Repeating low frequency icequakes in the Mont-Blanc massif triggered by snowfalls

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Abstract

Deformation mechanisms of glaciers are highly sensitive to basal temperature; the motion of temperate glaciers is dominated by basal slip while cold-based glaciers deform mainly by internal creep. While basal slip is usually aseismic, unstable slip sometimes occurs and can be detected by seismometers. I have detected clusters of repeating low frequency icequakes (LFIs) in the Mont-Blanc massif. Some properties of LFIs are similar to the high-frequency icequakes (HFIs) located at the base of Argentière glacier. Both HFIs and LFIs occur as bursts of tens to several thousand events, with typical inter-event times of several minutes and last for days or weeks. Unlike HFIs that have a broad spectra, LFIs have a characteristic frequency of about 5 Hz at all stations, suggesting a rupture length of about 100 m. Seismic amplitudes and seismic waveforms of LFIs progressively evolve with time within each cluster, suggesting changes in either rupture length or rupture velocity. Most LFIs are detected during snowfalls, while HFIs are not correlated with snowfalls.

In this study, I used all available seismic stations within or around the Mont-Blanc massif between 2017 and 2022. I found LFIs located all over the massif but mainly above 3000 m. Some clusters are clearly associated with cold ice (near Mont-Blanc summit) while others below 2700 m a.s.l. are likely located under temperate glaciers and two clusters could be associated with landslides. This observation of LFIs on cold glaciers is consistent with laboratory friction experiments suggesting that cold ice promotes unstable slip.

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Repeating low frequency icequakes in the Mont-Blanc massif triggered by snowfalls

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Key Points:

- I have detected low frequency icequake signals with a main frequency of 5 Hz that repeat every few minutes
- Low frequency icequakes mainly occur during and after snowfalls
- They are located on several glaciers of the Mont-Blanc massif mainly above 3000 m a.s.l. where ice is possibly cold

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Abstract

Deformation mechanisms of glaciers are highly sensitive to basal temperature; the motion of temperate glaciers is dominated by basal slip while cold-based glaciers deform mainly by internal creep. While basal slip is usually aseismic, unstable slip sometimes occurs and can be detected by seismometers. I have detected clusters of repeating low-frequency icequakes (LFIs) in the Mont-Blanc massif. Some properties of LFIs are similar to the high-frequency icequakes (HFIs) located at the base of Argentière glacier (*Helmstetter et al.*, 2015). Both HFIs and LFIs occur as bursts of tens to several thousand events, with typical inter-event times of several minutes and last for days or weeks. Unlike HFIs that have a broad spectra, LFIs have a characteristic frequency of about 5 Hz at all stations, suggesting a rupture length of about 100 m. Seismic amplitudes and seismic waveforms of LFIs progressively evolve with time within each cluster, suggesting changes in either rupture length or rupture velocity. Most LFIs are detected during snowfalls, while HFIs are not correlated with snowfalls. In this study, I used all available seismic stations within or around the Mont-Blanc massif between 2017 and 2022. I found LFIs located all over the massif but mainly above 3000 m. Some clusters are clearly associated with cold ice (near Mont-Blanc summit) while others below 2700 m a.s.l. are likely located under temperate glaciers and two clusters could be associated with landslides. This observation of LFIs on cold glaciers is consistent with laboratory friction experiments suggesting that cold ice promotes unstable slip (*McCarthy et al.*, 2017; *Saltiel et al.*, 2021; *Zoet et al.*, 2018).

1 Plain Language Summary

Glaciers flow due to slip at the base of the glacier and due to internal deformation. When the ice is at the melting point temperature, the presence of water at the base of the glacier promotes basal slip, while for cold ice (below melting temperature) the glacier is stuck to its bed and most deformation occurs within the glacier. The displacement of the glacier is usually slow and continuous, but in some cases slip can occur as intermittent fast slip events. These "icequakes" generate ground vibrations that can be recorded by seismic sensors. In this study, I analyze clusters of icequakes that repeat more or less regularly with time every few minutes, with progressive changes in amplitudes and inter-event times. The signals have a narrow spectrum with a main frequency of about 5 Hz that suggests a rupture length of about 100 m. These events mainly occur during snowfalls and are mostly located on glaciers above 3000 m. At these locations, the ice is often colder than the melting point temperature. These repeating icequakes are probably associated with unstable slip at the base of glaciers. This result is surprising since basal motion for cold ice (below melting point) is believed to be negligible, but it is however consistent with laboratory experiments suggesting that unstable slip is promoted by cold temperatures. A few events occur on or close to glaciers at lower elevations, where ice is at the melting point temperature. They may be associated with basal glacier motion or with gravitational instabilities induced by glacier retreat.

2 Introduction

Basal icequakes have been observed under very different settings (ice-streams, outlet glaciers, alpine glaciers, ice-clad volcanoes), with hard-beds or basal till, over a huge range of scales (1 m - 200 km), rupture durations (from 0.1s to 30 mn), frequency content (from 100 s to 500 Hz) and magnitude $-4 < m < 7$ (see for a review *Podolskiy and Walter* (2016)). Most of these events have a high waveform similarity, occur more or less regularly in time and display progressive changes in amplitude and recurrence times. Repeating basal icequakes are generally associated with stick-slip shear motion at "sticky-spots" at the ice-bed interface. The rupture area is stuck except during dynamic rupture (slip events). Stress decreases during slip events and increases between events due

to aseismic deformation. The nature of "sticky-spots" is difficult to identify. They could be associated with rock debris sliding over a hard bedrock (*Helmstetter et al.*, 2015) or with the ploughing of clasts embedded in the base of the ice through wet low diffusivity till (*Barcheck et al.*, 2018). Another common point is that most of these events occurred under glaciers or ice-streams with temperate basal ice layer (ice at the melting point temperature), allowing aseismic slip around the "stick-spot" to reload the asperity between events.

Glacier basal motion is mainly controlled by the temperature of the basal layer and by the nature of the bed (*Cuffey and Paterson*, 2010). For temperate-based glaciers, basal motion accounts on average for half of the total motion. Basal motion is due to slip on the ice-bed interface for hard beds, while for soft beds most of basal motion is due to shear within the till layer. In contrast, cold glaciers with a basal layer below meting point are believed to deform mainly by viscous creep within the bulk of the glacier, with negligible basal slip because ice is frozen to the bed.

The mechanisms responsible for stick-slip events are still debated. While basal seismicity has mainly been observed so far for temperate basal ice, the only laboratory friction experiments that reproduced unstable slip ("velocity-weakening" behavior) were using ice samples below the freezing temperature (*McCarthy et al.*, 2017; *Saltiel et al.*, 2021; *Zoet et al.*, 2018). Basal icequakes can be triggered or modulated by tides (*Wiens et al.*, 2008), snowfalls (*Allstadt and Malone*, 2014; *Thelen et al.*, 2013) and changes in basal water pressure (*Röösli, et al.*, 2016). Basal stick-slip motion is thus particularly informative of glacier sliding processes and of basal properties (*Barcheck et al.*, 2018; *Kufner et al.*, 2021; *Smith*, 2006).

In this study, I report observations of repeating icequakes in the Mont-Blanc area. Repeating high frequency icequakes, with a mean frequency above 100 Hz, have previously been detected under Argentière glacier in the Mont-Blanc massif (*Gimbert et al.*, 2021; *Helmstetter et al.*, 2015). These events were associated with the repeated failure of rock debris over the bedrock. This study describes another type of repeating icequakes, with much lower average frequency of about 5 Hz. Both types of repeating icequakes occur as bursts of events lasting for a few days or weeks, with progressive changes in inter-event times and amplitudes. But, unlike high frequency icequakes (HFIs), low-frequency repeating icequakes (LFI) occur mainly during or after snowfalls. They also occur at higher elevations, possibly associated with cold-based glaciers. These differences suggest that LFIs may be generated by a different physical mechanism.

3 Study area and instrumentation

3.1 Mount-Blanc massif and Argentière glacier

The Mont-Blanc massif extends over three countries (France, Italy and Swiss), culminates at 4807 m above sea level (a.s.l.), and includes about 155 km^2 of glaciers. There are both temperate valley glaciers with ice at the melting-point temperature (e.g., Mer de Glace and Argentière glaciers), polythermal (e.g., Taconnaz and Tête Rousse glaciers) and cold hanging glaciers (e.g., Glacier de la Verte, Glacier de l'Aiguille du Tacul). Mer de Glace is the longest glacier of the massif; it culminates at 4248 m a.s.l. and flows down to about 1600 m a.s.l. over a length of about 12 km. Argentière glacier is the second largest glacier of the massif, with a length of 10 km and a maximum thickness of about 400 m. This glacier is particularly interesting as it has been studied since several decades with measurements of surface displacement and basal slip (*Vincent and Moreau*, 2016), subglacial water flow discharge, mass balance and meteorological data (*Vincent et al.*, 2009). In addition, several ground penetrating radar experiments, boreholes and seismic reflection studies provided accurate information on the topography of the bedrock and on the seismic wave velocities (*Gimbert et al.*, 2021). Although our goal was initially to ana-

lyze icequake activity on Argentière glacier, I found out that most detected events did not occur on Argentière glacier but were distributed all over the Mont-Blanc massif.

3.2 Seismic stations

I used all available temporary and permanent seismic stations in the Mont-Blanc area. Table 1 gives the characteristics of each station used in this study. The stations inside the Mont-Blanc massif are shown in the map in Figure 11.

Several seismological experiments have been performed on Argentière glacier since 2017. A few seismic stations have been operated between October 2017 and May 2020 (stations B01-B04), with several gaps in the acquisition. The first station B01 was installed on Argentière glacier on 2017/10/4 at 2392 m a.s.l. (*Nanni et al.*, 2020). Then station B02 was installed at 70 m depth in a borehole close to B01 on 2018/4/20, following with B03 on 2018/10/23 at 2657 m a.s.l. and B04 on 2019/6/26 at 2524 m a.s.l..

Two other temporary seismic stations were in acquisition in summer or autumn 2021. Station DOM was located near Col du Dôme (45.8422°N, 6.8466°E, 4243 m a.s.l.) and station MDG on Mer de Glace (45.9203°N, 6.9264°E, 1897 m a.s.l.).

Two temporary one-month experiments with a larger number of sensors have been performed. From 2018/4/20 until 2018/5/31, the lower part of Argentière glacier has been instrumented with a network of 98 seismometers (stations AR001-AR100). The preliminary results of this experiment have been described by *Gimbert et al.* (2021) and the data is available from *Roux et al.* (2021). Another short-term experiment has been conducted from 2019/12/5 until 2020/1/10 using 13 sensors distributed in 3 antennas (*Helmstetter*, 2020). An antenna of 5 sensors (N11-N15) was located at Col des Grands Montets at about 3260 m a.s.l. with a distance between sensors of about 100 m. Another antenna of four sensors was located near station B03 at about 2650 m a.s.l. (N21-N24), and the last antenna was located near B04 at about 2500 m a.s.l. (N31-N34). All these sensors lost their GPS signal after being started in Chamonix on 2019/12/4 and before installation on the glacier the next day. I was not aware that these sensors should not be moved after acquisition starts. I thus used local earthquake signals in order to correct the clock drift, which reached about 1 s after one month. I found a timing accuracy of about 0.02 s which is not sufficient to use beam-forming methods. I thus selected only one sensor out of each antenna (N13, N21 and N31).

Station BLANC was installed within the Mont-Blanc massif near Torino Refuge at an elevation of 3379 m on 2019/6/14. I also used data from stations around the Mont-Blanc massif. Stations CI17-CI23 of the CIFALP project (*Zhao et al.*, 2018) were in operation between 2018/11/11 - 2019/12/3. Stations CI18-CI20 were reinstalled at the same location on 2019/12/20 (*Helmstetter and Guéguen*, 2020). Three stations (MFERR, VFER2 and AMID2) were installed by ETH Zurich in 2019 to detect and locate earthquakes in the Mont-Blanc massif. I also used permanent stations located further away: stations SEMOS, DIX, AIGLE, ILLEZ, SENIN, GRYON, FULLY, SALAN from the Switzerland Seismological Network (*Swiss Seismological Service*, 1983), Italian stations REMY, CIRO, LSD (*University of Genova*, 1967) and MRGE (*INGV*, 2006), and stations RSL and OGSI in France (*RESIF*, 1995).

3.3 Snow falls and atmospheric pressure

I used meteorological data to analyze the influence of precipitations and atmospheric pressure on the occurrence of LFIs. A permanent meteorological station is installed on a moraine above Argentière glacier near 2400 m a.s.l. as part of GLACIOCLIM observatory (*Six and Vincent*, 2014). However this station does not measure snow falls . The closest station that measures snow falls is a meteofrance station located outside the Mont-Blanc massif, in the Aiguilles Rouges massif, at 2365 m a.s.l. But there are many gaps

Table 1. Characteristics of all seismic stations used in this study

Name	Network code	Time interval	Sensor	Cut-off frequency	Sampling rate (Hz)
B01		2017/10/4-2018/9/13	Geobit-C100-MK2	10 s	1000
B02		2018/4/18-2019/2/4,	Geobit S 400 C	1 Hz	1000
		2019/7/16-2019/10/16,			100
		2019/12/6-2020/5/11			100
B03		2018/10/23-2019/3/22,	Geobit C100-MK2	10 s	1000
		2019/3/23-2019/5/14,			100
		2019/6/25 -2020/1/27			1000
B04		2019/6/26-2020/1/25	Geobit C100-MK2	10 s	100
DOM		2021/7/2-2021/8/28	Geobit S-100 1C	4.5 Hz	800
MDG		2021/9/18-2021/12/18	Geobit C100 3C	4.5 Hz	100
AR001-100	ZO	2018/4/25-2018/5/31	Fairfield ZLand 3C	4.5 Hz	500
N11-35	1D	2019/12/5-2020/1/10	Fairfield ZLand 3C	4.5 Hz	250
CI17-CI23	XT	2018/11/11-2019/12/3	Trillium Horizon	120 s	100
CI18-CI20	8C	since 2019/12/20	Guralp CMG40	40 s	200
MFERR	8D	since 2019/5/28	Lennartz LE-3D	1 s	100
AMID2, VFER2	8D	since 2019/12/4	Lennartz LE-3D	1 s	200
BLANC	GU	since 2019 06 14	Trillium 40s	40 s	100
REMY, LSD, CIRO	GU	since 2011 or before	Trillium 40s	40 s	100
MRGE	IV	since 2005/6/24	Trillium 40s	40 s	100
SEMOS	CH	since 2013/6/18	EpiSensor ES-T	none	250
DIX, AIGLE.	CH	since 2018 or before	Streckeisen STS2	120 s	200
SENIN, SALAN	CH	since 2018 or before	Streckeisen STS2	120 s	200
ILLEZ, FULLY	CH	since 2018 or before	Trillium Compact	120 s	100
GRYON	CH	since 2002/10/2	Trillium 240s	240 s	200
OGSI	FR	since 2016/6/15	Trillium Compact	20 s	200
RSL	FR	since 2010/5/28	Trillium 120PA	120 s	100

in the snow fall data during snow fall episodes. Therefore, I use data from the S2M database (*Vernay et al.*, 2019), which provides a reanalysis of meteorological and snow cover data. This model adjusts a guess from a numerical weather prediction model with the best possible set of available in-situ meteorological observations. It provides the hourly rate of snowfall on the Mont-Blanc massif for different ranges of elevations and slope orientations.

The GLACIOCLIM station only measures atmospheric pressure since 2019/9/13. Before this date, I use data from the closest Meteofrance station that measures atmospheric pressure located at Bourg Saint Maurice 24 km South from Mont-Blanc. I checked that both stations provide similar values after shifting the Bourg Saint Maurice pressure to correct the effect of elevation. When both stations are in operation the correlation coefficient between the pressure estimated at Argentière and Bourg-Saint-Maurice is 0.88.

4 Methods

4.1 Detection, classification and selection of repeating LFIs

I detected a first sequence of low-frequency icequakes by simply screening a one-hour long signal recorded by station B01 on 2017/12/19 at 22:00 UTC. In Figure 1, we can see very regular peaks in the seismogram repeating on average every 160 s. Signals are highly similar, with a duration of about 5 sec, an average frequency around 5 Hz and no high frequency energy. Once we identify one event, it is straightforward to detect similar events using the template-matching method (*Gibbons and Ringdal*, 2006). I first used this method with a relatively low correlation threshold (0.4), a time window of 5 s, a band-pass filter of 2-20 Hz, using the three components of station B01. By screening the waveforms of detected events, I noted significant and abrupt changes in the waveforms and amplitudes. I thus divided the set of detected events into different clusters using the hierarchical agglomerative clustering method with average linkage (*Sokal and Michener*, 1958).

In order to perform a more systematic detection, I applied the STA/LTA algorithm of *Allen* (1978) on all the data at the reference station using a signal-to-noise ration of 3 and a bandwidth filter between 3 and 10 Hz. I used different reference stations for different periods: B01 (2017/10/4 - 2018/6/12), B03 (2018/10/23 - 2019/9/11), N21 (2019/12/5 - 2020/1/10), B02 (2020/2/8 - 2020/5/12) and BLANC (2019/6/14 - 2022/6/1). I detected on average more than 300 events per day, with a large variability in amplitude, frequency content and signal duration, likely produced by different processes (crevasse opening, basal slip, avalanches, rockfalls, earthquakes, noise...). The number of detected events was much too large (several hundred thousand events) to apply the hierarchical clustering method in order to group events into clusters with similar waveforms. I thus screened manually the catalog to identify bursts of events with similar amplitudes and duration and quasi-periodic recurrence times. I also applied the hierarchical clustering method on all large events (peak ground velocity larger than 10 μm/s) to make sure that I did not miss any cluster of large amplitude signals.

This way I identified several thousand clusters of low-frequency signals for the whole time period. Within each identified cluster, I computed the average signal and used this stacked signal as the new template signal for this cluster. When the correlation between different templates was larger than 0.9, I merged the clusters. I then applied the template-matching algorithm on the continuous data at the reference stations with a correlation threshold of 0.5. I used different signal durations for different clusters (2, 3 or 5 s), starting about 0.5 s before the first arrival and ending just after the last visible arrival. If an event was detected by several templates, I chose the one with the largest correlation.

In this work, I am interested in detecting "low-frequency" repeating icequakes (LFIs) similar to those shown in Figure 1. Here, the term "low-frequency" means average fre-

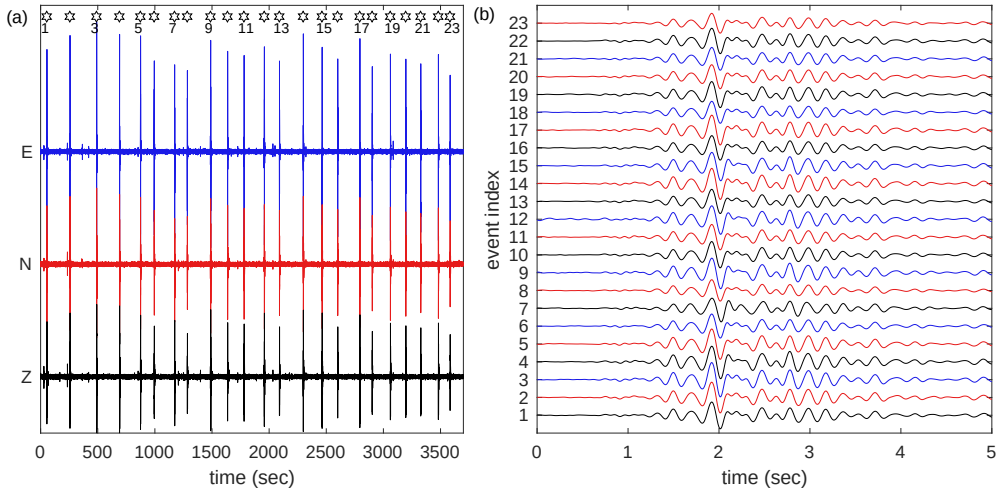


Figure 1. a) Seismic signal recorded by station B01 on 2017/12/19 at 22:00 UTC bandpass filtered between 1 and 20 Hz. LFIs are highlighted by stars. The corresponding seismograms for each event are shown in b) for the East component.

quencies of about 5 Hz, much lower than the average frequency of about 50 Hz for the high-frequency basal icequakes (HFIs) located below the lower part of Argentière glacier near 2350 m a.s.l. (*Gimbert et al.*, 2021; *Helmstetter et al.*, 2015). The definition of "repeating" events is also delicate (*Uchida and Bürgmann*, 2019). Here I consider repeaters as events occurring quasi-periodically in time, i.e., that are more regular than a Poisson random process (with uniform rate in time). I do not impose that they rupture the same asperity, as the location accuracy is not good enough compared to the rupture length.

Regularity in time is usually characterized by the coefficient of variation (ratio of standard deviation over average recurrence time), with a value equal to 1 for a Poisson process, smaller than 1 for quasi-periodic occurrence times and larger than one for clustered events. But the coefficient of variation does not provide a good way to identify repeating icequakes. Repeating LFIs occur as bursts of activity separated by quiescent periods, as observed before for HFIs (*Helmstetter et al.*, 2015). During active periods, both the inter-event times and the amplitude evolve progressively in time. The coefficient of variation is thus often larger than one, due to the succession of active phases and periods of very low activity (possibly misclassified events) and to progressive changes in recurrence time. To account for slow changes in activity rate, I normalize each recurrence time by the median value over a sliding window of 10 events. I also replace the standard deviation by the median absolute deviation, which is less sensitive to extreme events. Our modified "coefficient of variation" is thus defined as $median(|dt^* - 1|)$, where dt^* is the normalized recurrence times. I select all clusters with a coefficient smaller than 0.5, significantly smaller than values in the range 0.6-0.7 obtained for Poissonian synthetic catalogs.

During quiet phases between bursts of LFIs, events usually have a smaller correlation with the template than during bursts for the same peak amplitude. These isolated events may thus have a slightly different location or be due to a different triggering factor. I thus remove these isolated events before attempting to locate them or to analyze the correlation with potential triggering factors. For each cluster of repeaters, I remove events with inter-event times larger than 10 times the median value. A cluster is thus divided in several temporal sub-clusters, separated by gaps longer than 10 times the me-

dian inter-event time. In order to limit the number of sub-clusters, I then merge together sub-clusters if the gap is less than 1/4 of the duration of the smallest sub-cluster.

4.2 Localization

4.2.1 Stacking and picking signals

I attempted to locate each cluster of LFIs by manually picking P and S phases at a maximum of stations. Since individual events are rarely visible at stations outside the glacier, I stacked the signals for a selection of events for each cluster. For large clusters with more than 1000 events, I selected only the 1000 best events, with the largest amplitude and correlation with the template signal at the reference station. For all clusters I selected events that occurred during the bursts, because events that occurred isolated in time during quiet periods are more likely to be false detections and to come from a different source. Specifically, I computed the median recurrence time and removed events with inter-event time larger than 10 times this value. Signals were first bandpass filtered between 2 and 20 Hz. Instead of using the average over all selected events, I used the median signal because it improves the signal-to-noise ratio by removing the influence of outliers (*Allstadt and Malone*, 2014). This helps to reduce the influence of noisy signals or false detections. Before taking the median, I removed events with a very large noise amplitude, e.g., due to anthropogenic noise, instrumental issues or noise due to water flow. I computed the average noise amplitude over a time window of 20 s before each event and removed events with a noise amplitude larger than twice the median value.

I then manually picked first arrivals of P and S waves at all available stations listed in Table 1 when I could visually identify these phases. For the three node antennas installed in December 2019 (stations N11-N15, N21-N24, N31-N34), I selected only one station for each antenna (nodes N11, N21 and N31). Because of the small inter-node distance (about 100 m), large source-node distance (several kms) and clock errors for these stations, I believe including more sensors would not improve the location accuracy. In order to keep only the best constrained locations, I selected only clusters with a minimum of 7 phases picked at a minimum of 4 stations and also imposed at least one station outside the glacier. I did not use data from the nodes AR001-AR100 installed in April-May 2018 during Resolve experiment. These nodes detected only two clusters of LFI but these clusters could not be located accurately because they were not detected by stations outside the glacier.

4.2.2 Velocity model

Tomographic studies in the Alps do not have a good enough resolution and are not adapted to our study of shallow sources because they do not estimate seismic wave velocity above sea level. Therefore, I used phase arrivals from swarms of micro-earthquakes in the Mont-Blanc area in order to estimate average P and S wave velocities. I selected 1710 earthquakes detected by the regional seismological network Sismalp from 2017/1/1 until 2021/1/27 with latitude in the range 45.8-46°N and longitude between 6.8 and 7.1°E. Most of these events were part of a swarm located below the Grandes Jorasses summit at about 5 km depth below sea level, while another smaller swarm was located under Aiguille du Midi. For each station in Table 1 and for each earthquake I computed apparent P and S velocities from earthquake source times and phase arrivals. I then took the average over all events at each station and then averaged over all stations. This yielded $V_P = 5.68$ km/s and $V_S = 3.41$ km/s. Since icequakes are quite shallow and located at a larger elevation than most stations, I account for the surface topography to avoid ray paths in the air. I use NASA SRTM digital elevation data with a resolution of 30 m (*Jarvis et al.*, 2008). Our 3D velocity model is homogeneous below the surface and has $V_P = 0.34$ km/s and $V_S = 0.01$ km/s in the air. V_S needs to be positive in the air but its value has no influence on the results as long as $V_S \ll 1$ m/s. It covers the

Mont-Blanc massif and extends further away to include all seismic stations listed in Table 1. The grid spacing is fixed to 100 m in all directions and the depth ranges between 0 and 5 km a.s.l.. I cannot decrease the resolution because the size of the 3D velocity model of dimension $5 \times 100 \times 100$ km would be very large and the computing time too long.

Seismic wave velocities in the ice are significantly smaller than in the bedrock ($V_P =$ 3.62 km/s, $V_S = 1.83$ km/s) (*Gimbert et al.*, 2021). For stations located on glaciers, this can thus yield notable errors in the estimated travel times. However, the geometry of glaciers is not well known, except for Argentière glacier. But I cannot include the ice layer in the velocity model due to its limited resolution in space (grid size of 100 m). I thus use station corrections to minimize these errors.

4.2.3 Station corrections

Station corrections can account for un-modeled heterogeneities in the seismic wave velocities. Many stations are located on Argentière glacier above several hundred meters of ice. I estimated time corrections for these stations by computing travel-times in the velocity model described above ($V_P = 5.68$ km/s, $V_S = 3.41$ km/s below the surface) and in a 3D model accounting for different velocities within Argentière glacier. The geometry of the glacier is defined by a synthesis of radar and seismic profiles (*Gimbert et al.*, 2021). The seismic wave velocities in the ice ($V_P = 3.62$ km/s, $V_S = 1.83$ km/s) were inverted from the localization of high-frequency basal icequakes detected by the Resolve experiment (*Gimbert et al.*, 2021). I then estimated travel times for each velocity model (with and without glacier) on a rectangular grid covering the Argentière glacier (longitude between 6.956°and 7.046°E, latitude between 45.913°and 45.97°N) with a grid spacing of 30 m, for each station on the glacier and for each grid point. The time delay between the two model varies in space but is relatively homogeneous outside the Argentière glacier and at large distance from the station. The time correction for each station is thus defined as the average time delay for grid points located at the surface outside the glacier and south-west from the glacier. I do not include grid points located within the northern part of the grid because I found very few icequakes in this area and because the time delay computed for station N13 (near Col des Grands Montets) is very different for points located south or north from Argentière glacier (i.e., for ray paths that do or do not cross the glacier). The maximum time delay of 0.14 s is obtained for S waves at station B04, where the glacier thickness is the largest reaching about 450 m.

4.2.4 Location method

I use NonLinLoc location method (*Lomax et al.*, 2000), which uses a probabilistic location method providing more accurate estimates of location errors. This method provides the most likely location as well as a scatter of possible solutions. This is particularly interesting when there are multiple local minima of time residuals. I use the 3D velocity model described above and station corrections for stations on the glacier. I assume gaussian picking errors with a standard error of 0.1 s for both P and S waves. and minimize the root-mean-square residuals. The inversion is performed using the Octtree Importance Sampling Algorithm as it is much faster than a grid-search. The topography of the area is used to search for possible sources located only below the ground surface.

4.3 Magnitude

Among all types of magnitudes, the moment magnitude is generally preferred as it directly depends on physical source properties, rupture area and slip. However, it is difficult to estimate moment magnitude for our signals because they have a limited frequency range, a very small signal-to-noise ratio for most events and for stations outside

the Mont-Blanc massif and are likely dominated by surface waves. I thus estimated both the surface-wave magnitude M_s and the local magnitude M_l.

I used the definition of the surface-wave magnitude given by *Bormann and Dewey* (2014)

$$M_s = \log_{10}(A/2\pi) + 1.66 \log_{10} \Delta + 0.3, \tag{1}$$

where A is the maximum amplitude of the surface-wave on the vertical trace and Δ is the epicentral distance in degrees. Note that I use this definition of M_s out of its recommended range of frequencies (3-60 s) and epicentral distance ($2 < \Delta < 60°$).

The local magnitude is given by (*Bormann and Dewey*, 2014)

$$M_l = \log_{10}(A_d) + 1.11 \log_{10}(d) + 0.00189d - 2.09 + C, \tag{2}$$

where A_d is the amplitude in nm of the horizontal displacement seismogram that would have been recorded on a Wood-Anderson seismometer and d is the hypocentral distance (in km). This definition of M_l is only valid for crustal earthquakes in regions with attenuation properties similar to those of Southern California (*Bormann and Dewey*, 2014), I thus added a corrective term C. I estimated the correction term $C = 0.4$ to match the local magnitude of local earthquakes detected by Sismalp and computed using seiscomp software, for a selection of 30 earthquakes located in the Mont-Blanc massif with $0 < M_l < 3.1$ between 2018/12/21 and 2021/1/23.

For each cluster, I compute the magnitudes M_l and M_s of the largest event that occurred during active phases (rejecting isolated events). However, even the largest event is not always visible on all stations where this cluster was picked due to the weak signal-to-noise ratio. I thus applied the following procedure to estimate the amplitude A of the largest event at each station. For each station, I compute the amplitude A_i of each event i by computing the scaling amplitude factor between the signal y_i and the stacked signal y_s (*Gibbons and Ringdal*, 2006; *Schaff and Richards*, 2011)

$$A_i = A_s \frac{\sum_{j=1}^{N} y_i(t_j) y_s(t_j)}{\sum_{j=}^{N} y_s(t_j)^2} \ , \tag{3}$$

where y_s is the vertical component of the stacked signal, A_s is its peak amplitude and the time index j varies from 2 s before until 2 sec after the time of the peak amplitude of the stacked signal. This greatly improves the accuracy of the estimated peak amplitude for repeating signals, but is often still unreliable when the signal is buried in the noise. I thus fit a linear regression between the peak amplitude estimated at the reference station (B01, B02, B03 or BLANC) and at each other station, after selecting events that have a correlation with the stacked signal greater than its median value. This helps to remove noisy events and to obtain a more accurate value for the peak amplitude of the largest event of each cluster at each station.

5 Results

5.1 Characteristics of Seismic Signals

There are many different types of icequakes that have been detected on Argentière glacier (*Gimbert et al.*, 2021; *Helmstetter et al.*, 2015). Even when focusing on repeating basal events, I found very different frequency ranges, from HFIs with energy above 500 Hz located at a few hundred meters from the sensor (*Gimbert et al.*, 2021; *Helmstetter et al.*, 2015), to the LFIs described in this study. However, It is not clear wether the frequency content represents the frequency of the source process or if the signal is strongly affected by attenuation that depletes the signal in high-frequencies.

Figure 2 compares the seismograms and spectrums of low- and high-frequency repeating icequakes with a local earthquake recorded at station B01. The LFI signal has

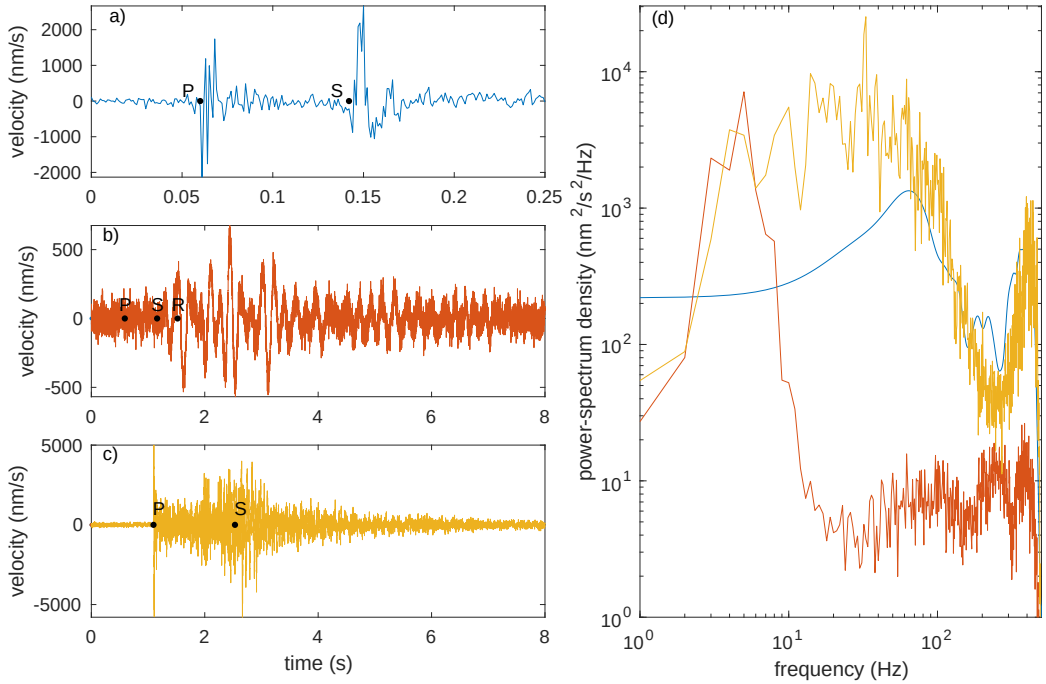


Figure 2. Seismograms of (a) a high-frequency icequake, (b) a low-frequency icequake and (c) a $M_l = 1.1$ local earthquake detected at station B01. Signals are vertical ground motion high-pass filtered at 1 Hz. Arrival times of P, S and surface waves ('R' in(b))) are shown by dots. The corresponding spectrums are shown in (c) for the high-frequency icequake in blue, low-frequency icequake in red and local earthquake in yellow.

less energy above 6 Hz compared with a local earthquake of $M_l = 1.1$ detected at a distance of 10 km, whereas the LFI is located closer at about 3.5 km from the sensor. This suggests that the lack of high frequency energy for the LFI could be a source property. However, the LFI is much shallower than the earthquake, so that attenuation is likely stronger for the LFI than for the earthquake located at 3.4 km below sea level. Moreover, the LFI signal is mainly composed of surface waves, which always have lower frequencies than body waves. But I don't think that these effects could explain the sharp decrease in the LFI spectrum above 6 Hz and the huge difference in high frequency energy above 10 Hz between the LFI and the earthquake.

Distinguishing the different phases for the LFI shown in Figure 2b is delicate. The different waves (P, S and Rayleigh waves) are more easily identified when bandpass filtering the data between 2 and 10 Hz, stacking over all events of the same cluster and looking at the signal polarization (see Figure 3).

5.2 Temporal Evolution

Clusters of repeating LFIs are generally active for a few hours or days. The same cluster can however reappear a few days or months latter. Figure 4 displays the temporal evolution of repeating events during one of the most active periods between 2018/10/27 and 2018/11/9. This figure only shows the 7 clusters with at least 1000 events during this time period. In addition, I also plot a smaller cluster of 190 events that displays a highly regular pattern and longer recurrence times (black dots in Figure 4). This figure illustrates the typical patterns as well as discrepancies between clusters. Clusters usu-

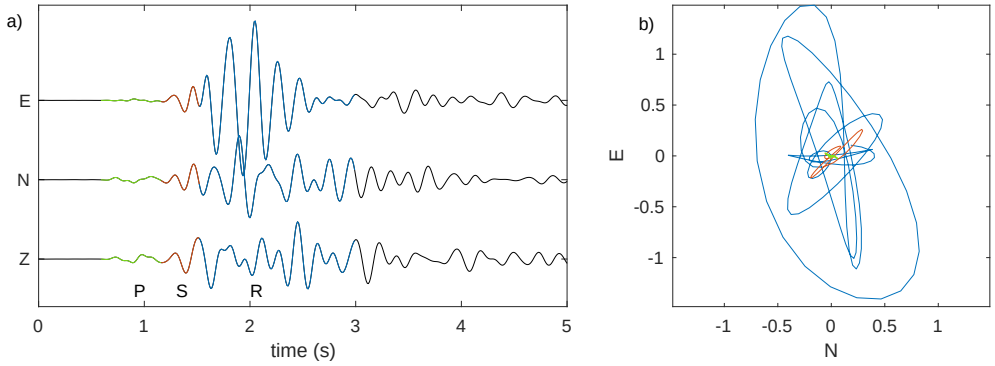


Figure 3. (a) Seismograms of the stacked signal for one cluster of LFIs detected at station B01 bandpass filtered between 2 and 10 Hz. (b) Velocity ground motion in the horizontal plane. I used a different color for each wave, P wave in green, S wave in red and surface waves in blue.

ally start as very small events with short and irregular occurrence times. But during the beginning of the cluster many small events are likely missed. In a second phase, both the amplitudes and the recurrence times increase in time and become more regular. Some sequences then stop abruptly or slow down slowly with a progressive decrease in amplitudes and increase in recurrence times. Different clusters stop and end at different times. I found no correlation between the LFI occurrence times between different clusters. This suggests that they are not interacting with each other and that the triggering factors or the "nucleation time" of clusters differ.

5.3 Correlation with snowfalls

Figures 5 and 6 compare the snowfalls and the rate of repeating LFIs for two time periods. Repeaters are mostly observed between October and May. Few events are observed in summer but they could be hidden by the increase in seismic noise during the melting period. Most bursts of repeaters coincide with snowfalls. This is confirmed by computing the cross-correlation between the snow-fall rate and the rate of repeating events shown in Figure 7. The cross-correlation function shows a peak for positive times (icequakes occurring after snowfalls) with a maximum at 1.6 days and returns to zero after 10 days. Smaller and broader peaks for negative times are spurious and result from peaks in the autocorrelation of snowfall data. LFIs are also negatively correlated with atmospheric pressure. This is surprising since decreasing the atmospheric pressure should have the same effect as decreasing the snow load. If snow load triggers LFIs, then increasing atmospheric pressure should also trigger LFIs. Atmospheric pressure is also strongly anti-correlated with snowfall rate (black curve in Figure 7) so that it is difficult to disentangle the relative effect of atmospheric pressure and show load on the triggering of LFIs. Changes in atmospheric pressure and snowfall load have indeed the same order of amplitude. I have analyzed the average temporal evolution of atmospheric pressure, snowfall load and the rate of LFIs during snowfall episodes. I have selected 29 snowfall episodes with a weight larger than 1 hPa that started at least 3 days after the end of the previous episode. I then stacked each variable for all snowfall episodes relative to the time of peak snowfall rate (see Figure 8). The results show that the snow load increases on average by 7 hPa three days after the peak of snowfall compared to its value three days before the peak. During the same time interval, atmospheric pressure decreases by 8 hPa and reaches its minimum value when the snowfall rate is maximum. It then recovers up

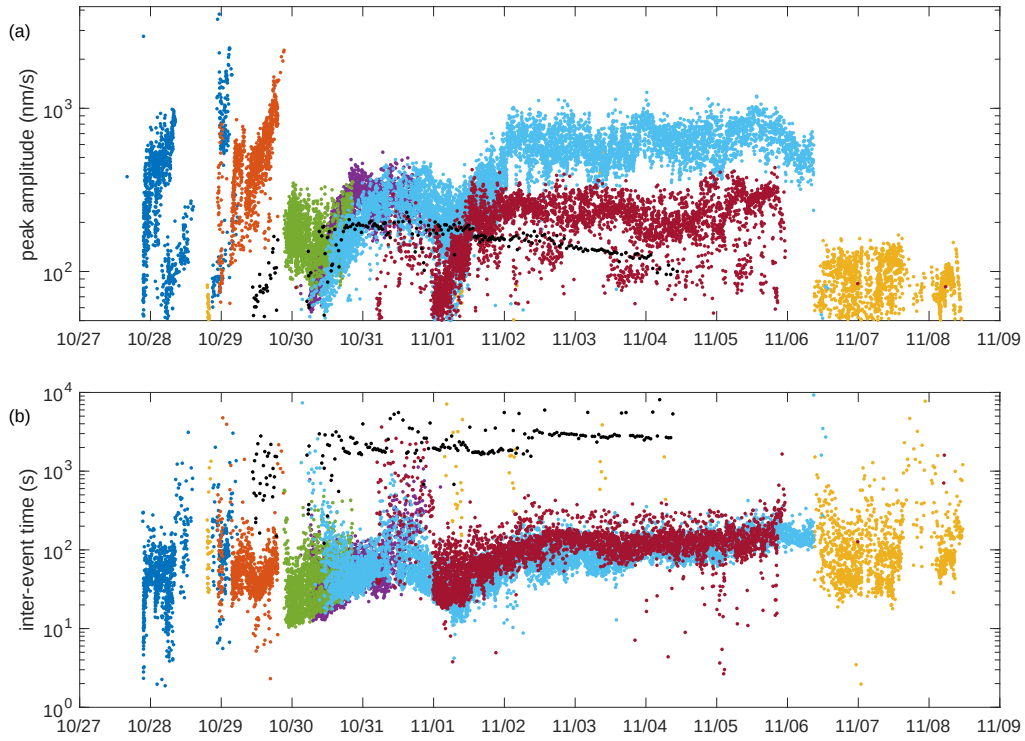


Figure 4. Temporal evolution of peak amplitude (a) and recurrence time (b) for a selection of 8 different clusters of repeaters between 2018/10/27 and 2018/11/9.

to -3 hPa three days after the peak of snow rate. Summing snow load and atmospheric pressure, the average effect on normal stress change is thus positive for times larger than one day after the peak of snowfall rate. The average rate of LFIs is larger than average for positive times, when both atmospheric pressure and snow load increase. Note however that this describes the average behavior but that individual sequences can differ widely from this typical pattern.

Figure 9 further confirms that LFIs occur predominantly during snowfalls, but also during times of low atmospheric pressure and when pressure increases. Figure 9 shows the probabilities distribution function (pdf) of atmospheric pressure, hourly atmospheric pressure change, and snowfall rate. It compares the pdfs at all times during seismic acquisition (blue curves) and at times of LFIs (red curves). LFIs are roughly two or three times more frequent than average during snowfalls and when atmospheric pressure is lower than 750 hPa. The change in atmospheric pressure has a smaller impact on the occurrence of LFIs, with the rate of LFIs increasing by 21% when the atmospheric pressure increases (Figure 9b).

I also estimated the relation between the cumulated snowfall weight during each snowfall episode and the rate of repeaters (Figure 10). I defined snowfall episodes from the snowfall hourly data as consecutive days (24 hrs) with a positive snowfall rate separated by at least 24 hrs without snow. Clusters were separated into temporal sub-clusters as described in section 4.1. For each snowfall episode, I selected sub-clusters that initiated after the beginning of the snowfall and I count all events of the sub-cluster until 10 days after the peak of snowfall rate, even after the end of the snowfall episode. Both the number of events and the number of clusters increase roughly exponentially with the cumulated snowfall weight. The correlation coefficient is $R = 0.52$ for the number of

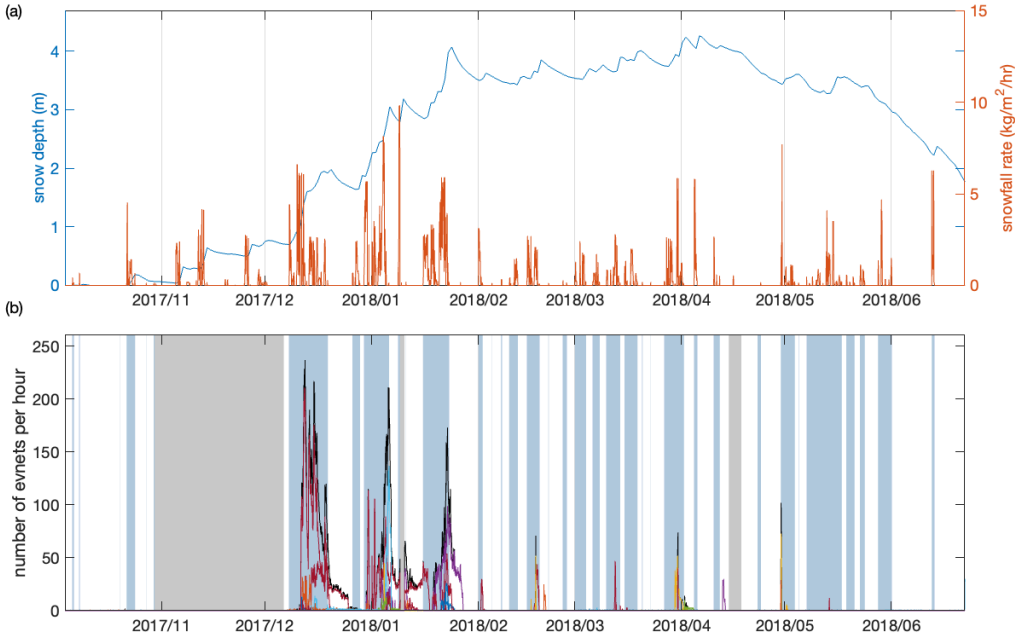


Figure 5. (a) Temporal evolution of snow depth and snow rate and (b) rate of repeating events detected at station B01. Blue shaded areas indicate snowfall episodes and grey areas data gaps. Different colors indicate different clusters. The black curve represent the sum over all clusters.

events and $R = 0.60$ for the number of clusters. These correlations are significant at the 99% confidence level. There is however a considerable scatter around this trend, many snowfall episodes not triggering repeaters. The magnitude of LFIs shows no significant correlation with the snowfall weight.

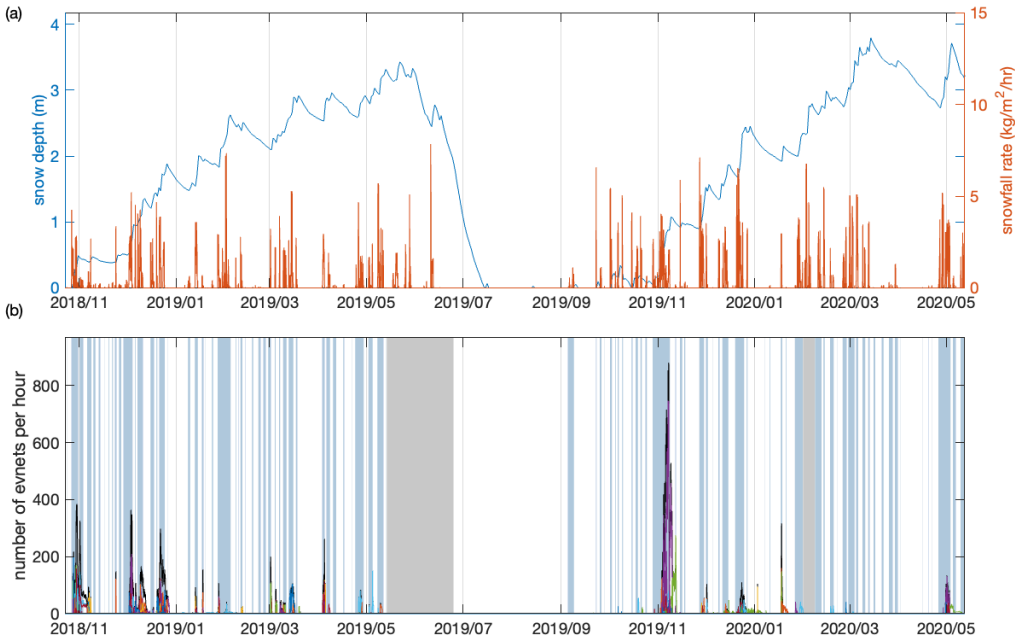


Figure 6. Same as Figure 5 for the time period 2018/10/23-2020/5/12. a) Temporal evolution of snow depth and snow rate and (b) rate of repeating events detected at station B03 before 2020/1/28 and at station B02 after 2020/1/28.

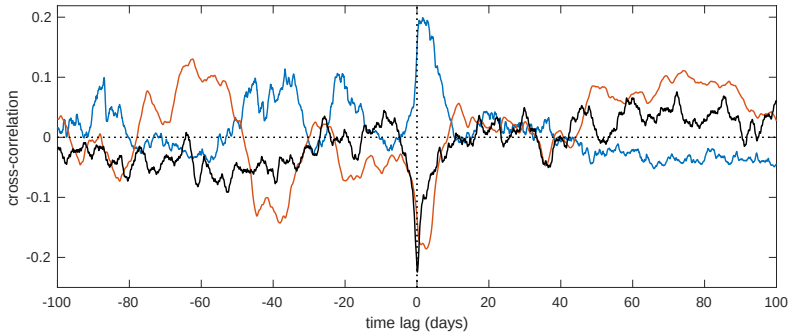


Figure 7. Normalized cross-correlation function between snowfall rate and hourly rate of LFIs for the time period 2017/10/4-2020/5/12 in blue, between hourly rate of LFIs and atmospheric pressure in red, and between atmospheric pressure and snowfall rate in black.

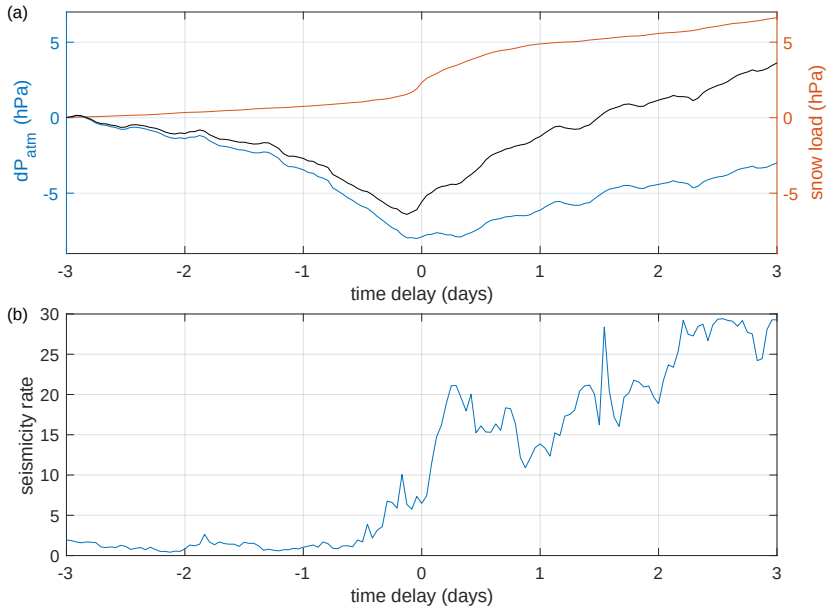


Figure 8. Average temporal evolution of (a) snow-fall weight in red, atmospheric pressure in blue, sum of these two terms in black and (b) rate of LFIs, stacking over 29 selected snowfall episodes with a total weight larger than 1 hPa (10 kg/m^2) and aligned in time relative to the peak of snowfall rate.

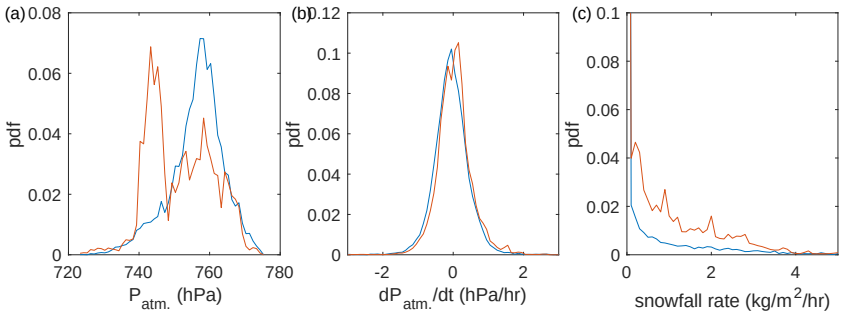


Figure 9. Probability distribution functions (pdf) of the atmospheric pressure (a), hourly atmospheric pressure change (b), and snowfall rate (c). In each plot, the blue curve represents the pdf at all times during seismic acquisition, while the red curves shows the pdf at the times of LFIs. LFIs occur predominantly during low atmospheric pressure (a), increasing atmospheric pressure (b) and during snowfalls (c).

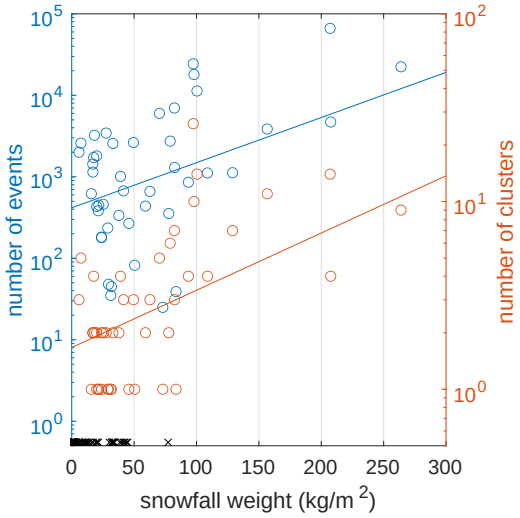


Figure 10. Evolution of the number of events (in blue) and of the number of activated clusters (in red) as a function of the snowfall weight during each snow-fall episode. Black crosses at the bottom indicate snowfall episodes that did not trigger any event.

5.4 Icequakes Location and Magnitudes

I have selected all 96 clusters with at least 7 phases picked by at least 4 stations, including at least one station outside Argentière Glacier. These criteria yield a horizontal location accuracy of about 1 km or less. A map is shown in Figure 11. Clusters are located all over the Mont-Blanc massif, from Glacier de Tré la Tête toward the South to Aiguille d'Argentière toward the North. Most clusters are located on or close to glaciers. For clusters outside glaciers, the distance to the closest glacier is generally smaller than the horizontal location accuracy. Figure 11 shows horizontal error ellipses corresponding to the 68% confidence interval, the length of theses ellipses should be multiplied by 1.62 to get the 95% confidence intervals.

Many clusters are located close to the crest between Aiguille des Grand Montets (near station N13) toward the West and Aiguille du Triolet toward the East. The high density of clusters in this area is likely a consequence of the distribution of seismic stations. Indeed, most seismic stations used for the detection (B01, B02 and B03) or the location (N13, N21, N31 and B04) are located on or close to Argentière glacier. Station BLANC was only used for the period 2019/6/14-2022/6/1 and is much noisier than stations B01, B02 and B03. Two clusters detected using station B03 as reference are located far away from Argentière Glacier, one cluster on the eastern face of Mont-Blanc and another cluster below the North face of Grandes Jorasses. The cluster located near the summit of Mont-Blanc has the largest magnitude and the best location accuracy. It was detected by 19 seismic stations up to 68 km away.

I also detected one cluster of LFIs located near Glacier de Trèlaporte (longitude 6.931°E, latitude 45.9054°N) and another below Glacier de l'Envers de Blaitière (6.928°E, 45.889°N) with unusual characteristics compared to the other clusters in the Mont-Blanc area. The cluster near Glacier de Trèlaporte is less regular than the other clusters and had a longer typical recurrence time (median of 33 mn). Both clusters were located near 2400 m a.s.l. about 100 m below the front of the glaciers and occurred mainly in late spring and summer. Given the location accuracy, they could possibly occur on the glaciers, which are likely temperate at this elevation. Or they could be associated with gravitational instabilities in the rock induced by the recent glacial retreat in this zone and promoted by the increase in melt-water in spring and summer. Indeed, repeating events have also been detected on landslides (*Uchida and Bürgmann*, 2019). Similar low-frequency repeating signals have been detected on Moosfluh rockslide in Switzerland, a rockslide recently reactivated by the retreat of Aletsch Glacier (*Helmstetter et al.*, 2018). This suggests that there is not a single mechanism that explains all our observations, but that different physical processes may generate LFIs, likely different for temperate and cold-based glaciers. And that some of our "LFIs" may in fact be due to landslides.

Figure 12 illustrates the characteristics of all located clusters. Most events are shallower than 100 m. Icequake depths range between the surface and 3664 m below, with an average of 746 m and a median of 107 m. Depth is generally smaller than vertical location error, with an average vertical error of 987 m (68% confidence interval). Icequake locations and depths are thus consistent with glacier basal sliding but the large vertical location error does not allow to demonstrate this assumption and to exclude that LFIs could occur within the glacier. Epicenters are often above 3000 m a.s.l, with an average value of 3215 m. The average time residual is 0.14 s, comparable to values obtained for local earthquakes detected by Sismalp in the Mont-Blanc massif. This suggests that both the velocity model and the phase arrivals are correct. The local and surface magnitudes have very similar values ranging between -1.4 and 0.1 A linear fit gives $M_l = 0.85M_s + 0.02$ with a correlation coefficient of 0.93. The surface-waves magnitude M_s better explains the observed amplitudes, probably because seismic signals are dominated by surface waves. The average standard deviation of magnitudes between stations is 0.26 for M_s and 0.29 for M_l. The distribution of magnitudes is difficult to interpret due to the small number of clusters. The decay for $M < -1$ is likely due to the detection thresh-

old and to the temporal changes in detection capacity when using different stations for detection.

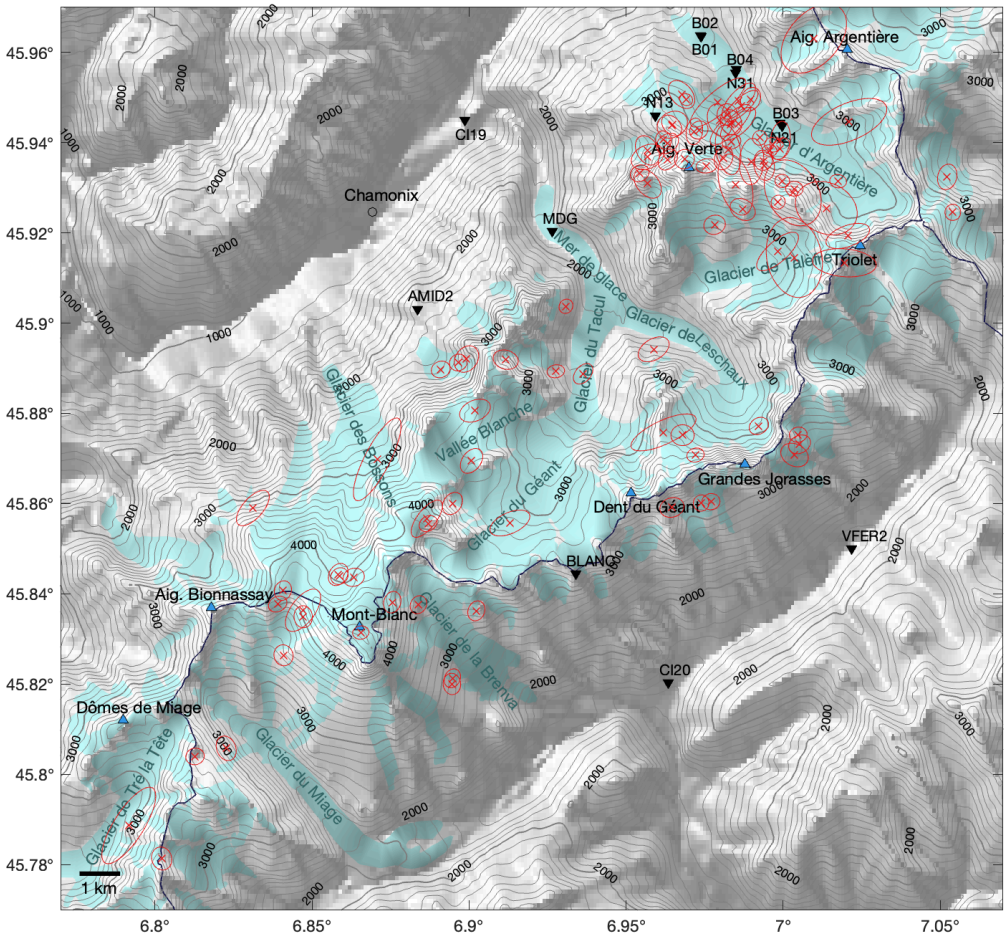


Figure 11. Map of repeating LFIs located in the Mont-Blanc massif (red crosses). Red lines show the horizontal error ellipses at the 68% confidence level. Seismic stations are shown by black triangles. Grey lines show the topography, black lines are national boundaries and blue areas are glaciers.

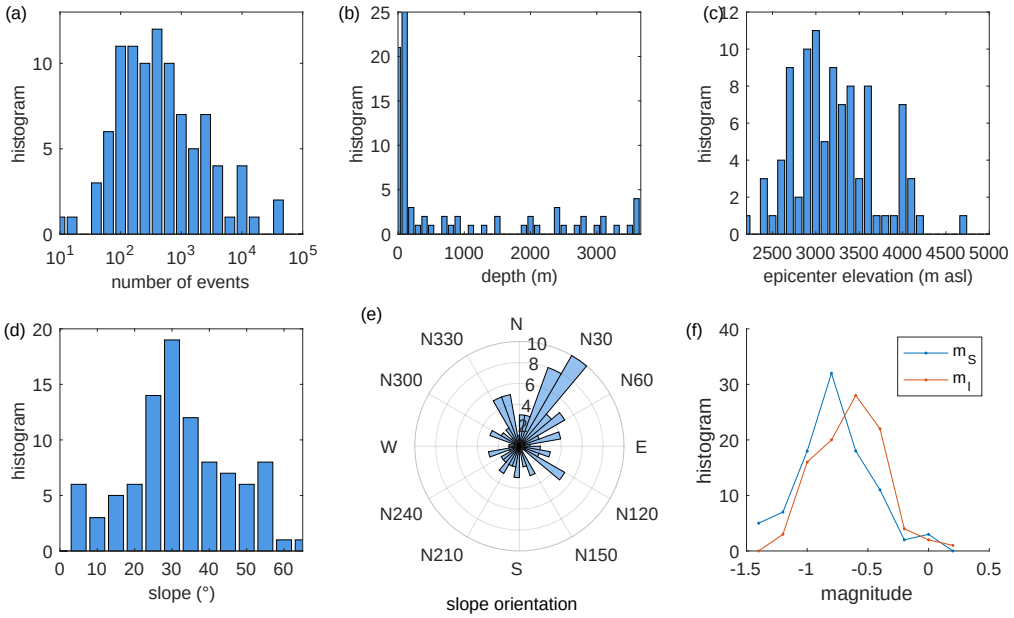


Figure 12. Characteristics of all located clusters: (a) distribution of the number of events per cluster (after removing temporally isolated events), (b) depth, (c) epicentral elevation, (d) slope and (e) slope orientation at the epicenter location, (f) surface wave and local magnitudes of the largest event of each cluster.

Figure 13 shows the seismograms and spectrums for the cluster located near the Mont-Blanc summit. The signal, stacked over all 446 events, is visible as far as 68 km away. The magnitude of the largest event is $M_S = 0$. The signal has the same frequency content over all stations with a peak near 5 Hz. This further suggests that this peak is a source property and is not affected by attenuation.

5.5 Precursory Tremor-Like Signal

While most clusters start with small events and random occurrence times, one cluster initiated on 2021/1/13 as a large amplitude and long-duration signal. This cluster was located near Glacier de la Brenva (6.902°E, 45.836°N) with the epicenter at 3250 m a.s.l.. The signal during the first 1000 s of this cluster is shown in Figure 14. The sequence started as a low-frequency but broadband signal (1-15 Hz) that lasted for about 100 s. It was detected at four seismic stations (BLANC, CI20, MFERR and CI19). Because there is no visible P and S waves, it cannot be located accurately. Fixing the hypocenter at the location of the LFI cluster, the regional seismic network Sismalp provides an estimate of the magnitude $m_l = 0.1$. Two LFIs are detected at the beginning of this "tremor", with amplitudes larger than the following events. This suggests that this signal could be a swarm of overlapping LFIs, similar to non-volcanic tremor (*Shelly et al.*, 2006; *Shelly et al.* , 2007). But the "tremor" signal duration and frequency content is also similar to signals generated by snow avalanches, rockfalls or seracs falls. It could also be generated by water flow but this seems unlikely since it occurred in January above 3000 m a.s.l..

5.6 Temporal Changes in Waveforms

Many clusters show progressive changes in waveforms, as illustrated in Figure 15 for the cluster with the largest number of events. This cluster located near the summit of Aiguille Verte was almost continuously active between 2017/12/11 and 2018/1/18. During this period I detected 28978 events at station B01 located at 3.5 km from the source. This cluster is also shown in Figures 1, 2 and 3. I applied a SVD-based Wiener filter to denoise the data (*Moreau et al.*, 2017), keeping the first 15 singular values and the closest 3 neighbors in both time and event index. The first arrivals (P and S waves) show little variation with time, suggesting that the source did not migrate. Apparent variations of S-P arrival times could be due to uncertainties on P-wave picks. I see however clear progressive changes for late arrivals, as large as 0.3 s.

6 Discussion

6.1 Location and Basal Conditions

Most clusters are located on or near glaciers, and at depths shallower than 100 m. Icequake locations and depths are thus consistent with glacier basal sliding. I assume that most LFIs are located at the ice-bed interface but the vertical location accuracy is too large to test this assumption. All repeatings icequakes or earthquakes have been located on major shear zones (ice-bed interface, major tectonic faults or subductions zones) (*Podolskiy and Walter*, 2016; *Uchida and Bürgmann*, 2019). The stick-slip phenomena is the only physical process that has been proposed to explain repeating events, except on volcanoes, therefore it seems unlikely that LFIs could be located within the glacier. Focal mechanisms could be used to estimate the source mechanism (e.g., fracture opening or slip, fault plane geometry and slip direction), but because LFI signals are monochromatic and emergent, it is very delicate to identify the direction of P waves first arrivals.

Epicenters are often above 3000 m a.s.l and mainly on North facing slopes (Figures 11 and 12). At these locations, the presence of cold ice is possible. Indeed, a temperature of -2°C has been measured at the base of Tête Rousse glacier, at 3100 m a.s.l.

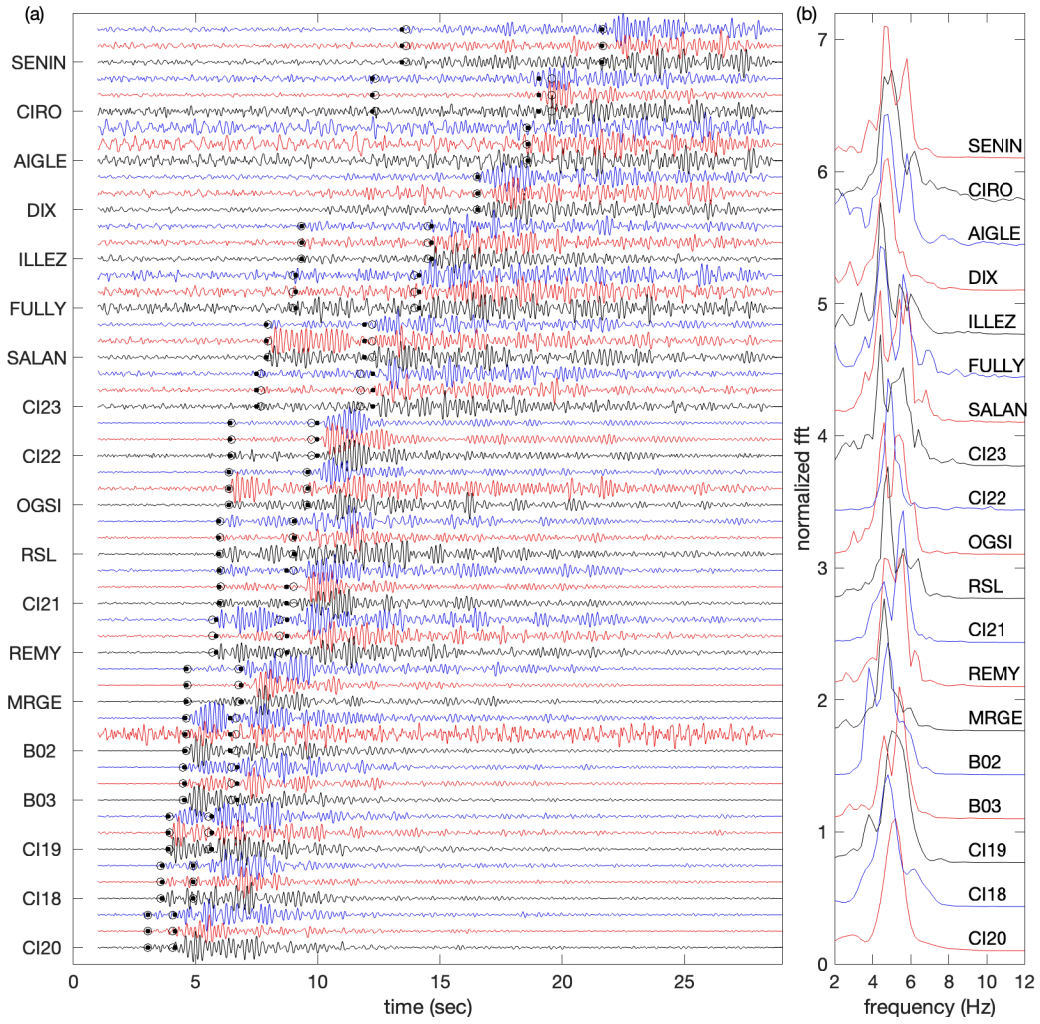


Figure 13. Seismograms (a) and (b) spectrums at all stations where the icequake signal could be picked for the cluster located near the Mont-Blanc summit. Seismograms (ground velocity) were stacked over all events of the cluster, filtered between 2 and 20 Hz and normalized by the peak amplitude of each trace. Picks of P and S waves are shown as black dots and estimated arrival times as open circles. Stations are ordered according to their epicentral distance, from 9 km for station CI20 up to 68 km for station SENIN. Spectrums of the vertical traces in (b) were also normalized by the peak value and shifted vertically for clarity.

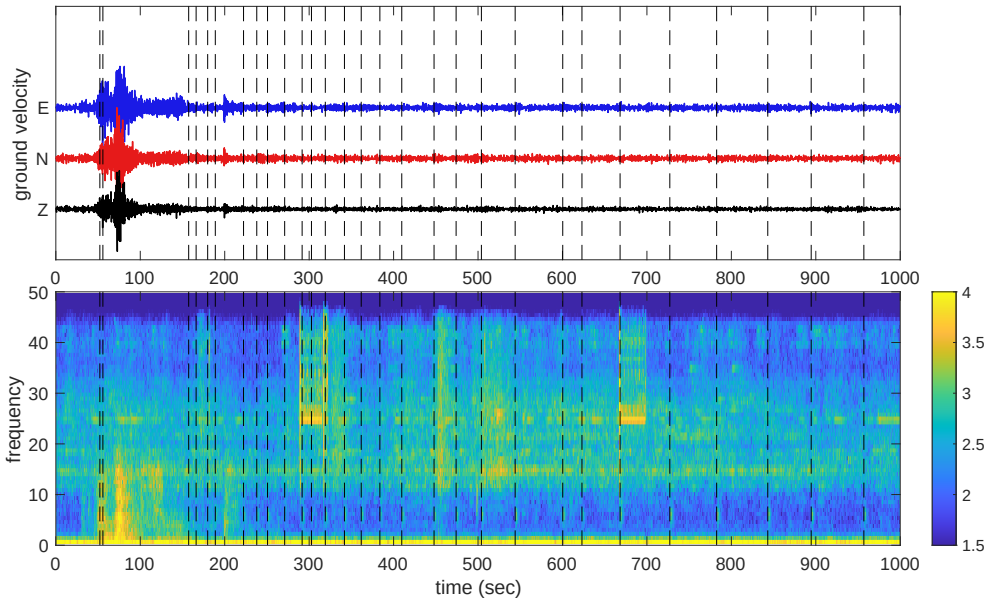


Figure 14. Seismograms (a) and (b) spectrogram of the signal recorded at station BLANC on 2021/1/13 at 21:55 UTC. Black vertical dashed lines correspond to LFIs. This cluster started at 21:55:52 and lasted for 15.78 hours. Seismograms in (a) are bandpass filtered between 1 and 10 Hz. A "tremor-like" signal is visible between about 50 s and 150 s and contains two LFIs. Spectrogram in (b) is averaged over the three components and color represents the $\log_{10}$ of the power spectrum.

(*Gilbert et al.*, 2012). Some clusters are clearly associated with cold ice, near Mont-Blanc summit or Col du Dôme. *Vincent et al.* (2020) measured a temperature of the ice close to the bedrock of -11°C at Col du Dôme in 2017 (elevation 4250 m a.s.l., latitude 45.841°N, longitude 6.8479°E). Many clusters are located around 3000 m a.s.l., possibly close to the transition between temperate and cold ice.

The motion of temperate glaciers (ice-bed interface at the melting point) is mainly due to basal slip, while cold-based hard-bedded glaciers (ice-bed interface below freezing) are thought to deform mainly by viscous flow in the bulk of the glacier (*Cuffey and Paterson*, 2010). There are however some observations of basal slip in polar glaciers at very cold temperatures (*Cuffey et al.*, 1999; *Cuffey and Paterson*, 2010). Laboratory ice-on-rock or ice-on-till friction experiments have been used to infer how the frictional properties of ice depend on temperature. These experiments have shown a transition from a rate-weakening (friction decreasing with sliding velocity) to a rate-strengthening behavior for increasing temperatures and a decrease of both healing and friction with temperature (*McCarthy et al.*, 2017; *Zoet et al.*, 2018). A rate-weakening behavior is required to generate dynamic rupture such as earthquakes or icequakes. The transition to rate-weakening friction is also favored by increasing sliding velocity, increasing debris concentration, and increasing drainage (*McCarthy et al.*, 2017; *Zoet et al.*, 2018). Other studies suggested that stick-slip events at the base of temperate glaciers or ice-streams could be due to the friction of sediments entrained by the glacier motion (*Lipovsky et al.*, 2019) or to the ploughing of clasts embedded in the base of the ice through till (*Barcheck et al.*, 2018; *Thomason and Iverson*, 2008). So far, laboratory friction experiments with ice-rock or ice-till interfaces have only observed a velocity-weakening behavior for cold ice, even for debris-laden ice (*McCarthy et al.*, 2017; *Saltiel et al.*, 2021; *Zoet et al.*, 2018).

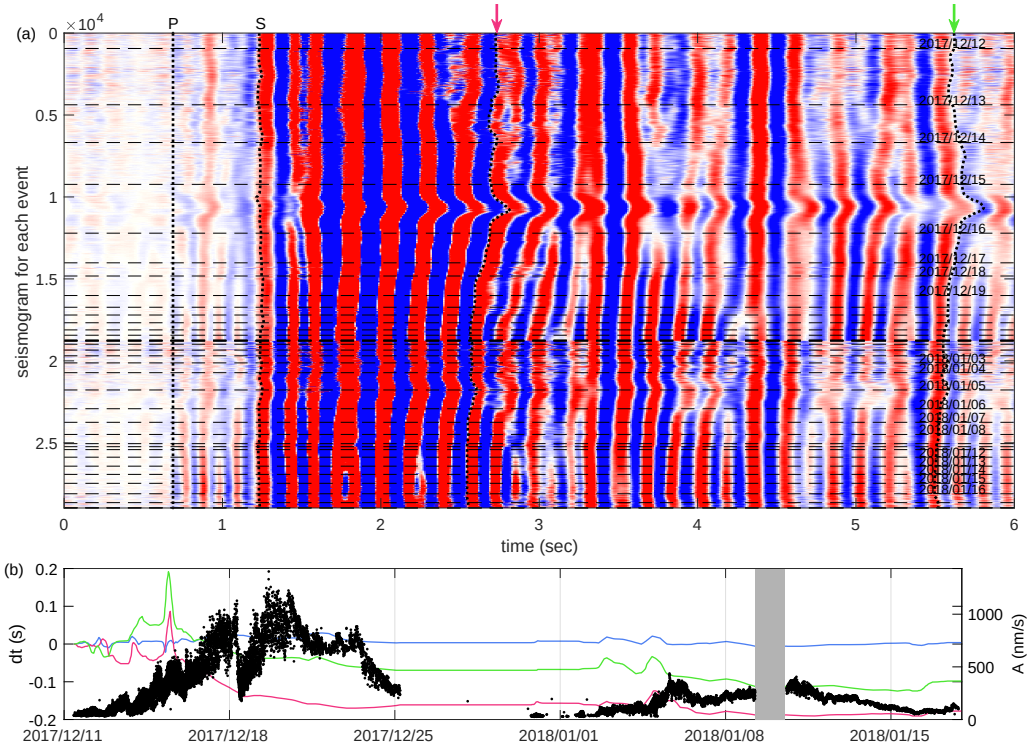


Figure 15. Temporal changes in waveforms for a cluster detected at station B01. (a) Seismograms for the North component of station B01 filtered between 2 and 20 Hz and normalized by the peak amplitude of each trace. I also applied a SVD-based Wiener filter (*Moreau et al.*, 2017) to improve the signal-to-noise ratio. Seismograms are aligned on the P wave arrival time, which was manually picked on the vertical channel with a stronger P wave amplitude than the north component. Arrival times of P and S waves are shown as near-vertical dotted lines (manual picks). The other two dotted lines marked by arrows correspond to late phase arrivals with strong temporal variations. Each dashed horizontal line corresponds to a new day. (b) Arrival time of different phases relative to the P wave arrival time and relative to the first event of the cluster: blue line for the S wave, pink and green lines for each phase indicated by a pink and green arrow respectively in (a). Black dots show the peak amplitude of each event. The grey area indicates a data gap.

Much larger and lower frequencies icequakes repeat about twice a day at the base of Willans Ice Stream in Antarctica because basal friction is modulated by oceanic tides (*Wiens et al.*, 2008). While most of the ice-stream is temperate at the base, the recent slowdown of the ice-stream and the occurrence of repeating stick-slip events may be due to basal freezing, with stick-slip events occurring on islands of cold based ice (*Joughin et al.*, 2004; *Saltiel et al.*, 2021).

6.2 Source properties

From the magnitudes of LFIs, we can estimate possible values of source properties. The seismic moment M_o is related to the moment magnitude M_w by $M_w = \log_{10}(Mo)/1.5–6.03$ (*Hanks and Kanamori*, 1979). Assuming that our values of $-1.4 < M_s < 0$ are representative of M_w, I obtain a seismic moment ranging between 8.9×10^6 and 1.1×10^9 N.m for the largest event of each cluster. These values are much larger than the moment magnitude $-3.2 < M_w < -2.2$ estimated for the high frequency icequakes detected at Argentière glacier (*Helmstetter et al.*, 2015). The seismic moment is related to the shear modulus μ (2.3 GPa for ice), the slip d and the rupture area A by $M_0 = \mu Ad$. I can thus only constrain the product of rupture area and slip. I can get a lower bound on the rupture radius $r = \sqrt{A/\pi}$ by assuming that during bursts of LFIs all the glacier displacement is due to seismic slip. This assumption may overestimate the seismic slip (and underestimate rupture length) if there is significant viscous deformation or underestimate d and over-estimate r if there is an acceleration of glacier displacement during bursts of LFIs. Cold glaciers move much slower than temperate glaciers. *Vincent et al.* (2020) measured a maximum ice flow velocity of 10 m/yr at Col du Dôme in 2017. The cluster with the largest magnitude $M_s = 0$ (located near the summit of Mont-Blanc) has a median recurrence time of 1000 s. This gives a slip per event of 0.3 mm and a rupture length of 23 m. If only half of the displacement is due to basal slip, then the slip is 0.15 mm and the rupture length $r = 33$ m.

The stress drop $\Delta\tau$ can be estimated as

$$\Delta\tau = \mu \frac{d}{r} \frac{7\pi}{16} \tag{4}$$

for a circular rupture (*Eshelby*, 1957), yielding $\Delta\tau = 42$ kPa for $d = 0.3$ mm and a radius $r = 23$ m. This value is about one hundred times smaller than the value observed for tectonic earthquakes (*Abercrombie*, 1995). It is about 100 times larger than the normal stress induced by the smallest snowfalls that trigger LFIs.

We can also estimate the rupture length from the main frequency of the signal, assuming that the peak in the spectrum corresponds to the corner frequency. *Madariaga* (1976) derived the following relation between the rupture radius r and the corner frequency f_c

$$f_c = kV_S/r \tag{5}$$

for numerical 2D simulations of a circular crack expanding at a constant rupture velocity V_r. Assuming $V_r = 0.9V_S$, the constant k is equal to 0.21 for shear waves. Assuming $f_c = 5$ Hz and a shear wave velocity $V_S = 2500$ m/s (intermediate between the value in the ice and in the bedrock) I obtain a source radius $r = 105$ m. This value is comparable with but larger than the length $r = 23$ m estimated above from the maximum seismic moment and the glacier velocity. This suggests that LFIs only account for a small fraction of glacier displacement rate even during bursts of LFIs. Using this value of the source radius $r = 105$ m and a maximum seismic moment of 1.1×10^9, I obtain a slip of 14 μm and a stress drop of 0.4 kPa comparable with the stress change induced by snowfalls.

6.3 Temporal changes in waveforms

Many clusters of repeating LFIs show progressive changes in waveforms, as illustrated in Figure 15. Figure 15a shows the waveforms of a cluster of 28000 LFIs that occurred near the summit of Aiguille Verte about 3.5 km away from station B01. Arrival times in the coda of both P and S waves vary by up to 0.2 s while the first arrivals do not change (Figure 15b). This suggests that the nucleation point does not evolve during clusters, i.e, there is no evidence for migration in time. These variations could thus be explained by changes in the medium, by changes in the rupture area or in the rupture velocity. I don't think that changes in the medium could explain such large changes in travel times (up to 10%) over such short time periods (a few hours or days). Most of these clusters occur in winter at large elevations where there is no or very little water. The snow layer evolves with time but the low-frequency seismic waves near 5 Hz are not strongly sensitive to this shallow layer. I thus propose two explanations for these changes in seismic signals, either changes in the rupture area or changes in the rupture velocity. Both parameters control the rupture duration and the signal frequency content.

A very slow rupture velocity of about 150 m/s has been measured for repeating basal icequakes at Whillans Ice Stream in West Antarctica (*Wiens et al.*, 2008). *Walter et al.* (2011) further observed temporal changes in rupture velocity between 100 and 300 m/s between successive events, correlated with inter-event times and slip amount. *Walter et al* (2015) reproduced these results in a laboratory stick-slip experiment, showing that rupture velocity depends on pre-rupture stress. A progressive change in rupture velocity could explain our observations of changes in seismic waveforms. However, in our case I found no clear correlation between changes in seismic waveform and changes in the amplitude of repeating LFIs (see Figure 15b). I thus don't know how to explain these possible changes in rupture velocity or rupture length.

It is not clear wether the duration of the signal larger than 5s is due to the source or to the seismic waves propagation. If the rupture lasts for several seconds, it suggests a very slow rupture to be consistent with the rupture length $r = 105$ m estimated from the main frequency of the signal of 5 Hz. Because of the shallow source, of the heterogeneous medium and of the complex topography, it is possible that the late arrivals are diffracted or reflected waves rather than direct waves.

6.4 Triggering by snow

Repeating LFIs are mainly observed during and after snowfalls, while high-frequency icequakes are not sensitive to snowfalls (*Helmstetter et al.*, 2015). Our observations are very similar to LFIs detected at Mount Rainier, an ice-covered volcano in the USA (*Allstadt and Malone*, 2014; *Thelen et al.*, 2013). Both sites generate bursts of LFIs lasting for days or weeks and triggered by snowfalls, with similar recurrence times of a few minutes, magnitudes $-1 < M < 0$ and peak frequency around 5 Hz. *Allstadt and Malone* (2014) reported that Mount Rainier is a temperate glacier, whose displacement is dominated by basal sliding, and interpreted the LFIs at Mount Rainier as due to stick-slip on asperities surrounded by aseismic basal sliding. However, the location of icequakes at Mount Rainer is not well constrained, and they could be located near the top of the volcano (at 4392 m a.s.l.) where the ice temperature is likely below the melting point (*Mills*, 1979).

Allstadt and Malone (2014) also observed a progressive change in waveforms within each cluster using coda wave interferometry, which they interpreted as due to a migration of the source with the glacier flow. In our case, I interpreted the temporal change in seismic waveforms as due to variations of rupture length and/or rupture velocity, because the first P and S arrivals did not change. This assumption may also explain the variations in seismic waveforms at Mount-Rainier.

Allstadt and Malone (2014) suggested that additional loading due to snowfalls perturbs the glaciers from smooth sliding to stick-slip regime. Using a rate-and-state friction law (*Dieterich*, 1979) to model the sliding of the glacier over its bed, we can indeed reproduce a transition from stable sliding to the stick-slip regime by increasing normal stress (*Helmstetter et al.*, 2018; *Lipovsky et al.*, 2017). The increase in normal stress associated with snowfalls is however partly cancelled by the associated decrease in atmospheric pressure, but the overall effect of atmospheric pressure and snow weight tends to increase the normal stress toward the end of each snowfall episode, when most LFIs occur (Figure 8).

The change in normal stress associated with snowfalls is very small compared with the normal stress at the base of glaciers. A snowfall of 25 cm with a density of 0.4 increases the normal stress by about 1 kPa, about 0.1% of the normal stress at the base of a 100 m thick glacier. It is thus surprising that such a small stress change triggers so many LFIs. However, earthquakes have been shown to be even more sensitive to smaller relative stress perturbations. Seismicity is modulated by ocean tides, corresponding to a stress change of about 10 kPa, while the normal stress at 10 km depth is about 300 MPa (*Thomas et al.*, 2009). This high susceptibility of earthquakes and LFIs suggests that faults and ice-bed interfaces are very close to the rupture threshold, at least at some points, and that rupture initiates rapidly when stress reaches the failure threshold.

For Alpine glaciers very close to the melting point temperature, another mechanism could explain the triggering by snowfalls. The additional weight induced by snowfalls slightly decreases the melting point temperature, so that the basal temperature may reach the melting point temperature. This could produce a transition between a locked ice-bed interface for cold ice and stable sliding at the melting point, which could be associated with stick-slip events progressively leading to stable sliding. The increase in pressure due to a typical snowfall of 25 cm with a density of 0.4 is about 1 kPa, leading to a change in melting temperature of about 10^{-4} K (Clausius-Clapeyron constant). Therefore this mechanism may only be active very close to the transition between cold-based and temperate glaciers.

The correlation between snowfalls and LFIs could suggest that LFIs occur within or at the base of the fresh snow layer. But then it is be difficult to explain why LFIs occur regularly in time and why they mainly occur above 3000 m a.s.l. And because seismic waves attenuate very fast in the snow and shear modulus is much smaller in the snow than in the ice, it is difficult to explain how the signal could be detected up to 68 km away.

Repeating LFIs triggered by snow falls have also been detected on Gugla rock glacier in Switzerland (46.1394°N, 7.8183°E) (*Guillemot et al.*, 2020; *Helmstetter et al.*, 2018). These studies suggested that these events were associated with stick-slip behavior at the base of the rock-glacier. However, I realized that most clusters detected at Gugla were also visible at other permanent seismic stations (stations MMK, SIMPL, EMBD, SNIB, VANNI and DIX in Switzerland, network code CH and Italian station SATI, network code GU). Several clusters have been located at distances between 2 and 7 km East or South-East from Gugla. These locations are not very accurate but are all possibly associated with glaciers above 3000 m a.s.l.. These events are thus very similar to LFIs in the Mont-Blanc area and may be produced by the same physical processes.

6.5 Comparison with earthquakes

Both faults and subglacial slip exhibit a wide spectrum of behavior, from stable slow slip to dynamic rupture, with transient slip events ranging over a wide range of spatial and temporal scales (*Peng and Gomberg*, 2010). Tectonic faults and subduction zones produce both fast earthquakes, with duration of the order of seconds, and slow slip events, with duration of days or months, and probably a continuum of slip modes in between

(*Thøgersen et al.*, 2019). LFIs in the Mont-Blanc area share several properties with low-frequency earthquakes (LFEs). LFEs are due to shear slip on faults like regular earthquakes but their signal lack of high frequency energy. They are mainly detected on transform faults (e.g. San Andreas) or subduction zones in the lower part of the locked seismogenic zone near the brittle-ductile transition (*Shelly et al.*, 2006; *Shelly et al.* , 2007). LFEs have much smaller stress drops, smaller slip-rates and smaller rupture velocities than regular earthquakes (*Thomas et al.*, 2016). Like LFIs, LFEs can be triggered by very small perturbations, like distant earthquakes or tides. *Thomas et al.* (2009) observed that LFEs on the San Andreas are very sensitive to tidally induced shear stress changes with peak-to-peak amplitudes less than 0.5 kPa. Both LFEs and LFIs seem to occur mainly near the transition between stable sliding (under temperate glaciers for LFIs and below the seismogenic zone for LFEs) and locked areas (under cold-based glaciers for LFIs and in the seismogenic zone for LFEs). LFEs are more sensitive than regular earthquakes to small stress changes. Similarly, the small snowfalls that trigger LFIs in the Mont-Blanc area do not produce any increase in the rate of HFIs (*Helmstetter et al.*, 2015).

Repeating earthquakes occur regularly on the same asperity (*Nadeau et al.*, 1995; *Uchida and Bürgmann*, 2019). The stress increases between events due to aseismic slip around the asperity. This mechanism can also explain the repeating HFIs on temperate glaciers, which have a large amount of aseismic basal slip. However, many LFIs occur on cold-based glaciers, so that there is very little slip at the ice-bed interface. The reloading between stick-slip events may thus be due to viscous creep within the bulk of the glacier rather than from slip around the asperity.

7 Conclusion and Perspectives

I have discovered repeating LFIs in the Mont-Blanc massif. Some clusters of LFIs are located on cold based glaciers (e.g., near Mont-Blanc summit or near Col du Dôme), a few ones on temperate glaciers or possibly on rockslides activated by glacial unloading. For most clusters the basal conditions are unknown but are likely close to the melting point temperature.

I found both similarities and major differences between repeating HFIS and LFIs Both LFIs and HFIs occur more or less regularly in time, repeating every few minutes, and display progressive changes in amplitude and recurrence times. While HFIs are located at the base of temperate alpine glaciers, most LFIs are located at higher elevations. LFIs are triggered by snowfalls while HFIs are not sensitive to snowfalls. The differences between HFIs and LFIs are similar to the ones between regular earthquakes and LFEs, suggesting that they reflect common physical processes controlling rupture nucleation and propagation. Low-frequency events are more sensitive to smaller perturbations, occur near the transition between the locked and the creeping areas, and have slower rupture velocities and smaller stress drop compared with high-frequency events. Understanding what controls the nucleation of LFIs could yield important information on basal properties and their temporal evolution.

The sources properties (depth, rupture length, rupture velocity, stress drop) of LFIs are difficult to estimate because I do not have near-field data. LFIs are difficult to monitor because they occur mainly at high elevations, on steep faces exposed to snow avalanches or serac falls. Installing seismometers in such places is thus difficult and dangerous. In addition, bursts of LFIs usually last for a few days and mainly occur during snowfalls. Even if we can detect and locate in real time the beginning of a cluster, we cannot go in the field to install seismometers nearby when the weather is bad, and LFIs often stop before the weather improves. Satellite images could be used remotely and retrospectively to estimate glacier motion. They could be used to test wether the glacier accelerates during bursts of LFIs or if clusters of LFIs occur at constant displacement rate. LFIs could be due to a transition between creep-dominated deformation within the glacier and basal

stick-slip motion. However, while some studies have estimated the average displacement rate in the Mont-Blanc area, the resolution is not yet good enough to detect short-term (days to weeks) temporary variations in velocity (*Millan*, 2019).

Similar repeating LFIs have also been observed in the Swiss Alps (*Helmstetter et al.*, 2018) and at Mount Rainier (*Allstadt and Malone*, 2014). They probably occur elsewhere on Alpine glaciers. Trying to detect these events using existing regional seismic networks near glaciated areas could help us to understand the link between LFIs and glacier basal conditions.

Numerical modeling could be interesting to learn more about LFIs source processes and triggering mechanisms. We could try to simulate seismic signals of LFIs by changing the rupture velocity or the rupture length to reproduce the observed temporal changes in seismic waveforms. Several processes could explain the triggering of LFIs by snowfall, either due to the increase in normal and shear stress or due the tiny change in melting point temperature with pressure. Numerical simulations could be used to test both hypothesis. *Helmstetter et al.* (2018) already attempted to reproduce repeating LFIs using the rate-and-state friction law. However, they assumed aseismic basal slip around the asperity. Our observations suggest that most LFIs occur on cold-based glacier, so that deformation is dominated by viscous creep rather than by basal slip. We could also test different friction laws developed for basal sliding, such as the model of *Gagliardini et al.* (2007).

8 Data availability statement

Some seismological data are available from the Federation of Digital Seismograph Networks (FDSN) network with network codes CH, GU, IV, FR, ZO, 1D, 8C. The list of all seismic stations used and network codes are given in Table 1. Some data is distributed by FDSN with restricted access (network codes XT, 8D). Data from temporary stations B01-B04, DOM and MDG on glaciers in the massif are (not yet) open and I am not allowed to share them. Catalogs of repeating LFIs and cluster locations are provided at `https://doi.org/10.5281/zenodo.6822165`. Meteorological data is available from GLACIOCLIM observatory (*Vincent et al.*, 2009) and S2M database (*Vernay et al.*, 2019). We used nonlinloc software (*Lomax et al.*, 2000) to locate LFIs. This program can be downloaded from `http://alomax.free.fr/nlloc/` and my input files (station locations, arrival times, velocity models, topography) can be downloaded from `https://doi.org/10.5281/zenodo.6822165`.

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