local heterogeneity. Unstructured triangular grids capture with ease watershed boundaries, stream networks, and soil and vegetation units (Qu & Duffy, 2007; Kumar et al., 2010; De Schepper et al., 2015). Because grid sizes can differ in Cycles-L, coarser grids can be used in

locations with simple topography and low land surface heterogeneity to improve model 438 efficiency, while finer grids can be used to capture complex topography and spatial het-439 erogeneity in soil and vegetation, an approach that is already suggested by the unstruc-440 tured mesh used to represent tile drains by De Schepper et al. (2015). These features 441 enable applications for precision agriculture in a cohesive framework. Cycles-L's unique 442 capability to simulate the two-way interaction between stream and riparian zones makes 443 it extremely useful to evaluate interventions in agricultural areas along floodplains where 444 flooding damage risk is high (Collins et al., 2022). 445

5.2 Simulating nitrogen discharge and concentration

446

When using the fertilization rate as prescribed by the survey data (Hirt et al., 2020), 447 the model prediction of water discharge and corn yield agreed well with the observations 448 and survey (Figures 3 and 4), but underestimated the stream NO_3^- -N concentration and 449 NO_3^- -N discharge (Figures 5 and 6). The discharge underestimation amounted to 9.7 kg ha⁻¹ y⁻¹ 450 of N (Table 2). Among the possible reasons are that the model is overestimating other 451 N losses or that N inputs are underreported. Therefore, we ran exploratory Cycles-L sim-452 ulations with arbitrary N input increases of 25% (not shown in the figures) and 50% over 453 the survey data (hereafter, Cycles-L 1.25x N and Cycles-L 1.5x N simulations). 454

The NO_3^- -N in discharge predicted by the Cycles-L 1.5x N simulation was higher 455 than the observed discharge (+7.4 over the observed 31.4 kg NO_3^- -N ha⁻¹ y⁻¹) but closer 456 to that in the default simulation; the NO_3^- -N in discharge predicted with Cycles-L 1.25x N 457 almost matched the observed discharge (Table 2). Although the 1.5x N simulation over-458 estimated stream NO_3^- -N concentration in winter and spring, deviations in multi-year 459 average N discharge for this time period were small, because the model's underestima-460 tion of water discharge for the same time period (Fig. 3b) compensated for deviations 461 in NO_3^- -N concentration. The 1.5x N simulation substantially overestimated NO_3^- -N con-462 centration in 2000 and 2001 and underestimated it in 2003 and 2004 (Fig. 6). For other 463 years, the predicted NO_3^- -N concentration agreed well with observations, especially for 464 the second half of the simulation (from 2008 to 2016), despite missing some peaks. When 465 averaged to each day of year, the model captured the seasonal variation of NO_3^- -N con-466 centration change, but overestimated the concentration in late winter and early spring 467 (Fig. 6b). 468

The Cycles-L 1x N, 1.25x N, and 1.5x N simulations produced almost identical corn 469 yield and water discharge. It suggests that crop growth was not N limited in WE-38 even 470 when using the 1x fertilization rate. Because crop growth was similar between the two 471 simulations, evapotranspiration simulations were close as well, hydrology was not affected, 472 and the three simulations produced similar stream discharge. Adding more N fertilizer, 473 however, increased stream N concentration. It should be noted that adding 50% more 474 N fertilizer did not increase N inputs to the watershed proportionally because of a par-475 allel reduction in N biological fixation of 6.3 kg ha⁻¹ y⁻¹ of N (Table 2). If we were to assume that indeed, inputs of N were underestimated, and that they would scale linearly 477 between our 1x and 1.5x simulations, we estimate that N inputs obtained through sur-478 veys were underestimated by 25 to 30%. 479

As in Ator and Garcia (2016), denitrification was a significant loss pathway. When 480 spatially averaged over the whole simulation period (from 2000 to 2015), denitrification 481 rates generally increased as N input increased within each crop rotation type (Fig. 8), 482 but strong variation existed depending on the rotation and field location. There seems 483 to be a correlation between well drained locations and the location of corn and soybean 484 in the field (Fig. 2), likely reflecting producers' choices that facilitate field operations in 485 cash crops, which may result in lesser than expected N denitrification losses in those fields 486 (Fig. 8). However, NO_3^- -N is transported mostly through groundwater, and grids that 487 gain NO_3^- -N through leaching from other grids may have higher denitrification rates than 488

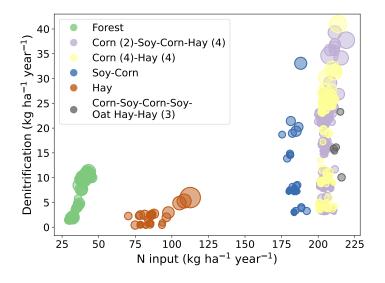


Figure 8. Average denitrification rate vs average nitrogen input as predicted by Cycles-L. Each circle represents one model grid, averaged over the whole simulation period. The sizes of the circles represent the degrees of soil saturation. Different colors represent different land uses/crop rotations.

those expected based only on surface N input. While forests and hay fields have lower 489 N input than the other crop rotations, most cropping model grids have average N input 490 between 175 and 225 kg ha⁻¹ y⁻¹, but their simulated denitrification rates varied sig-491 nificantly, from around 5 to 40 kg NO_3^- -N ha⁻¹ y⁻¹, in large part due to hydrological 492 control of leaching and denitrification. The movement of water alters both NO_3^- -N and 493 oxygen availability in space, which leads to significantly different spatial denitrification 494 rates (Groffman et al., 2009). Within each crop rotation type, denitrification rates tend 495 to increase when soil wetness increases (represented by the circles' size in Fig. 8), which 496 reflects the dominant control of oxygen on denitrification rates in the model (i.e., air filled 497 pore space decreases and so does oxygen replenishment). The importance of represent-498 ing these spatial interactions to model hot spots and hot moments of denitrification has 499 been highlighted earlier by Groffman et al. (2009) and measured in the field by Saha et 500 al. (2017). Our modeling framework advances in that direction. Improvements are needed 501 to represent denitrification in stream sediments and to include physical features such as 502 the specific location of buried carbon sources (Hill et al., 2014), to further refine our un-503 derstanding and modeling of denitrification spatial distribution (Wallace et al., 2020). 504

505

5.3 Strength of Cycles-L and opportunities for improvement

Because of its spatially distributed nature, Cycles-L represents a step forward to 506 simulate landscape level processes such as groundwater and stream water transport of 507 reactive N and other compounds as affected by crop rotation, soil type, and weather vari-508 ations within the watershed domain. It can also represent the heterogeneity of agroe-509 cosystem processes caused by topography, soil heterogeneity, and management practices, 510 owing to its physically-based hydrologic component and ability to simulate horizontal 511 and vertical transport of mineral N with water. By extension, other nutrients like sol-512 uble phosphorus (McConnell et al., 2020), dissolved organic C (Pabich et al., 2001), and 513 agrochemicals (Hladik & Kolpin, 2015) can be integrated in the same framework. 514

Cycles-L can be an important tool to evaluate costly interventions in silico before 515 deployment in the field, as complex interactions among subsurface, land surface, and crops 516 can be explored before committing resources on the ground, as exemplified by a com-517 parable model using a square grid domain (Beaujouan et al., 2001). Similarly, Cycles-L 518 can become a powerful tool for precision agriculture and precision conservation, becom-519 ing a core component of artificial intelligence applications (Gil et al., 2021). The spa-520 tial and temporal richness of the model outputs coupled with immersive visuals open new 521 opportunities to represent the dynamics of agroecosystems to develop research, educa-522 tional, and public engagement tools (C. Wang et al., 2019). 523

Comparing Cycles 1-D average corn yield with county-level yield averages, a coarse 524 comparison due to the amalgamation of disparate scales, indicates that overall Cycles 525 correctly captures the effect of interannual variations in weather on crop yield. So do other 526 1-D cropping system models applied in the region (Castaño-Sánchez et al., 2020). Cy-527 cles-L did not improve upon these results, although the comparison scope is limited to 528 this small watershed. The simulations with Cycles-L increased the minimum yield most 529 likely due to redistribution of subsurface water in drier years. It remains to be tested if 530 an even finer resolution (smaller triangles) would render a better representation of hy-531 drology and crop growth and yield. Such finer resolution would also require using dense, 532 grid-specific soil input information. While such soil information might not be available, 533 yield maps that would allow such testing are already regularly available, and assessing the effect of a finer resolution in representing certain processes is needed to advance ap-535 plications in precision agriculture. 536

Macropore flow in Flux-PIHM lumps vertical bypass flow, but also fast lateral flow 537 538 of perched water that reaches the stream with lesser mixing with water in the non-saturated soil matrix. In this watershed, measurements have revealed that water can reach streams 539 through ephemeral springs that exfiltrate after lateral transport (Redder et al., 2021), 540 and that water can have high concentration of NO_3^- -N that reflects limited mixing with 541 groundwater (M. R. Williams et al., 2015). When measuring in-stream NO_3^--N concen-542 tration, this spring contribution of water and NO_3^- -N can cause spikier readings in stream 543 NO_3^- -N concentration than when water reaching the stream is mixed with groundwa-544 ter, and is the case for Flux-PIHM (except for direct runoff). This is clearly difficult to 545 represent with lumped parameters, which can help explain the subdued variation in the 546 modeled versus measured NO_3^- -N concentration in the stream (Fig. 6). 547

The quality of Cycles-L predictions depends on both model structure and input data 548 quality. To represent, for example, large N discharge events, accurate input of the amount, 549 timing, and composition of the N amendments is critical. However, the composition of 550 animal manure is highly variable (Griffin et al., 2005), so that there is an inherent vari-551 ance in the addition of N and other nutrients to fields or watersheds via manure. In this 552 study, manure N input represented 42% of the N input in the 1x N scenario (Table 2), 553 and was on average twice as large as the NO_3^- -N watershed discharge. In addition, for 554 the simulations presented here, the prescribed management practices have the same plant-555 ing dates, tillage dates and practices, and fertilization dates and rates every year, which 556 are approximately correct on average but likely incorrect in any given year of the 16-year 557 simulation period. Therefore using the surveyed management data introduces uncertainty 558 559 that would reflect in deviations of stream flow and especially NO_3^- -N concentration (Fig. 6) independently of the model algorithms. The underestimation of NO_3^- -N discharge when 560 using survey data to represent fertilizer inputs (1x) and the improvement through the 561 modeled 1.25x and 1.5x scenarios suggest that N inputs through fertilizer could have been 562 underestimated on average by 30%. Indeed, a mismatch between field survey data on 563 N (and phosphorus) input and that needed to match crop yield and other variables has been reported before (USDA-NRCS, 2012, page 30). 565

⁵⁶⁶ Cycles-L couples a hydrologic model (PIHM), land surface model (Noah LSM), and ⁵⁶⁷ agroecosystem model (Cycles) together. The interactions among these components are complex and the number of parameters involved is large even when using a conservative approach for model development. Parameter sensitivity in Flux-PIHM has been examined in previous studies (Shi et al., 2014; Xiao et al., 2019), which revealed complex interactions among model parameters and between land surface-subsurface processes that are inherited in Cycles-L. Sensitivity analysis of Cycles-L can help identify critical model parameterization and reveal any potential dependence of model results on grid resolution.

Operationally, it is simple to set up and run 1-D models like a stand alone Cycles 575 1-D with standardized inputs. Once the soil profile and weather forcing are formatted 576 to conform to requirements, there is no impediment to run the model. Setting up and 577 running 3-D models is less straightforward. While the generation of input files, grid and 578 stream network has been automated in the past for CONUS to provide users a starting 579 point at the HUC12 level (Leonard & Duffy, 2014), automation does not warrant that 580 the setup provides a stable frame to represent hydrology. Often, the grid and stream net-581 work setup needs to be streamlined to secure convergence of fluxes and state variables 582 or to avoid resorting to small time steps that slow down execution. However, once a set 583 up is ready, it can be stored, shared, and re-used efficiently, and support running new 584 scenarios or applications that need to combine measurements and modeling (e.g., Drake 585 et al., 2018) with agility. 586

587 6 Conclusions

Cycles-L is among the first next generation physically-based spatially-distributed agroecosystem models that can represent landscape processes. The coupling of biogeochemical and hydrologic processes at the catchment scale places this model between 1-D models that simplify terrain and other attributes, and global models that connect atmospheric volumes in 3-D but are underlined by simplified land models. Cycles-L occupies therefore a unique operational space relevant to simulate interventions in the landscape.

In the test case presented here for Central Pennsylvania, Cycles-L simulated well 595 hydrology, grain crops yield, and N exports in the stream, despite some uncertainty in 596 the quality of the input data. Cycles-L retains, therefore, the strengths of Flux-PIHM 597 (Shi et al., 2013) and the 1-D Cycles model (Kemanian et al., 2022). Compared to the 598 uncoupled Flux-PIHM (water discharge) and Cycles (crop yield) models, the predictions 599 of Cycles-L are as good if not improved. The model skill at predicting the impact of to-600 pography, soil heterogeneity, and crop management on N fluxes temporally and spatially 601 can expand the domain of *in silico* agroecosystem analysis to landscape levels. 602

Further progress will depend on continuously balancing the complexity of the model algorithms with concomitant improvements in input quality, to take advantage of increasing computing capacity and to represent landscapes with increasing fidelity. We envision that tools like Cycles-L will become a critical component of the analytical toolkit of both academic and non-academic communities.

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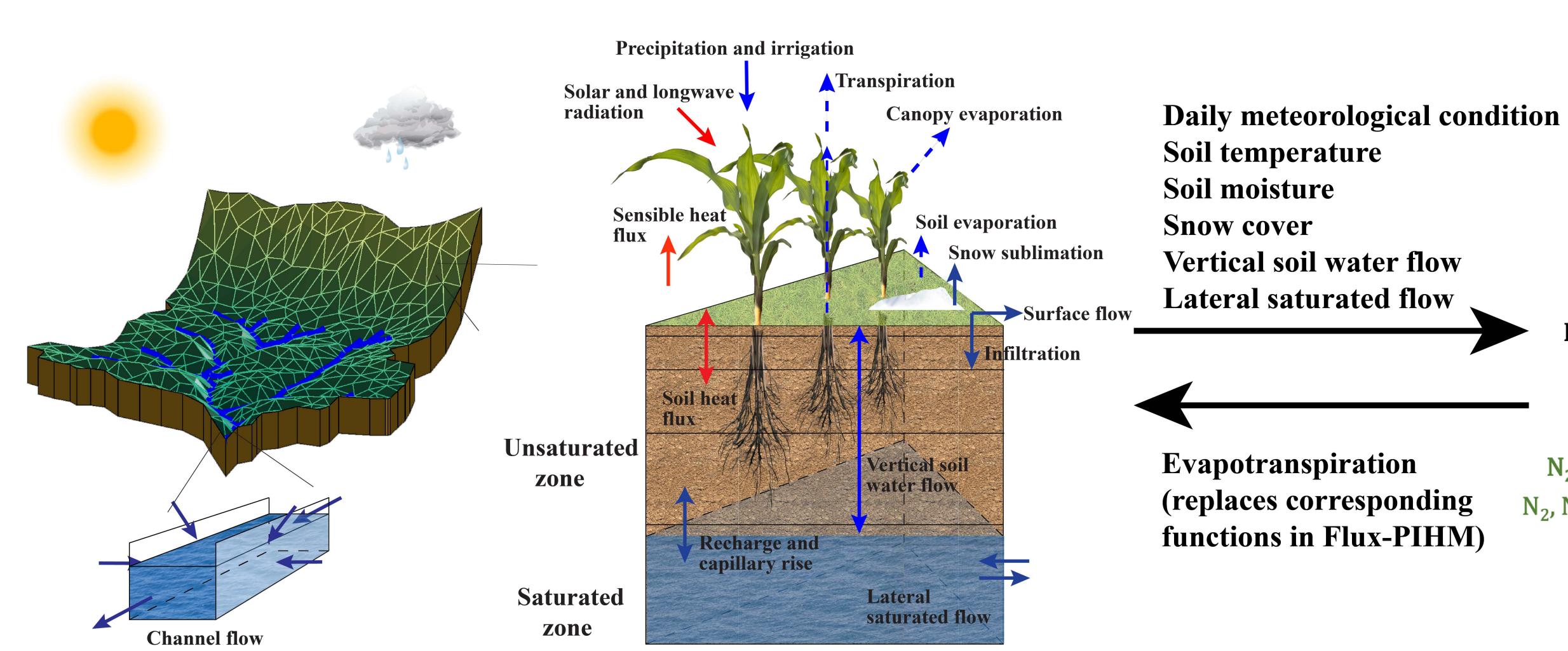
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Figure 1.

Flux-PIHM



Cycles



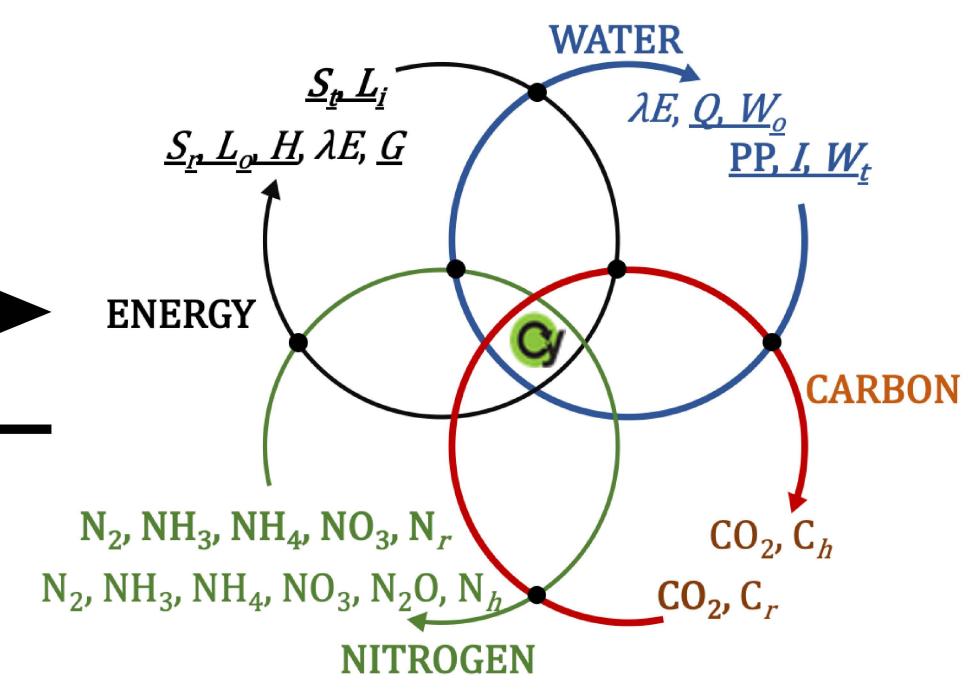
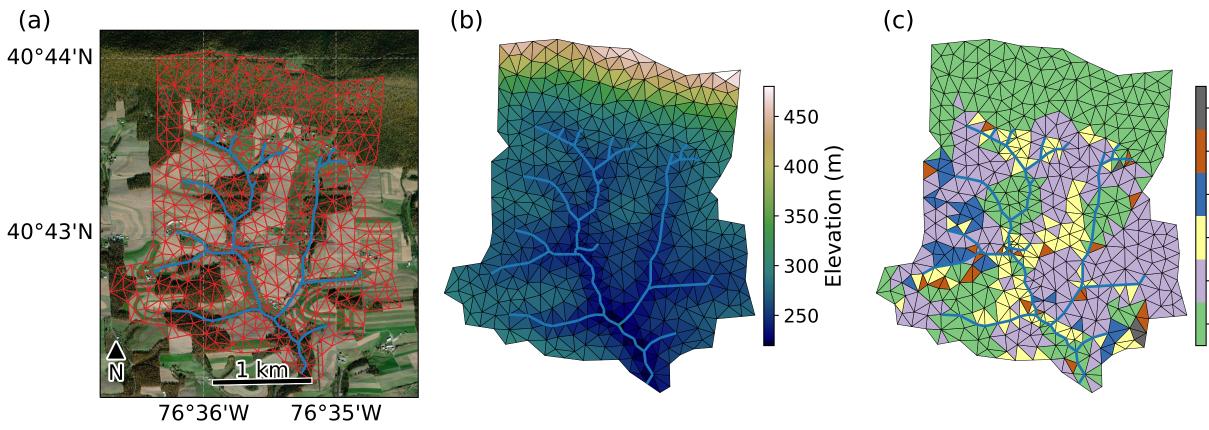


Figure 2.



(d)

Corn-Soy-Corn-Soy-Oat Hay-Hay (3)

- Hay

- Soy-Corn

- Corn (4)-Hay (4)

Corn (2)-Soy-Corn-Hay (4)

Forest

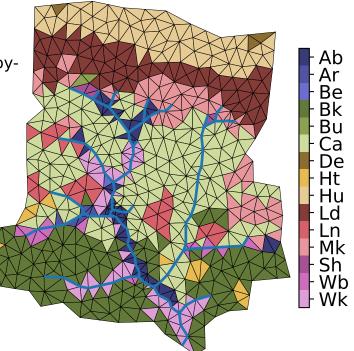
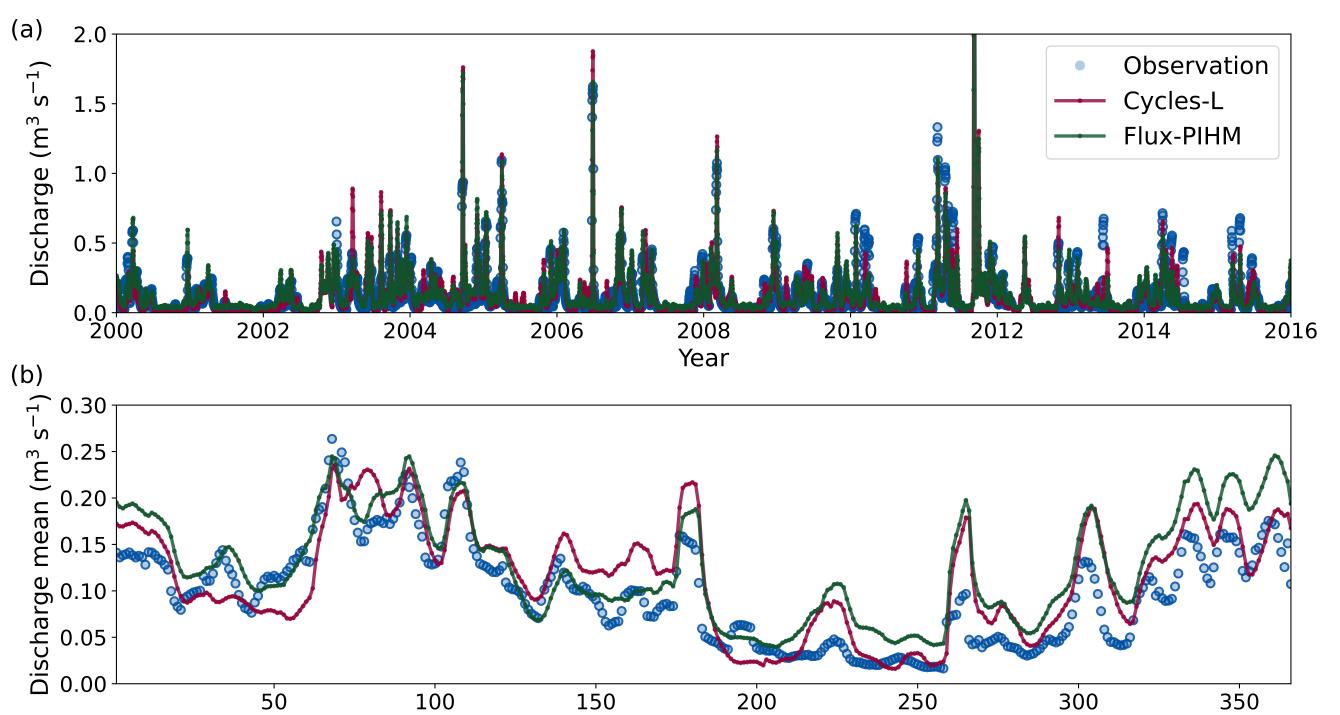


Figure 3.



Day of year

Figure 4.

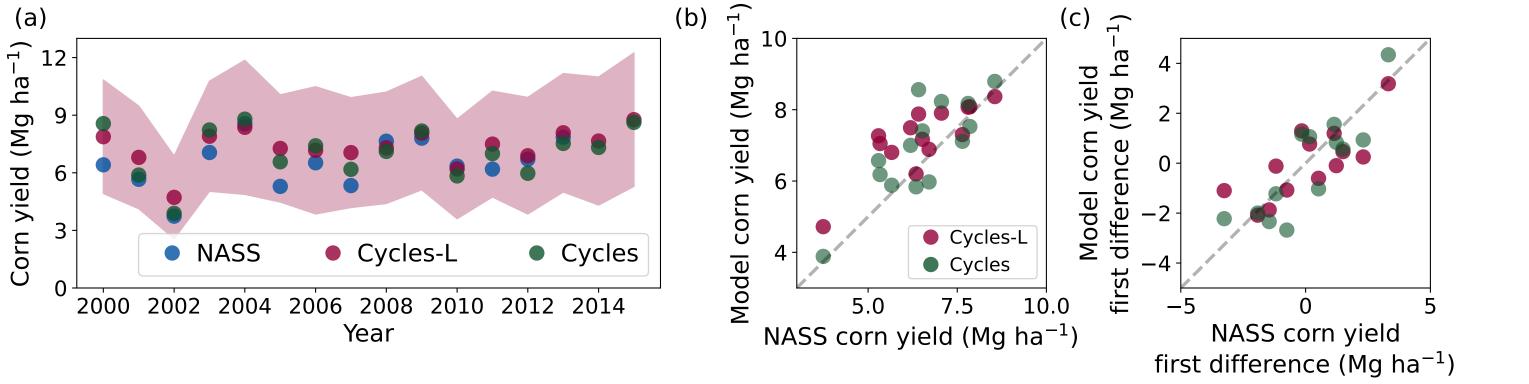


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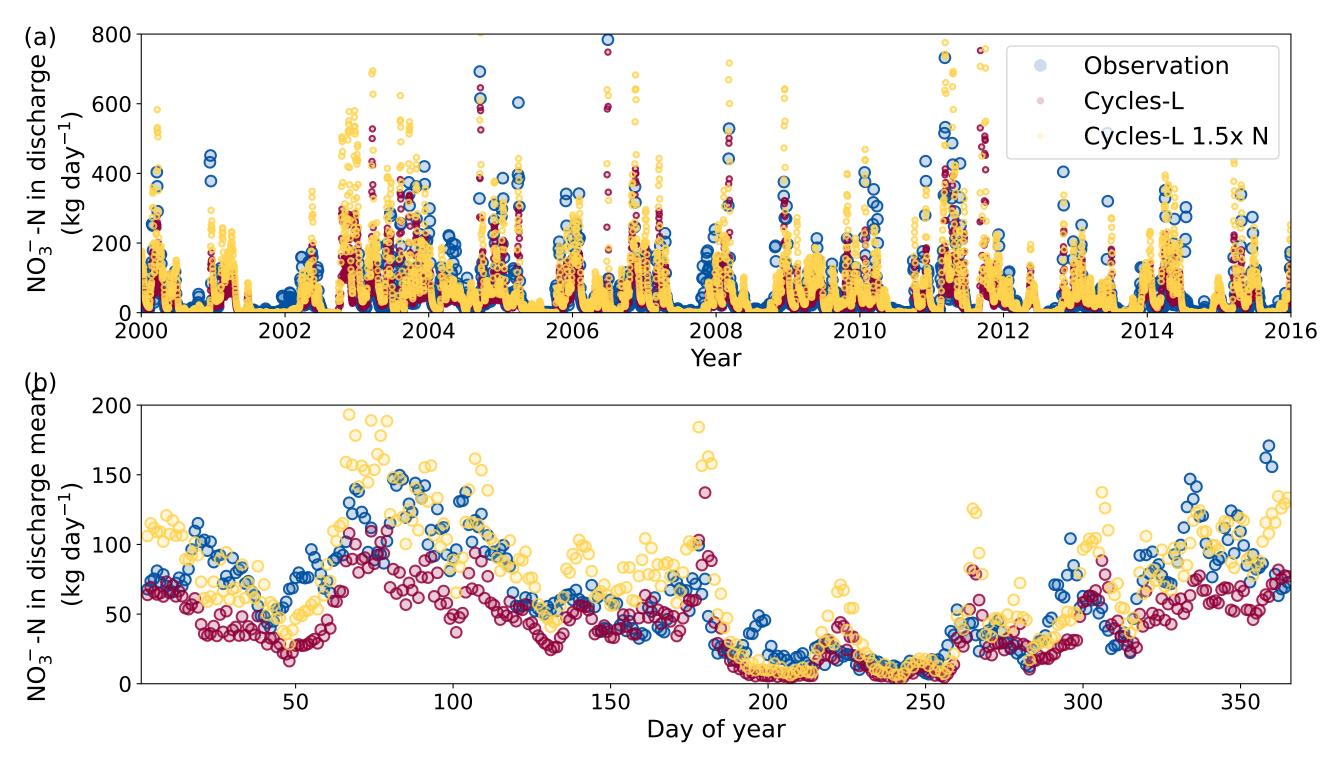


Figure 6.

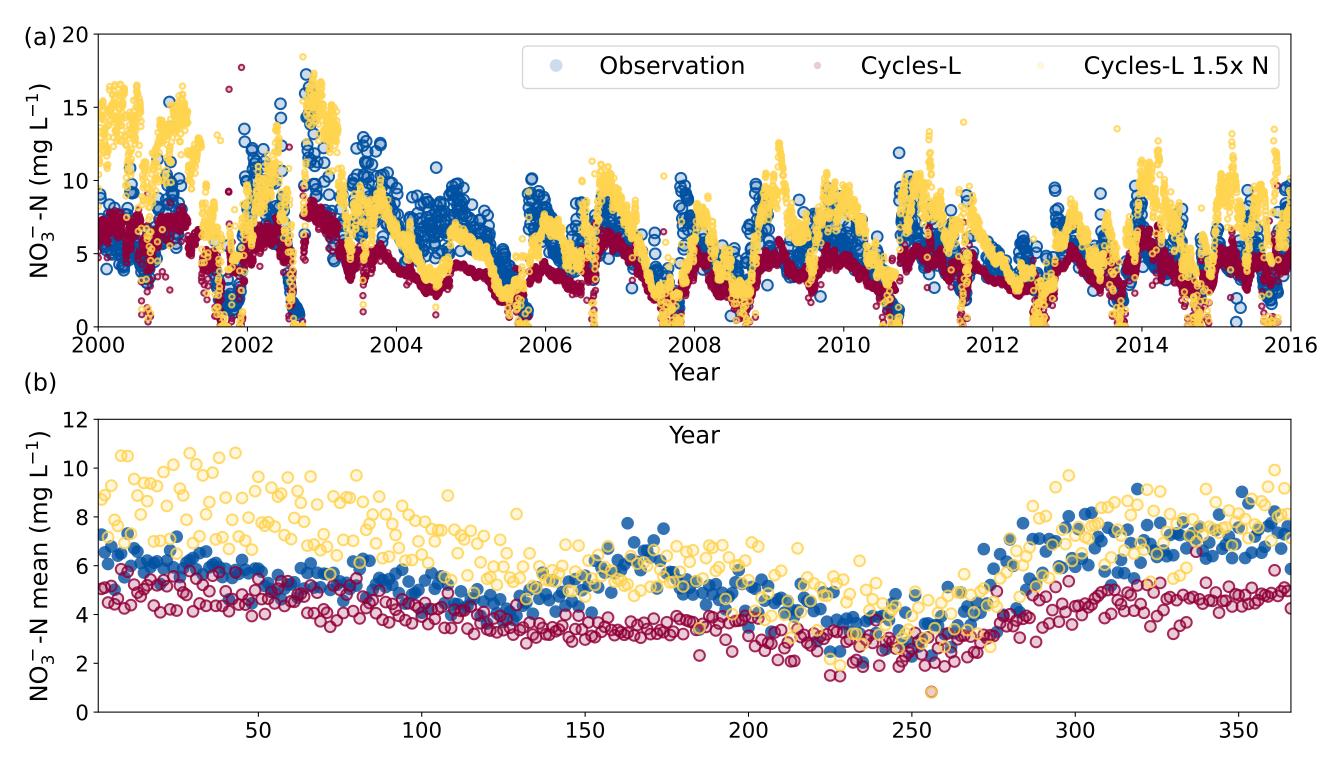


Figure 7.

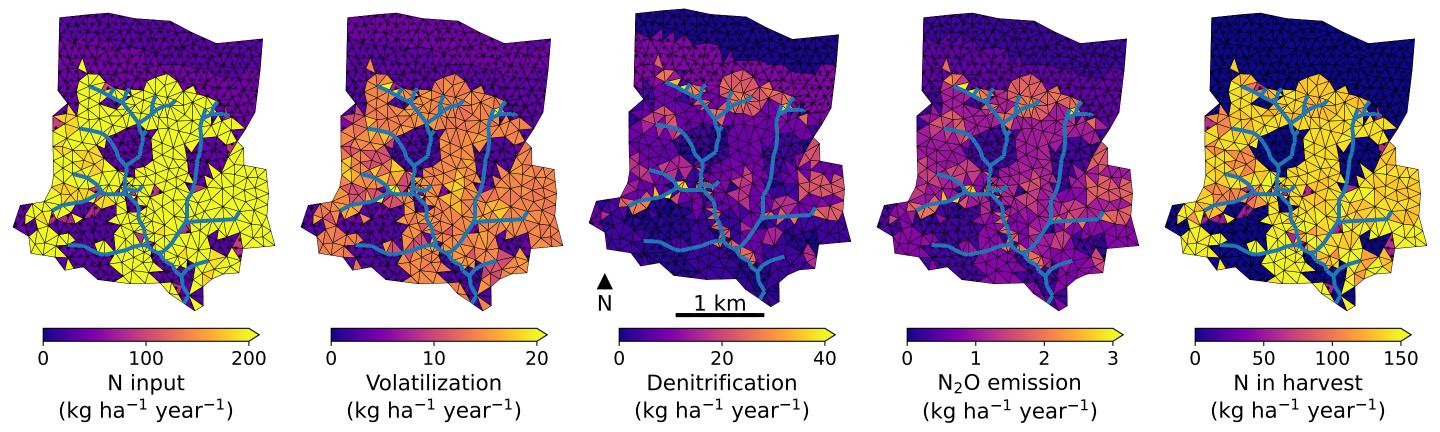


Figure 8.

