Mapping MMS Observations of Solitary Waves in Earth's Magnetic Field

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Abstract

Electrostatic solitary waves (ESWs) are a type of nonlinear time-domain plasma structure (TDS) generally defined by bipolar electric fields and propagation parallel to the local magnetic field. Formation mechanisms for TDSs in the magnetosphere have been studied extensively and are associated with plasma boundary layers and the braking of bursty bulk flows (BBFs). However, the rapid timescales over which these TDSs occur (< 2 ms) make them infeasible to count by eye over large time periods. Furthermore, high-cadence data are not always available. The Solitary Wave Detector (SWD) on NASA's Magnetospheric Multiscale (MMS) mission quantifies the occurrence and amplitude of TDS throughout the constellation's orbit; analysis of burst (65 kS/s) parallel electric field data indicates that the SWD captures appx. 60% of all bipolar TDS encountered in the tail region, enabling large-scale examination of their occurrence. Maps of TDS occurrence rates during several years of the MMS mission were generated from SWD data, showing enhanced TDS density in the tail region between 6-9 Re; enhance occurrence in or near shocks; and an unexpected enhancement in the dawn side of the tail and in the radiation belt.

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¹⁹ Key Points:

20	•	The MMS Solitary Wave Detector records time-domain structures in Earth's mag-
21		netosphere
22	•	SWD maps highlight regions like the Van Allen belts and the bursty bulk flow brak-
23		ing region

• The SWD shows intriguing nonlinear activity in the shocks, magnetotail, flank, and dawn-side outer radiation belt

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26 Abstract

Electrostatic solitary waves (ESWs) are a type of nonlinear time-domain plasma structure 27 (TDS) generally defined by bipolar electric fields and propagation parallel to the local mag-28 netic field. Formation mechanisms for TDSs in the magnetosphere have been studied ex-29 tensively and are associated with plasma boundary layers and the braking of bursty bulk flows 30 (BBFs). However, the rapid timescales over which these TDSs occur (<2 ms) make them 31 infeasible to count by eye over large time periods. Furthermore, high-cadence data are not 32 always available. The Solitary Wave Detector (SWD) on NASAs Magnetospheric Multi-33 scale (MMS) mission quantifies the occurrence and amplitude of TDS throughout the con-34 stellations orbit; analysis of burst (65 kS/s) parallel electric field data indicates that the 35 SWD captures appx. 60% of all bipolar TDS encountered in the tail region, enabling large-36 scale examination of their occurrence. Maps of TDS occurrence rates during several years 37 of the MMS mission were generated from SWD data, showing enhanced TDS density in 38 the tail region between 6-9 Re; enhance occurrence in or near shocks; and an unexpected 39 enhancement in the dawn side of the tail and in the radiation belt. 40

41 **1** Introduction

Kinetic instabilities are important for understanding the mediation of energy between 42 particles and electromagnetic fields in space plasmas. Time Domain Structures (TDS) are 43 an important subset of electric field structures associated with the non-linear evolution of 44 these kinetic instabilities. TDS are typified by short time-duration pulses in the electric field 45 component parallel to the background magnetic field, E||, and have broadband frequency 46 spectra (Temerin et al., 1982; Matsumoto et al., 1994; Ergun et al., 1998). TDS have been 47 speculated to be important for particle acceleration processes in the Earths magnetosphere 48 (F. S. Mozer et al., 2016). They can include unipolar electric field signatures that are as-49 sociated with an electrostatic potential drop, known as double layers, as well as bipolar elec-50 tric field signatures, called electrostatic solitary waves (ESWs). (Vasko et al., 2017) ESWs 51 can correspond to a variety of plasma structures, including electron phase-space holes (Muschietti 52 et al., 1999), ion phase-space holes(Main et al., 2006), electron bunching associated with 53 non-linear wave evolution (Wilder et al., 2016), and structures resulting from plasma mix-54 ing (Holmes et al., 2018). TDS and ESWs have been observed in several regions of geospace, 55 including the auroral acceleration region (Ergun et al., 2002; Andersson et al., 2002), the 56 dayside magnetopause (Cattell et al., 2002), the bursty bulk flow (BBF) braking region of 57 the Earths magnetotail (Ergun et al., 2015), the Earths bow shock (Goodrich et al., 2018), 58 and the solar wind upstream of Earth (Mangeney et al., 1999; Malaspina et al., 2013). 59

One example of TDSs that are important to understanding the magnetosphere is the 60 fast Earthward flows resulting from magnetic reconnection in the magnetotail. These flows 61 decelerate as they approach Earth and are diverted around the ring current. This braking 62 occurs on the nightside, skewed towards the dusk, between 6 and 10 Re away from Earth 63 (Sergeev et al., 2009; Ergun et al., 2015; McPherron et al., 2011). As these flows decel-64 erate, their associated kinetic energy is deposited into the local plasma population, lead-65 ing to a turbulent cascade (Stawarz et al., 2015). One significant question is how that tur-66 bulent cascade is dissipated on the kinetic scales. Ergun et al. (2015) and Zhang et al. (2020) 67 reported the presence of double layers in the flow-braking region, which can act to dissi-68 pate small-scale currents in turbulence. A clear signature of these double layers is a train 69 of electron phase-space holes. One challenge in studying the characteristics of electron phase 70 space holes and other ESWs in the BBF braking region is the fact that they correspond 71 to structures on the order of a few Debye lengths. These structures consequently require 72 high-resolution electric field measurements in order to be studied. 73

Another example in which TDSs can play an important role is at shocks. Localized ion-acoustic waves and other nonlinear, localized wave events have long been associated with shocks and may play a role in thermalizing the heated electron and ion distributions (e.g. Formisano & Torbert, 1982; Fuselier & Gurnett, 1984; Wilson et al., 2014; Goodrich et al., 2018). TDSs are also seen along the separatrix of magnetic reconnection (e.g. Wilder et al. (2016)). Nonlinear kinetic structures are an important indicator of substantial energy exchange or dissipation.

In 2015, NASA launched the Magnetospheric Multi-scale (MMS) mission in order to 81 study the phenomenon of magnetic reconnection in Earths magnetosphere, with an instru-82 ment suite optimized for the study of kinetic plasma physics. The MMS suite includes six 83 electric field double probes: the Spin-plane Double Probes (SDP) are 120 m tip-to-tip in 84 the spin plane (Lindqvist et al., 2016) and the Axial Double Probes (ADP) extend 15 m 85 from each side of the spacecraft along the axis of rotation (Ergun et al., 2016). Together, 86 the SDP and ADP capture the 3-D electric field. The EDP burst data mode includes DC-87 coupled electric fields measured at a configurable rate up to 16,384 samples/s and AC cou-88 pled fields measured at up to 262,144 S/s. Burst-mode data also includes electron and ion 89 distributions and moments measured by the Fast Plasma Investigations (FPI) at 30 ms and 90 150 ms cadence, respectively(Pollock et al., 2016). The high-cadence burst data is ideal 91 for investigating TDS events. However, high-cadence burst is available for less than 4% 92 of an MMS orbit on average. The advantage MMS has for the study of ESWs and TDSs 93 is an onboard, always-on Solitary Wave Detector (SWD). This algorithm operates in each 94 spacecrafts digital signal processing (DSP) board and searches the burst data from the spin-95 plane electric double probes (SDP) for non-linear spiky wave structures (Ergun et al., 2016). 96 Specifically, SWD examines only signals from the first set of opposing spin-plane probes 97 (V1-V2) by default and uses V3-V4 as a fallback. The SWD algorithm reports the num-98 ber of TDS events detected in a given amplitude range as a histogram. In addition to study-99 ing individual wave events in the burst, MMS therefore provides the capability to study ESWs 100 in a statistical manner, since SWD data is available throughout the entire orbit and not re-101 stricted to burst data periods. 102

In the present study, we investigate the incidence of time domain structures in the 103 Earths magnetosphere with a focus on the near-Earth magnetotail. During intervals where 104 burst electric field data is available in the magnetotail, we compare the SWD data with the 105 actual observations of ESWs by the EDP instrument. We find that the SWD detects ap-106 proximately 60% of solitary waves observed in the tail (Table 1). We then generate sta-107 tistical maps of SWD counts, observing TDS occurrence throughout the Earths magne-108 tosphere. Additionally, we find that the SWD captures many of the boundaries in the Earths 109 magnetosphere, including the bow shock, radiation belts, magnetopause, and possibly even 110 the BBF braking region. This suggests that algorithms like the SWD can be useful in large-111 scale studies of magnetospheric activity. 112

2 Solitary Wave Detector Algorithm

The MMS DSP SWD algorithm operates in real-time aboard each MMS spacecraft. The DSP analog-to-digital converters take capacitively coupled voltages from the V1-V2 spin-plane electric double probes (EDP) as inputs. A 1/256th second sliding window is used to test for the presence of TDS; within the SWD algorithm, EDP data is downsampled from 262,144 S/s to 65,536 kS/s and its average value over a single 256-point window's width is removed. A pseudo-RMS value is then determined for each unique window as follows (Ergun et al., 2016):

$$pRMS = \frac{1}{n} \sum_{i=0}^{n-1} |E12_i| \tag{1}$$

where *n* is the number of samples per window and $E12_i$ is the *i*th measured parallel electric field value between spin-plane probes 1 and 2. Bin voltage thresholds were precomputed and stored in the DSP (Ergun et al., 2016).

The peak value of |V| within the window is divided by the pRMS to determine the number of pseudo-standard deviations of the peak. If this value is above a configurable constant (currently 4), the event is determined to be a solitary wave or nonlinear structure and one of four counters is incremented (Ergun et al., 2016). Each second, these counters are recorded and reset. Four event counters are used to register the peak amplitudes of the event. The four counters represent, approximately, 0.3 to 3 mV/m, 3 to 12 mV/m, and >50 mV/m. The instrument saturates at 333 mV/m.

In short, the SWD selects peaks in 4 ms periods that are 4 pseudo-standard devia tions above background, which corresponds to approximately 3.58 standard deviations (true
 RMS). Under a purely random sequence of sufficient amplitudes, the SWD selects one event
 every 5000 seconds (background).

3 SWD Case Study and Validation

This case study occurs between 2016-08-09/09:00:00-10:00:00 UTC. An overview of the event can be found in Figure 1.

TDS Amplitude Bin	Absolute N	Intercept	Slope	r	r^2	StdErr
3 - 12 mV/m	28299	0.3784	0.6125	0.699	0.487	0.005
12 - 50 mV/m	7354	0.0981	0.6206	0.720	0.518	0.005
50+ mV/m	322	0.0076	0.5932	0.599	0.359	0.007

Table 1: Regression parameters for efficacy of MMS SWD bins 2, 3, 4 as gauged by relative measurement accuracy against ground algorithm (MMS1,2,3,4 2016-08-09 09:00:00 -10:00:00 UTC)

The key assumption behind the SWD is that the presence of time-domain structures 138 (TDS) - electron holes or otherwise - can be deduced from one component of the electric 139 field at a high enough sample rate. With only one axis of measurement per spacecraft, how-140 ever, some fraction of TDS events will be missed, particularly those with low-amplitude. 141 By contrast, high-amplitude ESW as observed in Goodrich et al. (2018) are rare and vi-142 sually distinct (Figure 1, near 2016-08-09 09:20:00 UTC). Furthermore, two closely-spaced 143 bipolar structures may raise the RMS background so that neither of the events are detected. 144 The challenge in gathering useful statistics about TDS is to accurately detect and count 145 lower-amplitude TDS. 146

3.1 MMS SWD Calibration and Interpretation

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Bipolar electric field structures are known to be abundant in the near magnetotail, so we characterize how well the SWD detect these structures so that the SWD data can be better interpreted. We compare the SWD with selections from AC-coupled burst data recorded from the 1-2 spin plane electric double probes (EDP) shown in Figure 1(f). A more

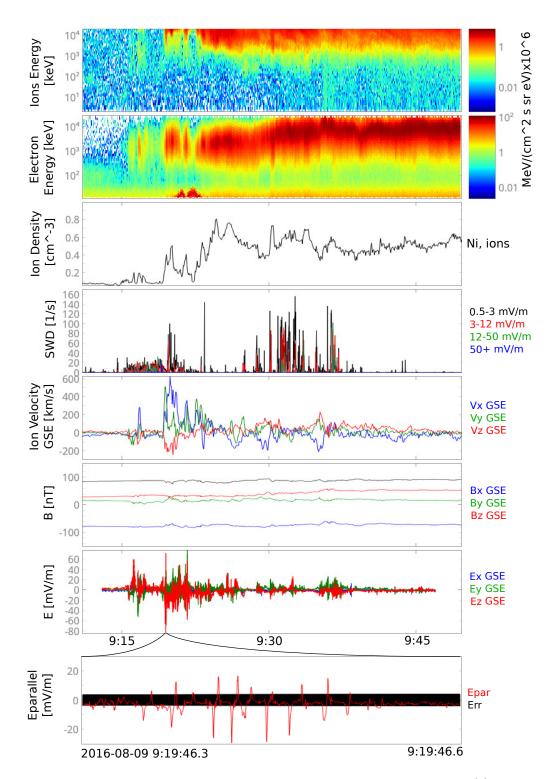


Figure 1: Case study plot for bursty bulk flow braking event in Earth near-tail; (a) electron energy spectra; (b) ion energy spectra; (c) ion density; (d) DSP SWD counts; (e) ion bulk velocity; (f) GSE electric field; (g) GSE magnetic field; and (h) zoomed segment of Eparallel, showing individual ESWs. MMS1 data from 2016-08-09 09:00-9:45 UTC. From the Bx (GSE) component of the magnetic field, the MMS spacecraft was in the southern lobe. At around 9:20 UT, the Bx-component magnitude decreases, as the Vx (GSE) component turns strongly northward, with a magnitude exceeding 600 km/s. Further, after the flow enhancement there is an increase in plasma density. All of these are signatures of a bursty bulk flow (BBF) (Sergeev et al., 2009). BBFs are a phenomena where ESWs can be observed (Ergun et al., 2015) and are thus ideal to evaluate the performance of the SWD.

sophisticated algorithm acting on high-cadence data is used to segment solitary waves and 152 characterize them by rescaling to fit a prototypical bipolar waveform, or kernel. A descrip-153 tion of this ground algorithm is located in Appendix A. The observation period for this char-154 acterization is 2016-08-09 from 9:00-10:00 UTC, the same data displayed in Figure 1. Dur-155 ing this time period, MMS was in the near tail circa GSE X = -7.7, Y = 3.2, Z = 0.44. This 156 characterization is primarily relevant to observations in the tail (e.g. the BBF braking re-157 gion) and less applicable where ion-acoustic waves are more active, such as the bow shock 158 (Goodrich et al., 2018). 159

A linear fit of SWD against ground TDS detector counts for the highest three bins (2-4) is described in Table 1, and plots showing data and regression lines for each bin are found in Figure 2. In these regressions, the abscissa is the ground algorithm count; the ordinate is the count rate provided by DSP SWD.

The correlation coefficients of these regressions are in the range of 0.59 - 0.62; for 164 every bipolar event present per second (as established by the ground TDS algorithm), the 165 SWD registers approximately 0.6 events per second. Variance in TDS counts only explain 166 35-51% of the variance in SWD counts for the two highest bins. Particularly at high bipo-167 lar event densities, the SWD tends to underestimate occurrence rates; if other non-ESW-168 like structures are present, e.g. Whistler waves, which still fulfil the SWD requirement of 169 a high peak-to-pRMS ratio, the SWD count can be inflated. Such non-bipolar events may 170 explain the unusually high expected Bin 2 count rate of 0.3784 given zero TDS. 171

Another possible mechanism for variance in the SWD is erroneous binning, where superposed structures artificially increase peak-to-peak values or digital filtering flattens them, causing detected structures to be placed in too high or too low a bin. To reduce the error caused by this effect, the ground detector assigns amplitude bins using the average peak amplitude for each TDS rather than the maximum absolute value.

The MMS SWD algorithm allows TDS occurrence rates and amplitudes to be logged 177 over full orbits of the MMS constellation. (Ergun et al., 2016) Previous studies have char-178 acterized limited numbers of ESWs by velocity, temporal duration, potential, length, etc. 179 In general, ESWs have been detected by the Geotail and THEMIS spacecraft with veloc-180 ities between 6,000-38,000 km/s, temporal durations between 0.5-20 milliseconds, lengths 181 circa 1 λ_D , and potential depths of 1.3-270 V. (Omura et al., 1999) Physical scales of ESWs 182 and BBFs tend to scale with Debye length, which decreases as |B| increases, e.g. at dis-183 tances closer to Earth; consequently, ESWs far from Earth or in the far tail (>80 Re) are 184 typically larger than those closer to the Earth (Omura et al., 1999). 185

Pulse trains of ESWs with smaller amplitudes (~100 $\mu V/m$) have been observed in 186 the far tail (circa GSM X = -120 Re) as reported in other research (Kojima et al., 1999). 187 From 2015-2020, MMS' apogee over Earth remained within 30 Re or less, and the min-188 imum threshold necessary to trigger the SWD corresponded to an amplitude of 0.5 mV/m. 189 During observation periods near the dayside magnetopause, when the MMS spacecraft are 190 in close formation (<10 km separation), the same patterns of solitary waves have been seen 191 on multiple satellites (Holmes et al., 2018). Large ranges in length scales and speeds have 192 been observed (Graham et al., 2016), on the order of 10-20 λ_D and 3000-10000 km/s re-193 spectively (F. S. Mozer et al., 2016). The scope of this case study is thus limited to the 194 particular regime between 1.5-30 Re in GSE X and Y and -6 to +6 in GSM Z where time 195 domain structures of interest exceed amplitudes of 0.5-3 mV/m. 196

3.2 Spatial Map Observations

¹⁹⁸ In the previous subsection, we have shown that the SWD can detect approximately ¹⁹⁹ 60% of bipolar events in the Earth's magnetotail, enabling its use in statistical studies. Since

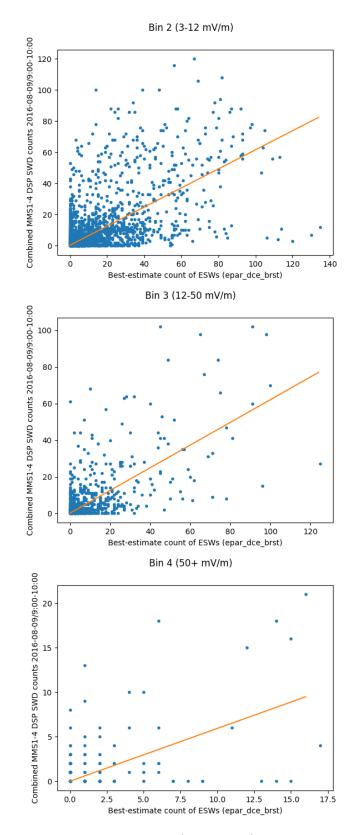


Figure 2: Case study of DSP SWD counts (Bins 2, 3, 4) plotted against ground algorithm bipolar event counts (blue) with best-fit regression lines (orange)

the SWD is the first algorithm of its kind on a spacecraft, it is valuable to map out the counts 200 through the duration of the mission so as to determine an average representation of con-201 ditions in the magnetosphere. We thus generate maps (Figures 3-4) using data from all 202 four MMS spacecraft starting in August 2015 (shortly after launch) through March 2020. 203 This encompasses a broad range of magnetospheric history and space; the MMS space-204 craft surveyed nearly all points within a radius of 30 Re from Earth defined by our rectan-205 gular grid scale of 1 Re. Most of the characteristic features of Earth's magnetosphere are 206 present in the SWD maps: the bow shock, magnetosheath, and one or both of the Van Allen 207 belts are visible. The bow shock visible in SWD maps can be compared to the bow shock 208 clearly denoted by the ion bulk velocity discontinuity (rapid divergence from solar wind bulk 209 velocity, Figure 5) and the ion density gradient (sharp increase in ion density, Figure 6), all 210 shown with a plotted average bow shock and magnetopause. In SWD maps, the bow shock 211 signature extends farther into the solar wind than the statistical shock or either boundaries 212 shown by ion data. By comparison, the magnetopause boundary appears absent from the 213 SWD maps, while it is clearly visible in ion density (sharp density decrease, corresponding 214 to Earth's near-vacuum plasmasphere) and bulk velocity (gradual reversal of flows in the 215 +X direction). A different gradient is visible in SWD maps, closer to the midline of the mag-216 netosheath. 217

Based on past statistical studies showing tailward BBFs are more prominent on the dusk (+Y) side of the magnetotail, while Earthward flows are nearly symmetrically distributed or slightly more prominent on the dusk side (Kiehas et al., 2018), it is an unexpected result that the SWD counts are concentrated on the dawn (-Y) side. ARTEMIS studies in the midtail magnetosheath have shown substantially higher fluxes for hot electron enhancements on the dawn side versus the dusk side, which could explain this asymmetry (Wang et al., 2015).

Figure 4 shows that the average for 3-12 mV/m solitary waves in the magnetosheath is approximately 1.5/s per spacecraft. Within the solar wind, and towards the magnetotail, the average is approximately 0.001/s, or one TDS every 1000 seconds. The largest observed average value, of around 250/s in bin 1, highlights the instrument's maximum counting capability of 256/s; a maximum of 10-50/s in bins 2-3 is seen around the bow shock and magnetopause.

As seen in Figure 1, TDS with amplitudes >50 mV/m are relatively rare, contributing to the sparseness of maps of higher amplitude bins (Figure 4, bottom). For the maps of 50+ mV/m TDS, all spatial bins have averages lower than $10^{-4.5}/s$, corresponding to an average period of approximately 9 hours between individual detection events. By contrast, the high counts in the bow shock could include various ESW and non-ESW time-domain structures such as double layers and non-linear acoustic wave bursts (Goodrich et al., 2018).

Similar gradients in count rates across the magnetopause, bow shock, and solar wind 237 are present in all amplitude bins. The spatial resolution of these maps is limited by sam-238 ple density and dynamic range (i.e. number of amplitude bins), but some key differences 239 between the maps are present. For example, a hot spot near GSM X,Y = (-3,-4) Re ap-240 pears sharpest in the 12-50 mV/m amplitude range (Bin 3) as compared to bins 1, 2, or 241 4, while the Van Allen belt ring structure at 2-3 Re appears much more continuous in Bin 242 1 than Bins 2-4. The overall BBF braking region SWD enhancement, by contrast, is ap-243 proximately the same size (15 Re across) across all bins. Interestingly, the map of 12 to 244 50 mV/m TDS (Figure 4, top) has a visible peak in the dawn-side radiation belt at L =245 4. The character of the events cannot be examined for this unexpected peak since MMS 246 does not acquire burst data inside 7 Re. 247

- These maps indicate that some TDS are present within the solar wind but not at a
- significant level (less than one per 10^7 seconds). This finding is consistent with WIND ob-
- servations in the solar wind (Malaspina et al., 2013).

251 4 Conclusions

The primary goal of the Magnetospheric Multiscale Mission is to improve our understanding of magnetic reconnection and the distribution of energy across multiple scale regimes in Earth's magnetosphere. The Solitary Wave Detector aboard MMS is a unique algorithm that provides complex data about electric field phenomena relative to its hardware cost and downlink impact.

Through a statistical study of typical SWD and parallel electric field data, we find that the SWD performs as intended; namely, it observes electron phase-space holes and detects structures associated with magnetic reconnection (Ergun et al., 2016). We found that SWD counts are approximately 60% correlated with TDS detectable via ground software on the spin-plane electric double probes. However, with none of the amplitude levels' r-squared values exceeding 0.518, only around 45% of the variance in SWD is explained by actual TDS occurrence.

It is difficult to determine the exact nature of events observed by SWD, because the algorithm does not differentiate between different types of plasma structures. Nonetheless, it correctly and consistently identifies large excursions in the electric field. For a scientistin-the-loop (SITL) whose task is to select which segments of high-fidelity data should be downlinked, enhancement in SWD counts can highlight plasma activity like dipolarization fronts and bursty bulk flows (Le Contel et al., 2017), which can inform potentially novel observations that may be more difficult to see in survey data.

The SWD algorithm also presents information in a simple format that is amenable 271 to visualization. Within spatial maps of average SWD counts, one can perceive basic fea-272 tures of Earth's magnetosphere: the bow shock, magnetopause, and van Allen belts. Each 273 feature has a recognizable signature and is essentially spatially consistent with our under-274 standing of Earth's magnetospheric system. Filtering by amplitude bin enhances the vis-275 ibility of certain regions and reduces the visibility of others, showing spatial differences in 276 energetic ESW evolution. Moreover, compiling multi-year observations from MMS can bring 277 previously unobserved large-scale asymmetries and gradients into view. Through a four-year 278 mapping of data from MMS, we show various important features of the magnetosphere as 279 illuminated by the SWD. 280

At Earth's bow shock, the SWD can pick up a variety of nonlinear plasma structures including solitary waves, double layers, and nonlinear ion-acoustic wave packets that are bursty in nature (Goodrich et al., 2018, 2019). At the magnetopause, magnetic reconnection is a potential source for solitary waves by producing unstable electron distributions and/or strong currents (Graham et al., 2016). Both the bow shock and magnetopause are visible in maps of SWD data.

One striking result is how well the SWD captures the Van Allen belts. F. Mozer et 287 al. (2013) suggested that TDS, including double layers and ESWs, are important for the 288 dynamics of the Van Allen belts, and the present study confirms that these structures are 289 ubiquitous in that region (Figures 3-4). Past (and present) research has used transitions 290 in data revealed by new instruments to perform statistical analyses of the regions and dy-291 namics giving rise to those transitions (Neugebauer & Snyder, 1962); that the SWD con-292 sistently marks the location of magnetospheric phenomena suggests that it is also possi-293 ble to perform more detailed statistical studies of SWD counts in various regions. 294

Substorm models of magnetospheric activity have typically included bulk flows (BF) toward the Earth resulting from energy released during tail magnetic reconnection (Sergeev et al., 2009). SWD maps show a clear enhancement in TDS density in this tailward 6-9 Re region.

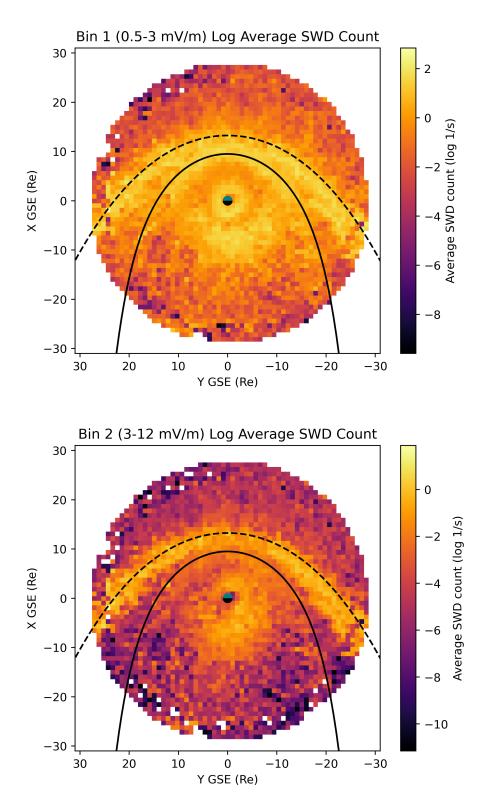


Figure 3: Composite maps from MMS 1-4 of log mean SWD count rates (Bins 1-2) within GSM X-Y plane between August 2015 and April 2020; statistical bow shock (dashed), magnetopause (solid) and Earth (blue/black) shown.

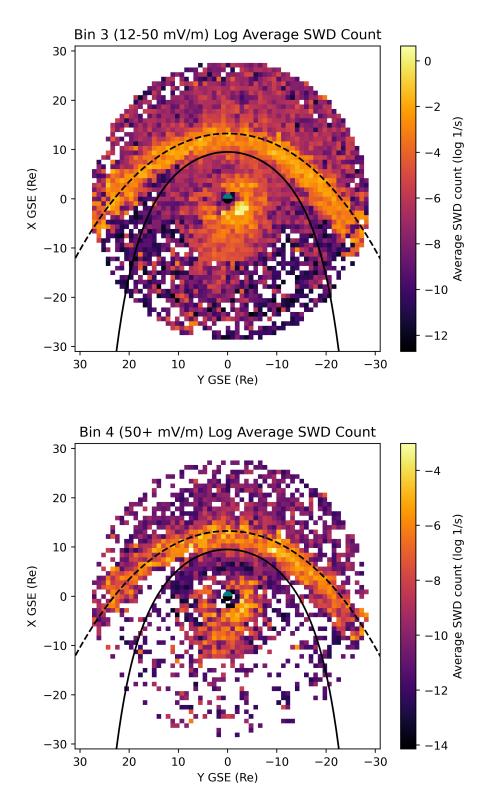


Figure 4: Composite maps from MMS 1-4 of log mean SWD count rates (Bins 3-4) within GSM X-Y plane between August 2015 and April 2020; statistical bow shock (dashed), magnetopause (solid) and Earth (blue/black) shown.

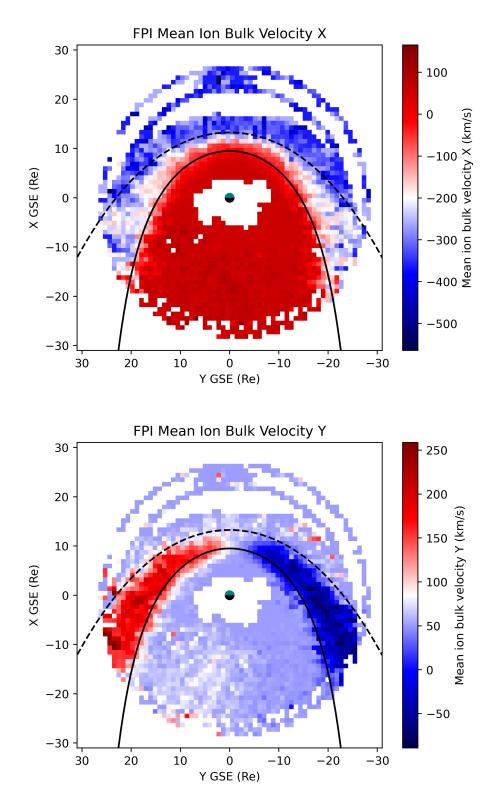


Figure 5: FPI ion bulk velocity along GSE X (top) and Y (bottom) vectors; statistical bow shock (dashed), magnetopause (solid) and Earth (blue/black) shown. Data gathered between August 2015 and April 2020.

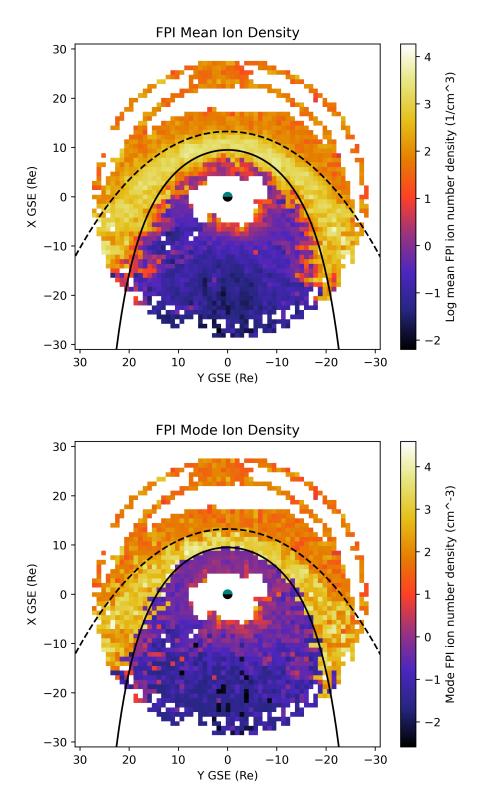


Figure 6: Average (top) and typical (bottom) ion number density; statistical bow shock (dashed) and magnetopause (solid) and Earth (blue/black) shown. Data gathered between August 2015 and April 2020.

Most surprisingly, the dawn-dusk braking region is asymmetrically biased towards the 299 dawn side of Earth; this is an unexpected and important result. This asymmetry is present 300 in maps from bins 1-4, corresponding to all amplitudes of TDS > 0.5 mV/m observed by 301 MMS SWD. A hot spot within this region is visible around X = -2 Re, Y = -3 Re (Figure 302 4, top); given that these observations are mostly independent of Earth's rotation, this fea-303 ture may be fixed with respect to the solar wind and not some structure of Earth's mag-304 netic field fixed to the surface (e.g. the South Atlantic Anomaly). A slight asymmetry in 305 bulk GSE Y velocity is also visible on the dusk tail of Earth near 10 Re (Figure 5); how this 306 connects to the SWD asymmetry is unclear. Future work evaluating SWD and FPI data 307 in the context of IMF direction changes, hot electron enhancements and other parameters 308 could provide more clarity regarding this asymmetry (Wang et al., 2015; Kiehas et al., 2018). 309

Appendix A Methods

311

A1 DSP SWD Validation

A TDS counter was implemented in software for this validation. It operates on the principle of minimizing the maximum electric field difference between candidate solitary structures and a pseudo-sinusoidal bipolar function. Once TDS are fit, their time-series data are removed from the remaining data and fit parameters recorded. Fitting parameters include the peak-to-peak width, amplitudes of both peaks, residuals of real data against the fit, and the predicted center time of the ESW.

The ground algorithm takes as input 65 kS/s electric field data interpolated from 8192 318 S/s burst data collected across spin plane probes V1-V2. It identifies bipolar solitary wave 319 structures top-down by searching for the largest time-domain structure by peak amplitude. 320 After locating the maximum absolute electric field value, the algorithm attempts to iden-321 tify the structure's polarity by searching within a fixed number of samples of that absolute 322 maximum for a corresponding local minimum or maximum. The algorithm then fits a mod-323 ified sine wave to the structure's position, average peak-to-peak amplitude, and peak-to-324 peak spacing, interpolates the fitted data to align with the DCE data, records the fit pa-325 rameters, then subtracts the fitted structure from the data. 326

The prototypical bipolar ESW signal used for validation has an amplitude of 1; peak-327 to-peak value of 2; and resolution of 122 sample points. The first peak is positive, and the 328 second is negative; we refer to this polarity as a positive ESW. In the fitting process, it is 329 centered on the ESW within 1 sample point and scaled horizontally until the x-index of each 330 peak is within 1 sample point of the x-index of the corresponding recorded peak. To match 331 the sample rate of EDP data, this horizontal fit is interpolated onto the recorded time range. 332 The horizontal fit is subsequently scaled vertically on either side of the zero-crossing to match 333 the amplitude of each peak. 334

An error parameter is calculated by dividing the sum of the absolute values of the subtracted sequence by the sum of the absolute values of the original sequence. If this pseudo-RMS is less than 0.2, a value manually tuned to the calibration data sequence, the fit is considered successful and the structure is counted. Otherwise, the fit is rejected. Any nonbipolar signal (like a single peak from dust impact, or a nearly continuous whistler wave) would be rejected due to its lack of similarity to the prototypical ESW signal.

In either case, the data series from the beginning to the end of that particular TDS is set to 0. The time duration of data zeroed out per structure is limited to at most 1.5 ms for structures below 50 mV/m and increases stepwise to 3.5 ms for structures larger than 100 mV/m. This conservative upper limit was set according to the assumption that structure width scales linearly with amplitude. The typical amount of time-series data removed was three times as long as the distance between the two detected peaks.

The fitting and zeroing process repeats until the maximum amplitude across the en-347 tire modified data sequence falls below a certain threshold; at that point, the algorithm writes 348 all recorded parameters and success/rejection values. The amplitude threshold set for this 349 work was 3 mV/m. At and above this value, the algorithm was able to terminate; with the 350 threshold set lower, e.g. between 0.5 and 1.5 mV/m, the algorithm produced greater than 351 90% failed fits near the threshold. Since the lowest SWD bin within this limit is Bin 2 (3-352 12 mV/m), Bin 1 (0.5-3 mV/m) was excluded. More sophisticated algorithms could im-353 prove on this lower limit. 354

As the ground TDS detection algorithm ignores any time segments already analyzed, it is incapable of detecting solitary waves with more than 10-20% overlap. When simulated e-parallel data (with ESWs placed with uniformly random distributions and amplitudes) is supplied as an input, the ground TDS counter is able to detect 75% of all artificial ESW placed within the data, corresponding to a 25% false negative rate. Since the SWD is only able to count a single TDS within each of its sampling windows, we expect that a similar limitation will be present.

As for false positives, the ground TDS detection algorithm only examines a signal if its maximum amplitude exceeds that of all other signals in the same time series. The MMS SWD algorithm false positive rate, by comparison, is dependent on the density of non-ESW signals; it will nearly always trigger on a continuous wave provided the wave's frequency is near 1-2 kHz. In other words, the SWD has continuous false positives in certain locations, e.g. the bow shock, where the electric field is constantly changing.

A2 Map Generation

Maps were generated using binning (Oliphant, 2006; Van Der Walt et al., 2011; Hunter, 369 2007). The continuous nature of the SWD enables continuous, full-orbit mapping data from 370 DSP activation (Ergun et al., 2016). Maps were generated using DSP SWD, geocentric 371 magnetic coordinate ephemeris and FPI data collected from 2015-08 to 2020-03. 3D spa-372 tial maps were flattened into 2-dimensional XY-plane maps prior to statistical analysis; in 373 this manner, dwell times in each bin were accurately represented. Maps are rendered with 374 the North pole (GSE +Z) pointing out of the page. Blank (white) pixels represent spatial 375 bins where none of the spacecraft recorded data. 376

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Figure 1.

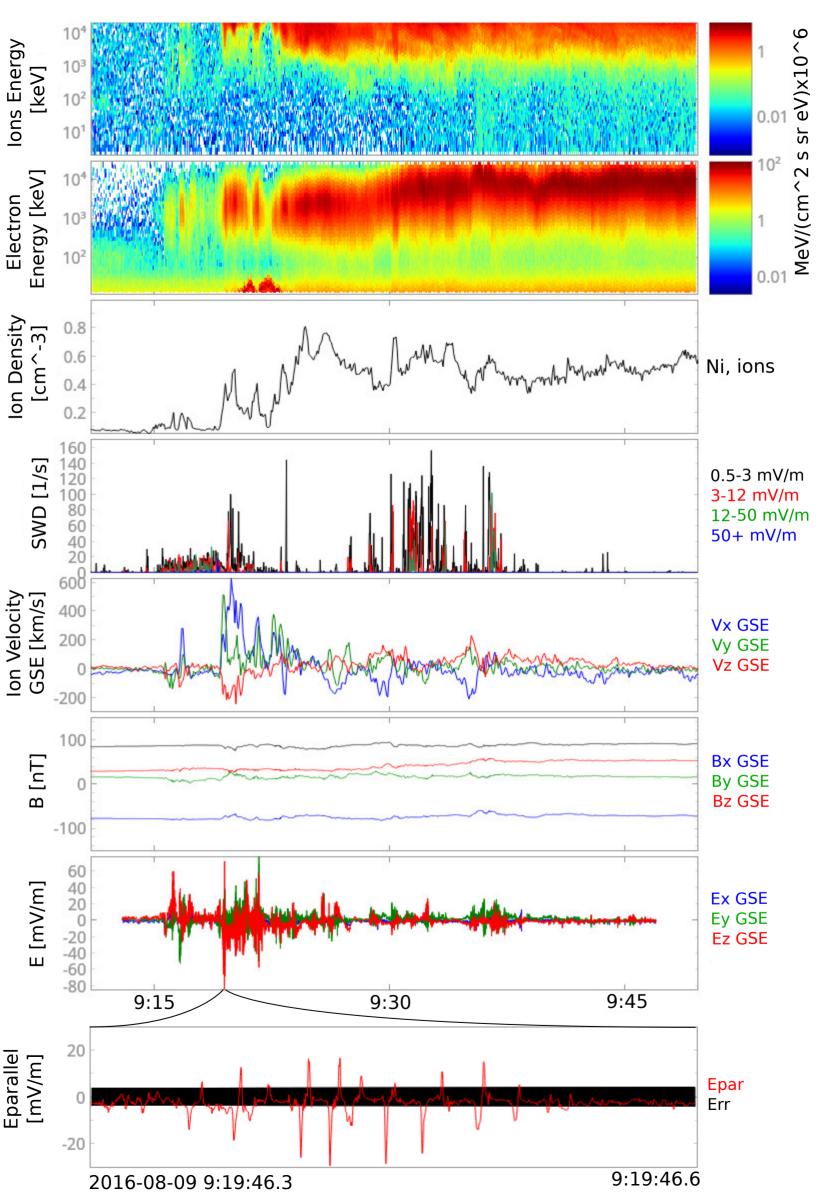


Figure 2A.

Bin 2 (3-12 mV/m)

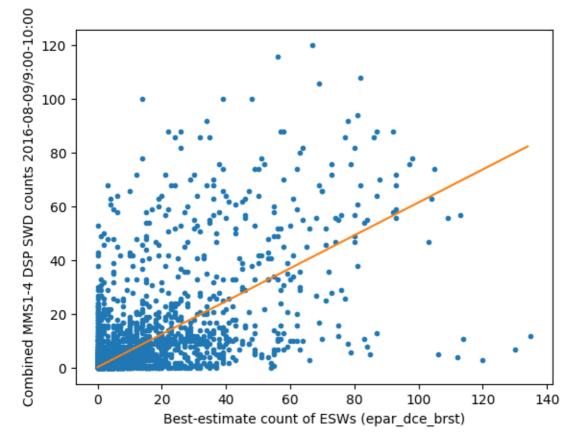


Figure 2B.

Bin 3 (12-50 mV/m)

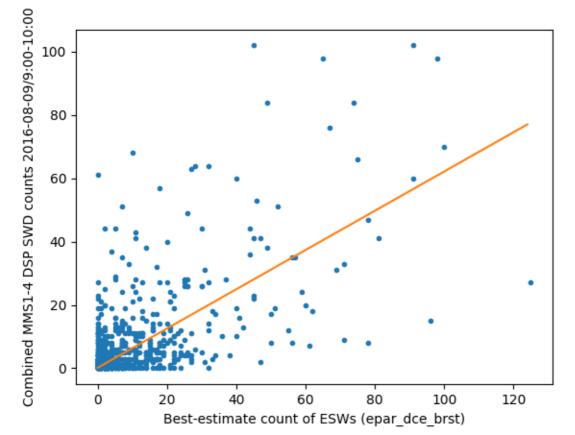


Figure 2C.

Bin 4 (50+ mV/m)

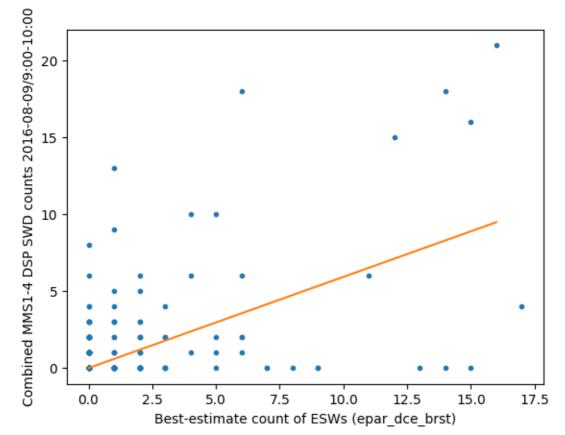
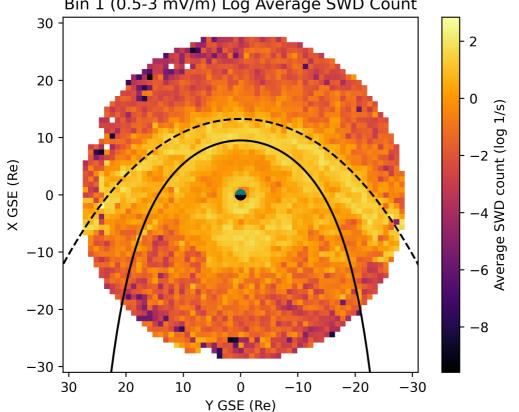
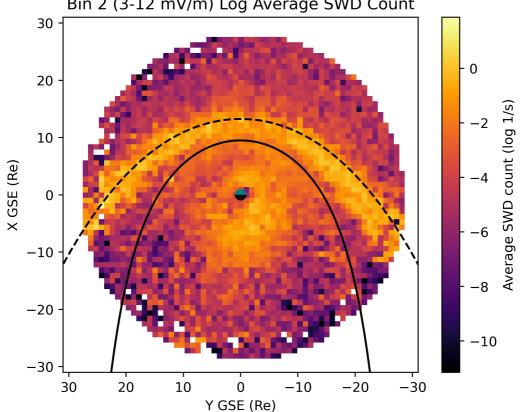


Figure 3A.



Bin 1 (0.5-3 mV/m) Log Average SWD Count

Figure 3B.



Bin 2 (3-12 mV/m) Log Average SWD Count

Figure 4A.

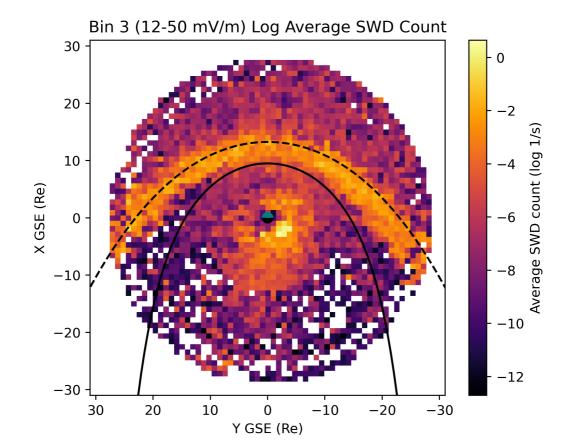


Figure 4B.

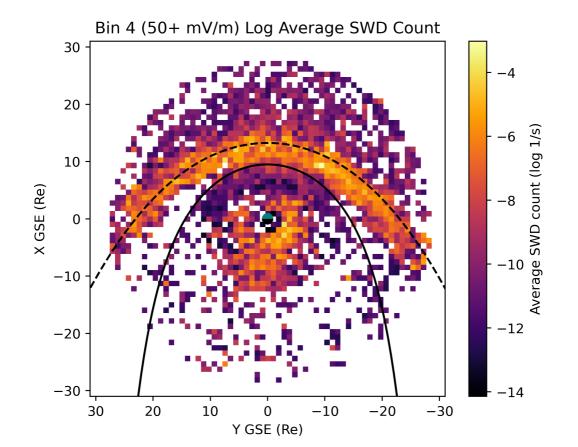


Figure 5A.

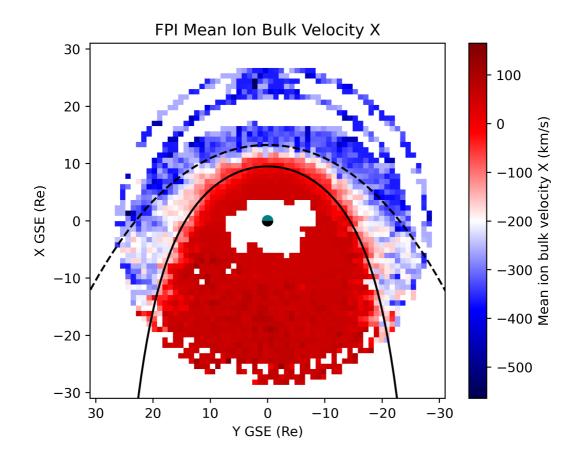


Figure 5B.

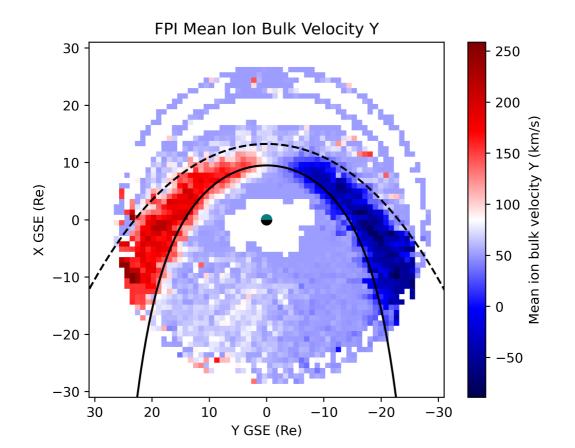


Figure 6A.

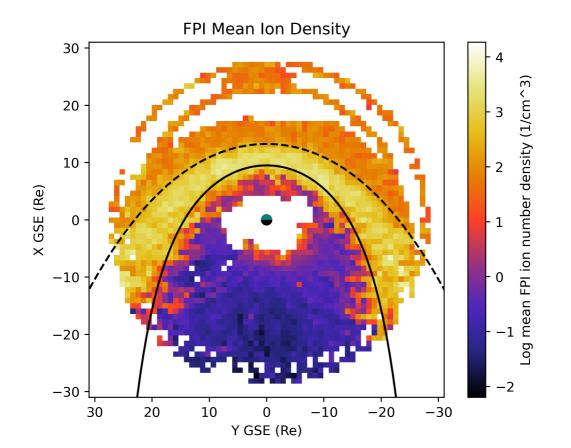


Figure 6B.

